Modelling the influence of the hippocampal memory system on the oculomotor system

Abbreviated title: Mapping the dynamics of hippocampal responses in oculomotor regions

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Abstract

Visual exploration is related to activity in the hippocampus (HC) and/or extended medial temporal lobe system (MTL), is influenced by stored memories, and is altered in amnesic cases. An extensive set of polysynaptic connections exists both within and between the HC and oculomotor systems such that investigating how HC responses ultimately influence neural activity in the oculomotor system, and the timing by which such neural modulation could occur is not trivial. We leveraged TheVirtualBrain, a software platform for large-scale network simulations, to model the functional dynamics that govern the interactions between the two systems in the macaque cortex. Evoked responses following the stimulation of the MTL and some, but not all, subfields of the HC resulted in observable responses in oculomotor regions, including the frontal eye fields (FEF), within the time of a gaze fixation. Modeled lesions to some MTL regions slowed the dissipation of HC signal to oculomotor regions, whereas HC lesions generally did not affect the rapid MTL activity propagation to oculomotor regions. These findings provide a framework for investigating how information represented by the HC/MTL may influence the oculomotor system during a fixation and predict how HC lesions may affect visual exploration.

Author Summary

No major account of oculomotor (eye movement) guidance considers the influence of the

hippocampus (HC) and broader medial temporal lobe (MTL) system, yet it is clear that

information is exchanged between the two systems. Prior experience influences current

viewing, and cases of amnesia due to compromised HC/MTL function show specific

alterations in viewing behaviour. By modeling large-scale network dynamics, we show

that stimulation of subregions of the HC, and of the MTL, rapidly results in observable

responses in oculomotor control regions, and that HC/MTL lesions alter signal

propagation. These findings suggest that information from memory may readily guide

visual exploration, and calls for a reconsideration of the neural circuitry involved in

oculomotor guidance.

Introduction

Memory influences ongoing active exploration of the visual environment (see Hannula et al., 2010 for review). For instance, more viewing is directed to novel versus previously viewed items (Fagan, 1970; Fantz, 1964), and more viewing is directed to areas that have been altered from a prior viewing (Ryan, Althoff, Whitlow, & Cohen, 2000; Smith, Hopkins, & Squire, 2006). A number of studies have implicated a network of subregions within the hippocampus (HC) and/or broader medial temporal lobe (MTL) responsible for the influence of memory on viewing behavior. Amnesic cases who have severe memory impairments due to compromised function of the HC and/or MTL show changes in their viewing behavior compared to neurologically-intact cases (Chau, Murphy, Rosenbaum, Ryan, & Hoffman, 2011; Hannula, Ryan, Tranel, & Cohen, 2007; Olsen et al., 2015; Ryan et al., 2000; Warren, Duff, Tranel, & Cohen, 2010). Similar findings have been observed in older adults who have suspected HC/MTL compromise (Ryan, Leung, Turk-Browne, & Hasher, 2007), and certain viewing patterns have been shown to track with entorhinal cortex (ERC) volumes (Yeung et al., 2017). Visual exploration predicts HC activity during encoding (Liu, Shen, Olsen, & Ryan, 2017), and, conversely, HC/MTL activity predicts ongoing visual exploration that is indicative of memory retrieval (Hannula & Ranganath, 2009; Ryals, Wang, Polnaszek, & Voss, 2015). The relationship between visual sampling and HC activity is weakened in aging, presumably due to decline in HC structure or function (Liu, Shen, Olsen, & Ryan, 2018). Such evidence collectively demonstrates that HC/MTL function is related to oculomotor *behavior*. The indirect implication of these studies is that the HC must influence *neural activity* in the oculomotor system.

Studies in non-human primates have shown that HC/MTL activity is linked to

oculomotor behavior. The activity of grid cells in the ERC are tied to eye position

(Killian, Jutras, & Buffalo, 2012), while HC/MTL activity is modulated by saccades

(Sobotka, Nowicka, & Ringo, 1997) and fixations (Hoffman et al., 2013; Leonard et al.,

2015). How HC/MTL activity traverses the brain to influence the oculomotor system has

not been shown to date. The oculomotor system is itself a highly recurrent and distributed

network (Parr & Friston, 2017) comprised of cortical and subcortical regions responsible

for the execution of a saccade (e.g., frontal eye field, FEF; superior colliculus, SC) as

well as regions that exert cognitive control over where the eyes should go (e.g.,

dorsolateral prefrontal cortex, dlPFC; anterior cingulate cortex, ACC; lateral intraparietal

area, area LIP) (Bisley & Mirpour, 2019; Johnston & Everling, 2008). Prior work has

speculated as to which regions of the brain may be important for bridging the memory

and oculomotor systems (e.g., Meister & Buffalo, 2016; Micic, Ehrlichman, & Chen,

2010), but these discussions were limited to regions examined in isolation. There are no

known direct connections between hippocampal subfields and the oculomotor system.

Yet, by examining whole-cortex connectivity, we have shown that there is an extensive

set of polysynaptic pathways spanning extrastriate, posterior parietal, and prefrontal

regions that may mediate the exchange of information between the oculomotor and

memory systems (Shen, Bezgin, Selvam, McIntosh, & Ryan, 2016). Given the vast

anatomical connectivity within and between the memory and oculomotor systems, trying

to discern the functional network involved in bridging them is not a trivial problem to

tackle. Specifically, the large and complex contribution of recurrent anatomical

connections to the functional dynamics of large-scale brain networks must be considered

(Spiegler, Hansen, Bernard, McIntosh, & Jirsa, 2016). One crucial question concerning

such functional dynamics is whether HC/MTL activity is able to influence the activity

related to the preparation of a saccade. In order to impact ongoing visual exploration,

HC/MTL activity would likely need to resolve in the oculomotor system within the time

of an average duration of a gaze fixation (~ 250-400 ms) (Henderson, Nuthmann, &

Luke, 2013).

To examine the extent to which HC/MTL activity could influence the oculomotor

system, we leveraged a computational modeling and neuroinformatics platform,

TheVirtualBrain, and simulated the functional dynamics of a whole-cortex directed

macaque network when stimulation is applied to HC and MTL nodes of interest.

Critically, we examined whether and when evoked activity culminated in responses in

key regions within the oculomotor system. Finally, we observed the extent to which the

propagation and timing of such activity was altered following lesions to one or more

HC/MTL regions in order to understand the neural dynamics that may underly altered

visual exploration in cases of HC/MTL dysfunction, such as in amnesia or aging.

Results

We modelled the influence of HC/MTL activity on the oculomotor system using a

connectome-based approach using TheVirtualBrain (see Methods for details). Following

Spiegler and colleagues (2016), we assigned a neural mass model to each node and set

each to operate near criticality, which is considered to be the point at which information

processing capacity is maximal (G. Deco et al., 2014; Ghosh, Rho, McIntosh, Kötter, &

Jirsa, 2008). Nodes were then connected together as defined by a weighted and directed

macaque structural connectivity matrix and the distance between them defined by a tract

lengths matrix. Without stimulation, this network exhibits no activity. However, with

stimulation, activity dissipates throughout the network according to the spatiotemporal

constraints imposed by the connectivity weights and distances. Cortical network

dynamics were set via additional parameter tuning such that stimulating V1 resulted in

biologically plausible timing of evoked responses in downstream visual cortical regions.

Finally, we systematically stimulated HC subfields and MTL regions of interest and

detected evoked responses across the rest of the network.

<u>HC Subregion Stimulation</u>

Stimulation of HC subfields and MTL regions of interest evoked widespread activation

across the network, similar to previous surface-based model simulations (Spiegler et al.,

2016). Figure 1 shows an example of activity dissipation following CA1 stimulation.

Evoked responses were first detected in other HC subfields and MTL regions but then

spread to prefrontal and extrastriate cortices, and later to posterior parietal cortex. The

full list of activation times for each of the 77 nodes can be found in Supplementary Table

2. However, in all subsequent analyses, we present only the results pertaining to our

nodes of interest, identified as those along the shortest paths between HC/MTL and

oculomotor regions (see Shen et al., 2016) or those that have been specifically suggested

in the literature to be potentially relevant (e.g., area LIP; Meister & Buffalo, 2016).

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Figure 1. Dissipation of activity over time across the cortex following stimulation of
CA1. Average above-threshold activation (arbitrary units) for each node for a 10-ms
epoch following each time point is plotted on the macaque cortical surface. Activations
were log scaled for the purposes of visualization. From left to right: ventral, dorsal,
medial and lateral views of the macaque cortical surface.

Stimulation of HC subregions CA1, subiculum (S), pre-subiculum (PrS), and

para-subiculum (PaS) resulted in observable responses in almost all of the cortical nodes

of interest, and within regions 46, 24, and FEF, of the oculomotor system (for CA1

example, see Figure 2A). Within our oculomotor regions of interest, activity was first

observed in area 46, followed by 24, and FEF, regardless of HC stimulation site.

Stimulation of the PrS resulted in the fastest observable responses in these oculomotor

areas (under 70 ms; Figure 3A). Stimulation of CA1 resulted in rapid activity that

culminated in oculomotor regions in under 220 ms (Figure 3B). Stimulation of either the

S or the PaS resolved into area 46 activity by 200 ms, into area 24 by 250 ms, and finally

into FEF by 500 ms (Figure 3C-D). Responses in area LIP occurred substantially later

than the other oculomotor areas and even later than all other cortical nodes for CA1 and

PrS stimulations (> 440 ms; Table 1). No evoked response was detected in area LIP

following stimulation of S or PaS. Responses were not observed in the majority of the

pre-defined cortical hubs following CA3 stimulation, and activity did not culminate in

observable responses in the oculomotor areas (Figure 2B). See Table 1 for activation

times for all nodes of interest.

Figure 2. (A) Stimulation of the CA1 (red circle) resulted in observable responses (blue circles) in multiple HC/MTL nodes, intermediary nodes, and in regions governing oculomotor control, including the frontal eye fields (FEF). (B) Stimulation of the CA3 (red circle) resulted in observable responses (blue circles) limited to HC/MTL nodes. Very few responses were observed in cortical areas and none were observed in oculomotor areas. Size and shade of the circles scale with elapsed time prior to an observed response. Grey lines denote direct structural connections between nodes. For visualization purposes, only regions that contribute to the shortest paths *from* HC/MTL *to* oculomotor nodes are shown. Connections between intermediary nodes (middle column) are not shown. Connections that are unidirectional and *away from* oculomotor areas (i.e., to HC/MTL) are indicated by dashed lines.

Figure 3. Response profiles (envelope of region time series) of oculomotor areas following stimulation of PrS (A), CA1 (B), S (C) and PaS (D). Activation is given in arbitrary units (a.u.). The onsets of the responses for each oculomotor area indicated by arrows. Area LIP did not exhibit a response that exceeded its baseline threshold following S and PaS stimulation.

MTL Stimulation

Stimulation of any of the broader regions within the MTL (entorhinal cortex, ERC;

perirhinal cortex, 35, 36; parahippocampal cortex, TF, TH) resulted in observable

responses within oculomotor areas 46, 24, and FEF well under 100ms, faster than the

responses observed from HC subfield stimulation. Of the MTL regions, stimulation of

area 35/36 resulted in the earliest responses in areas 46, 24, and FEF (within 25 ms).

Although evoked responses in area LIP occurred in under ~250 ms for all but ERC

stimulations, area LIP again exhibited the most delayed response across all nodes of

interest following MTL stimulations. See Table 1 for activation times for all nodes of

interest.

Cortical Responses

HC and MTL region stimulation (except for CA3) resulted in signal propagation across

all of our pre-identified cortical regions of interest. When CA3 was stimulated, cortical

responses were only observed in areas V2 and 25; no other signal was observed. Notably,

responses in areas 5 and 7a were generally observed *following* activity from oculomotor

regions, including FEF, suggestive of a possible feedback response. The exception is S

stimulation, in which responses in area 5 preceded responses in oculomotor regions by

~100 ms. Responses in V4 also followed oculomotor responses; except in cases of CA1,

TF, and TH stimulation. Likewise, responses in area 23 followed oculomotor responses,

except in cases of PrS and TH stimulation. See Table 1 for activation times for all nodes

of interest.

Lesion Models: HC subregions

Some models of HC and MTL lesions showed an appreciable effect on activation times

while others did not. Only the results for lesions that affected any activation time by at

least ±10 ms are shown. Lesion of CA3 changed neither the pattern nor the timing of

observable responses following stimulation of each of the other HC/MTL regions (data

not shown). Lesion of CA1 resulted in a lack of signal to V2, V4, area 23, and slowing of

signal from the subicular complex to various regions, including oculomotor regions FEF

and area 24 (Figure 4A; Supplementary Table 3). Lesion of CA1 also led to small

increases in the speed of signal following CA3 stimulation to the subicular complex, and

from MTL regions to TF/TH, and to other regions within the subicular complex (all less

than 10 ms).

Figure 4. Changes in activation times following HC lesions. Subicular stimulation
following CA1 (A) and ERC (B) lesions. Only nodes of interest are presented on the
brain surface plots. Activation time differences were computed by subtracting the pre-
lesion activation times from the post-lesion ones. Absence of response following a lesion
indicated in grey. From left to right: ventral, dorsal, medial and lateral views of the
macaque cortical surface.

Lesions to either the S or PaS produced little change to either the pattern or timing

of responses following stimulation of the other HC/MTL regions (data not shown).

Lesions to the PrS produced moderate changes (<20 ms) in timing: there was some

slowing of activity propagation from PaS to some cortical regions, including oculomotor

regions, and some speeding of signal propagation within the HC subfields and to TF/TH

(Supplementary Table 4).

A combined lesion to all HC subfields (CA3/CA1/S/PaS/PrS) did not

considerably change the pattern of signal propagation from the MTL cortices to

oculomotor regions. In cases where speeding/slowing was observed, the timing

differences were less than 15 ms, and mostly less than 10ms. Signal from the MTL

cortices still culminated within the oculomotor regions well under 50 ms (except for ERC

-> FEF at 79 ms, and LIP whose responses remained >140 ms) (Supplementary Table 5).

<u>Lesion Models: MTL regions</u>

Lesion of the ERC resulted in considerable slowing of observable signal in areas 24, 46

and FEF (30-340ms) following S (Figure 3B) or PaS stimulation (Supplementary Table

6). TF and/or TH lesions resulted in slowing (10-400ms) of signal following CA1, S, and

PaS stimulation to one or more of areas 24, 46 and FEF, and a lack of response in FEF

following PaS stimulation (only the combined TF/TH is shown; Supplementary Table 7).

<u>A</u>rea 35 and/or 36 lesions also resulted in slowing (10-90ms) of signal following CA1, S,

and PaS stimulation to one or more of areas 24, 46 and FEF, although not as severe as the

slowing observed following TF/TH lesions (only the combined 35/36 lesion is shown;

Supplementary Table 8).

<u>Other Cortical Lesions</u>

In our original stimulations, signals in regions 5, 7a, 23, and V4 were predominantly

observed following observable responses in oculomotor areas 24, 46 and FEF, suggesting

these cortical areas are receiving feedback signals rather than primarily serving as hubs to

transfer signal from the HC/MTL to the oculomotor regions. To explore this in more

depth, we simulated a combined lesion of 5/7a/23/V4 and examined signal propagation.

Following this combined cortical lesion, stimulation of each of the HC/MTL regions

(except for CA3) continued to result in observable signal in areas 24, 46 and FEF.

Interestingly, while area LIP exhibited the slowest overall responses in the intact

simulations, the combined cortical lesion led to substantial speeding of signal to LIP from

HC (200-270 ms faster) and MTL (80-300 ms faster) regions owing to speeded responses

in intermediary visual cortical and parietal areas (Supplementary Table 9).

Discussion

A preponderance of evidence has demonstrated a correlation between HC/MTL neural

activity and oculomotor behavior (Hannula et al., 2010; Killian, Potter, & Buffalo, 2015;

Liu et al., 2017), but research had not shown whether HC/MTL activity can reach the

oculomotor system in time to influence the preparation of a saccade. The HC is well

connected anatomically to the oculomotor system through a set of polysynaptic pathways

that span MTL, frontal, parietal, and visual cortices (Shen et al., 2016) but the existence

of anatomical connections does not provide conclusive evidence of the functional

relevance of specific pathways. By considering the functional dynamics and recurrent

interactions of the large-scale network involved in the HC/MTL guidance of eye

movements, we show that propagation of evoked HC/MTL neural activity results in

neural activity observable in areas 24 (ACC), 46 (dlPFC) and FEF, which are important

for the cognitive and motoric control of eye movements, respectively (Johnston &

Everling, 2008). Critically, the culmination of neural signal in these oculomotor regions

occurred within the time of a typical gaze fixation (~250-400 ms; Buswell, 1935;

Henderson et al., 2013): within 200 ms following HC subfield stimulation (except for

CA3), and within 100 ms following stimulation of each MTL region. Our findings

suggest that the underlying neural dynamics of the memory and oculomotor systems

allow for representations mediated by the HC/MTL to guide visual exploration – what is

foveated and when – on a moment-to-moment basis.

The lack of responses in the FEF following CA3 stimulation is not surprising,

given that there are no known direct connections, and fewer polysynaptic pathways,

between the CA3 and the oculomotor regions investigated here (Shen et al., 2016). These

functional and anatomical differences align well with the purported representational

functions of CA3 versus CA1. Foveated information may be bound into detailed memory

representations via the auto-associative network of the CA3 (*pattern separation*; Norman

& O'Reilly, 2003; Yassa & Stark, 2011), whereas CA1 would enable the comparison of

stored information to the external visual world (*pattern completion*; Rolls, 2013; Yassa &

Stark, 2011).

Stimulation of the subiculum and parasubiculum resulted in relatively slower

responses observed in each of the oculomotor regions, whereas stimulation of

presubiculum resulted in rapid responses observed in the oculomotor regions. The

subiculum and parasubiculum may largely provide information that supports the grid cell

mapping of the ERC (Boccara et al., 2010; Peyrache, Schieferstein, & Buzsáki, 2017;

Tang et al., 2016). These regions may then function as a 'pointer' by providing online

information of an individual's location in space (Tang et al., 2016). This slowly changing

spatial layout may not then require a rapid influence on the oculomotor system, but

instead, may allow for the presubiculum, which has cells that are responsive to head

direction (Robertson, Rolls, Georges-François, & Panzeri, 1999) to precisely locate and

foveate visual objects. These functional distinctions are speculative, and remain to be

tested.

Stimulation of each of the MTL cortices resulted in observable responses in each

of areas 24, 46 and FEF that were faster than any of the responses observed following HC

subregion stimulation. The MTL cortices are intermediary nodes that may permit the

relatively rapid transfer of information from HC to the oculomotor system. The unique

representational content supported by each region may influence ongoing visual

exploration in a top-down manner. The PRC provides lasting information regarding the

features of objects (Erez, Cusack, Kendall, & Barense, 2016; Graham, Barense, & Lee,

2010), the PHC provides information regarding the broader spatial environment

(Alvarado & Bachevalier, 2005; Eichenbaum, Yonelinas, & Ranganath, 2007; Sato &

Nakamura, 2006), and the ERC may provide information regarding the relative spatial

arrangements of features within (Yeung et al., 2017), and among objects within the

environment (Buckmaster, 2004; Yeung et al., 2019). Signal from the MTL may be used

to accurately, and rapidly, prioritize gaze fixations to areas of interest.

HC subfield lesions only minimally altered the timing of activity from MTL to

oculomotor regions; the relatively rapid propagation of signal from MTL to FEF (<

100ms) was preserved. Lesions to MTL regions resulted in slowing of signal from some

HC subfields to oculomotor regions. This pattern of results suggests that different

patterns of visual exploration (i.e., rate, area) may occur in cases of HC/MTL damage

depending on the location of the lesion. Lesions restricted to HC subfields may result in

an increase in the rate of gaze fixations due to the intact, rapid responses from the MTL

to oculomotor regions. This is consistent with prior work in which a developmental

amnesic case with HC subfield volume reductions showed an increase in gaze fixations

compared to control participants (Olsen et al., 2015). Similarly, older adults, who had

functional changes in the HC, showed increases in visual exploration (Liu et al., 2017).

ERC and PHC lesions may slow the use of information regarding the broader, ongoing

spatial environment; this could result in the need to continually revisit regions to re-

establish the relations within and among objects, and with their broader environment, and

thus an increased area of visual exploration and/or increase between-object gaze

transitions would be observed. Such behavior has been shown by older adults, which may

be related to structural and/or functional changes in the ERC (Chan, Kamino, Binns, &

Ryan, 2011; Yeung et al., 2017, 2019).

A future question for investigation is how distinct types of representations from

the HC/MTL are integrated and prioritized to influence visual exploration, including

saccade timing and the ordering of gaze fixations to distinct targets. Alternatively, the

functionally distinct representations of the HC/MTL may not actually be integrated

within the oculomotor system; rather, each may guide visual exploration at different

moments, as time unfolds, as new information in the visual world is sampled, and as task

demands are enacted and ultimately met. In either case, multiple memory 'signals' are

evident within patterns of gaze fixations, including memory for single stimuli (Althoff &

Cohen, 1999; Smith & Squire, 2017), memory for the relative spatial (and non-spatial)

relations within (Yeung et al., 2017), and among objects (Hannula et al., 2007; Ryan et

al., 2000; Smith et al., 2006). Dissociations in these memory signals can be observed

within single gaze patterns in neuropsychological cases (Ryan & Cohen, 2003).

Memory may influence visual exploration through multiple routes. Responses

emanating from the HC/MTL that ultimately resulted in observable responses in the

ACC, dlPFC, and FEF traversed through multiple frontal, visual, and parietal nodes. Yet,

despite previous speculation for the involvement of area LIP in bridging the memory and

oculomotor systems (Meister & Buffalo, 2016), we found no evidence that the functional

dynamics operating within the constraints of the macaque connectome could support this

notion. Additionally, responses were also observed *following* responses in the oculomotor

regions in regions 5, 7a, 23 (posterior cingulate), and V4, suggesting that they may

receive feedback from oculomotor regions, rather than serving as hubs that relay

information between the HC/MTL and oculomotor systems (Meister & Buffalo, 2016).

Area 5 has been implicated in mapping visual and body-centered frames of reference to

support visually-guided reaching (Seelke et al., 2012). Cells in area 7a are responsive to

eye position and saccades (Bremmer, Distler, & Hoffmann, 1997). The posterior

cingulate is part of the default mode network (Buckner, Andrews-Hanna, & Schacter,

2008; see Vincent, Kahn, Van Essen, & Buckner, 2010 for a homologous default mode

network in the macaque) that is active during internally directed cognitions. Neurons in

V4 of the macaque are known to integrate visual and oculomotor information, and show

remapping of space towards that of a saccade target, thereby bridging pre- and post-

saccade spatial representations (Neupane, Guitton, & Pack, 2016). Information from the

HC/MTL may guide gaze selection and execution, and the resulting spatial selections are

continually updated throughout cortex to promote ongoing exploration, and feed back

into memory.

It should be noted that future work remains to examine signal propagation across

subcortical-cortical pathways. The present work did not include such pathways because

although CoCoMac does contain tracer data regarding the presence/absence of thalamic

connections, it does not provide connection weights, which are critical to constraining the

dynamics of the model. We have validated the tractography methodologies used here for

estimating cortical connection strengths against available tracer data (Shen et al., 2019);

however, validated methods for running tractography in subcortical regions in macaques

do not currently exist. Nonetheless, a lack of subcortical considerations does not diminish

the evidence of the rapid communication between the hippocampal and oculomotor

systems via cortical routes, within the time window of a typical gaze fixation.

382   Neuropsychological, neuroimaging, and neurophysiological studies provide

important information regarding the representational content that is supported by distinct

regions of the brain. A network analysis approach can be instrumental in revealing the

broad dynamics by which such representational content governs behavior (Mišić, Goñi,

Betzel, Sporns, & McIntosh, 2014; Vlachos, Aertsen, & Kumar, 2012). Memory for

objects and their spatial relations provide rapid guidance for gaze prioritization and

accurate targeting for foveation. Disruptions to the HC/MTL result in an altered rate and

pattern of visual exploration (Hannula et al., 2007; Olsen et al., 2015), consistent with the

dynamics of our lesion models. The contribution of HC/MTL is not considered in most

models of oculomotor guidance and control (e.g., Hamker, 2006; Itti & Koch, 2000) (but

see Belopolsky, 2015). The present work therefore calls for a reconsideration of the

neural architecture that supports oculomotor guidance: the HC/MTL provides

information to guide visual exploration across space and time.

395	**Methods**

395   **Methods**

Large-scale network dynamics were simulated using TheVirtualBrain (TVB;

thevirtualbrain.org) software platform. The connectome-based model represented each

node of the network as a neural mass, all coupled together according to a structural

connectivity matrix which constrains the spatial and temporal interactions of the system

(Breakspear, 2017; Gustavo Deco, Jirsa, & McIntosh, 2011).

Data

A macaque network with 77 nodes of a single hemisphere was defined using the FV91

parcellation (Felleman & Van Essen, 1991) and its structural connectivity was queried

using the CoCoMac database of tract tracing studies (cocomac.g-node.org) (Bakker,

Wachtler, & Diesmann, 2012; Stephan et al., 2001). A review of the extant literature was

also performed to ensure the accuracy of anatomical pathways within and across MTL

and oculomotor systems (see Shen et al., 2016). Self-connections were not included in the

connectivity matrix.

409   As CoCoMac only provides categorical weights for connections (i.e., weak,

moderate or strong), we ran probabilistic tractography on diffusion-weighted MR

imaging data from 10 male adult macaque monkeys (9 *Macaca mulatta*, 1 *Macaca*

fascicularis, age 5.8 ± 1.9 years) using the FV91 parcellation to estimate the fibre tract

capacities and tract lengths between regions. Image acquisition, preprocessing and

tractography procedures for this particular dataset have been previously described (Shen

et al., in press., 2019). Fiber tract capacity estimates (i.e., 'weights') between each ROI

pair were computed as the number of streamlines detected between them, normalized by

the total number of streamlines that were seeded. Connectivity weight estimates were

averaged across animals and applied to the tracer network, keeping only the connections

that appear in the tracer network. The resulting structural connectome was therefore

directed, as defined by the tracer data, and fully weighted, as estimated from

tractography. Tract lengths were also estimated using probabilistic tractography.

Node dynamics

The dynamics of each node in the macaque network were given by the following generic

2-dimensional planar oscillator equations:

$$\dot{V}_i = \tau\left(-fV_i^3 + eV_i^2 + gV_i + \alpha W_i + \xi\sum_{j=1}^{N} w_{ij}V_j(t - \Delta_{ij}) + \gamma I\right)$$
$$\dot{W}_i = \tau^{-1}(cV_i^2 + bV_i - \beta W_i + a)$$

where the fast variable V represents mean subthreshold neural activity (i.e., local field

potential) at node i, W is a slower timescale recovery variable; the differential time

constants of V vs. W are controlled by the time scale separation parameter τ.

The local coupling is scaled by g, while the global connectivity scaling factor ξ

acts on all incoming connections to each node, which are also weighted individually by

the connectivity weights matrix w (as described above). Exogenous stimulation currents

of interest in the present study enter the system through the input variable I. Transmission

between network nodes was constrained according to the conduction delays matrix $\Delta =$

L/v, where L is a matrix of inter-regional tract lengths and v is axonal conduction

velocity. As in Spiegler et al. (2016), cubic, quadratic, and linear coefficients for V and W

were set such that the dynamics reduce to a classic Fitzhugh-Nagumo system. Additional

model parameters are listed in Supplementary Table 1.

Brain dynamics operate near criticality (Ghosh et al., 2008). In this state, the

nodes will naturally oscillate with constant magnitude. Setting the local parameter g so

that the system operates near criticality will allow the node to respond with a strong

amplitude, and a longer lasting oscillation. If far from the critical point, the amplitude

responses will be weak, slow, and fade quickly, and if spreading within a network, the

excitation will decay quickly as it travels. Given our network's structure, re-entry points

allow a node to be re-stimulated, making the excitation last longer and travel farther

through the network (Spiegler et al., 2016). Following Spiegler et al. (2016), we tuned the

model parameters such that the working point of each node was in a critical regime. The

system of delay-differential equations shown above were solved numerically using a

Heun Deterministic integration scheme, with step size dt=0.1 ms.

Model tuning & stimulation parameters

Simulations were run for 7000 ms, with stimulus onset occurring after 5000 ms to allow

for settling of the initial transient resulting from randomly specified initial conditions. A

single pulsed stimulus was used, with duration of 100 ms. To determine when nodes

became active following stimulation, we first computed the envelope of each node's

timeseries using a Hilbert transform. Each node's baseline activity was taken as the mean

amplitude of the envelope in the 200 ms prior to stimulation. The activation threshold of

each node was defined as the baseline activity ± 2 std and activation time of each node

was taken as the time its envelope amplitude surpassed the activation threshold.

To create a biologically realistic model, we stimulated V1 to find activation times

of the following areas: V1, V2, V3, V4, middle temporal and medial superior temporal.

Conduction velocity (v) was set to 3.0 m/s, and was within the range of conduction

velocities estimated in empirical studies of the macaque brain (Caminiti et al., 2013;

Girard, Hupé, & Bullier, 2001). Activation times following V1 stimulation were

compared to available empirical data (Schmolesky et al., 2017) and relevant model

parameters were adjusted accordingly. The parameter g was set to -0.1 such that the

system operated close to the criticality by dampening local excitability. Global coupling ξ

was set to 0.012 and stimulus weighting (γ) was set to 0.03 so that simulated response

times of visual areas following V1 stimulation exhibited a pattern of activations

resembling the known hierarchical processing organization of the visual system (V2: 4

ms, V3: 4 ms, V4: 8 ms, MT: 9 ms, MSTl: 37 ms, MSTd: 47 ms, FEF: 99 ms).

Differences with empirical activation times (e.g., MST and FEF) may be due 1) a lack of

subcortical-cortical pathways in our model; and 2) the use of the same conduction

velocity for all connections.

The same model and stimulation parameters were then used to stimulate the

subregions of the hippocampus (CA3, CA1, subiculum, pre-subiculum, para-subiculum),

enthorinal cortex (ERC), areas 35 and 36 of the perirhinal cortex (PRC), and areas TF

and TH of the parahippocampal cortex (PHC), to look for the activations of nodes whose

pathways may serve to mediate the exchange of information between the memory and

oculomotor systems (Shen et al., 2016). These nodes of interest included areas V2, V3,

V4, VP, MT, MSTd, PO, MIP, FST, 7a, granular insular cortex, anterior cingulate cortex,

46, 12, proisocortex, 5, 10, 11, orbitofrontal area 13, orbitofrontal area 14, 23, 25, 32,and

11. We further examined whether activation was observed in regions important for

oculomotor guidance, including the lateral intraparietal area (area LIP), the dorsolateral

prefrontal cortex (area 46), anterior cingulate cortex (area 24), and the frontal eye fields

(FEF).

<u>Lesion models</u>

Lesions of particular HC and MTL subregions were simulated by removing their afferent

and efferent connections to the rest of the network. Stimulations of other HC and MTL

sites were repeated on these lesion models.

<u>Code availability</u>

Simulations were carried out using the command-line version of TheVirtualBrain (TVB)

software package in Python, which is available for download at http://thevirtualbrain.org.

The customized TVB code for the simulations presented here is available upon request.

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Table 1. Activation times (ms) following stimulation of hippocampal subfields and medial temporal lobe regions. Only nodes of interest (HC/MTL regions, oculomotor regions, and regions that are involved in the shortest paths between HC/MTL and oculomotor nodes) are shown. S= subiculum, PrS = pre-subiculum, PaS=para-subiculum; ERC = entorhinal cortex; 35/36 = perirhinal cortex; TF/TH = parahippocampal cortex. *0* = stimulation onset; N/A = no response observed. For a comprehensive set of activation times for all nodes in the network, see Supplementary Table 2.

		Stimulated Node								
		CA3	**CA1**	**S**	**PrS**	**PaS**	**ERC**	**35**	**36**	**TF**	**TH**
	CA3	*0*	48	31	37	27	0	21	20	48	1
	CA1	137	*0*	0	0	46	0	8	2	0	0
	S	115	17	*0*	26	37	0	16	10	0	0
	PrS	84	23	119	*0*	25	6	13	11	0	0
	PaS	350	17	96	28	*0*	50	15	0	0	32
	ERC	169	40	0	4	0	*0*	0	0	7	13
	35	567	6	21	49	50	0	*0*	0	9	19
	36	317	1	14	10	6	0	0	*0*	6	14
	TF	137	0	20	0	44	11	12	6	*0*	0
	TH	7	0	29	0	0	20	29	18	0	*0*
Observation Node	**5**	N/A	322	50	92	555	249	129	141	69	64
	10	N/A	59	24	83	106	12	10	12	81	20
	11	N/A	12	68	74	166	10	7	8	38	48
	12	N/A	96	186	93	285	15	9	10	24	34
	13	N/A	10	18	62	132	8	7	11	19	19
	14	N/A	9	27	57	76	9	9	11	13	20
	23	N/A	165	384	12	231	43	37	52	24	13
	25	435	6	19	35	57	6	11	8	9	12
	32	N/A	38	63	88	89	10	13	14	14	17
	Ig	N/A	11	63	75	189	11	4	6	21	13
	Pro	N/A	52	96	12	48	3	1	4	29	20
	7a	N/A	381	202	336	795	256	53	52	103	59
	FST	186	47	147	52	79	6	1	3	0	6
	MIP	N/A	237	523	215	296	405	113	126	70	48
	PO	656	208	593	190	248	355	99	107	60	39
	MSTd	N/A	286	664	287	494	33	23	23	94	53
	MT	N/A	260	857	272	483	189	107	23	36	83
	V4	N/A	76	353	103	244	280	147	142	5	15
	VP	753	55	266	86	259	223	98	101	2	41

V3	N/A	260	841	257	409	398	154	163	68	68
V2	215	56	274	48	66	139	16	17	6	0
24	N/A	107	250	55	238	24	22	25	22	16
46	N/A	84	135	15	187	12	9	11	17	23
FEF	N/A	217	452	68	500	79	19	15	34	71
LIP	N/A	535	N/A	445	N/A	561	233	230	176	144