

1 Life-history traits inform on population trends when assessing the 2 conservation status of a declining tiger shark population

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8

9 Abstract

10 1. The assessment of the conservation status of wide ranging species depends on
11 estimates of the magnitude of their population trends. The accuracy of global trend
12 estimates will depend on how many locations within a species range are sampled and
13 where in the range population size is sampled.

14 2. We ask how the spatial extent of sampling within a species range interacts with non-
15 linear patterns in long-term trends to affect estimates of decline in standardised catch
16 of tiger sharks (*Galeocerdo cuvier*) in a shark control program on the east coast of
17 Australia. We use Bayesian random effects models to estimate long-term population
18 trends. We compare estimates of trends where we use all data spanning 11.5 degrees
19 of latitude to estimates that used spatial subsets of the data. We also introduce a

20 method to that uses prior information on species life-history to inform on the expected
21 level of population variation.

22 3. As more regions were included in the model the trend estimates converged towards
23 an overall decline of 64% over three generations. Trends estimated from data only
24 from northern regions underestimated the regional decline, trends estimated from
25 data only from southern regions overestimated the regional decline. When a subset of
26 regions were modelled, rather than the full data-set, the estimated trend depended on
27 the choice of the Bayesian prior for population variation. The prior informed by life-
28 history traits performed well, a prior incorrectly informed by life-history traits of a
29 much slower growing shark species performed poorly.

30 *Synthesis and applications* The rate of decline in tiger sharks is consistent with a listing East
31 Coast Australia tiger sharks as endangered under local legislation. Monitoring programs
32 that aim to estimate population trends should attempt to cover the extremes and mid-
33 points of a population's range. Life-history information can be used to inform priors for
34 population variation and may give more accurate estimates of trends that can be justified
35 in debates about red listing of threatened species, particularly when sampling is limited.

36 **Keywords: Bayesian model, informed prior, migratory species, IUCN red list, megafauna**

37 **Introduction**

38 Determining the status of species threatened by human activities is important for
39 informing the investment of conservation funds (Rodrigues et al. 2006). A species' status is
40 often defined on the basis of trends in population size (Conservation of Nature Species

41 Survival Commission 2001). For instance, some Great Hammerhead Shark populations
42 (*Sphyrna mokarran*) were listed as critically endangered on the International Union for the
43 Conservation of Nature (IUCN) Red List, partly on the basis of an >80% population decline
44 over the past three generations (Camhi et al. 2009). The performance of management
45 actions aimed at averting decline should also be assessed by monitoring population trends
46 (e.g. Ward-Paige et al. 2012). Monitoring data will be most useful when it covers sufficient
47 spatial and temporal scales to estimate trends accurately.

48 Accurate estimates of the magnitude of a population change may be confounded by short-
49 term and localised variation in abundance, or masked by measurement errors (Gaston &
50 McArdle 1994). Migration into and out of the sampling area may also bias local abundance
51 measurements of mobile species (Forney 2000). Our ability to observe a species may also
52 vary place to place because of environmental variation, for instance, catch indicators of
53 tiger shark (*Galeocerdo cuvier*) abundance vary inter-annually with temperature (Payne et
54 al. 2018). This issue is likely to be worsened where sampling of abundances is limited to
55 few locations within a species' broader range, because fewer sites are more likely to exhibit
56 random variations that do not reflect the population's true trend (Forney 2000). The
57 precision of population trend estimates will therefore depend on the spatial extent of
58 sampling.

59 Appropriately formulated statistical models can separate short-term noise from important
60 trends. Linear and log-linear models have been popular approaches trend analysis (e.g.
61 Dudley & Simpfendorfer 2006; Baum & Blanchard 2010; Keith et al. 2015; Knappe 2016).
62 Linear models provide a simple phenomenological model of trends, but may miss non-linear

63 changes and be influenced by short-term temporal ‘outliers’ (Fewster et al. 2000; Knapé
64 2016). Non-linear statistical models, like smoothing splines, are another popular
65 phenomological approach, because they smooth over short-term deviations in abundance
66 to capture longer-term non-linear trends (Fewster et al. 2000; Forney 2000; Knapé 2016).
67 A choice must then be made in the modelling about the degree of smoothing. This choice is
68 usually made based on sample size (Fewster et al. 2000) or the level of smoothing is fitted
69 empirically with a method like generalized cross validation (Wood 2006). However,
70 empirical approaches to smoothing can lead to over-fitting and biased inferences on trends
71 (Knapé 2016).

72 A model’s fit to time-series data can also be controlled by using process models that
73 explicitly account for species life-history traits (Kindsvater et al. 2018; Sköld & Knapé
74 2018). Process models can be effective at discerning short-term noise from longer term
75 trends driven by population dynamics (e.g. Wilson et al. 2011; Rueda-Cediel et al. 2018),
76 but accurate estimation of population parameters can be difficult if the population trend
77 exhibits a ‘one-way-trip’ (Szuwalski & Thorson 2017). ‘One-way-trips’ will be common in
78 species data that is being analysed for extinction risk. Process models, such as those used to
79 model trends in fished populations also make additional assumptions that can lead to
80 biased reporting of trends (Edgar et al. 2018). What we need is an approach that takes
81 strength from both the phenomological and process based approaches to obtain accurate
82 estimates of population trends in the face of monitoring data that is limited in geographic
83 and temporal extent.

84 Here we apply Bayesian random-effects models to fit trends to population declines. We use
85 a species' life-history traits as Bayesian prior information to control the level of smoothing
86 in the fitted trend line. Inclusion of life-history information can improve the estimation of
87 population trends, and may be particularly beneficial for overcoming the deficiency of
88 monitoring data for many potentially threatened species (Kindsvater et al. 2018). The
89 approach is thus a hybrid that blends phenomological description of trends with ecological
90 processes that inform the smoothing. We use simulations to explore the accuracy of fitted
91 trends for species with a range of population growth rates.

92 As a case-study we modelled multi-decadal trends in a declining tiger shark population
93 from the east coast of Australia (Holmes et al. 2012; Roff et al. 2018). The data are from the
94 Queensland Shark Control Program (QSCP) a unique spatially replicated annual time-series
95 of shark catch and effort that covers 1962-2017. We aimed to determine (A) how the choice
96 of prior influences the models' ability to detect a long-term trend in relative abundance;
97 and (B) whether the appropriate choice of a prior can give a more accurate estimate of the
98 large-scale trend when sampling is constrained to fewer regions.

99 **Methods**

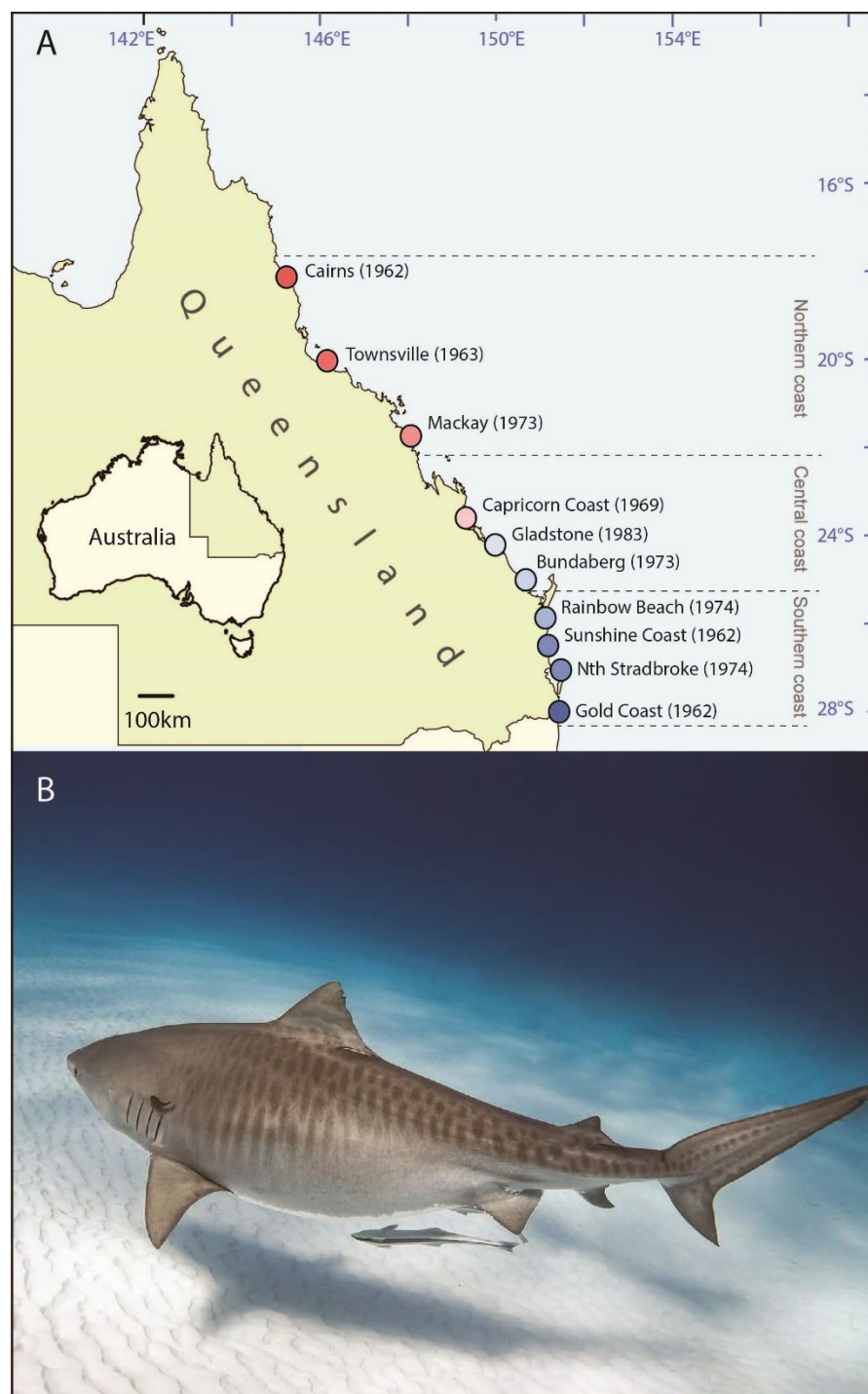
100 **Case-study**

101 We analysed temporal variation in shark catch per unit effort in the Queensland Shark
102 Control Program (QSCP, Kidston et al. 1992). The QSCP was instigated in 1962 at several
103 sites around south-east Queensland, and has since been expanded to 11 regions across
104 1760km of coastline, ranging from the tropics (16.7°S) to sub-tropical areas (28.2°S, Figure

105 1). The QSCP uses a series of baited drumlines and mesh nets to capture sharks. The nets
106 and drumlines are checked by contractors 15-20 days of each month, who also record the
107 length and taxonomic identity of captured sharks. A previous analysis of this same data-set
108 found declines in four major groups of sharks caught in the QSCP, and declines were
109 consistent across regions, suggesting a common trend across the eastern coast of Australia
110 in these shark groups (Roff et al. 2018). This included a 75% decline in tiger sharks
111 between 1962 and 2017 (Roff et al. 2018). Effort data in the form of total number of nets
112 and drumlines was reconstructed using historical records from contractor's logbooks
113 between 1962-2017. Historical effort records account for seasonal lifting of gear and
114 swapping of gear between beaches during seasons to avoid bycatch of turtles and whales,
115 and annual effort was adjusted to reflect these changes (Roff et al. 2018). Where catch
116 records were unclear or uncertainty existed regarding number of drumlines or nets,
117 beaches were excluded from the analysis (Roff et al. 2018). Since the early 1990's,
118 drumlines and net types have been standardised across the program (Sumpton et al. 2010).

119 A recent analysis of the QSCP data found declines in four major groups of sharks across
120 regions, suggesting a common trend across the eastern coast of Australia in these shark
121 groups (Roff et al. 2018). Here, we explore the impact of model choice and the spatial
122 extent of data on estimates of tiger shark declines. We focus on tiger sharks because: (1)
123 they are reliably identified due to their distinctive body stripes (Fig 1b) (Holmes et al.
124 2012; Roff et al. 2018); (2) there are extensive catch records for this species, providing
125 sufficient data for us to analyse the effect of using data from a sub-set of regions; (3) they
126 may be of conservation concern because the previous found declines of ~75% between

127 1962 and 2017 (Roff et al. 2018) and (4) the declines were non-linear, making tiger sharks
128 a useful test-case for exploring the impact of non-linear trends on estimates of decline.
129 For inclusion in the IUCN red list, populations must exhibit observed, estimated, inferred or
130 suspected population size reductions over the last 10 years, or over three generations
131 (Conservation of Nature Species Survival Commission 2001). Many regional agencies also
132 apply the IUCN red listing criteria to determine local listing of species, including the state of
133 Queensland and Australia (Committee 2019; Environment & Heritage Protection 2019).
134 Analysis of sharks caught in the QSCP indicate an estimated age at 50% of maturity (A50)
135 for female sharks of 10-13 years (Holmes et al. 2015). Based on this criteria, we analysed
136 the QSCP dataset of 11 regions for trends in tiger shark catches between two time periods:
137 three generations which was 1984 to 2017; and the longer term trend over 1970 to 2017.
138 1970 was the earliest year shared by all sites used in the regional subsets.



139

140 **Figure 1** A) Map of the study region, showing major regions, first year of shark program
141 sizes and scaling of sites from north to south, B) mature female *Galeocerdo cuvier* (~3m
142 length) showing characteristic vertical striping pattern. Photo credit: Juan Oliphant

143 Model

144 We used Bayesian random effects models to fit non-linear trend lines to tiger shark CPUE
145 patterns. The model of the count of shark catch for each region, gear type and year ($y_{i,g,t}$)
146 was as follows:

$$147 \quad y_{i,g,t} \sim nbinom(\mu_{i,g,t}, \theta)$$

148 Where θ was the scale parameter of the negative binomial distribution and $\mu_{i,g,t}$ was the
149 expected abundance. The expectation was specified:

$$150 \quad \ln(\mu_{i,g,t}) = \alpha + \beta x_{i,g,t} + b_i + z_t + E_{i,g,t}$$

151 Where α was a global intercept, β was the additive effect of mesh nets, $x_{i,g,t}$ was an
152 indicator variable for nets (=1) or drumlines (=0), b_i was an independent, normally
153 distributed random effect of region, with standard deviation σ_{b_i} . Gear and region
154 effects were included to help control for differences in catches in different location by
155 different gear types (e.g. Holmes et al. 2012). z_t was a latent first order random walk, with
156 standard deviation σ_{RW1} (e.g. Rue & Held 2005):

$$157 \quad z_{t+1} - z_t \sim norm(0, \sigma_{RW1})$$

158 The random walk allows for non-linear trends in abundance with time, but will shrink
159 toward a flat line for small values of σ_{RW1} . The term $E_{i,g,t}$ was an offset term that accounted
160 for variation in the number of drum lines and nets across time and regions. This model is
161 similar to that used in Roff et al. (2018), except that we ignored site level variation by
162 summing over drum/net sites within a region.

163 We specified prior distributions for the parameters α , β and the hyper-parameters θ ,
164 σ_b and σ_{RW1} . For α and β we used broad normal priors with mean zero. These are the
165 defaults in the software we used (Martins et al. 2013). For σ_b we also used the default that
166 is a weakly informative loggamma prior with parameters 1 and 1e-5. For θ we used the
167 penalized complexity prior with one parameter. We set this parameter to a value of 7 based
168 on a simulation study (Supplementary material). The penalized complexity prior will
169 shrink the negative binomial distribution toward a Poisson distribution if there is not
170 strong evidence for over-dispersion ($\sigma^2 \gg \mu$) (Simpson et al. 2017). Using weakly
171 informative priors means computations are more efficient and avoids overfitting the data
172 to the variance parameters (Simpson et al. 2017). Finally, we refitted models with several
173 different priors for σ_{RW1} , as is explained below. To perform Bayesian computation we used
174 the programming package INLA (Integrated Nested Laplace Approximation) (Rue et al.
175 2009, 2017) as implemented in the R programming environment (INLA version 17.06.20; R
176 version 3.4.4; Martins et al. 2013; R Core Team 2018).

177 **Prior choice for the standard deviation of the random walk**

178 The prior for the standard deviation of the random walk controls the level of smoothing in
179 the trend line. A prior that has greater density closer to a smaller standard deviation will
180 shrink the trend toward a constant line. We used life-history information on the annual
181 potential for variation in tiger shark abundance to inform the prior for the random walk
182 (Simpson et al. 2017). The standard deviation of a random walk has a direct interpretation
183 in terms of population growth: For the exponential population model $N_t = N_{t-1}e^{r_t}$, where
184 r_t is an annually varying instantaneous growth rate and is sampled from a normal

185 distribution, the standard deviation of a (logged) random walk will equal the standard
186 deviation of r ($\sigma_{RW1} = \sigma_r$). In applying this approach to CPUE data, we assumed that CPUE
187 was proportional to population abundance.

188 One potential pitfall of the above approach is that normally distributed values of r_t imply
189 the same probability of increases as decreases, thus, a prior constrained by population
190 growth may also limit our ability to observe large population declines. To overcome this
191 problem we used a penalized complexity prior for precision of the variance of the random
192 walk (Simpson et al. 2017). The penalized complexity prior had a high density near a
193 standard deviation of zero, but also a long tail (Figure 2). The long tail accommodates the
194 possibility of rapid declines provided they result in sustained changes to CPUE. For
195 instance, a sudden decline in CPUE would be smoothed over if the population immediately
196 recovered the next year, which might be indicative of a temporary migration. Whereas, we
197 would expect a sudden decline that was caused by overfishing to result in a sustained
198 decline in CPUE, such sustained changes would be captured by the model, but we explore
199 this assumption below.

200 Given that tiger sharks are large predators with relatively late age at maturity (estimated at
201 10-13 years by Holmes et al. (2015)), a low fecundity and a high adult survival rate (Cortés
202 2002), we assumed that the instantaneous growth rate represents the near maximum rate
203 of negative or positive annual change in the population. Therefore, we choose the penalized
204 complexity prior such that there was only a 0.025 probability of a standard deviation
205 greater than a prior estimate of r for tiger sharks. The exact probability level of 0.025 is
206 arbitrary, but the probability should be small enough that annual changes larger than r are

207 unlikely. The penalized complexity prior combined with the normally distributed random
208 walk meant the probability of $r_t > r_{max}$ (or $r_t < -r_{max}$) was 0.016.

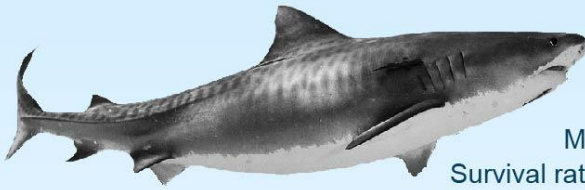
209 We obtained an estimate of the maximum annual instantaneous growth rate by applying
210 the corrected Lotka-Euler equation to *G. cuvier* life-history parameters (Cortés 2016; Pardo
211 et al. 2016). We used life-history parameters from the local region where possible
212 (Supplementary information). The estimate of the instantaneous rate of increase for Pacific
213 tiger sharks was 0.24, which is consistent with previous estimates from the Atlantic (Cortés
214 2016; Pardo et al. 2016).

215 We compare results from the best-guess prior with three other priors. The first was the
216 INLA default prior (a loggamma with parameters (1, 1E-5)). The second and third were
217 penalized complexity priors parameterised to represent a very slow growing shark species
218 ($U = \log(1.01)$) and a very fast growing shark species ($U = \log(1.66)$) (Cortés 2002). We
219 also tried ‘traditional’ broad gamma priors (e.g. the gamma(0.01, 0.01) prior) however we
220 found that they caused significant issues with model estimation. Such priors are now
221 eschewed by statisticians, because they allow for unrealistically high variance (e.g. Simpson
222 et al. 2017).

223 In the INLA implementation we set the ‘scale.model’ option equals ‘FALSE’ to ensure the
224 value provided for σ_{RW1} was interpreted as the marginal standard deviation. We also set
225 ‘constr’ equals ‘FALSE’ to remove the sum to zero constraint.

226

1. Obtain life history parameters for the species



Tiger shark

Galeocerdo cuvier

Maximum age = 28 years

Survival rate of adults = 0.93

Reproductive cycle biennial or triennial.

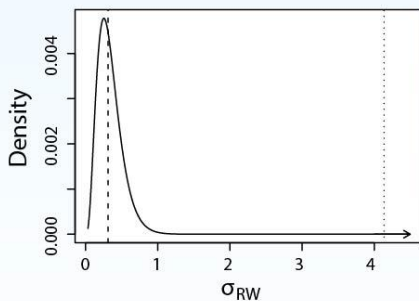
Annual number of female offspring per mother = 30 - 70

2. Estimate maximum population growth rate

$$1 = \sum_X^W l_X m_X e^{-rX}$$

Euler's equation for $r = 0.24$

3. Specify informed prior for long-term population variation



We used a penalized complexity prior (Simpson *et al.* 2017), which defines

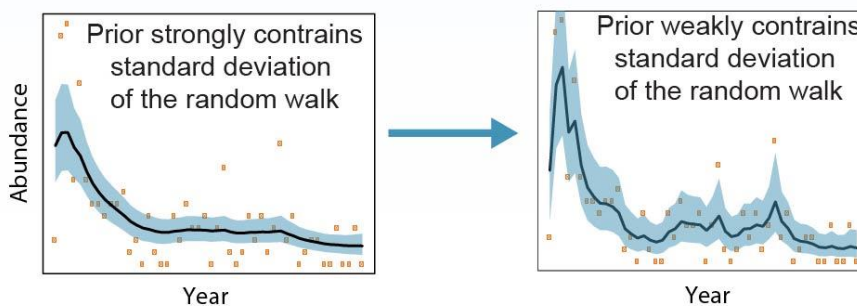
$$\text{pr}(\sigma_{RW} > U) = \alpha$$

Where α is a probability level (= 0.025)

U is a quantile

σ_{RW} is the standard deviation of the random walk

4. Model population data with a random walk to estimate the trend



227

228 **Figure 2** The approach for using life-history information to inform on trends in population

229 modelling. From Cortes 2002

230 **Analyses**

231 We initially ran a simulation study to explore the impact of prior choice on estimation for
232 species with a range of life-history traits. We simulated random walks and then fit models
233 to the simulated data. We simulated drifting random walks (with an average decline of
234 2.5% per year) that covered the range of shark species population growth rates with
235 simulations for values of $exp(\sigma_r) = 1.01, 1.34$ and 1.66 (Cortés 2002). For each trend and
236 life-history type we simulated 20 replicate time-series of 30 years. Annual observations
237 were then sampled from a negative binomial distribution with an expectation equal to the
238 random walk value in each year and a dispersion (size) parameter = 2, to generate
239 overdispersed counts. We repeated these analyses drawing observation errors from a
240 Poisson distribution. We assumed effort was fixed over time and initial CPUE was set at 10
241 (approx. mean for tiger sharks). For each time-series we fitted three negative binomial
242 models with different penalized complexity priors: $\sigma_{rw} = \ln(1.01), \ln(1.34)$ and $\ln(1.66)$. In
243 total we simulated 120 random time-series, fitting a total of 360 models. Each set of model
244 fits was evaluated by: (1) the product of the likelihood of the true (simulated) mean given
245 the fitted marginal probability distributions in each year and; (2) using the predictive
246 ordinate (Held et al. 2010).

247 We also studied the ability of different priors and models to detect sudden sustained
248 population crashes. In these simulations we used the same priors and observation errors as
249 above and an initial CPUE of 50. We created time-series where the mean abundance was
250 stable for 27 years, then collapsed in the 28th year to one of four values (12.5%, 25% or

251 50%). Models were fitted with random walks and either three or six years of post-decline
252 observations (see Supplementary material).

253 For the tiger shark data we explore the impact of the extent of sampling and prior choice on
254 estimates of decline over the time periods 1970 to 2017 and 1984 to 2017. We fit models to
255 60 subsamples of time-series drawn from different subsets of all regions and different
256 prior specifications. We performed a factorial set of analyses crossing the four prior
257 densities for σ_{RW1} with subsets of the number of regions included in the model fitting. We
258 included 15 subsets of the set of 11 regions. The 15 subsets were a factorial cross of 1, 3, 6
259 and 9 regions crossed with a selection of regions grouped into: (A) the northern-most
260 regions, (B) middle latitude regions, (C) southern-most regions and, (D) regions equally
261 dispersed across the full extent of the dataset (fig. 1). For the subsets, we chose regions that
262 had the most complete time-series. We also ran all priors for the complete set of 11 regions.

263 We compared results from all tiger shark model fits for their predictions of the magnitude
264 of the population decline across two time-periods. Comparisons were made to the 11
265 region model with the life-history prior as our best-estimate. The % magnitude of
266 population decline from the reference year was calculated as $-100(1 - z_{2017}/z_0)$ where
267 z_{2017} was the value of the smoother in the most recent year and z_0 was its value at the
268 reference year (1970 or 1984). We used INLA's 'lincomb' feature to calculate the marginal
269 posterior distribution of the % decline statistic. We then compared scenarios for their
270 median values and 95% credible intervals.

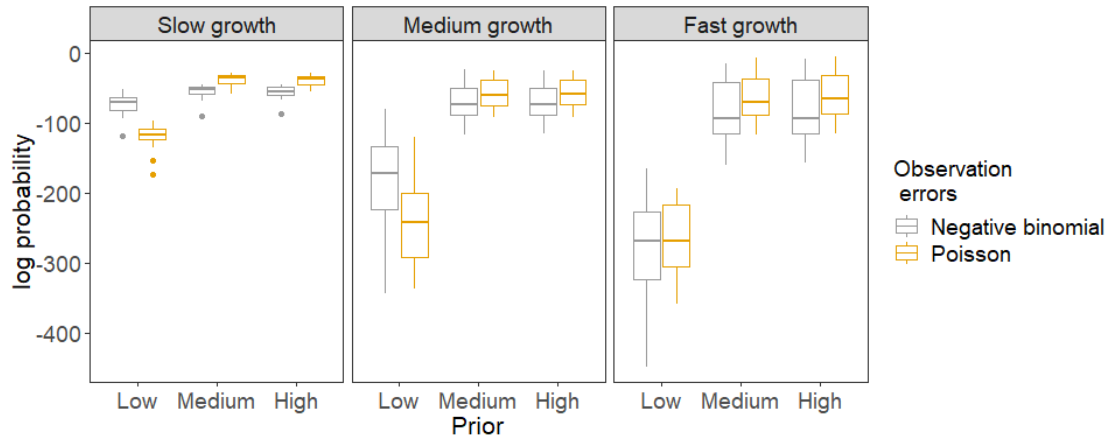
271 We also compared results for the tiger sharks by fitting a Generalized Additive Mixed
272 Model (GAMM) with maximum likelihood methods and cross validation (with the R

273 package mgcv, version 1.8-23 Wood 2017). The GAMM was fit with random effects by
274 regions (for sub-samples with >1 region) and a thin plate smoothing spline applied to year.
275 The maximum degrees of freedom was set to either 1/3 the number of years (Fewster et al.
276 2000), or chosen with cross-validation (Wood 2017).

277 **Results**

278 The simulation study indicated that model fits were a more accurate representation of the
279 true mean for slower growing species when compared to fast-growing species (Fig 3). Slow
280 growing species had less variability overall, so it was easier to detect the simulated trend.
281 For all species, fits were more accurate with either medium or fast priors, when compared
282 to the slow prior (Fig. 3). Interestingly, the predictive ordinate, a standard in-sample
283 evaluation measure did not detect any differences in the accuracy of fits by different priors
284 (Fig S2). In general, fits to the model with Poisson errors, rather than over-dispersed
285 negative binomial errors, were slightly more accurate (Fig 3, S2).

286 The simulation study of a sudden rapid decline showed that the faster priors were more
287 likely to detect a sudden decline in CPUE (Fig S3). With the slow prior, the model estimated
288 probability of a decline was always near 0.5. The models fitted to observations that were
289 negatively binomially distributed were less sensitive to the decline than if the data were
290 Poisson distributed. For instance, the probability of detecting a sudden decline with
291 medium or fast priors was near one when data were Poisson distributed for any magnitude
292 of decline and length of post-decline data. When data were negative binomially distributed
293 the probability of decline was estimated to be between 0.55 and 0.88 for three years of
294 post-decline data and between 0.6 and 0.9 for six years of post-decline data (Fig S3).



295

296 **Figure 3** Results from simulation study for the log probability of the true simulated mean

297 across all sample years given the results of the fitted model. Horizontal axes give the

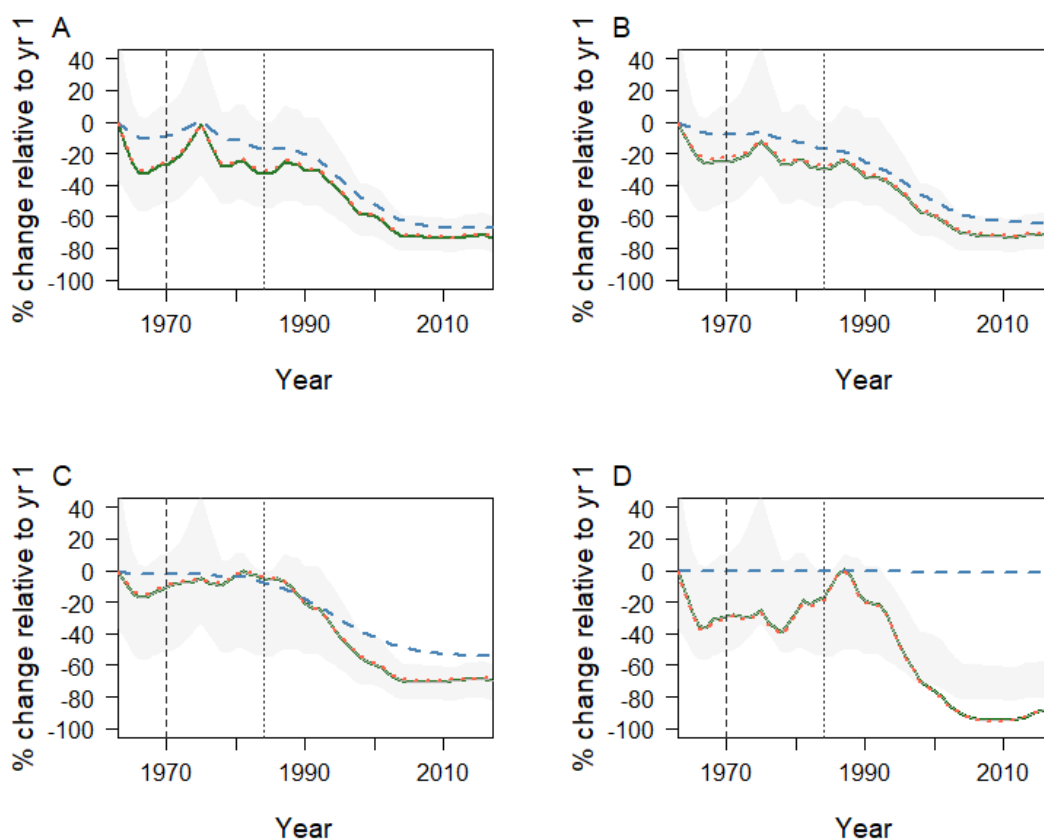
298 different priors, the panels show results from models fitted to time-series data simulated

299 for species with different life-history traits. Higher (less negative values) indicate the

300 model performed better at recovering the true trend. Boxes give the inter-quartile range

301 and the horizontal bar gives the mean value. Vertical error bars extend no more than

302 1.5xIQR.



303

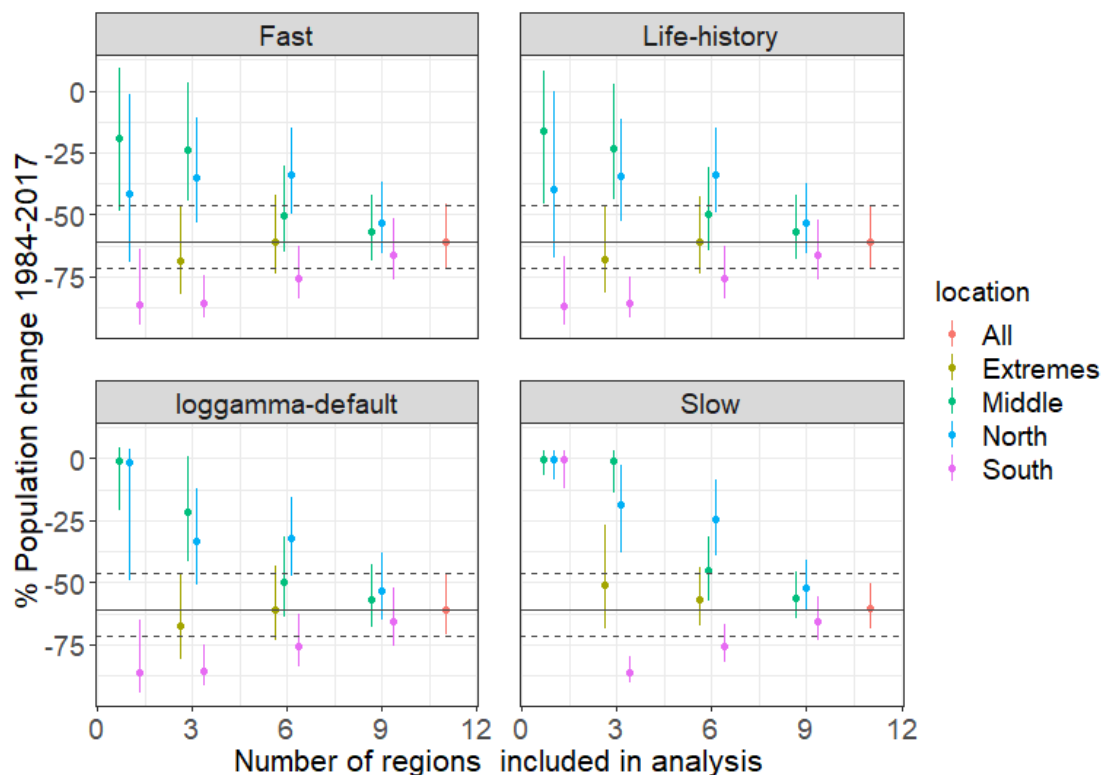
304 **Fig 4** Examples of non-linear trends fitted to the tiger shark data. Models fitted to all
305 regions (A), and 6 and 3 extreme-latitude regions (B, C), and just the southern-most region
306 (Gold Coast) (D). Lines show the fitted values for the random walk with 95% C.I.s (shading)
307 for the life-history prior (solid), slow life history prior (dashed) and INLA default prior
308 (dotted, orange). For comparison the 95% C.I.s for model fitted to all data with the life-
309 history prior is included as the shaded polygon.

310 For tiger sharks the magnitude of decline over three generations was reasonably accurate
311 with any prior and data from six or more regions (Fig 4, Fig 5). The slow prior tended to
312 under-estimate non-linearities in the trend and shrunk back to no trend when there were
313 only data for 1-3 regions (Fig 4D, Fig 5). The slow prior also tended to have the poorest

314 coverage of the true magnitude when there were only 1-6 regions included. The slow prior
315 was also more confident about the magnitude of the trend (narrower credible intervals, Fig
316 5). Results were similar when estimating declines over 1970 - 2017 (Fig S4). It is notable
317 that INLA's default prior gave similar results to the prior informed by life-history traits (Fig
318 5).

319 With a greater number of regions the estimate of decline converged to 64%. Subsets with
320 southern regions tended to overestimate the decline, whereas subsets with middle and
321 northern regions tended to underestimate the decline (Fig. 5). Data subsets that mixed
322 extreme north and south regions were closer to the 64% decline than data subsets just of
323 north or south regions. There was a notable spike in abundance during the 1970s predicted
324 by the model that used all regions and the life-history prior (Fig 4A), which was not present
325 in subsets of the data (Fig 4B-D).

326 A generalized additive mixed model fitted using maximum likelihood methods showed a
327 similar pattern to the Bayesian model of convergence of trend estimates as more regions
328 were added, and greater declines estimated if data were taken from southern regions when
329 compared to data taken from northern regions (Fig S5). The GAMM had similar results for
330 either standard setting for its degrees of freedom.



331

332 **Fig 5** Estimated magnitudes of decline for the each prior (panels) and each scenario for
333 subsets of regions (coloured points) over 3 generations (1984-2017). Points give median
334 estimates and bars give 95% C.I.s. For comparison, the black and dashed lines give the
335 median and 95% C.I.s for the life-history prior fitted to data for all regions.

336 Discussion

337 Important statistics for informing on the status of threatened species and the effectiveness
338 of management interventions are estimates of the magnitude of population change
339 (Rodrigues et al. 2006). We found the accuracy of population change estimates can be
340 improved by fitting non-linear trends where the level of smoothing is informed with life-
341 history traits and that greater spatial replication of time-series can improve the reliability
342 of estimates. Accurate estimates of population change for wide-ranging species are

343 therefore best based on sampling that covers a large part of their range. However, spatially
344 extensive sampling can be expensive and not all species will have spatially extensive time-
345 series available for assessing trends (Kindsvater et al. 2018). We additionally found that
346 using prior information on life-history traits can help to establish more robust estimates of
347 decline by smoothing over short-term and local deviations in population size.

348 We introduced a method for using Bayesian priors to inform on the degree of non-linearity
349 in population trends. The method may help to overcome some of biases that come from
350 analysing abundance indices with purely descriptive statistical models (Maunder et al.
351 2006). For instance, models that limit population growth by life-history parameters can
352 overcome biased trends that resulted from change in detection probability of cryptic
353 species (Sköld & Knape 2018). The results for the three generation decline were similar for
354 all priors, so long as all sites were included in the analysis. The generalized additive model
355 also estimated a similar rate of decline as the Bayesian model. The convergence in
356 estimates across these different methods occurred because the tiger sharks CPUE data had
357 a strong trend. Where patterns in the data are strong, the prior will be less influential (e.g.
358 Kindsvater et al. 2018).

359 Despite the consistencies in trend estimates across the different methods, we still advocate
360 using prior information to inform on population variability. The informed prior gave
361 estimates closer to the global trend when subsets of the data were used. It is also powerful
362 that we can tune the level of smoothing in the Bayesian model for a species life-history.
363 Life-history does not figure into the choice of smoothing for generalized additive models,
364 which instead be made by evaluating smoothing against the data at hand, or with reference

365 to simulation studies that are often from very different organisms (Fewster et al. 2000;
366 Knape 2016). In our simulations the predictive ordinate (an in-sample evaluation measure)
367 performed poorly in that it did not distinguish among different priors. This suggests that
368 using the in-sample measures may lead to overfitting of the smoothing splines. We suggest
369 that a-priori decisions about smoothing will provide more accurate trend estimates.
370 Informed priors may also be more easily justified than choices about smoothing made with
371 reference to other organisms. Defensible parameter choices are important when model
372 results may be contested, such as when governments make potentially contentious
373 decisions about the status of populations (e.g. Edgar et al. 2018).

374 When life-history traits are uncertain we suggest using a penalized complexity prior that
375 allows for greater variation (and non-linearity) in the long-term trend. Our simulations
376 study suggested that priors that allow for higher variance gave more accurate results than
377 priors that restricted variance. However, the decision to allow for overestimation of
378 variance may not be safe if a different prior distribution other than the penalized
379 complexity priors was used. For instance, very flat priors that give equal prior weighting to
380 low and high temporal variances can perform very poorly (Simpson et al. 2017). The shape
381 of the penalized complexity prior was specifically designed to allow the data to speak for
382 themselves when trends are strong, but to shrink estimates towards no trend when the
383 data are weak or noisy (Simpson et al. 2017). Our results add further support to usefulness
384 of penalized complexity priors for applied problems.

385 An avenue that requires further research is testing the utility of the new method across
386 many species with a broader range of life-history types. We expect the approach will work

387 best when short-term variation in abundance, such as that caused by temporary
388 migrations, is much more variable than long-term trends. For very fast growing species,
389 such as those with maturity ages of <1 year, a statistical model fitted to annual data may
390 confound real population trends with short-term deviations. Classification errors for IUCN
391 red list status tend to be greater for species with fast population growth than species with
392 slow population growth (Rueda-Cediel et al. 2018). For instance, the results of our
393 simulation study were most accurate for slow growing species, whereas accuracy was more
394 variable for fast growing species. The random walk model could still be effective if the
395 temporal resolution of sampling was increased (e.g. with sub-annual data).

396 A further improvement to the model would be to specify a prior that allows for greater
397 population declines than population increases. Rapid declines in population abundance
398 tend to be more common than rapid increases (Anderson et al. 2017), because the
399 processes that cause declines, like overfishing, often operate on a much faster time-scale
400 than reproduction and population recovery. An alternative would be to use a more complex
401 model, like the Gompertz, that allows for a hard upper limit on population increases (Sköld
402 & Knape 2018). Our simulation study of rapid declines suggested that the random walk
403 with penalized complexity prior can still detect rapid declines in abundance, because its
404 long probability tail does allow for rare but rapid changes in abundance. Conservation
405 management must balance the risk of missing a true decline against the chance of false
406 alarm. A next step therefore, would be to apply Bayesian decision analysis to optimise
407 models for the balance between the cost of missed detection and the cost of false alarms.

408 The decline of tiger sharks we observed is consistent with a decline in large sharks
409 throughout the world's oceans (e.g. Baum & Myers 2004; Ferretti et al. 2008; Roff et al.
410 2018). The current global population trend for tiger sharks is unknown, although there is
411 considerable variation across different oceans, with some regions showing no change
412 (Baum & Myers 2004) and others large declines (Baum et al. 2003). Overall, their relatively
413 high growth and reproductive rates (Cortés 2002; Holmes et al. 2015) means that tiger
414 sharks are not considered at high risk of extinction (Simpfendorfer 2009). The
415 conservation status of tiger sharks globally escalated from "Lower Risk/near threatened"
416 under the IUCN listing to "Near Threatened" in 2005 (Simpfendorfer 2009).

417 Tiger sharks may warrant listing as Endangered under state and national threatened
418 species legislation (IUCN Criteria A2, >50% decline over three generations). The trend we
419 observed in Queensland may be part of a broader scale trend. Genetic studies indicate the
420 east coast population is part of a well mixed Indo-Pacific population (Holmes et al. 2017).
421 Further, in nearby New South Wales tiger shark catches have also declined, a decline that
422 has been attributed to increased fishing pressure in temperate waters (Reid et al. 2011).
423 While our study does not cover the entire Indo-Pacific population, the large spatial extent
424 of the current study (11 regions across 1760km of coastline) plus declines in adjacent NSW
425 nearly 1000km south (Reid et al. 2011) likely reflects a large scale regional trend spanning
426 18° in latitude across tropical and temperate coastlines of eastern Australia. While the
427 inclusion of time-series data from throughout Indo-Pacific would strengthen evidence for a
428 whole of population decline, long-term datasets spanning multiple generations are largely
429 absent for adjacent regions in the Pacific.

430 While some uncertainty exists in the historical data used here, data collection was
431 standardized in the QSCP in the early 1990's. This implies trends in recent decades when
432 declines have been observed are robust (see Roff et al. (2018) for discussion). Our
433 proposed statistical method may also help smooth over temporal and regional variability in
434 trends by estimating the long-term trend that is consistent across regions, and by
435 controlling for differences in gear type.

436 We considered how estimates of population trends for wide-ranging species depend both
437 on the spatial extent of data and the model used to partition short-term variation from
438 long-term trends in population size. We found that the choice of model and the spatial
439 extent of sampling interact to effect population trends. Informing priors with life-history
440 information could improve the accuracy of estimates, particularly when sampling was
441 constrained to fewer regions across a species range. Informed priors provide theoretical
442 grounds for choosing the level of smoothing when modelling population trends. The trends
443 estimated here, while dependent on the quality of the CPUE data, suggest that tiger sharks
444 should be listed as a threatened species under Australian state and possibly national
445 legislation.

446 **Authors contributions**

447 CB and JR conceived of the manuscript idea and designed the study. JR obtained the data,
448 performed quality control and conducted initial analyses. CB conducted the modelling. CB
449 and JR created the figures and wrote the manuscript.

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