Active membrane conductances and morphology of a collision detection neuron broaden its impedance profile and improve discrimination of input synchrony

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Running head: Impedance profile of a collision detection neuron

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Abstract

Brains processes information through the coordinated efforts of billions of individual neurons, each encoding a small part of the overall information stream. Central to this is how neurons integrate and transform complex patterns of synaptic inputs. The neuronal membrane impedance sets the gain and timing for synaptic integration, determining a neuron's ability to discriminate between synaptic input patterns. Using single and dual dendritic recordings *in vivo*, pharmacology, and computational modeling, we characterized the membrane impedance of a collision detection neuron in the grasshopper, *Schistocerca americana*. We examined how the cellular properties of the lobula giant movement detector (LGMD) neuron are tuned to enable the discrimination of synaptic input patterns key to its role in collision detection. We found that two common active conductances g_H and g_M, mediated respectively by hyperpolarization-activated cyclic nucleotide gated (HCN) channels and by muscarine sensitive M-type K^+ channels, promote broadband integration with high temporal precision over the LGMD's natural range of membrane potentials and synaptic input frequencies. Additionally, we found that the LGMD's branching morphology increased the gain and decreased delays associated with the mapping of synaptic input currents to membrane potential. We investigated whether other branching dendritic morphologies fulfill a similar function and found this to be true for a wide range of

30   morphologies, including those of neocortical pyramidal neurons and cerebellar Purkinje cells. These

31   findings further our understanding of the integration properties of individual neurons by showing the

32   unexpected role played by two widespread active conductances and by dendritic morphology in

33   shaping synaptic integration.

New & Noteworthy

Neuronal integration depends on complex interactions between synaptic input patterns and the

electrochemical properties of dendrites. We used an identified collision detection neuron in

grasshoppers to examine how its morphology and two membrane conductances determine the gain and

timing of synaptic integration in relation to the computations it performs. The neuronal properties

examined are ubiquitous and therefore further a general understanding of neuronal computations,

including those in our own brain.

Keywords: dendritic processing, collision avoidance, impedance, lobula giant movement detector

Introduction

By the nineteen forties, neuroscientists had recognized that neuronal membranes exhibited a

frequency dependent impedance and had begun investigating which cellular mechanisms contributed

to their resistance, capacitance, and inductance (Cole 1941). The capacitance of the membrane is

determined by its lipid bilayer, and its resistance by permeability to ion fluxes, but the inductance came

from an unknown source. After the discovery of active conductances, it became clear that their kinetics

produced a phenomenological inductance, and that its properties could be investigated using Hodgkin

and Huxley's equations (Mauro 1961; Mauro et al. 1970).

Membrane capacitance low-passes, while inductance high-passes input currents. Their

combination can thus result in bandpass filtering and resonance. In the decades since, researchers have

learned a great deal about the roles of active conductances in shaping the electrical properties of

neurons, and the influence of neuronal bandpass properties on rhythmic activity within neural networks

(Das et al. 2017; Hutcheon and Yarom 2000; Wang 2010). In addition to generating neural rhythms, the

membrane impedance shapes the integration properties of dendrites determining their ability to

discriminate between patterns of synaptic inputs.

Voltage-gated channels modify the membrane impedance through their time varying

conductances. The range of input frequencies affected depends on the channel kinetics. Non-

inactivating channels that decrease their conductance as the membrane potential approaches their

reversal potential produce negative feedback on changes in membrane potential and thus a

phenomenological inductance. In the LGMD two such inductive channels, HCN and M, produce the

largest resting conductances, influencing the selectivity and timing of its responses (Dewell and

Gabbiani 2018a, 2018b). The impedance profile of a neuron is also influenced by its dendritic

morphology. An extended morphology causes dendritic compartmentalization which increases the

attenuation and lag of postsynaptic potentials traveling towards the spike initiation zone, but

simultaneously enhances local coincidence detection and nonlinear processing (Häusser and Mel 2003;

London and Hausser 2005). Dendritic branching and tapering could optimize synaptic integration by

increasing the spatial homogeneity of postsynaptic potentials' influence at the site of spike initiation

(Cuntz et al. 2007). Additionally, the dendritic morphology of pyramidal and Purkinje neurons is

believed to favor the neurons' response to inputs of certain frequencies thus promoting neuronal

resonance (Dhupia et al. 2015; Ostojic et al. 2015).

We have chosen to explore these questions in the LGMD (O'Shea and Williams 1974), an

identified neuron in locusts that selectively responds to visual stimuli mimicking impending collision

(Rind and Simmons 1992; Schlotterer 1977). The LGMD's stimulus selectivity arises from the precise

spatiotemporal patterning of synaptic inputs (Jones and Gabbiani 2010; Peron et al. 2007a; Zhu and

Gabbiani 2016) and complex dendritic computations, including filtering by active conductances such

as sodium, low voltage calcium, calcium-dependent potassium, inactivating potassium, HCN, and M

channels (Dewell and Gabbiani 2018a, 2018b; Gabbiani et al. 2002; Peron and Gabbiani 2009).

Different aspects of the LGMD's firing patterns – including burst firing – have been tied to the

generation of escape behaviors (Dewell and Gabbiani 2018a; Fotowat et al. 2011; McMillan and Gray

2015). Currently, no one has characterized the LGMD's membrane impedance to determine how it

shapes this neuron's dendritic integration and visual computations.

Neuronal membrane properties have mainly been studied with cultured neurons or brain slices

and the natural synaptic input patterns are still unknown for most neurons, so much remains

unanswered about how the impedance properties of neurons influence synaptic integration and neural

computations *in vivo*. As both g_H and g_M are sensitive to numerous modulators (Delmas and Brown

2005; Wahl-Schott and Biel 2009), our ability to conduct experiments *in vivo* ensures that the channels

are in the relevant modulatory state. We discovered that the LGMD membrane impedance is broadband

and generates small delays between synaptic current and membrane potential that remain consistent

across membrane potentials. The HCN and M channels, their interactions, and the neuronal

morphology all contribute to producing this broadband impedance profile which increases the LGMD's

ability to discriminate behaviorally relevant patterns of synaptic inputs from irrelevant ones.

Materials and Methods

Animals

Experiments were performed on adult female grasshoppers 7-12 weeks of age (*Schistocerca*

americana). Animals were reared in a crowded laboratory colony under 12 h light/dark conditions.

Animals were selected for health and size without randomization, and investigators were not blinded to

experimental conditions. Sample sizes were not predetermined before experiments. The surgical

procedures used have been described previously (Dewell and Gabbiani 2018a; Gabbiani and Krapp

2006a; Jones and Gabbiani 2012).

Visual stimuli

Visual stimuli were generated using Matlab (RRID:SCR_001622) and the Psychophysics

Toolbox (PTB-3, RRID:SCR_002881) on a personal computer running Windows XP. A conventional

cathode ray tube monitor refreshed at 200 frames per second was used for stimulus display (LG

Electronics, Seoul, Korea). Looming stimuli are the two-dimensional projections of an object

approaching on a collision course with the animal. They consisted of an expanding dark square

simulating a solid object with half size l approaching at constant speed v (illustrated in Figure 1B). The

expansion profile is characterized by the ratio $l/|v|$, as previously described (Gabbiani et al. 2001).

Electrophysiology

Sharp-electrode LGMD intracellular recordings were carried out in current-clamp or voltage-

clamp mode using thin walled borosilicate glass pipettes (outer/inner diameter: 1.2/0.9 mm; WPI,

Sarasota, FL; see Jones and Gabbiani, 2012, as well as Dewell and Gabbiani, 2018a for details). The

membrane potential (V_m) and current (I_m) were low-pass filtered with cutoff frequencies of 10 kHz and

5 kHz, respectively. Most recordings were digitized at a sampling rate of 20,073 Hz (for some

experiments V_m was digitized at 40,146 Hz). We used a single electrode clamp amplifier capable of

operating in discontinuous mode at high switching frequencies (20-35 kHz; SEC-10, NPI, Tamm,

Germany). Responses to current injections were recorded in discontinuous current clamp mode (DCC).

For dual recordings we inserted under visual guidance a second sharp electrode into the excitatory

dendritic field of the LGMD (see Figure 3A) with a motorized micromanipulator (Sutter Instruments,

Novato, CA). Membrane potential was recorded with a second SEC-10 amplifier in bridge mode with

electrode resistance and capacitance compensation when not injecting current and in DCC mode while

injecting current. Switching frequencies, signal filtering and digitization were identical for both

recordings.

The physical distance along the dendrites and an estimate of the electrotonic distance between

recording electrode pairs were measured as follows. First, all cells were stained with Alexa Fluor 594

and imaged with a CCD camera to record electrode positions (Dewell and Gabbiani 2018a). Next, an

image of the neuron and electrodes (cf. Figure 3A) was imported into ImageJ (RRID:SCR_003070),

the dendritic path between the electrode tips was manually traced, and the corresponding path length

recorded. To estimate the electrotonic distance we measured the amplitude of the back-propagating

action potentials (bAP) at each location and used the difference in these amplitudes. As in a previous

study, the differences in bAP amplitude provided a more reliable explanatory variable for distance

dependent effects (Dewell and Gabbiani 2018a).

A neuron's frequency-dependent membrane properties are characterized by its impedance

profile. The subthreshold impedance can be decomposed into input impedance which describes local

change in membrane potential at the site of an input current and transfer impedance that describes

change in membrane potential at remote locations after propagation through the neuron. Both input and

transfer impedance shape synaptic integration within dendrites. Additionally, impedance properties at

the site of spike initiation influence the transformation of membrane potential into spiking activity,

including the frequency filtering and timing of a neuron's output. If a neuron's conductance distribution

is uniform, then the transfer and input impedances will have similar properties. When it is not, the

impedance profile varies by location and transfer depends on the recording locations and the direction

of signal propagation (Hu et al. 2009; Vaidya and Johnston 2013).

To measure the impedance profile, we injected sine waves of increasing frequency called chirp

(or zap) currents. We recorded the injected membrane current simultaneously with the membrane

potential to avoid any discrepancies between the computer-generated waveform and the current

injected by the amplifier. The chirp currents used were identical to those described in Dewell and

Gabbiani (2018b). The chirp current is defined as $I(t) = I_p sin\phi(t)$, where I_p is the peak current, $\phi(t)$

is the phase of the sine wave, and its instantaneous frequency is defined as $f(t) = \frac{1}{2\pi}\frac{d\phi}{dt}$ (in units of

Hz). We generally used chirps with a duration of 20 s (sometimes 30 s, as is illustrated in Figure 3B)

that increased in frequency either linearly or exponentially with time. In most experiments, as well as

for all simulations, we used exponentially increasing chirp currents. The linear chirp started at 0 Hz

and was calculated as $I(t) = I_p \sin(\pi\beta t^2)$, with t being the time from the start of the chirp (in units of

s) and β the rate of increase in instantaneous chirp frequency (in Hz/s). The exponential chirp was

given by $I(t) = I_p \sin(2\pi f_0 t e^{\beta t})$, where f_0 is the initial chirp frequency and β determines the

(accelerating) rate of frequency increase (Barrow and Wu 2009). For all exponential chirps, we used f_0

$= 0.05$ Hz and $\beta = 0.24$ Hz which produced a chirp current increasing to 35 Hz over 20 s. We saw no

differences in the calculated impedance profiles with chirps having different frequency profiles, in

accordance with previous comparisons of impedance profiles between chirps of increasing and

decreasing frequencies (Ulrich 2002; Erchova et al. 2004; Hu et al. 2002; van Brederode and Berger

2008; van Brederode and Berger 2011) or comparison of linearly increasing chirps and sums of sine

wave stimuli (Hutcheon et al. 1996).

Pharmacology

We applied the HCN- channel blocker ZD7288 and the M-channel blocker XE991 either

directly in the bath saline or by local puffing as previously described (Dewell and Gabbiani 2018a,

2018b). For local puffing we used a micropipette connected to a pneumatic picopump (PV830, WPI,

Saratoga, FL). Drugs were mixed with physiological saline containing fast green (0.5%) to visually

monitor the affected region. For both delivery methods, drug concentrations within the lobula were

~200 µM for ZD7288 and ~100-200 µM for XE991. In dual recording experiments, mecamylamine

was applied to block excitatory postsynaptic potentials (EPSPs) and was present in both control and

drug conditions. Blockade of EPSPs reduced membrane noise as well as noise in the calculated

impedance profiles. In paired comparisons, mecamylamine caused small increases in impedance

amplitude (~5%) but this difference was smaller than the variability between animals or between

dendritic locations. For control data we thus pooled recordings with and without mecamylamine.

Experimental design and statistical analyses

Data analysis was carried out with custom MATLAB code (The MathWorks, Natick, MA).

Linear fits were done by minimization of the sum of squared errors. Before each chirp current a -2 nA

hyperpolarizing step current was used for monitoring the input resistance and the membrane time

constant. Unless otherwise specified, all statistical tests were made using the Wilcoxon rank sum test

(WRS) which does not assume normality or equality of variance. Normality of the data was assessed

by using a Lilliefors test for any tests assuming it.

The complex impedance Z was calculated as $Z(f)$ = fft(V_m)/fft(I_m) where fft is the (frequency

dependent) fast Fourier transform, I_m the membrane current, and V_m the membrane potential. Both I_m

and V_m were down sampled to 2 kHz before the fft. Z was calculated for each trial and then averaged

across trials. The complex impedance is composed of its real part, the resistance R, and its imaginary

part, the reactance X: $Z = R + i\,X$. A positive reactance, or inductance, indicates that changes in V_m

precede changes in I_m. Conversely, a negative reactance, or capacitance, indicates that changes in I_m

precede changes in V_m. The impedance amplitude is calculated as the absolute value of Z: $|Z(f)| =$

$\sqrt{R(f)^2 + X(f)^2}$. The impedance phase is calculated by the inverse tangent of the reactance divided

by the resistance: $\Phi(f) = \tan^{-1} X(f)/R(f)$. This impedance phase is equal to the angle between the

x-axis and a line from the origin to a point of the impedance locus plot (cf. Figure 5C).

Input impedance (Z_{IN}) was calculated from the V_m and I_m recorded at the site of current

injection. Transfer impedance (Z_{TR}) was calculated with the I_m from the site of current injection and the

V_m from the non-injected site. Voltage attenuation was calculated as the relative reduction in

impedance amplitude from the current injection site to the non-injected site: $V_{att}(f) =$

$(|Z_{IN}(f)| - |Z_{TR}(f)|)/|Z_{IN}(f)|$. Similarly, the phase lag was calculated as the input minus the transfer

impedance phase. The input and transfer impedance phases were each converted to the time domain by

$t_{phase}(f) = \Phi(f)/(2\pi f)$ where f is the instantaneous chirp frequency (in Hz) calculated as $f(t) =$

$\frac{1}{2\pi}\frac{d}{dt}\sin^{-1}(\frac{I(t)}{I_p})$, for details see (Dewell and Gabbiani 2018b). The mean V_m delay was then calculated

by averaging across frequencies the absolute value of the delay between the input current and

membrane potential.

Resonant strength was calculated from the input impedance amplitude as the ratio of the

maximum impedance to the steady state (0 Hz) impedance. The impedance frequency variation (f_{var})

was calculated as the standard deviation (across frequencies ranging from 0 to 35 Hz) of the impedance

amplitude profile divided by the mean impedance amplitude. Unlike resonance strength, f_{var}

incorporates both the strength and breadth of the bandpass, giving an indication of how ohmic (or

broadband) the membrane is. Indeed, an ideal resistor would have a frequency variation of zero while a

membrane exhibiting sharp bandpass attributes would produce high frequency variation. The

membrane constant values used for our electrical circuit models yielded f_{var} values of 18.4 for the

lowpass circuit, and 378 for the strongest bandpass circuit (see below; Fig. 4G). There is a potential

drawback to the statistic, though, since it depends on the frequency range examined, limiting the ability

to compare values between studies examining different frequency ranges.

For calculating the power density of the membrane potential, we used the Matlab multitaper

power spectral density estimate (function 'pmtm'), with a time-half bandwidth product of 4 measured

over 15 octaves at frequencies of 2^{-4} to 2^{11} Hz with 8 voices (scales) per octave. The mean was

subtracted from all data before calculating the power density estimate and the resulting estimates were

then averaged across trials. For estimating the time-varying power density we used Matlab's

continuous wavelet transform (function 'cwt'). The frequency range was set from 0.1 to 2,000 Hz and

the signal was not extended. As for the spectral density estimate, wavelet transforms were calculated

for individual trials and the resulting wavelet transform coefficients were then averaged across trials. In

the calculation of both measures, the raw data was used with no down sampling or filtering.

Electrical circuit model

The LGMD membrane impedance was compared to the impedance of an equivalent cable

based on a series of either RC or RLC circuits. RC circuits describe passive membranes, while RLC

circuits can approximate the frequency-dependent properties of active neuronal membranes. Active

conductances are both frequency and voltage dependent, while inductances are only frequency

dependent. The RLC circuit was modeled as illustrated in Figure 4F. The membrane impedance density

was calculated as:

228
$$Z_m = \frac{R_m}{1 - l_{rat} + l_{rat}/(1 + i\tau_L\omega) + i\tau_m\omega}$$

229   where Z_m is the input impedance density (in units of Ωcm^2), R_m is the membrane resistivity (Ωcm^2), C_m

230   is the membrane capacitance (F/cm^2), τ_m (s) is membrane time constant ($\tau_m = R_m C_m$), τ_L is the

231   inductance time constant (s), ω is frequency in rad/s, l_{rat} is the ratio of the membrane conductance that

232   is in series with the inductor (range [0–1]), and $i = \sqrt{-1}$. If l_{rat} is zero, then no current will pass through

233   the inductor and the circuit is equivalent to an RC circuit with membrane impedance:

234
$$Z_m = R_m/(1 + i\tau_m\omega).$$

In both cases, the input impedance (Z_{IN}) was calculated by dividing Z_m by the unit surface area of the

cable (cm^2). We used the average dendritic circumference of our full LGMD model (20.85 µm) for the

cable circumference.

Transfer impedance measures were based upon a cable of fixed diameter and infinite length.

The voltage transfer along the cable was calculated as $V_{TR} = e^{-l/\lambda}$, where l (cm) is the distance

between the two locations and λ is the cable's length constant (cm), $\lambda = \sqrt{Z_m/(R_a d b_f)}$. R_a is the axial

resistivity (Ωcm), d is the diameter (cm), and $b_f = 3$ is the branch factor – a scalar added to account for

additional attenuation due to the dendritic branching. The transfer impedance Z_{TR} at distance l from the

site of current injection is the product of Z_{IN} and V_{TR}.

Morphological neuron models

Comparisons between different cell morphologies used published neuron models downloaded

from ModelDB (RRID:SCR_007271) and a simplified Rall model (Rall 1964). The Rall model

(illustrated in Fig. 1) had 64 sections, each 20 µm long. The soma had a 20 µm diameter and the

dendritic arbor had 5 branch levels. The base branch had a 12 μm diameter with each level decreasing

in diameter according to the 2/3 power law (Rall 1964). Among the available morphologies, we

selected neurons spanning a wide range of branching patterns and sizes. The morphologies used

included a cerebellar Purkinje neuron (Miyasho et al. 2001; Ostojic et al. 2015), a CA1 pyramidal

neuron (Migliore et al. 2004), an oriens-lacunosum/moleculare (OLM) hippocampal interneuron

(Sekulić et al. 2015), and a human layer 2/3 temporal cortex pyramidal neuron (Eyal et al. 2016). As

we sought to compare the influence of the cell morphology, all models were passive with identical

membrane properties close to those used in the LGMD model ($C_m = 0.8$ μF/cm^2, $G_m = 0.1$ mS/cm^2, Ra

$= 350$ Ωcm). All simulations were carried out using the NEURON software simulation package. For a

passive model measuring impedance with chirp currents, as was done experimentally, or with

NEURON's built-in impedance tools yielded the same result, so we used the built-in impedance

measurement to speed up the simulations carried out for Fig. 8A and B.

In Fig. 8G, the percentage of cell surface area with improved transfer impedance amplitude was

calculated from the data depicted in Fig. 8F (right). Specifically, we calculated the transfer impedance

amplitude between all neuron segments and compared it to the impedance amplitude of an isopotential

model (using the same cell morphology but with axial resistivity set to zero). The impedance amplitude

of an isopotential cell is $R/(1 + \tau_m^2\omega^2)^{0.5}$, where R is the membrane resistance (MΩ), ω is the frequency

(s^{-1}), and τ_m is the membrane time constant (s). As C_m and G_m were the same for all morphologies, their

membrane time constants were the same ($\tau_m = C_mG_m$) while the membrane resistance changed with

their total membrane area A ($R = (AG_m)^{-1}$). For each segment, we summed the surface area of all

segments to which a broadband signal transferred with greater gain than the isopotential value (dashed

line in Fig. 8F, right) and divided by the neuron's total surface area. Frequencies of 0 to 1,000 Hz were

used and averaged with equal weight.

Similarly, to obtain Fig. 8I we compared the transfer impedance phase between all segment

pairs and compared it to the impedance phase of an isopotential equivalent. The impedance phase of an

isopotential cell is $\tan^{-1}(-\tau_m \omega)$, as illustrated in Fig. 1B, right. For the phase measurements, a weighted

average was used with the transfer amplitude between the segment pair determining the weight for

each frequency. As signals of some frequencies transfer better than others, the transfer phase of these

signals influences the membrane synchrony more. The percentage area with increased impedance

phase was then calculated by summing the surface area of segments with more synchronous transfer

phase than an isopotential equivalent cell and dividing by the total membrane surface area of the

neuron. These calculations effectively measure the average signal transfer of a passive cell with

realistic morphology under the simplifying assumptions that broadband inputs impinge upon the

neuron with a uniform density. Although these assumptions would not necessarily hold *in vivo* where

the locations and frequency of inputs is constantly changing, they provide a method of estimating

transfer impedance without relying on the less realistic assumptions that all inputs impinge on a single

location or that all signals only integrate at a single location, like the neuron's spike initiation zone.

Results

Broader impedance profiles improve the discrimination of input timing. The input impedance

(Z_{IN}) of passive neurons can be approximated by RC circuits containing a parallel capacitance and

resistance. It is well known that such circuits exhibit a sharp lowpass filtering of input currents. If a

sinusoidal current is applied to an RC circuit or a passive neuron, then higher frequencies produce

smaller changes in membrane potential resulting in a frequency dependent gain (Fig. 1A). The

impedance phase similarly decreases with input current frequency (Fig. 1B). The slower the

membrane, or equivalently the higher the membrane time constant, the faster gain and phase decay

with frequency. Conversion of the impedance phase to time shows that the delay between an input

current and the resulting change in membrane potential is equal to τ_m for low frequencies (Fig. 1C).

This Z_{IN} delay decreases with increased signal frequency. Long, frequency dependent delays reduce the

ability of neurons to discriminate between synaptic input arrival times. To prevent this, auditory

neurons that precisely discriminate the timing of their synaptic inputs have small time constants (~0.3

ms), thereby minimizing the delay between input currents and change in V_m (McGinley et al. 2012;

Mikiel-Hunter et al. 2016; Remme et al. 2014).

Simulations with model CA1 pyramidal neurons show that g_H increases the ability of a neuron

to discriminate the timing of its synaptic inputs (Migliore et al. 2004). In such simulations, a barrage of

synaptic inputs impinges on randomly selected dendritic branches with varying degrees of synchrony.

The input synchrony is altered with the addition of a random temporal jitter applied to each input.

Replacing g_H by an inductance results in a similar increase in synchrony discrimination. To

demonstrate this, we simulated 100 synaptic inputs impinging with varying degrees of synchrony onto

an artificial model neuron (Fig. 1D; Rall model, Methods). In the passive case, lowpass filtering

prevented discrimination of input synchrony (Fig. 1D, blue line). Furthermore, the spike timing was

less reliable and had a longer latency (Fig. 1E, blue line). As in the CA1 model simulations, active

dendritic conductances, in this case g_H and g_M, increased the discrimination of the input synchrony and

produced spikes with shorter, more consistent latencies (Fig. 1D and E, black). Replacing these

conductances with an inductance resulted in the exact same increase in input synchrony discrimination

with slightly improved spike timing, illustrating the role played by g_H and g_M's phenomenological

inductance (Fig. 1D and E, red).

Among these three models, the passive Rall branching model is the most effective low-pass

filter (Fig. 1F,G, blue). The active conductance and the inductance models differ slightly, but share key

similarities (Fig. 1F,G). In both models the gain and phase decrease less with frequency than in the

passive case, reducing lags at low frequencies. We quantified these two points by computing the

frequency variation (Fig. 1H) and the mean V_m delay (Fig. 1I). Earlier work showed that

discriminating between temporal patterns of excitatory inputs is key to the LGMD's selectivity for

looming stimuli (Jones and Gabbiani 2010). What then is its impedance profile, and can it explain

synaptic pattern discriminability in the LGMD?

The spectral power density of the LGMD's membrane potential is concentrated at low

frequencies. The LGMD possesses three dendritic fields with the largest one, field A, integrating

excitatory inputs originating from every facet of the compound eye (Fig. 2A). It responds more or less

vigorously to approaching objects that activate thousands of facets based on the object's trajectory and

spatial coherence (Dewell and Gabbiani 2018a; Gray et al. 2001). Currently, it is unknown what

synaptic input current frequencies most neurons experience *in vivo*. To address this question, we first

measured the power spectrum of the membrane potential for spontaneous activity. The LGMD receives

a high number of spontaneous synaptic inputs (Fig. 2D; Jones and Gabbiani, 2012) and its membrane

time constant is short *in vivo* (~ 7 ms; Gabbiani and Krapp, 2006; Peron et al., 2007; Dewell and

Gabbiani, 2018a, 2018b). This raises the possibility that high frequency components might dominate

the LGMD's membrane potential power spectrum. However, we found that 87% of the power was

contained below 35 Hz, with 50% at less than 7.5 Hz (Fig. 2E, black lines).

Next, we computed the spectral power density in response to looming stimuli. During the

course of such a stimulus the number of activated ommatidia increases from ~10 to over 2,500,

producing an increase in activated synapses from ~100 to over 20,000 (Rind et al. 2016). As this

increased synaptic input occurs in ever tighter time windows (Fig. 2C), it might lead to a shift in power

towards higher frequencies. However, low frequency power increased during looming stimuli, with

over 50% of it below 1.5 Hz (Fig. 2E, blue lines). As most of the membrane depolarization and spiking

activity generated by looming occurs over the last second before collision, we also used wavelet

analysis to resolve the frequency content of the membrane potential in the time domain (see Methods).

During this period there was an increase in power spectral density at higher frequencies (Fig. 2F, gray

box), but most power remained centered around 1-2 Hz (Fig. 2F). The concentration of the LGMD

membrane potential power at low frequencies despite high frequency synaptic input could be due to

the activation characteristics of these inputs or to low-pass filtering by the LGMD's membrane. We

tested the latter possibility by measuring the frequency-resolved input and transfer impedance of the

LGMD's membrane. The input impedance reveals the mapping of current to local dendritic membrane

potential frequencies, while the transfer impedance documents the change in membrane potential

frequency content as the signal propagates from the dendrites toward the SIZ.

Single and dual dendritic LGMD recordings *in vivo* in response to chirp currents. The LGMD's

input and transfer impedance were measured by recording *in vivo* the membrane potential with sharp

electrodes (Fig. 3A). These experiments consisted of injecting chirp currents (sine waveforms with

time-varying frequency) during single or paired recordings in the excitatory dendritic field (see

Methods). Superposing chirp currents on different holding currents allowed us to measure impedance

at multiple steady-state membrane potentials (V_{ss}; Fig. 3B), and thus at different steady-state activation

levels of subthreshold conductances present in the LGMD membrane. In general, chirp responses

looked consistent across V_{ss} values, tapering slightly with increasing frequency. Examination of

different periods of the chirp show that at low frequencies the oscillations in membrane current and

potential were synchronous, while at higher frequencies the membrane potential lagged behind the

current and the change in potential was smaller (Fig. 3C). We conducted similar experiments in

voltage clamp and found similar changes to occur (Fig. 3D).

Quantification of transfer impedance characteristics was made as a function of the distance

between different pairs of dendritic recordings. The inter-electrode distance was measured both as the

dendritic path length between the electrodes in experimental micrographs (path distance, Fig. 3A), and

as the difference in back propagating action potential (bAP) amplitudes (electrotonic distance). At the

base of the excitatory dendritic field, the bAP amplitude was ~40 mV and decayed to <10 mV in distal

dendritic branches. The recording locations in the present study were in larger branches with bAP

amplitudes between 20 and 40 mV. The path distances between these electrode pairs ranged from 63 to

150 μm. The difference in bAP amplitudes was well correlated with changes in membrane potential

transfer properties (Fig. 3E). In contrast, there was no correlation between path distance and voltage

attenuation ($r(9) = 0.17$, $p = 0.63$, Pearson linear correlation), likely due to differences in dendrite

diameter or number of branch points between the recording pairs. With increased electrotonic distance

between recording pairs, there was reduced voltage transfer and an increased delay. The closest

recordings had ≤10% voltage attenuation, while for more distant pairs this value increased to almost

50% (Fig. 3E). The average phase and time lags between locations were ~3° and 0.5 ms between the

most synchronous pairs and ~10° and 2 ms between the most asynchronous pairs. For subsequent

analyses of transfer impedance, data from all recording pairs were pooled.

Consistency of impedance amplitude across holding potentials and chirp frequencies. The

impedance amplitude is the absolute value of the complex impedance and represents the gain function,

mapping at each frequency a given synaptic or electrode current into a change in membrane potential.

We measured the impedance amplitude at different V_{ss} values and examined how its profile changed

with holding potential. The LGMD dendrites have a resting membrane potential near -65 mV, can be

hyperpolarized by inhibitory inputs to below -70 mV, and are depolarized by excitatory inputs to >-50

mV during looming stimuli (Fig. 2C). We thus used V_{ss} values spanning that range and confined below

the spike threshold potential.

Input impedance amplitude was highest at low membrane potentials (<-75 mV), particularly at

low frequencies (Fig. 4A, dashed box). Yet, despite the LGMD's resting HCN and M conductances

(Dewell and Gabbiani 2018a, 2018b) changes in V_{ss} produced little change in impedance amplitude

(Fig. 4A). This differs from other HCN and M channel-expressing neurons that exhibit a pronounced

resonant frequency (Gastrein et al. 2011; Gutfreund et al. 1995a; Hu et al. 2002; Hutcheon et al. 1996).

The transfer impedance amplitude similarly changed little with membrane potential and tapered only

slightly with increased frequency (Fig. 4B). Accordingly, the voltage attenuation between paired

recording locations also showed a high overlap across holding potentials (Fig. 4C). The variability of

the voltage attenuation between recording pairs was higher though, due to the differences in

electrotonic distance (Fig. 3E). The constancy of impedance amplitude at different V_{ss} values implies a

constant total membrane conductance across holding potentials. While other channel types might

contribute, HCN and M channels account for the majority of the LGMD's resting membrane

conductance, suggesting that their total conductance remains roughly constant. This in turn would

increase the consistency of EPSP amplitudes across holding potentials. This idea was confirmed by

injecting currents simulating EPSP waveforms at the same V_{ss} values used to measure impedance,

resulting in peak depolarizations that were independent of V_{ss} (r(89) = -0.05, p = 0.63, 91 V_{ss} values

from 16 recordings in 9 animals).

The resonance properties of an electrical circuit are characterized by its bandwidth and

resonance strength (the Q factor, Horowitz and Hill, 2015). However, neuronal membranes have

complex impedance profiles that are not as easily characterized. The most commonly used measure of

neuronal resonance strength is the ratio of peak to steady-state (0 Hz) impedance (Koch 1984a).

Unfortunately, this measure ignores impedance at other frequencies. So, in addition to this standard

measure (see below, Fig. 6H), we wanted an additional measure that incorporated impedance at

frequencies below and above the resonant frequency and thus we characterized the variability of the

impedance amplitude by its standard deviation across frequencies normalized to the mean impedance

amplitude, which we call the frequency variation (see Methods). The frequency variation of the

LGMD's input impedance amplitude was 10-15% and decreased slightly with membrane

depolarization (Fig. 4D, black). Transfer impedance amplitude had a frequency variation of ~20% and

also decreased with depolarization (Fig. 4D, red). The power spectral density at 0 Hz was 1,000-fold

higher than at 35 Hz during looming stimuli and 25-fold higher during spontaneous inputs (Fig. 2E).

For the same frequencies, both the input and transfer impedance amplitudes were less than 2-fold

higher. For comparison, if the synaptic inputs during looming were broadband and the lowpass spectral

density were due to membrane filtering, this would imply a frequency variation >250%. The lack of

prominent lowpass filtering rules out the membrane impedance as the cause of the power spectrum

concentration at low frequencies (Fig. 2E,F). Instead, this suggests that the low frequency power is due

to the activation characteristics of the synaptic input currents during a looming stimulus.

To test what electrical components could produce the impedance amplitude properties of the

LGMD, we created an array of RC and RLC circuit models (Fig. 4E, F), as in earlier studies (Koch

1984b; Mauro 1961; Rall 1964). For both model types we used a specific membrane capacitance (C_m)

and conductance (G_m) yielding a time constant (τ_m) of 6.9 ms, close to that measured experimentally in

the LGMD (Dewell and Gabbiani 2018a, 2018b; Gabbiani and Krapp 2006a; Peron et al. 2007a). The

RLC circuit contained, in addition to the parallel conductance and capacitance, a series conductance

and inductance to account for the effects of restorative membrane conductances like g_M and g_H (Fig.

4F). We varied the percentage of G_m that was in series with the inductance and the inductance time

constant (τ_L) to determine which, if any, parameters reproduced the LGMD's impedance amplitude.

These two parameters then model the percentage of the membrane conductance passing through the

active channels and the time constant of the active conductance. For most of the tested parameter

space, the circuit model's input impedance amplitude varied more with frequency than that of the

LGMD (Fig. 4G). Circuits with a fast inductance ($\leq$ 10 ms) had impedance amplitudes as consistent as

that of the LGMD, while slow inductances increased the frequency variation beyond that of an RC

circuit, which was already higher than that of the LGMD. This is surprising considering that the

LGMD's resting membrane conductance is heavily dependent on rectifying HCN channels with a time

constant of ~1 s (Dewell and Gabbiani 2018a). To assess the importance of the LGMD's membrane

time constant to the frequency variation, we examined the same range of inductance values in an RLC

circuit with doubled τ_m (increasing τ_m by increasing C_m or by decreasing G_m had the same effect). With

the higher τ_m, no inductance parameters produced a frequency variation as low as that of the LGMD.

Therefore, the low frequency variation of the LGMD's impedance profile depends on a fast τ_L in

addition to the fast τ_m. Of the LGMD's known conductances, g_M is the most likely candidate to provide

such a fast inductance.

Impedance phase reveals high current – voltage synchrony across membrane potentials.

Membrane capacitance produces a phase lag between input currents and their resulting change in

membrane potential that increases both with frequency and distance of propagation. Conductances like

g_H and g_M counteract this lag and increase the synchrony between synaptic input currents and the

membrane potential (Hu et al. 2009; Narayanan and Johnston 2008; Ulrich 2002; Vaidya and Johnston

2013). To characterize the timing of the LGMD's membrane potential with respect to current inputs,

we thus measured the frequency-dependent dendritic impedance phase. In a passive, isopotential

neuron, membrane capacitance forces input impedance phase to saturate at -90° as input current

frequency increases (Mauro 1961; Narayanan and Johnston 2008). Conversely, a positive impedance

phase indicates that the change in voltage precedes the change in current, a feature requiring a

physiological process that resembles an electrical inductance. Like impedance amplitude, the LGMD's

impedance phase varied little with V_{ss} values, distinguishing it again from other neurons (Gutfreund et

al. 1995a; Narayanan and Johnston 2008). For all holding potentials, the phase was positive at low

frequencies (≤ 1 Hz). Although phase decreased with frequency, it saturated well above -90° and in

some recordings even increased at frequencies > 20 Hz. This was the case for both the input and the

transfer impedance phase (Fig. 5A and B, respectively). The LGMD subthreshold membrane potential

exhibited zero phase and hence was most synchronous with input current at ~1 Hz, in contrast to

spiking which is most synchronous with input currents of ~6 Hz (Dewell and Gabbiani 2018b).

Plotting as in Fig. 5C the real and imaginary components of the input impedance, called

respectively resistance and reactance, illustrates both the low frequency inductive and the high

frequency capacitive properties of the input impedance phase (corresponding to positive and negative

reactance, respectively). Such impedance locus plots combine the information on the impedance

amplitude (Fig. 4A) and phase (Fig. 5A): for each point in a locus plot if one were to draw a line

segment from the origin to the point, the length of the segment would be equal to the impedance

amplitude and the angle relative to the x-axis is the impedance phase. Fig. 5C confirms that the input

reactance was consistent across V_{ss} values while the input resistance increased at hyperpolarized

potentials resulting in a rightward shift of the curves as V_{ss} decreased. The impedance locus plot of the

transfer impedance reveals even less change across membrane potentials, with only a small increase in

transfer resistance at hyperpolarized potentials (Fig. 5D). The relative phase of the input and transfer

impedances is the membrane potential phase lag with larger values indicating increased transfer delay

(Fig. 5E). The phase lag between input and transfer phase was also consistent across V_{ss} values and

was negative at frequencies ≤ 1 Hz, indicating an inductive phase shift on the propagating membrane

potential. The low frequency inductive characteristics of both the input and transfer impedance reveal

the influence of a slow inductor, consistent with the presence of a slowly rectifying HCN conductance.

Signal frequencies with zero reactance (and therefore an impedance phase of zero) have no

delay between membrane current and potential. On average, the LGMD's membrane potential and

current were offset by ~2 ms at the input location independent of V_{ss} (Fig. 5F, grey). The mean delay

of the transfer impedance was ~3 ms at V_{ss} near -80 mV and decreased with depolarization (Fig. 5F,

red). We similarly measured the delay between membrane potentials recorded at two positions, which

was ≤ 1 ms (Fig. 5F, brown). To test how this measured timing compared to that of an RLC circuit, we

surveyed the same parameter range as depicted in Figure 4. No inductance parameters generated a

circuit as synchronous as the LGMD. Circuits with a large and fast inductance generated the lowest

input impedance delay, but this was still > 3.5 ms (Fig. 5G). Reproducing the LGMD's low frequency

inductive phase (Fig. 5A,B) required an RLC circuit model with a slow inductance ($\tau_L \approx 1$ s). The

dashed black lines of the low frequency insets (Fig. 5A,B & D) were produced by inductance

parameters marked by the black star in Fig. 5G. Although the addition of a slow inductance to an RLC

circuit reproduced the low frequency inductance of the LGMD membrane, it increased the input and

transfer asynchrony of the circuit model further from that of an RC circuit (Fig. 5H). In contrast, the

asynchrony between the membrane potential recorded at the two locations could be reproduced by

either cable model (Fig. 5H, right). This shows that the LGMD must have an additional synchronizing

influence unaccounted for by the circuit model. Whether this increased synchrony is explainable by the

LGMD's active membrane conductances is not immediately evident.

HCN and M channels reduce impedance amplitude and frequency variation. To assess the

influence of HCN and M channels on the LGMD's input impedance profile, we measured the input

impedance before and after addition of two channel specific blockers: ZD7288 and XE991,

respectively. Blocking g_H reduces the resting membrane potential and input resistance of the LGMD

(Dewell and Gabbiani 2018a), so after HCN blockade we applied chirps with lower peak current and

higher holding current to generate equivalent V_{ss} values and changes in membrane potential (Fig. 6A).

After g_H blockade a decrease in the membrane potential was seen with increasing chirp frequencies.

The impedance amplitude doubled at low frequency and decreased more steeply with input frequency

(Fig. 6B). A reduction in inductance was also clear from the decreased impedance phase (Fig. 6C).

Blockade of g_M increases the LGMD's resting membrane potential and input resistance (Dewell

and Gabbiani 2018b), so we used decreased holding currents and chirp amplitudes after blockade to

account for these changes. After g_M blockade, a resonance emerged (Fig. 6D, arrowhead). This was

reflected in the peak near 4 Hz in the impedance amplitude profile (Fig. 6E). This resonance likely

helps generate the increased spiking observed in response to ~4 Hz current inputs following g_M

blockade (Dewell and Gabbiani 2018b). The impedance phase increased at frequencies ≤ 2 Hz and

decreased at higher frequencies (Fig. 6F). These effects suggest that in addition to implementing an

inductance evident above 2 Hz, g_M also counteracts an additional inductance that increases impedance

amplitude at frequencies around 4 Hz and phase at frequencies ≤ 2 Hz.

Both g_M and g_H reduced frequency variation, causing a larger reduction at depolarized and

hyperpolarized potentials, respectively, consistent with their activation kinetics (Fig. 6G). The

increased frequency variation after block of either channel was due to a large increase in the range of

resistance across frequencies and a reduced high frequency reactance. We also calculated the

resonance strength, a common measure of how bandpass a membrane is, and found it to be small at all

V_{ss} values in control conditions and after g_H block (Fig. 6H, black and red). After g_M block, though, at

resting V_m and above a strong membrane resonance was observed with impedance amplitude around 4

Hz double that of steady state (0 Hz; Fig. 6H, green). Both conductances contribute to decrease the

membrane impedance amplitude of the LGMD, with g_H causing the largest reduction at and below

resting Vm and g_M at depolarized potentials, respectively. Although we did not measure the effects of

g_H and g_M blockade on transfer impedance, input and transfer resonance were similar in control

conditions (with resonant strengths differing by < 0.05 for >75% of trials). So, the changes in transfer

resonance after channel block would most likely parallel those of input resonance.

In addition to reducing the impedance amplitude and making it more consistent across

frequencies, both g_H and g_M decreased the delay between input current and the resulting change in

membrane potential. After blockade of either channel the input delay increased, with g_M blockade

having the largest effect (Fig. 6I). After g_M blockade the minimum phase was more capacitive at high

frequencies and the maximum phase more inductive at low frequencies (Fig. 6F). After g_H blockade,

the input impedance phase decayed to a minimum at a lower frequency (Fig. 6C). The decrease in

input impedance delay produced by g_H and g_M would improve the LGMD's ability to discriminate the

timing of its synaptic inputs (see below), but even after blocking the channels, the delay between I_m

and V_m was still smaller than any RLC circuit model (compare Fig. 6I and Fig. 5H). This suggests that

there must be an additional mechanism beyond these membrane conductances that further reduces

these delays, as confirmed by investigating the impact of neuronal morphology (see below).

Pronounced effect of g_M on temporal input discrimination. We have previously shown that

blockade of g_H reduced the LGMD's ability to discriminate the spatial pattern of its synaptic inputs

(Dewell and Gabbiani 2018a), but the role of the LGMD's active conductances in discriminating

temporal patterns has not been addressed. We tested this with the same sort of simulations described in

Figure 1, using a full LGMD model that reproduces most of its experimental properties (Dewell and

Gabbiani 2018a, 2018b). Increased noise in the timing of synaptic inputs quickly reduced spiking (Fig.

7A, black). Simulations conducted without g_H slightly reduced the model's sensitivity to input timing,

but g_M's removal created a substantial reduction (Fig. 7A). The removal of both conductances

decreased the ability to discriminate between input timings by over half (Fig. 7A, blue). These changes

in spike probability were accompanied by similar effects on spike timing. Removal of g_M increased the

spike latency (measured from the start of synaptic excitation) as well as its variability (Fig. 7B). This

confirms previous experimental findings on the importance of g_M in spike timing precision (Dewell

and Gabbiani 2018b). In the LGMD, g_H plays a critical role in the discrimination of synaptic input

patterns during prolonged excitation (Dewell and Gabbiani 2018a), but the present simulations indicate

that it does not play a similar role for brief periods of synaptic excitation.

Neuronal morphology increases membrane gain and high frequency synchrony. To test the

influence of morphology on membrane impedance we compared simulations between passive models

that were either isopotential or had realistic branching and attenuation. These simulations build upon

earlier ones that examined the role of morphology on signal propagation and impedance in other

neurons (Holmes et al. 1992; Jaffe and Carnevale 1999; Mainen and Sejnowski 1996; Vetter et al.

2001). The principal difference in the current simulations is the characterization of morphological

influence on the impedance delay and calculation of the net influence of morphology on input currents

distributed throughout the dendritic arbors.

Plotting the input impedance delay of every section of the full LGMD model (Fig. 8A) revealed

that it was reduced from that of an isopotential model (dashed line) indicating higher synchrony

between a local input current and membrane potential. For the same frequency range used in

experiments, the passive model segments had a mean input delay of 2.1 ± 1.1 ms, matching

experimental data (c.f. Fig. 5H). This suggests that the LGMD morphology plays a bigger role in the

membrane potential's delay relative to input current than its active conductances. The input impedance

amplitude was also altered by cell morphology, decreasing less with frequency than in an isopotential

equivalent model (Fig. 8B; solid vs. dashed lines). The input frequency variation of the model sections

was 8.6 ± 4.7% for the physiologically dominant frequency range (< 35 Hz; see Fig. 1), demonstrating

that the LGMD's morphology alters the input impedance amplitude profile as much as its active

conductances. At higher frequencies, the input impedance amplitude remained monotonically

decreasing, but was always higher than that of the isopotential model (Fig. 8B, dashed line).

To determine whether the effects of morphology on impedance was unique to the LGMD, we

conducted similar simulations using four other neuronal morphologies covering a range of sizes and

branching patterns (Fig. 8C). The additional morphologies examined were taken from cerebellar

Purkinje, layer 2/3 pyramidal, CA1 pyramidal, and oriens-lacunosum moleculare (OLM) neurons. The

membrane conductance and capacitance were uniform and the same for all models producing a

membrane time constant of 8 ms. Simulations with slower τ_m yielded qualitatively similar results. For

all morphologies, input impedance delay decreased (Fig. 8D) and amplitude increased (Fig. 8E)

relative to their isopotential equivalents (otherwise identical models with zero axial resistance).

Hence, the branched structures of the LGMD and other neurons enhance local inputs with

increased gain and higher synchrony between input currents and changes in membrane potential. This

is offset in part by lower signal transfer because the branching and axial resistance also increase

voltage attenuation between cell regions. The net effect of the morphology on the membrane

impedance is therefore not immediately apparent. In experiments, transfer impedance was measured by

injecting current at a single location and recording the membrane potential at another. Synaptic

currents, however, impinge at thousands of locations spread out across the dendrites. Furthermore,

these inputs don't propagate independently to the site of spike initiation.

The precise effect of morphology on synaptic integration depends on the pattern of its inputs,

which are unknown for most neurons, so we assumed broadband inputs spread across the entire arbor.

To assess the net effect of morphology on impedance we thus calculated the transfer impedance in an

all-to-all manner, with current frequencies between 0 and 5 kHz injected successively into each model

segment and the impedance measured in all other segments of the model. An example of transfer

impedance profiles from one dendritic segment of the LGMD is illustrated for a 35 Hz current in Fig.

8F (delay on left, amplitude on right). These plots show that segments near the current injection site

(arrowheads) had higher transfer impedance while more distant segments had lower transfer

impedance than an isopotential equivalent (dashed lines). For all segments of all models, at all

frequencies, nearby segments exhibited increased and distant segments decreased transfer impedance

relative to the isopotential models. To determine how far signals propagated before the increased

attenuation overcame the increased input impedance, we quantified, for each segment, its area of

increased transfer impedance relative to an isopotential equivalent. This was recorded as the

percentage of membrane for which transfer amplitudes were higher and delays shorter compared to the

equivalent isopotential model. In Fig. 8F, this percentage would correspond to the surface area of the

segments marked in brown divided by the total membrane area (brown and black).

For currents injected into some LGMD segments, the surface area with increased transfer

amplitude was as high as 90% and amounted to ~70% for the average segment (Fig. 8G, black). The

Purkinje model had a similar area of increased transfer as the LGMD, while models of the pyramidal

and OLM neurons, however, had an increased transfer amplitude from most segments to ~90% of the

neuron's surface area (Fig. 8G). In addition to quantifying the area of improved transfer, we also

calculated membrane area weighted averages of the transfer amplitude to examine the net effect of the

morphology on signal transfer. Examination of the net transfer amplitude at different frequencies

showed that each morphology generated a bandpass increase in transfer amplitude (Fig. 8H). The CA1

pyramidal model had the highest increase, with 40 Hz inputs increasing by 9%. The LGMD and

Purkinje morphologies generated smaller increases, 4-5%, shifted at higher frequencies near 65 Hz.

This shows that the branching morphologies of neurons provide a bandpass increase to the overall

membrane gain. As branched morphologies cause membrane potentials to attenuate, it would not have

been surprising if their net effect were a reduced transfer amplitude relative to an isopotential model,

but this was not the case.

For all morphologies, the reduction in input delay was partially offset by the increase in transfer

delay. The improved timing of the input impedance spread throughout most of the neurons, and the

lower transfer delay propagated to almost the same membrane area as did the increased transfer

amplitude (Fig. 8I). To calculate the total transfer delay, values were weighted by the strength of the

transfer amplitude: if there is minimal signal transfer between 2 segments then the timing of that

transfer is less relevant. The net impact of morphology on the average transfer delay was small (≤ 0.3

ms for all frequencies; Fig. 8J). All morphologies had slightly smaller net transfer delays than an

isopotential equivalent model for signals above 100 Hz. The amount of this improvement scaled with

the τ_m used for simulations; simulations with $\tau_m = 16$ ms had twice the improvement in delay due to

morphology. The overall effect of the morphologies on transfer timing was minimal on low frequency

signals, but could improve the timing of high frequency signals, like those generated from fast synaptic

currents.

Discussion

Here we have described the impedance properties of the LGMD *in vivo*, measured over the

range of frequencies encompassing most of the signal power mediated by the LGMD's synaptic inputs.

We found that the membrane impedance amplitude of the LGMD is consistent over the range of

subthreshold membrane potentials and input frequencies involved in the detection of approaching

objects. Further, the membrane impedance revealed small delays between input current and resulting

changes in membrane potential. This membrane timing and gain consistency were both shaped by the

conductances g_H and g_M, as well as the neuron's branching morphology. Extensive modeling revealed

that these changes to the LGMD's impedance profile increase its ability to discriminate the temporal

patterns of excitatory synaptic inputs.

Despite a high rate of spontaneous and stimulus-evoked synaptic inputs due to the large number

of excitatory synapses the LGMD receives (Rind et al. 2016), most of its membrane power was

concentrated at low frequencies (Fig. 2E). During looming stimuli, as the rate of excitation increased,

the dominant signal frequency actually decreased with over 50% of the membrane potential spectral

power below 1.5 Hz (Fig. 2E, F). As neither the input nor the transfer impedance amplitude of the

LGMD were lowpass over the same frequency range (Fig. 4A, B), this must reflect the characteristics

of pre-synaptic inputs to the LGMD. Neither the membrane gain, nor the delay between I_m and V_m

changed dramatically over the frequencies tested, favoring integration over a broad frequency range

during looming.

To determine what shapes the frequency dependence of the impedance gain we used

pharmacological manipulations and computational modeling. We found that the neuron's morphology

and the active conductances g_H and g_M (Fig. 6G) dramatically reduced frequency variation of the

impedance gain, making the LGMD membrane impedance more broadband. This was surprising, as

both g_H and g_M usually make neurons more bandpass (Hönigsperger et al. 2015; Hu et al. 2009;

Hutcheon and Yarom 2000; Narayanan and Johnston 2008). The primary effect of g_H on the membrane

impedance (Fig. 6B,C), is actually the same as in other neurons, a reduction of lowpass filtering and

impedance delay. Whether g_H narrows the membrane bandpass properties or broadens them, as it does

here and in CA3 interneurons (Anderson et al. 2011), depends on the relative balance of its effects and

those of other membrane properties.

In addition to showing low frequency variation and delays between I_m and V_m , the impedance

of the LGMD also showed consistency across holding potentials. As an object approaches, increasing

excitation causes dendritic depolarization of >20 mV, so changes in dendritic integration properties

with membrane potential would influence the detection of impending collisions. Neither the amplitude

nor the phase of the membrane impedance changed much from -70 to -55 mV (Fig. 3 and 4). This

consistency can also be largely explained by g_H and g_M. At hyperpolarized potentials g_H increases,

dominating the membrane conductance, while conversely g_M increases with depolarization. At the

LGMD's resting membrane potential (-65 mV), both channels have large conductances and shallow

activation kinetics (Dewell and Gabbiani 2018a, 2018b). If the activation ranges of g_H and g_M had less

overlap, the impedance profile would be less consistent across membrane potentials and the channels

would be more likely to create separate hyperpolarized and depolarized resonances as seen in

pyramidal cells (Hu et al. 2002, 2009).

674   Synaptic integration is influenced by the input timing as well as its gain. We found that the

LGMD exhibited shorter delays between I_m and V_m than could be explained by a circuit model (Fig.

5H). These delays were reduced by both g_H and g_M (Fig. 6I). On average, blockade of g_M produced a

larger reduction than g_H, except at frequencies near the peak membrane power during looming stimuli

(~1.3 Hz; Fig. 2F). The influence of g_H at low frequencies is consistent with its effect on synaptic

pattern discrimination during looming (Dewell and Gabbiani 2018a), while having only a small effect

in model simulations with brief periods of excitatory inputs (Fig. 7A). In contrast, the ability to

discriminate the timing of these simulated synaptic inputs was greatly reduced by removal of g_M from

the LGMD model (Fig. 7), a feature that would be difficult to test experimentally because the g_M

blocker XE991 also has presynaptic effects (Dewell and Gabbiani 2018b). Previously, simulations of

these same brief periods of excitation using a model of a CA1 pyramidal neuron found g_H to

dramatically increase sensitivity to input timing (Migliore et al. 2004). In those CA1 simulations the g_H

time constant was ~40-fold faster than in our LGMD model, but it was very similar to the LGMD's g_M

time constant. This further supports the idea that these effects are mainly due to the change in

membrane impedance, rather than channel type.

689   Although g_H and g_M decreased I_m-V_m delays, the delays remained lower after their blockade

than those of an equivalent circuit model. Testing a morphologically realistic, passive LGMD model

revealed that the neuron's shape influenced the membrane's input impedance as much as the active

conductances (Fig. 8A, B). The branching morphology introduces new electrical paths whose axial

resistivity does not decrease with frequency. This led to increased input gain and reduced input delays.

Previous modeling of pyramidal and Purkinje neurons have also found that dendritic branches reduced

lowpass filtering (Dhupia et al. 2015; Ostojic et al. 2015). This led us to wonder how the influence of

LGMD's morphology on impedance compared to other cell morphologies, and whether the increase in

input impedance caused by an extended neuronal morphology was counteracted by decreased signal

propagation. We tested this with transfer impedance simulations of five neuronal morphologies.

Transfer impedance is defined between two locations. While it is technically infeasible to

simultaneously record intracellularly from many places within a neuron, in a model it is no more

difficult to measure transfer between one hundred locations than between two. The reason we chose to

measure the all-to-all transfer rather than just transfer from individual dendrites to the site of spike

initiation is simple. In neurons, *in vivo* synaptic currents impinge throughout the dendrites and do not

propagate in isolation, but continuously integrate with new inputs. As far as we know, this is the first

examination of the sum transfer of a dendritic arbor in this fashion. It revealed that in the LGMD, as

well as other cells, the net effect of morphology is an increase in all-to-all impedance gain and a

decrease in high frequency delay between I_m and V_m. Additionally, we found that the net increase in

gain is bandpass between 30 and 100 Hz (Fig. 8H). Although their magnitudes were consistent, the

frequency range of these changes depended on the simulated membrane time constant; for simulations

with a slower membrane the bandpass gain increase shifted to lower frequencies (data not shown). This

furthers previous findings on the effects of dendritic morphology on a neuron's integration capabilities

(Dhupia et al. 2015; Mainen and Sejnowski 1996; Moore et al. 1988).

Ultimately the integration properties of a neuron are dictated by the pattern of its inputs and its

computational role. For hippocampal pyramidal neurons that receive theta rhythmic inputs, a strong

theta (4-10 Hz) resonance and synchrony could be advantageous (Hu et al. 2009; Hutcheon and Yarom

2000; Vaidya and Johnston 2013). Similarly, it might be a computational benefit for cortical neurons to

exhibit large impedance changes with membrane potential to enhance differences between up and

down network states (Gutfreund et al. 1995b; Hasselmo 2005; Heys et al. 2010; Wang 2010). For

auditory neurons, specialized in detecting high frequency sound waves, a very fast membrane time

constant and high frequency inductance lead to broadband membranes with resonance at frequencies

up to 400 Hz (Mikiel-Hunter et al. 2016; Remme et al. 2014). The LGMD detects approaching objects

and discriminates their specific input statistics from a wide range of other input patterns through their

integration over a wide range of membrane potentials. This involves discriminating synaptic input

patterns on the order of milliseconds to tens of milliseconds (Jones and Gabbiani 2010) as well as over

several seconds (Dewell and Gabbiani 2018a). Thus, achieving broadband membrane impedance with

minimal delay across input frequencies and membrane potentials by a balance of active membrane

conductances and an extended morphology is exactly what is needed to fine tune escape behaviors.

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Dewell and Gabbiani, Fig. 1

Figure 1. Membrane impedance shapes the ability of neurons to discriminate and transmit the timing

of their inputs. A) The membrane impedance amplitude of a passive isopotential neuron (modeled as

an RC circuit) decays with frequency, more rapidly so the slower the membrane time constant (τ_m).

The impedance amplitude determines the gain between input currents and membrane potential.

Formula: R_m – membrane resistance; ω – frequency (radian). B) The impedance phase, which

determines the timing between input currents and membrane potential, also decreases with frequency

in passive isopotential neurons. The corner frequency (ω_c) of the membrane impedance for such RC

models is determined by the τ_m. C) Converting the phase into the time domain reveals that for low

frequency signals the delay between membrane current and potential equals τ_m and that this delay

depends on frequency. D) Simulations with a Rall branching neuron model (schematic at right) tested

the ability to discriminate the synchrony of 100 synaptic inputs. If the model contained the active

conductances g_H and g_M, spikes were generated by synchronous inputs but not if input synchrony was

decreased by adding random noise to the synaptic activation times (black). Removal of the active

conductances greatly decreased the ability to discriminate the timing of synaptic inputs (blue). If the

voltage dependent conductances were replaced by a voltage independent inductance, the ability to

discriminate input timing was returned. E) The timing of spikes changed accordingly, such that for the

models with inductances the spike time more faithfully conveyed the timing of its inputs. F,G) The

voltage independent inductance produced similar changes to the impedance gain (F) and impedance

timing (G) as did the voltage dependent conductances. H) The passive model had higher frequency

variation indicating that it was more lowpass and less broadband. I) The mean absolute delay between

I_m and V_m was higher for the passive model, causing the reduction in timing reliability for the model.

Figure 2. Spontaneous and looming stimulus-evoked spectral power density of the LGMD's membrane potential. A) Micrograph of the LGMD, illustrating its dendritic fields (labeled A, B and C), the spike initiation zone (SIZ, marked with *) at the start of the axon, and the soma which lies outside of the neuron's electrical signal path (adapted from Gabbiani et al., 2002). Scale bar: 25 μm. B) A looming stimulus consists of a black square expanding symmetrically on the animal's retina (bottom). It simulates an object of half size l approaching on a collision course at constant velocity v (< 0), subtending an angular size $2\theta(t)$ at the retina (top). C) Looming stimuli produce an angular size that increases nonlinearly over time (top, blue line). Most of the response to looming stimuli occurs shortly before the projected time of collision as can be seen in the average membrane potential (V_m, middle) and firing rate (bottom, displayed as mean ± standard error of the mean, sem, for 59 looming stimuli; N = 16 animals). D) Example recording of dendritic membrane potential within the LGMD while the eye was exposed to uniform illumination (V_m low-pass filtered at 10 kHz and digitized at 40 kHz). E) Despite the high frequency of spontaneous inputs, the V_m power is concentrated at frequencies below 5 Hz (black, abscissa is on logarithmic scale). During looming stimuli, the signal power increased 125-fold but remained concentrated at low frequencies (blue). Inset shows the data on a double logarithmic scale. Solid lines and shaded regions are mean ± sem (N = 16 animals). F) Using wavelet analysis to measure the membrane potential power density in both the frequency and time domains reveals that during spiking there is increased high frequency power (dashed square), but the peak power remains at

 frequencies <10 Hz. Plot displays the average power density map of the same 59 looming responses

905 shown in C and E.

Dewell and Gabbiani, Fig. 3

Figure 3. Characterization of LGMD's membrane impedance profile with *in vivo* dendritic recordings.

A) Either single or dual recordings were made from dendritic field A and the primary neurite

connecting field A to the SIZ. Image taken with a CCD camera during a dual recording after staining

the LGMD with Alexa 594. The internal solution of both electrodes contained Alexa 594 for

visualization. Red and green ellipses encompass the region sampled by the proximal and distal

electrode, respectively, across 12 recording pairs (8 animals). B) To measure membrane impedance,

chirp currents (sine waveforms of increasing frequency) were injected at different steady-state

membrane potentials (V_{ss}). At top is an example of a linearly increasing chirp current followed by four

recordings of the membrane potential in response to this chirp current superposed on different holding

currents (I_{hold}). The values of I_{hold} and V_{ss} (dashed lines) were 2, 0, -2, -4 nA and -56, -64, -74, -86 mV,

respectively (from top to bottom). C) Examples traces of low and high frequency sections of the

measured membrane current and potential. At low frequencies the current and potential are

synchronous (~0° impedance phase) but at high frequencies the potential trails the current (negative

impedance phase). Note that at high frequencies the membrane potential is reduced relative to the

current indicating a reduction in impedance amplitude. D) Impedance measurements were similar

when measured in voltage clamp. E) Signals attenuated more and had longer lags as the electrotonic

distance increased between recording electrodes (estimated by the difference in amplitudes of the

backpropagating action potential, bAP). Each point and error bar report the mean value and sd (across

different V_{ss} values) for a recording pair (N = 11 recording pairs from 8 animals). Mean bAP

amplitudes were 32 and 26 mV for the proximal and distal electrode; the dendritic path distance

between recordings ranged from 63 to 149 µm with a mean of 105 µm.

 Dewell and Gabbiani, Fig. 4

Figure 4. The LGMD membrane impedance amplitude and voltage attenuation behave similarly across

frequencies and membrane potentials. A) Input impedance (Z_{IN}) amplitude profiles measured at

different steady-state membrane potentials (V_{ss}, see Fig. 3B) and displayed as mean ± sem (lines and

shaded regions) reveal a high degree of overlap across membrane potentials. The lines only show clear

separation for low frequencies (<10 Hz, dashed square) at membrane potentials >10 mV below V_{rest} (-

65 mV). N = 76 recordings from 56 animals. B) The transfer impedance (Z_{TR}) amplitude between

different dendritic sites also varied little across membrane potentials. The inset shows the average input

and transfer impedance amplitudes (solid lines) overlaid with those of an RLC circuit model as

depicted in panel F (dashed lines). N = 13 recording pairs from 10 animals. C) Voltage attenuation

(V_{att}) is more variable between recordings than impedance amplitude (note the larger sem regions in C

when compared to A or B) with ~20–35% reduction in voltage between dendritic locations. The inset

compares attenuation with that of the best-fit RLC model of panel F. Same data set as in B. D) The

frequency variation (f_{var}) of the input and transfer impedance amplitude as well as that of voltage

attenuation decreased slightly with membrane depolarization. The frequency variation shows the

consistency across frequencies, with a value of 0 indicating an ideal resistor. E,F) RC and RLC

circuits, respectively, were chained to obtain equivalent cylinder models for comparison with the data.

For both circuit models $G_m = 116\ \mu S/cm^2$ and $C_m = 0.8\ \mu F/cm^2$. See methods for details on impedance

calculations. G) Heatmap illustrating the effect of the RLC circuit inductor parameters on the

frequency variation of its input impedance. The left edge ($G_L = 0$) corresponds to the RC circuit

depicted in E. Slower inductor time constants (τ_L) increased frequency variation. Increasing the ratio

G_L/G_m increased frequency variability for slow inductors and decreased it for fast inductors. The red

line delimits the parameter region that had a frequency variation as low as the LGMD data. The star

indicates the parameter values used for the insets in panels B and C which best matched the shape of

the LGMD impedance amplitude profiles. H) Heatmap of an RLC circuit with τ_m twice that of the

LGMD. For this slower circuit model, no inductor parameter yielded an impedance as consistent across

frequencies as the LGMD data. In G and H plotted values are for input impedance; transfer impedance

maps look similar but with frequency variations of ~1.06 times those in the input impedance maps for

all parameters.

Figure 5. LGMD membrane synchrony and consistency across membrane potentials. A) Z_{IN} phase

profiles (mean ± sem) are inductive (exhibit positive phase) only at frequencies < 1 Hz (inset), show

high overlap across membrane potentials, and level off around -30°. N = 76 recordings from 56

animals. B) Z_{TR} phases similarly exhibit induction at frequencies < 1 Hz (inset) and overlap across

membrane potentials. N = 13 recording pairs from 10 animals. C, D) Impedance locus plots show the

real (resistance) and imaginary (reactance) components of the impedance, pooled across frequencies

(dotted arrow). The membrane inductance at low frequencies is evidenced by the points with positive

reactance. At hyperpolarized potentials, resistance increased but otherwise the LGMD maintained a

consistent profile across membrane potentials. E) Phase lag of membrane potential at the 'recording-

only' location relative to that at the 'recording and current injection' location. At frequencies <1 Hz

there was a phase advance with the more distant location preceding the input location (inset). The

phase lag increased steadily with frequency. F) Impedance delay was measured as the mean absolute

time lag between pairs of simultaneously recorded variables. Z_{IN} delay corresponds to the lag between

the input current and local membrane potential. Z_{TR} delay was calculated from the lag between the

input current and membrane potential at the secondary recording location and V_m transfer delay from

the lag between the membrane potentials at the two recording locations. Z_{TR} delay decreased with

membrane depolarization. G) RLC circuit Z_{IN} delay as a function of its inductor parameters. Z_{TR} delay

was ~1.1 times higher than Z_{IN} values shown. The LGMD low frequency inductive phase could only

be reproduced by a slow inductor. Dashed black lines in insets of A, B and E produced by parameters

979   marked by black star in G. H) The LGMD exhibited lower delay between membrane current and

980   voltage (phase nearer 0°) than an RC circuit model ($G_L = 0$) or the RLC circuit model marked by the

981   black star in G. No RLC circuit with comparable time constant produced as small a mean Z_{IN} or Z_{TR}

982   delay as the LGMD.

Figure 6. Blockade of either HCN or M channels increased impedance frequency variation and delay

between I_m and V_m. A) Example chirp currents (top) and membrane potential responses (bottom)

before (left, black) and after (right, red) ZD7288 application. After drug application the chirp

amplitude was decreased and I_{hold} was increased to produce a similar V_{ss} and similar changes in

membrane potential. B) After blocking HCN channels with ZD7288, input impedance increased 2-fold

at low frequencies. Population average impedance (across animals and V_{ss}) is shown as mean ± sem

(solid line and shaded region). The grey line is the difference between the averages. C) Impedance

phase decreased at all frequencies after HCN blockade, reducing membrane current-voltage synchrony.

D) Example chirp currents (top) and response (bottom) before (left) and after (right) XE991

application. After drug application the chirp amplitude and I_{hold} were decreased to produce a similar V_{ss}

and similar changes in membrane potential. E) After blocking M channels with XE991 a large increase

in low frequency input impedance was also seen with peak at ~4 Hz. F) After M channel block

impedance phase increased at low frequencies (<2 Hz) but decreased at higher frequencies. G) The

increased low frequency impedance after blockade of HCN or M channels produced higher Z_{IN}

frequency variations across steady-state membrane potentials. Z_{IN} frequency variation is displayed as

linear fit (solid lines) and 95% confidence intervals (dotted lines). M channel blockade increased

variation mainly at depolarized potentials while HCN blockade had a greater effect at hyperpolarized potentials. H) The resonance strength, calculated as the maximum impedance amplitude divided by steady-state impedance amplitude ($|Z_{IN}(0)|$), was <1.2 for all membrane potentials under control conditions and after HCN block. After I_M block, however, a larger resonance was observed at depolarized membrane potentials. I) The mean absolute time lag between the input current and local membrane potential, increased by ~1 ms after HCN block (red) and ~2 ms after M channel block (green). Control data (black) is the same as shown in Fig. 5F. Control data from 53 recordings at 181 V_{ss} from 44 animals; ZD7288 data includes 9 recordings at 36 V_{ss} from 6 animals; XE991 data includes 6 recordings at 14 V_{ss} from 6 animals.

Dewell and Gabbiani, Fig. 7

Figure 7. LGMD model simulations show g_H and g_M increase sensitivity to synaptic input timing and reduce spike latency. A) In the full LGMD model (black), synchronous inputs reliably generated spikes, but for inputs with less reliable input timing ($\sigma > 15$ ms) no spikes were produced. Removal of g_H (red) slightly decreased the input timing selectivity, and removal of g_M (green) or both conductances (blue) produced larger reductions in the timing discrimination. In each condition the leak reversal potential was adjusted to maintain a constant resting membrane potential. B) The timing of the spikes generated were also less reliable. The full LGMD model generated spikes with the shortest latency after the inputs began. After g_M blockade spikes occurred later and with less reliable timing.

Figure 8. Simulations of passive neurons reveal the influence of morphology on impedance characteristics. A) Every section of the LGMD model (thin black lines) had shorter input impedance delays than an isopotential model (dashed line). B) All sections of the LGMD model (thin black lines) exhibited a decrease in input impedance amplitude smaller than that of an isopotential model (dashed line). For each section the impedance amplitude is normalized to impedance at 0 Hz ($|Z_{IN}(0)|$). The difference between the input impedance amplitude and that of an isopotential model was maximal at ~200 Hz. C) The effect of neuronal morphology on impedance was tested in the LGMD (black) and 4 other cell morphologies of different size and shape: a cerebellar Purkinje cell (purple), a hippocampal CA1 pyramidal cell (red), a cortical layer 2/3 pyramidal cell (blue), and a CA1 oriens lacunosum-moleculare interneuron (OLM; green). D) All neuron models tested had large decreases in input delay compared to an isopotential equivalent model. Data is color coded as depictions in C and presented as mean ± sd (solid lines and shaded regions). E) All morphologies had more consistent input impedance amplitude relative to their isopotential equivalents, with lower frequency variation. Data presented as in D. F) Data from example dendritic segments of the LGMD model shows that at 35 Hz the transfer

impedance delay (left) increased and the amplitude (right) decreased with distance from the site of current injection (arrowheads). Segments for which transfer impedance had higher amplitude or shorter delay than that of an isopotential equivalent neuron (dashed line) are brown. Data in G and I measured by summing the surface area of brown segments and dividing by the total surface area. G) For each neuron model segment, we summed the surface area of other model segments for which signal transfer was increased compared to an isopotential equivalent and divided by the neuron's total surface area. Bar widths indicate how many model segments had improved transfer (higher gain and lower delay) for each percentage range, and grey squares mark the average segment. All morphologies had increased transfer amplitudes compared to an isopotential equivalent model, with the LGMD and Purkinje morphologies having improved transfer for a smaller percentage of the neuron segments. H) For all models, an average all-to-all transfer impedance was measured as a function of frequency and compared to the impedance of an isopotential equivalent. The increase of each cell's mean transfer amplitude as a function of frequency from isopotential reveals a bandpass increase in average transfer gain. I) The percentage of membrane area with reduced transfer delay was similar for each morphology as that with an increase in transfer gain. Plotted as in G. K) The average all-to-all transfer delay from I_m to V_m for each model was similar with no difference at low frequencies, a slightly longer delay near the frequency of the cell's peak gain, and reduced delays at higher frequencies.