High-throughput microfluidic characterization of erythrocyte shape and mechanical variability

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The motion of red blood cells (RBCs) in microchannels is important for microvascular blood flow and biomedical applications such as blood analysis in microfluidics. The current understanding of the complexity of RBC shapes and dynamics in microchannels is mainly based on several simulation studies, but there are a few systematic experimental investigations. Here, we present a combined study, which systematically characterizes RBC behavior for a wide range of flow rates and channel sizes. Even though simulations and experiments generally show good agreement, experimental observations demonstrate that there is no single well-defined RBC state for fixed flow conditions, but rather a broad distribution of states. This result can be attributed to the inherent variability in RBC mechanical properties, which is confirmed by a model that takes the variation in RBC shear elasticity into account. This represents a significant step toward a quantitative connection between RBC behavior in microfluidic devices and their mechanical properties, which is essential for a high-throughput characterization of diseased cells.

microfluidic flow | cell deformation | red blood cell | shape and dynamics | mesoscopic simulation

During their 120-day lifespan, red blood cells (RBCs) withstand tremendous stresses and deformations as they travel hundreds of kilometers through the vascular system. Their distinctive biconcave discocyte shape has evolved to meet the requirements for large, repetitive and reversible deformations. The ability to deform and change shape is vital for RBCs, as they pass vessels whose diameter is smaller than their own size (1, 2). Changes in elastic properties and shape of RBCs are of great interest in microcirculation research, because they affect many essential microvascular processes, including blood flow resistance (3–5), the viscosity of whole blood (6–9), ATP release and oxygen delivery (10–12). Alterations in RBC material properties and shape are often associated with different blood diseases and disorders (13, 14), such as sickle cell anemia (15, 16), diabetes mellitus (17, 18), and malaria (19–21). The importance of RBC behavior in flow also motivates large research efforts in blood processing and analysis using microfluidic devices (22–26).

Stimulated by the interest in RBC behavior in microvasculature and microfluidics for blood analysis, a number of experiments and simulations with RBCs flowing in narrow channels and capillaries have been performed (3, 4, 27–33). Typical deformed shapes are so-called parachutes and slippers (4, 5, 34). Parachutes are characterized by a parachute-like shape and a position in the channel center. Slippers take an off-center position in flow and exhibit a tank-treading motion of the RBC membrane due to shear gradients. The occurrence of different RBC shapes is governed by several parameters, including flow rate, cell confinement characterized by the ratio between cell diameter and channel size, RBC elastic properties (e.g. shear elasticity, bending rigidity), and the viscosity ratio λ between RBC cytosol and suspending medium (or plasma) (4, 5, 34). Recent simulation studies in two dimensions (2D) (5, 34) and three dimensions (3D) (4) predict a RBC state diagram with various shapes and dynamics for a wide range of flow rates and cell confinements. Even though 2D simulations qualitatively capture some of the RBC states, it is clear that

Significance Statement

The ability to change shape is crucial for the proper functioning of red blood cells under harsh conditions in the microvasculature, since their shapes strongly affect the flow behavior of whole blood. Our results from simulations and systematic experiments reveal the shapes and dynamics of red blood cells for different flow conditions and channel dimensions, generally in good agreement. However, in the experiments, cells do not exhibit a single well-defined shape for fixed flow conditions. We show that this distribution of shapes can be attributed to the variability in mechanical properties of red blood cells.

F.R. performed experiments; J.M. and D.A.F. performed simulations; A.A.N. fabricated silicon masters for microdluidic chip production; F.R., J.M., and D.A.F. analyzed data; D.A.F., G.G., and J.G. designed research; all authors discussed the results and wrote the paper.

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the motion of RBCs is inherently three dimensional and the correspondence between 2D and 3D diagrams is at best qualitative. For example, the 3D simulations (4) predict a tumbling state, where a RBC flips like a coin in Poiseuille flow within a very narrow channel, which does not exist in 2D and has not been observed experimentally so far. One of the limitations of this simulation study (4) is that it was performed for the viscosity ratio $\lambda = 1$, while under physiological conditions, $\lambda \approx 5$ (35). Furthermore, there exists no systematic experimental investigation, which would corroborate or challenge the simulated state diagram of RBC shapes and dynamics in microchannels, even though several RBC states (e.g. parachutes, slippers) have been observed experimentally. Moreover, recent simulations of a RBC in rectangular channels (33) suggest that there might be bistable states even for fixed flow conditions, depending on the initial position of a RBC as it enters the channel, which might indicate a sensitive dependence on the channel geometry. These gaps in our fundamental understanding of RBC behavior in microchannels prevent a knowledge-based design of efficient microfluidic devices for blood analysis.

In this work, we present a combined experimental and simulation study of RBC behavior in microchannels in order to address the challenges above. Microfluidic experiments are performed for a wide range of flow conditions, covering a wide range of cell velocities (between $0.1\,\mathrm{mm/s}$ and $4\,\mathrm{mm/s}$) and channel sizes (between $9.75\,\mathrm{\mu m}$ and $14.75\,\mathrm{\mu m}$ in hydraulic diameter). This constitutes the data base for the analysis of more than $35\,000$ cells and allows, for the first time, a systematic construction of an experimental RBC state diagram. Simulations are performed for $\lambda \approx 5$ and are in good agreement with experimental observations. A remarkable experimental result is that, for fixed flow conditions, there is no single well-defined RBC state, but rather a distribution of shapes, while simulations generally show a single RBC state. This outcome arises from the inherent variability in RBC mechanical properties, which has to be taken into account. Empirical approximation of the inherent variation in RBC shear elasticity leads to RBC state distributions, which agree well with experimental observations. Furthermore, the experiments show the existence of tumbling polylobe shapes in large enough channels at high flow rates, which were before only observed in pure shear flow (9, 36). The combination of experimental and simulation results allows us to fill several gaps in understanding of RBC behavior in microchannels and to make a step toward a quantitative characterization of RBC mechanical properties and their variability. Future microfluidic investigations will reveal how diseases affect cell mechanical properties and can be used for a precise blood analysis. Such studies will also advance our understanding of the effect of different RBC shapes and dynamics on microvascular blood flow in health and disease.

Results

Shape and dynamics diagram from simulations.

To map RBC behavior for various conditions, a number of simulations with a periodic channel of square cross-section were performed for a wide range of channel sizes and flow rates. The side length D of a square channel determines RBC confinement, $\chi = D_r/D$, where $D_r = \sqrt{A_r/\pi}$ is the effective RBC diameter and A_r is the RBC membrane area. The flow rate was characterized by a non-dimensional shear rate as

$$\dot{\gamma}^* = \frac{\eta_o D_r^3 \bar{\dot{\gamma}}}{\kappa_r} = \tau \bar{\dot{\gamma}}, \qquad [1]$$

where $\bar{\dot{\gamma}} = \bar{v}/D$ is the effective shear rate, $\bar{v} = Q/A$ is the average flow velocity with cross-sectional area $A = D^2$ and volumetric flow rate Q, η_o is the dynamic viscosity of a suspending fluid, and $\tau = \eta_o D_r^3/\kappa_r$ is a characteristic relaxation time of a RBC with membrane bending rigidity κ_r. The cytosol viscosity η_i inside a RBC is about five times larger than the plasma viscosity (35). The RBC relaxation time τ is equal to $0.85\,\mathrm{s}$ for $\eta_o = 9 \times 10^{-4}\,\mathrm{Pa{\cdot}s}$ (a water-like PBS solution) and average properties of a healthy RBC, corresponding to $D_r = 6.56\,\mathrm{\mu m}$ and $\kappa_r = 70\,k_B T = 3 \times 10^{-19}\,\mathrm{J}$. Another important parameter, which characterizes the relative importance of RBC shear elasticity to bending rigidity, is the Föppl-von Kármán number $\Gamma = Y_r D_r^2/\kappa_r \approx 2700$, where $Y_r = 18.9 \times 10^{-6}\,\mathrm{N/m}$ is the membrane Young's modulus corresponding to a shear modulus of $\mu_r = 4.6 \times 10^{-6}\,\mathrm{N/m}$.

Figure 1 shows the simulated state diagram of RBC shapes and dynamics for a physiological viscosity contrast $\lambda = \eta_i/\eta_o = 5$. Three different states can be identified. At strong enough confinements and high flow rates, a parachute shape is observed, where the cell moves in the center of the channel and is deformed into a parachute-like shape by strong fluid forces. Here, we do not differentiate between symmetric and slightly asymmetric parachute shapes. At weak confinements, a RBC tumbles at low $\dot{\gamma}^*$ and attains a slipper shape at high $\dot{\gamma}^*$. Both states are characterized by an off-center cell position. Slippers exhibit a nearly stationary orientation with tank-treading dynamics of the membrane. Hence, they will also be referred to as tank-treading cells. In the tumbling state, the cell exhibits typical tumbling motion without significant membrane tank-treading. It is important to note that for any fixed flow condition in simulations, a single state can generally be assigned with some exceptions very close to the state boundaries.

The diagram in Fig. 1 is qualitatively similar to the diagram for RBC behavior in tube flow at $\lambda = 1$ in Ref. (4).
In case of $\lambda = 5$, the tumbling region is larger than for $\lambda = 1$ and expands toward higher $\dot{\gamma}^*$ values. This is due to the
fact that high viscosity contrasts suppress membrane tank-treading, thereby making the slipper state unfavorable.
In fact, RBCs at $\lambda = 5$ in simple shear flow do not exhibit tank-treading motion at all (9, 36). However, under
strong confinement, membrane tank-treading becomes possible, as we observe slippers in the diagram in Fig. 1, while
under weak confinement no slipper shapes should be expected. An interesting result for $\lambda = 5$ in comparison to $\lambda = 1$
in Ref. (4) is that the parachute region shifts toward higher confinements. This is counter-intuitive in view of the
argument that slippers should be suppressed at $\lambda = 5$. This result is consistent with 2D simulations for different
viscosity contrasts (5, 34), which showed that slippers have their mass located closer to the centerline than parachutes,
despite their position being slightly away from the channel center.

RBC shapes from microfluidic experiments.

For experiments, a microfluidic device depicted in Figs. 2A and 2B has been employed. The design generally followed
that previously described for real-time deformability cytometry (RT-DC) (37). Cells are focused by sheath flow before
entering a region where the flow is split into two outer branch flows and the channel flow, depicted in Fig. 2B. This
was necessary to decrease the flow rate inside the measurement channel to the desired range, because RT-DC is
usually used for the deformation of nucleated cells, which requires much larger flow velocities than employed here.
At the beginning of the measurement channel, cells have to pass a serpentine region, so that cells which enter far
off-center are forced to the channel center. We observed that cells entering off-center primarily end up as slippers.
This made it necessary to introduce the serpentine region to avoid that the way cells enter the channel influences the
final state in the channel. Influence of the position at the channel entrance on the final state inside, especially the
connection between starting off-center and ending up in a slipper shape, was recently described by Guckenberger et
al. (33).

Cells were observed roughly 4.5 mm downstream of the channel entrance (blue region in Fig. 2A) to guarantee that
cells have enough time to relax to a stable state, if there is one. Typical cell states observed are shown in Figs. 2C-I
and Movies S4-S10, and are divided into several classes. Figure 2C shows a nearly undeformed discocyte performing
a flipping rotation in flow, which corresponds to the tumbling cells from the simulations. Discocyte-shaped RBCs
also displayed a rolling motion or movement with a fixed inclination angle with respect to the flow axis, depicted in
Fig. 2D. These states, which preserve the biconcave disk-like shape, mostly occur at low flow rates.

Increasing flow rate leads to deformation of the cells. The first mode of deformation is a bulging out of the front
with a narrow tail at the rear of the cells, shown in Fig. 2E. Such cells usually have an off-center position and are
classified as slippers. The states described in Figs. 2D and 2E are summarized as tank-treading RBCs, as they
are similar to the tank-treading cells from the simulations, even though the membrane rotation cannot be directly
observed experimentally. Further increase of the flow rate may lead to parachutes. Parachutes observed in the
experiments were not always perfectly symmetrical. Therefore, a further distinction between asymmetrical (Fig. 2F)
and symmetrical parachutes (Fig. 2G) was made. Still, both classes were summarized as parachutes for comparison
with the simulations.

In wide enough channels at high flow rates, an additional state, a polylobe, was observed, which was not identified
in simulations. Polylobe cells display several lobes and can be clearly differentiated from the slipper and parachute
shapes. Polylobes exhibited a nearly solid tumbling motion without significant shape changes (Fig. 2H) or strong
shape changes which persisted during RBC passage (Fig. 2I). Polylobe shapes were observed at high shear rates in
simple shear flow both experimentally and numerically (9, 36).

In experiments, multiple RBC states are always observed for a fixed flow condition for different cells. Therefore,
experiments provide shape probability distributions for different ranges of cell velocities and confinements, as shown
in Fig. 3A for channels with $\chi = 0.44 - 0.46$ and $\chi = 0.65 - 0.68$. Confinements χ were estimated by dividing the
effective cell diameter $D_r =$ 6.56 μm by the hydraulic diameter of the channel cross section. Cell velocities were binned
in ranges of 0.25 mm/s from 0 to 4 mm/s. Each data point is the weighted average probability of the measurements
performed for the respective range of hydraulic diameters, see Materials and Methods for more details. The shape
probability distributions in Fig. 3A clearly show that low confinement and cell velocities correspond primarily to
tumbling RBCs. With increasing confinement, tank-treading becomes dominant at low velocities and parachutes
take over with increasing velocity. The probability for polylobes increases with velocity as well, but is only relevant
for large channel sizes. The shape probability distributions for all investigated channel sizes and a state diagram
considering all subclasses introduced above can be found in Figs. S1-S3.

Comparison between experiments and simulations.

Experimental data were assembled into a state diagram shown in Fig. 3B as a function of RBC velocity and the confinement, similarly to the simulated diagram in Fig. 1. The experimental diagram in Fig. 3B was constructed assuming the most probable shape. The saturation of the color indicates the probability for this state. The dashed lines represent the state boundaries from the simulations; the lower line corresponds to the limit between tumbling and tank-treading, while the upper line shows the boundary for tank-treading to parachute. The experimental diagram clearly shows that there are no sharp transitions between different states, as the probability to find the predominant state fades away the closer the state boundary is approached.

Qualitatively, experimental and simulation diagrams are very similar. For low confinements and small cell velocities, tumbling is the most likely state. With increasing velocity and confinement, tank-treading becomes more apparent, and for high confinements and high velocities, parachutes dominate.

However, there are several noticeable differences. For instance, the band, where tank-treading occurs, is narrower for the simulations in comparison to the experimental data. The differences in the state boundaries are likely due to different channel geometries and the variability in cell properties (e.g. size, bending rigidity, shear elasticity). Microfluidic channels in experiments did not have a perfect square geometry employed in simulations due to fabrication limitations, see Fig. S4 and Table S3. Furthermore, real RBCs are clearly not identical to each other and possess an appreciable variability in their size and mechanical properties, which will be discussed later. Another difference between the two diagrams is the existence of a polylobe region in experiments, which is absent in simulations. A possible reason is a difference in viscosity contrasts λ. In simulations, a physiological viscosity contrast of $\lambda = 5$ was targeted, while experiments likely have $\lambda \approx 10$ because the viscosity of blood plasma is about twice larger than the viscosity of PBS used as a solvent. In pure shear flow, a high viscosity contrast prohibits tank-treading motion of vesicles (38, 39) and RBCs (9, 36).

Finally, it is worthwhile to mention that a small fraction of cells showed state changes within the region of observation. For instance, some RBCs entering the observation region as slippers or parachutes left it as a tumbling polylobe (see Movie S11). Similarly, RBCs entering as polylobes obtained a stable position in the channel and switched to a slipper or parachute within the observation window (see Movie S12). These examples suggest that there might be ranges of flow conditions and RBC mechanical properties, where two different states are quasi-stable and can interchange. Another possibility is that small perturbations in the flow due to geometrical irregularities of the channel trigger a state change. Interestingly, such state changes are mainly observed for channel sizes and flow rates close to the transitions between different shape and dynamics states.

Approximation of RBC variability.

Despite the good agreement between simulation and experimental diagrams in Fig. 3, the main dissimilarity is the existence of multiple RBC states for fixed flow conditions in experiments, while simulations generally yield a single state for fixed conditions. We attribute this result to the variability in mechanical properties of RBCs. Here, different RBC sizes (roughly within $6.5 - 9\,\mu\text{m}$), RBC shear elasticities ($\mu \in [2, 10]\,\mu\text{N/m}$) as well as cytosol and membrane viscosities may affect the observed state.

To investigate this proposition, we construct an empirical distribution for the variability of RBC properties and use it to estimate the frequency of appearance of different RBC states for fixed flow conditions. Since we have not investigated numerically the dependence of RBC behavior on the cytosol and membrane viscosities, the effect of their variability cannot be studied here. Furthermore, we focus only on the variability in membrane shear elasticity and omit any variations in RBC size, so that a one dimensional distribution is considered. Fig. 4A shows a sample distribution of RBC shear elasticity. It is constructed by assuming a Gaussian distribution for the shear modulus of young RBCs with a variance σ and by including the effect of membrane stiffening during the lifetime of RBCs. The distribution in Fig. 4A assumes an average shear modulus of young RBCs $\mu_{\text{young}} = 5.5\,\mu\text{N/m}$ with $\sigma = 2\,\mu\text{N/m}$ and an average shear modulus of old RBCs $\mu_{\text{old}} = 6\,\mu\text{N/m}$ (40, 41).

In Fig. 1, the simulation data are plotted as a function of average shear rate $\bar{\dot{\gamma}}$ scaled by a characteristic relaxation time τ based on the membrane bending rigidity κ_r. This choice of τ was made to facilitate a better comparison of the obtained shape and dynamics diagram with that for $\lambda = 1$ in Ref. (4). Alternatively, the average shear rate $\bar{\dot{\gamma}}$ can be normalized by $\tau_\mu = \eta_o D_r/\mu_r$, and the ratio $\tau/\tau_\mu \approx \Gamma/4$ simply corresponds to the average Föppl-von Kármán number $\Gamma \approx 2700$ for a healthy RBC. Therefore, the non-dimensional shear rate can be considered to be a linear function of shear modulus in the regime of linear membrane deformation. In turn, the flow rate (or equivalently cell velocity) can be interchanged with the shear modulus (i.e. a slow flow and soft cells are equivalent to a fast flow and stiff cells or $v \sim \bar{\dot{\gamma}} \sim 1/\mu_r$) within the linear regime of deformation. In this way, we can superimpose the proposed elasticity distribution in terms of μ_r onto the experimental state diagram in Fig. 3B for different cell velocities v, in order to obtain an estimation how the variability in RBC elasticity would result in the distribution of different RBC

states for fixed flow conditions.

Predicted state distributions in comparison to those measured experimentally are shown in Figs. 4*B* and 4*C* for two channel sizes as a function of cell velocity. They show very good qualitative agreement, indicating that this is the primary reason for the observation of multiple RBC states in experiments for fixed flow conditions. Clearly, the main limitation of the predicted distributions is that they are based only on the variation in membrane shear modulus and do not consider other possible differences between RBCs. In general, variations in RBC properties should be represented by a multidimensional distribution, which can be superimposed onto a multidimensional state diagram with axes representing different RBC properties.

Discussion

Even though a number of previous experimental studies (27–31, 33) have demonstrated the existence of different RBC states (e.g. parachutes, slippers), our experimental investigation is the first where different RBC states are systematically mapped into a diagram as a function of channel size and flow rate. This was possible due to a large number of experimental observations, as more than 35 000 cells were processed. In addition, present experiments directly demonstrate the existence of new RBC states in Poiseuille flow, such as tumbling and polylobe, not observed previously in microfluidic channels. Tumbling discocytes have been predicted in simulations (4) and now confirmed experimentally, even though such dynamics is not very intuitive, as RBCs tumble in Poiseuille flow in channels with sizes comparable to the RBC diameter. Simulations show that a tumbling cell assumes an off-center position, which results in asymmetrical shear stresses rotating the cell. Furthermore, RBC tumbling occurs at relatively low flow rates, at which fluid stresses are too weak to deform the RBC into a parachute or slipper. In the experiments, the cells at low flow rates may take up an off-center position due to sedimentation within the channel. At high flow rates, experimental observations demonstrate the existence of polylobe shapes, observed recently in pure shear flow (9, 36), also in channels wider than about 13 μm.

In addition to the RBC state diagram, our microfluidic experiments show that there is no single state for fixed flow conditions, but rather a distribution of different cell states for each flow rate. In contrast, simulations yield primarily a single RBC state for a fixed confinement and flow rate. This result can be clearly attributed to the variability in RBC properties, which is inherently present in RBC samples. A simplified approximation for the variability in RBC shear elasticity demonstrates a good correspondence between experimentally observed distributions and those obtained by the superposition of the proposed variability distribution onto the state diagram. This reveals the complexity in real blood samples, especially if quantitative predictions of cells' mechanical properties are aimed for. In addition to the variation in shear elasticity, variability in cell size, membrane bending rigidity, and cytosol and membrane viscosities are likely to have an effect on measured distributions of RBC states. To take these parameters into consideration, a detailed understanding of the effect of these properties on the RBC state diagram is required.

The good agreement between the simulated and experimental diagrams in Fig. 3 allows us to make a step toward the quantification of experimental observations. Reliable simulation data can be used to determine mechanical properties of flowing RBCs. As an example, for a fixed flow rate, the fraction of RBCs whose shear modulus is smaller/larger than a particular value can be determined by a state boundary between different RBC states. Thus, by carefully selecting flow rate and cell confinement (or channel size), specific values of RBC shear elasticity can be targeted and softer/stiffer cells can be differentiated through the observation of their shapes and dynamics in channel flow. This can be useful in blood analysis, since RBC deformability might be altered in many blood related diseases and disorders, such as malaria, sickle-cell anemia, diabetes, etc. (13, 14, 21).

Data presented in Fig. 3 also exhibit appreciable differences between simulations and experiments. The differences in state boundaries likely come from the different channel geometries (a square channel in simulations and a trapezoidal channel in experiments) and the variability in cell properties. Another difference is that tumbling RBCs and slippers generally display more deformation in simulations than in experiments. Also, experiments demonstrated the existence of polylobe shapes, which have not been observed in simulations. These discrepancies indicate that further improvements/ additions might be needed for the simulation model to fully capture experimental observations. A recent simulation study (33) suggests that RBCs might have bistable states in a channel under certain conditions determined by flow velocity and the cells' initial position in the channel. In our experiments, the initial position and orientation of RBCs as they enter the channel have some variability and cannot be precisely controlled. Considering the results from Ref. (33), it can be expected that the probability to find tank-treading cells in the experiment would decrease if all cells would start at a perfectly centered position. Another limitation of experiments is that the observations are made within a window of about 435 μm in length, which cells pass relatively fast. The performed simulations indicate that the full period of cell dynamics (e.g. when the membrane of a tank-treading cell performed half of its full rotation) is often about several times longer than the observation times in experiments. This means that

Fluid parameters	Scaled units
p_0	$1.5 \times 10^4 \ \frac{k_B T}{r_c^3}$
b	$1.49 \times 10^4 \ \frac{k_B T}{r_c^3}$
η_o	$80 - 365 \ \frac{\sqrt{m k_B T}}{r_c^2}$
n	$12 \ r_c^{-3}$

Table 1. SDPD fluid parameters in simulation units. Mass and length for SDPD fluid are measured in units of the fluid particle mass m and the cutoff radius r_c. p_0 and b are parameters for the pressure equation, η is the fluid's dynamic viscosity, and n is the number density. In all simulations, we have set $m = 1$, $r_c = 1.0$, and the thermal energy $k_B T = 0.1$.

only a portion of cell dynamics is directly monitored for every single cell, which prevents the complete elimination of the existence of dynamic deformations observed for tumbling RBCs and slippers in simulations.

Conclusions

In summary, our combined simulation and experimental investigation of RBC shapes and dynamics in microchannels provides a consistent RBC state diagram and illustrates the complexity of RBC behavior in microflow. The simulation results agree well with experimental observations, allow the characterization of RBC variability in shear elasticity, and permit us to make a significant step toward quantitative measurements of RBC mechanical properties. These results are expected to encourage further numerical and microfluidic investigations of RBC behavior in microchannels or microvessels in order to better understand how various properties of RBCs affect their behavior in microflow and to advance toward reliable and fast detection of changes in RBC deformability relevant in many blood diseases and disorders.

Materials and Methods

Mesoscale simulations.

To model fluid flow, we use the smoothed dissipative particle dynamics (SDPD) method (42) with angular momentum conservation (43) implemented by our group within the LAMMPS package (44). SDPD is a particle-based hydrodynamic technique employed to model the flow both RBC cytosol and suspending medium. SDPD allows a direct input of fluid transport properties such as viscosity and of the equation of state for pressure, permitting a flexible control of fluid compressibility (45).

The SDPD fluid parameters are given in Table 1. Here, p_0 and b are parameters of the equation of state $p = p_0(\rho/\rho_0)^\alpha - b$, where ρ is the instantaneous particle density, $\alpha = 7$, and $\rho_0 = n$ with n being fluid's number density. Relatively large values of p_0 and α provide a good approximation of fluid incompressibility, since the speed of sound c for this equation of state is $c^2 = p_0 \alpha/\rho_0$.

To span a wide range of flow rates, different values of fluid viscosities $\eta_o \in [80; 365] \ \sqrt{m k_B T}/r_c^2$ were employed in simulations (m is the fluid's particle mass). Since the fluid viscosity modifies linearly the RBC relaxation time scale τ, large values of viscosity were used to model high flow rates in order to keep the Reynolds number $Re = \bar{\dot{\gamma}} D_r^2 n/\eta_o$ in simulations sufficiently low. Thus, in all simulations, $Re = 0.2$ was fixed, while η_o was computed for a desired flow rate $Q = \bar{\dot{\gamma}} D^3$.

RBC model.

RBC membrane is modeled as a triangulated network of springs, incorporating stretching, bending, and area-compression resistance (46, 47). The membrane is made of $N = 3000$ vertices. The model also contains area- and volume-conservation constraints to mimic incompressibility of the lipid bilayer and cell's cytosol. Table 2 summarizes the parameters for the RBC model in units of D_r and the thermal energy $k_B T$, and the corresponding average values for a healthy RBC in physical units. To relate simulation parameters to the physical properties of RBCs, we need a basic length and energy scales, while a relation for time scale is based on the characteristic RBC relaxation time τ. The membrane constitutes an impenetrable surface, which is modeled by bounce-back reflections of both cytosol and suspending-medium particles from inside and outside the membrane, respectively (46). Coupling between the RBC membrane and SDPD fluids is implemented through dissipative (friction) forces (46).

Simulation setup.

A single RBC is suspended into a viscous fluid inside a square channel with a side length D. The length of the channel is $L = 10 D_r$ in all cases. Periodic boundary conditions are assumed in the flow direction. The channel walls are modeled by frozen particles which assume the same structure as the fluid, while the wall thickness is equal to r_c. To prevent wall penetration, fluid particles as well as vertices of a RBC are subject to bounce-back reflection at the fluid-solid interface. To ensure that

RBC parameters	scaled units	physical units
A_r		135×10^{-12} m^2
D_r	$\sqrt{A_r/\pi}$	6.56×10^{-6} m
V_r	$0.33\, D_r^3$	93×10^{-18} m^3
T		310 K
Y_r	$1.9 \times 10^5\, \frac{k_B T}{D_r^2}$	18.9×10^{-6} N/m
κ_r	$70\, k_B T$	3×10^{-19} J
k_d	$4.2 \times 10^4\, \frac{k_B T}{D_r^2}$	4.3×10^{-6} N/m
k_a	$2.1 \times 10^6\, \frac{k_B T}{D_r^2}$	2.1×10^{-4} N/m
k_v	$1.4 \times 10^7\, \frac{k_B T}{D_r^3}$	220 N/m^2

Table 2. RBC parameters in units of the effective RBC diameter D_r and the thermal energy $k_B T$, and the corresponding average values for a healthy RBC in physical units. A_r is the RBC membrane area, V_r is the RBC volume, T is the temperature, Y_r is the membrane Young's modulus, κ_r is the membrane bending rigidity, and k_d, k_a, and k_v are the local area, global area, and volume constraint coefficients, respectively ([46], [47]). In all simulations, we have chosen $A_r = 135$ and $k_B T = 0.1$, which implies that $D_r = 6.56$.

no-slip boundary conditions are strictly satisfied at the walls, we also add a tangential adaptive shear force ([48]) which acts on the fluid particles in a near-wall layer of a thickness r_c. The ratio of cytosol viscosity to that of suspending fluid is $\lambda = 5$. The flow is driven by a force f applied to each fluid particle (both cytosol and external fluid), mimicking a pressure gradient $\Delta P/L = fn$, where ΔP is the pressure drop.

Blood samples.

Blood was taken after informed consent from healthy donors by finger pricking with a lancet (Sarstedt Safety-Lancet Normal 21, Nürmbrecht). The study was approved by the Institutional Review Board of the University Medical Center Carl Gustav Carus at the Technische Universität Dresden (EK89032013, EK458102015). $0.5 - 1.5\,\mu$l of whole blood was pipetted and suspended into 0.5 ml of PBS. The osmolarity of the PBS was determined by an osmometer (The Fiske Micro-Osmometer Model 210, Norwood MA) at every measurement day and was found in the range of (313 ± 4) mOsm/kg (mean $\pm$ SD). Experimental measurements were performed at 24 °C within 30 minutes after blood drawing.

Experimental setup.

The experimental setup is similar to that previously described for real-time deformability cytometry (RT-DC) ([37]). Briefly, an Axiovert 200M (Zeiss, Oberkochen) inverted microscope was equipped with an EC Plan-NEOFLUAR 40x/0.75 objective (Zeiss, Oberkochen). To record the images, a MCI1362 CMOS camera (Mikrotron, Unterschleissheim) was connected to the microscope. The camera was controlled by the analysis software Shapeln (Zellmechanik Dresden, Dresden), which enables online cell tracking. The microscope was equipped with a custom-built illumination source using a high power blue LED ([37]). The LED was synchronized with the camera shutter for an exposure time of 2 µs. Flow in the microfluidic-chip was initiated and controlled by a syringe pump (Cetoni neMESYS, Korbussen), which was connected to the chip with FEP-tubing. The flow rate of the cell suspension was controlled by a computer program provided by the manufacturer. For a series of experiments using a particular channel size, the range of flow rates was set such that the motion of cells with velocities between 0.1 mm/s and 4 mm/s could be observed.

Before starting experiments, the device was first filled with PBS from the sheath inlet at a flow rate of 1 µl/s. The chip was considered filled when the fluid reached the top of the sample inlet hole and the flow rate was then lowered to 0.1 µl/s. This procedure prevents bubble formation when connecting the sample inlet tubing later. After connecting the sample tubing, the chip was filled with the RBC-suspension at 0.1 µl/s from the sample tubing. When cells were observed flowing through the chip, the flow rate was lowered to 0.001 µl/s for both sample and sheath flow and after 6 minutes waiting time for flow equilibration, cells were recorded. The online-tracking software developed for RT-DC ([37]) has been used to analyze and save images of RBCs. No continuous videos were recorded, in order to avoid numerous frames with an empty channel (no RBCs present). The software automatically stores and generates data about the position of a cell in the channel for each frame and other useful parameters such as size and aspect ratio.

Experimental procedure.

Diluted blood suspension (2 µl whole blood in 0.5 ml PBS) was flowed into the sample inlet, while the sheath inlet was fed with PBS. Starting from a sheath flow of 0.002 µl/s, the flow rate was incrementally increased by 0.002 µl/s up to a final total flow rate of 0.04 µl/s. The sheath to sample flow ratio was kept 3 : 1 for all measurements.

Recording was done at a frame rate of 100 Hz for flow rates smaller than 0.006 µl/s, 500 Hz for the range of 0.006 µl/s - 0.02 µl/s, and 900 Hz for flow rates larger than 0.02 µl/s. For each flow rate about 50 cells were recorded. For post analysis, the videos of the cells were separated in sections that contained the passage of only one cell, from which the mean velocity and shape classification were determined.

Layout of the microfluidic chip.

The syringe pump and the microfluidic chip layout typically used in RT-DC did not permit to achieve flow velocities small enough to observe non-deformed cells. Therefore, the channel system in Fig. 1A was designed to reduce the flow rate inside the measurement channel. Thus, the incoming total flow was split into three branches, where the main portion of the flow was diverted away into two outer branches and only a small fraction flows through the measurement channel. The widths of measurement channels and outer branches are given in Table S1. To increase the number of cells that reach the measurement channel, the cells were focused by a sheath flow before entering the region where the flow was split. The chip design from the inlets until the focusing channel was identical to that used for RT-DC (37). The cells that enter the measurement channel pass a serpentine region, which was introduced to prevent them from adhesion at the channel wall (see Movies S13, S14). The measurement channel has a total length of 5.35 mm and measurements were performed approximately 4.5 mm after the entrance over a length of 435 μm. This channel length was chosen to give the cells enough time to obtain a stable state. The devices were designed with the free software KLayout (49).

Device fabrication.

Microfluidic chips were made from PDMS for every experiment using standard soft lithography techniques and sealed with a glass cover slip after plasma surface activation. The aim was to achieve square cross sections with varying channel sizes. For this, it was necessary to produce a master on a silicon-wafer for every intended channel width. For the fabrication of the masters, first the silicon wafer was spin-coated with the photoresist AZ15nxT (The MicroChemicals GmbH, Ulm). A first spinning step of 10 s at 500 rpm (acceleration of 100 rpm/s) spreads the photoresist over the whole wafer. Then, the spinning frequency was increased in a second spinning step (acceleration of 300 rpm/s) to get a coating of the silicon with a thickness that equals the desired channel height on the finished chips. The frequency of the second spinning step for each wafer is given in Table S2.

After the wafers were coated, they were soft-baked for 5 minutes at 110 °C. In the next step, the coated wafer was exposed to UV-light (400 nm) with the photomask on top in contact mode, with an exposure power of 450 J/s. Then, the wafer was post-baked at 120 °C for 2 minutes to enhance cross-linking of the activated part of the photo-resist and the wafer. In a final step, the wafers were developed in a mixture of AZ400K developer (The MicroChemicals GmbH, Ulm) and water (1:2) for approximately 100 seconds. The developer dissolved the photo resist that was not activated. Finally, a hydrophobic coating (1H,1H,2H,2H-perfluorooctyl-trichlorosolane vapor (abcr, Germany)) was deposited onto the wafer under vacuum.

Even though microfluidic channels were designed to have a square cross-section, the fabrication of perfectly squared channels is difficult for such small systems. Therefore, channel sizes were characterized by a hydraulic diameter $D_h = 4A/P$, where A is the channel's cross-sectional area and P is the perimeter. The top width and the channel height were measured using a profilometer on the silicon wafers, which are used as masters in the production of the PDMS-microfluidic chips. The bottom width of the channel was measured with an inverted microscope by focusing on the bonding site of the PDMS and cover-glass. The width was then determined using a customized software. Because top and bottom widths of the channels did not always match, the cross-section was assumed as a symmetric trapezoid (see Fig. S4). The dimensions of all the channels used in the experiments can be found in Table S3.

Data analysis.

Each data point in probability distributions in Fig. 3A and 4B,C corresponds to a weighted average probability of the measurements performed for the respective range of hydraulic diameters. For calculation of the average, every value was weighted by the number of cells N_i that were observed in the respective experiment i. Thus, experiments with a higher cell count have a higher weight $w_i = N_i / \sum_j N_j$. The weighted averages $\bar{x}$ and corresponding standard deviations σ were calculated as $\bar{x} = \sum_i w_i x_i$ and $\sigma^2 = \sum_i w_i (x_i - \bar{x})^2$. Here, x_i is the probability of a RBC state in the respective velocity range in experiment i. The error bars represent the weighted error for the set of data points.

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Fig. 1. State diagram of RBC shapes and dynamics from simulations. Different shapes and dynamics of RBCs in square-channel flow for a wide range of confinements χ and non-dimensional shear rates $\dot{\gamma}^*$. The RBC model represents average properties of a healthy RBC with $Y_r = 18.9 \times 10^{-6}$ N/m, $\mu_r = 4.8 \times 10^{-6}$ N/m, $\kappa_r = 3 \times 10^{-19}$ J, and $\lambda = \eta_i/\eta_o = 5$. The symbols correspond to separate simulations with different RBC states: parachute (cyan circle), tank-treading (green square), and tumbling (magenta diamond) cells. On the top, several representative shapes in flow are shown, see Movies S1-S3. Note that the state-boundary lines are drawn schematically to guide the eye.

Fig. 2. Microfluidic chip design and observed RBC states. (*A*) Complete layout of the channel system. Inlet i₁ is for sheath flow, the sample inlet i₂ supplies the blood cells and the w denotes the waste outlet. The region within the red rectangle is shown in more detail in *B*. The blue rectangle highlights the measurement region. (*B*) Section of the channel layout (marked by red rectangle in *A*) where the total flow Q_i is separated into channel flow Q_c and outer branch flow Q_o. The arrow direction corresponds to the flow direction and the arrow width qualitatively represents the flow rate at a given point (not to scale). The serpentines at the channel entrance are necessary to center cells and avoid their attachment to the channel wall. (*C-I*) Examples of observed cell states in the measurement region. Images were created by minimum intensity projection from images of the same cell during channel passage. The scale bar in *C* is 10 μm and applies to all images. The colored rectangles highlight the classes these cells are assigned to (see Figs. 1 and 3). (*C*) Tumbling cell with $v = 0.146$ mm/s, 75 ms between images. (*D*) Discocyte with a constant inclination angle at $v = 0.963$ mm/s, 15 ms between images. (*E*) Slipper at $v = 0.951$ mm/s, 20 ms between images. Cells as in *D* and *E* are classified as a tank-treading state. (*F*) Non-symmetrical parachute with $v = 2.207$ mm/s, 10 ms between images. (*G*) Symmetrical parachute at $v = 4.066$ mm/s, 5 ms between images. Cells as in *F* and *G* are classified as parachutes. (*H*) Tumbling polylobe at $v = 3.378$ mm/s, 5 ms between images. (*I*) Shape changing polylobe at $v = 3.140$ mm/s, 5 ms between images. Cells as in *H* and *I* are classified as polylobes.

Fig. 3. Experimental distribution of RBC states and comparison with simulation. (A) Velocity dependent probability distribution of shapes for the smallest ($\chi = 0.44$ - 0.46) and largest ($\chi = 0.65$ - 0.68) confinements from the experiments. The background shade highlights the shape with the highest probability in the corresponding velocity range. (B) State diagram of experimentally observed RBC states. The colors indicate the state with the highest probability within the corresponding confinement and velocity range. The saturation of the colors correlates with the probability to find the state. The dashed lines mark the state boundaries from the simulations; lower: tumbling to tank-treading, upper: tank-treading to parachute. The numbers above the graph show the number of cells that were classified for this range of confinements.

Fig. 4. Characterization of RBC variability. (*A*) Distribution of the stiffness (shear modulus) of RBCs over their lifetime. (*B,C*) Comparison of the probabilities from experiment and approximation of RBC variability for different RBC states using the assumed distribution for *B)* χ = 0.58 - 0.61 and *C)* χ = 0.46 - 0.48. Left: experiment, right: theory. The numbers above the graph show the number of cells that were classified for this range of velocities.