Violating the normality assumption may be the lesser of two evils

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1 Abstract

- 2 **1.** Researchers are often uncertain about the extent to which it may be acceptable to violate the
- 3 assumption of normality of errors, which underlies the most-frequently used tests for statistical
- 4 significance (regression, *t*-test, ANOVA, and linear mixed models with Gaussian error).
- 5 2. Here we use Monte Carlo simulations to show that such Gaussian models are remarkably robust to
- 6 even the most dramatic deviations from normality.
- 7 3. We find that *P*-values are generally reliable if either the dependent variable *Y* or the predictor *X* are
- 8 normally distributed and that bias only occurs if both are heavily skewed (resulting in outliers in both
- 9 X and Y). In the latter case, judgement of significance at an α -level of 0.05 is still safe unless sample
- 10 size is very small. Yet, with more stringent significance criteria as is used when conducting numerous
- 11 tests (e.g. $\alpha = 0.0001$) there is a greater risk of making erroneous judgements.
- 12 4. Generally we conclude that violating the normality assumption appears to be the lesser of two evils,
- 13 when compared to alternative solutions that are either unable to account for levels of non-
- 14 independence in the data (most non-parametric tests) or much less robust (e.g. Poisson models which
- 15 require control of overdispersion and sophisticated resampling). We argue that the latter may pose a
- 16 more substantial threat to the reliability of research findings when pragmatically acknowledging that,
- 17 in the majority of publications, statistical expertise is limited.
- 18

19 Introduction

In the biological, medical and social sciences, the validity of research findings is generally assessed via statistical significance tests. Valid significance tests ensure the trustworthiness of scientific results and should reduce the amount of random noise entering the scientific literature. Brunner and Austin (2009) even regard this as the "primary function of statistical hypothesis testing in the discourse of science". A *P*-value of < 0.05 is usually accepted as sufficiently low for rejecting the null hypothesis. However, the validity of parametric significance tests depends on the whether model assumptions are violated.

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28	In a growing body of literature, researchers express their concerns about irreproducible results (Open
29	Science Collaboration 2015; Ebersole et al. 2016; Camerer et al. 2018; Silberzahn et al. 2018) and it
30	has been argued that the inappropriate use of statistics is a leading cause of irreproducible results
31	(Forstmeier, Wagenmakers & Parker 2017). Yet researchers may often be uncertain about which
32	statistical practices can be considered as safe and which are prone to yield overconfident conclusions.
33	Searching the literature, we found relatively little pragmatic advice (Box & Watson 1962; Mardia
34	1971; Lumley et al. 2002; Gelman & Hill 2007; O'Hara 2009; Zuur, Ieno & Elphick 2010) on the
35	question of whether and when it may be safe to violate the assumption of normality of errors, which
36	underlies the most commonly used tests for statistical significance (linear models "lm" and linear
37	mixed models "lmm" with Gaussian error, which includes the often more widely known techniques of
38	regression, t-test, and ANOVA). How much deviation is tolerable under which circumstances (in
39	terms of sample size and α -threshold)?
40	
41	We here use Monte Carlo simulations to explore how violations of the normality assumption affect
42	the probability of drawing false-positive conclusions (the rate of type I errors), because these are the
43	greatest concern in the current reliability crisis (Open Science Collaboration 2015). We aim at
44	deriving simple rules of thumb, which researchers can use to judge whether the violation may be
45	tolerable and whether the P-value can be trusted. Furthermore, we provide an R package
46	("TrustGauss") that researchers can use to explore the effect of specific distributions on the reliability
47	of <i>P</i> -values. Counter to intuition, we find that violations are rarely problematic, and we argue that the
48	commonly recommended solutions to the problem (e.g. using non-parametric tests, generalized linear
49	models) may represent a greater threat to the reliability of conclusions because of their lower
50	flexibility or robustness.
51	
52	The linear regression model and its assumptions

53 At this point we need to briefly introduce the notation for the model of least squares linear regression.

54 In its simplest form, it can be formulated as $Y_i = a + b \times X_i + e_i$, where each element of the dependent

variable Y_i is linearly related to the predictor X_i through the regression coefficient b (slope) and the

56	intercept a. e_i is the error or residual term, which describes the deviations of the actual from the true
57	unobserved (error) or the predicted (residual) Y_i and whose sum equals zero (Sokal & Rohlf 1995;
58	Gelman & Hill 2007). An F-test is usually employed for testing the significance of regression models
59	(Ali & Sharma 1996).
60	
61	Basic statistics texts introduce (about) five assumptions that need to be met for interpreting all
62	estimates from linear regression models safely (validity, independence, linearity, homoscedasticity
63	and normality; Gelman & Hill 2007). Recall that these criteria are concerned with the dependent
64	variable Y , or — to be more precise — the regression error e . The predictor X is usually not
65	considered. We refrain from revisiting all criteria in detail, but want to specifically focus on the
66	normality assumption here, which is usually tested via inspecting the distribution of the dependent
67	variable or of the residuals (Zuur, Ieno & Elphick 2010). Both visual approaches (probability or QQ-
68	plots) and formal statistical tests (Shapiro-Wilk) are commonly applied. Formal tests for normality
69	have been criticized because they have low power at small sample sizes and almost always yield
70	significant deviations from normality at large sample sizes (Ghasemi & Zahediasl 2012). Thus,
71	researchers are left with their intuition to decide how severely the normality assumption is violated
72	and how robust regression is to such violations.
73	
74	Normally distributed errors are generally assumed to be the least important (yet probably the most
75	widely known) out of the five regression assumptions (Gelman & Hill 2007). Deviations from
76	normality do not bias regression coefficients (Williams, Grajales & Kurkiewicz 2013) and usually do
77	not impair hypothesis testing (no inflated type I error rate, e.g. Bishara & Hittner 2012; Puth,
78	Neuhauser & Ruxton 2014; Ives 2015; Szöcs & Schäfer 2015; Warton et al. 2016) even at relatively
79	small sample sizes, and with large sample sizes ≥ 500 the Central Limit Theorem guarantees that the
80	test statistic is on average normally distributed (Lumley et al. 2002). Importantly, the robustness of
81	regression methods to deviations from normality of the regression errors e does not only depend on
82	sample size, but also on the distribution of the predictor X (Box & Watson 1962; Mardia 1971).

83

84 Simulations to assess effects on *P*-values

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85	To illustrate the consequences of violating the normality assumption, we performed Monte Carlo
86	simulations on five continuous and five discrete datasets that were severely skewed, platy- and
87	leptokurtic or zero-inflated (distributions D0-D9; Figure 1A left column), going beyond previous
88	studies that examined less dramatic violations (Bishara & Hittner 2012; Puth, Neuhauser & Ruxton
89	2014; Ives 2015; Szöcs & Schäfer 2015; Warton et al. 2016). We explored these 10 distributions
90	across a range of sample sizes ($N = 10, 25, 50, 100, 250, 500, 1000$). Starting with the normal
91	distribution D0 for reference, we sorted the remaining distributions D1–D9 by increasing tendency to
92	produce strong outliers (calculated as the average distance of the maximum or minimum from the
93	sample mean relative to the standard deviation of the sample for the case of $N = 100$). We used these
94	data both as our dependent variable Y and as our predictor variable X in linear regression models,
95	yielding $10 \times 10 = 100$ combinations of <i>Y</i> and <i>X</i> for each sample size (see Figure S1 for distributions
96	of the independent variable <i>Y</i> , the predictor <i>X</i> , and residuals).
97	
98	We assessed the significance of the models via an <i>F</i> -test wherever possible and used a likelihood ratio
99	test otherwise. We fitted these models to 50,000 datasets for each combination of the dependent and
100	predictor variable. We did not simulate any effect, which means that both the regression coefficient b
101	and the intercept a were on average zero. This enabled us to use the frequency of all models that
102	yielded a <i>P</i> -value ≤ 0.05 as an estimate of the type I error rate at an α -level of 0.05. The null
103	distribution of <i>P</i> -values is uniform on the interval [0,1] and because all <i>P</i> -values are independent and
104	identically distributed, we constructed confidence intervals using a beta-distribution (cf. Casella &
105	Berger 2002; QQ-plots of expected vs observed <i>P</i> -values are depicted in Figure S1). We assessed the
106	deviation of observed from expected $-\log_{10}(P-\text{value})$ at an expected value of 3 ($P = 10^{-3}$) and 4 ($P =$
107	10 ⁻⁴) and by estimating the scale shift parameter $v = \sigma_{observed} / \sigma_{expected}$ (Lin 1989), where σ is the
108	variance in $-\log_{10}(P$ -value).
100	
109	

110 Since some of the predictor variables were binary rather than continuous, our regression models also

111 comprise the situation of classical two-sample *t*-tests, and we assume that the results would also

112 generalize to the situation of multiple predictor levels (ANOVA), which can be decomposed to 113 multiple binary predictors. To demonstrate that our conclusions from univariate models (involving a 114 single predictor) generalize to the multivariate case (involving several predictors), we fitted the above 115 models with a sample size of N = 100 to the same 10 dependent variables with three normally 116 distributed predictors and one additional predictor sampled from the 10 different distributions. We 117 further fitted the above models as mixed-effects models using the lme4 R package (v 1.1-14; Bates et 118 al. 2015). For that we simulated N = 100 independent samples each of which was sampled twice, such 119 that the single random effect "sample ID" explained roughly 30% of the variation in Y. We encourage 120 readers to try their own simulations using our R package "TrustGauss". 121 122 Results 123 The rate at which linear regression models with Gaussian error structure produced false-positive 124 results (type I errors) was very close to the expected value of 0.05 (Figure 1B). When sample size 125 was high (N = 1000), type I error rates ranged only between 0.044 and 0.052, across the 100 126 combinations of distributions of the dependent variable Y and the predictor X. Hence, despite of even 127 the most dramatic violations of the normality assumption (see e.g. distributions D4 and D9 in Figure

128 **1A**), there was no increased risk of obtaining false-positive results. At N = 100, the range was still

remarkably narrow (0.037–0.058), and only for very low sample sizes (N = 10) we observed 4 out of

130 100 combinations which yielded notably elevated type I error rates in the range of 0.086 to 0.11.

131 These four cases all involved combinations of the distributions D4 and D9, which yield extreme

outliers. For this low sample size of N = 10, there were also cases where type I error rates were clearly too low (down to 0.015, involving distributions D1–D3 where extreme values are rarer than under the normal distribution D0; for details see **Table S1**).

135

136 Next we examine the scale shift parameter (Figure 1C) which evaluates the match between observed

137 and expected *P*-values across the entire range of *P*-values (not only the fraction at the 5% cut-off).

138 Whenever either the dependent variable *Y* or the predictor *X* was normally distributed, the observed

and expected *P*-values corresponded very well (first row and first column in Figure 1C).

140 Accordingly, the P-values fell within the 95% confidence bands across their entire range (rightmost 141 column in Figures S1). This observation was unaffected by sample size (Table S2). However, if both 142 the dependent variable Y and the predictor X were heavily skewed, consistently inflated P-values 143 outside the confidence bands occurred, yet this was almost exclusively limited to the case of N = 10144 (Figure 1C). For larger sample sizes only the most extreme distribution D9 produced somewhat 145 unreliable *P*-values (Figure 1C). This latter effect of unreliable (mostly anti-conservative) *P*-values 146 was most pronounced when judgements were made at a very strict α -level (Figure 1D $\alpha = 0.001$ and 147 **Figure 1E** $\alpha = 0.0001$). At a sample size of N = 100, and for $\alpha = 0.001$, observed $-\log_{10}(P$ -values) 148 were biased maximally 3.36-fold when both X and Y were sampled from distribution D9. This means that *P*-values of about $P = 10^{-10}$ occurred at a rate of 0.001 ($P = 10^{(-3 \times 3.36)} = 10^{-10.08}$; Figure 1D). At N 149 150 = 100, and for α = 0.0001, the bias was maximally 4.54-fold (**Figure 1E**). Our multivariate and 151 mixed-model simulations confirmed that these patterns are general and also apply to models with 152 multiple predictor variables (Figure S3) and to models with random effects (Figures S4). 153 154 In summary, P-values from such Gaussian models are highly robust to even substantial violation of 155 the normality assumption and can be trusted, except when involving distributions with extreme 156 outliers (distribution D9). For very small sample sizes, judgements should preferably be made at $\alpha =$ 157 0.05 (rather than at more strict thresholds) and should also beware of outliers in both X and Y. 158 159 **Drawbacks of alternative solutions** 160 When the assumption of normality of errors is not met, it is often recommended to switch to either 161 non-parametric tests (e.g. Spearman rank correlation, Wilcoxon signed-rank test) or to model a more 162

specific error structure in a generalized linear model "glm" (e.g. binomial, negative binomial, Poisson,

163 zero-inflated Poisson). How risky are these approaches in terms of yielding type I errors?

164

165 In contrast to Gaussian models, for instance Poisson models are not at all robust to violations of the

166 distribution assumption. For comparison, we fitted the above univariate models involving the five

167 discrete distributions (D1, D2, D4, D6, D8) with a sample size of N = 100 using a Poisson error

168	structure. This yielded heavily biased type I error rates (at $\alpha = 0.05$) in either direction ranging from 0
169	to as high as 0.56, (Figures S2). Such inflations of type I error rates in glms have been reported
170	frequently (Warton & Hui 2011; Ives 2015; Szöcs & Schäfer 2015; Warton et al. 2016) and this
171	problem threatens the reliability of research whenever such models are implemented with insufficient
172	statistical expertise. First, it is absolutely essential to control for overdispersion in the data, which may
173	be particularly strong when Poisson errors are applied to measurements of areas (e.g. counts of pixels
174	or mm ²), latencies (e.g. counts of seconds), or concentrations (e.g. counts of molecules), besides the
175	more classical abundances (e.g. counts of animals). Failure to account for overdispersion will
176	typically result in very high rates of type I errors (Warton & Hui 2011; Ives 2015; Szöcs & Schäfer
177	2015; Warton et al. 2016; Forstmeier, Wagenmakers & Parker 2017). Second, even after accounting
178	for overdispersion, some models may still yield inflated type I error rates, therefore requiring
179	statistical testing via a resampling procedure (Warton & Hui 2011; Ives 2015; Szöcs & Schäfer 2015;
180	Warton et al. 2016). While most statistical experts might advocate for such a sophisticated approach
181	to count data, we are concerned about practicability when non-experts have to make decisions about
182	the most adequate resampling procedure. In this field of still developing statistical approaches it
183	seems much easier to get things wrong (and obtain a highly overconfident P-value) than to get
184	everything right. Finally, with the inclusion of random effects glmms are much more computationally
185	intensive than lmms and often fail to converge, leading to the recommendation to model all traits as
186	Gaussian (e.g. Ives & Garland 2014).
187	

187

188 The biggest downside of non-parametric approaches is that they are less advanced and user-friendly 189 compared to linear (mixed) models (e.g. Akritas & Brunner 2003), such that only simple procedures 190 are widely known and applied. The latter, however, are applicable only to the simplest and idealized 191 scenario of fully independent data points and of only a single explanatory variable with no 192 confounding factors or covariates to be controlled for. Real data sets rarely fulfil that condition, such 193 that simple non-parametric tests often suffer from pseudoreplication and unaccounted confounds. 194 Pseudoreplication, i.e. overestimation of the number of truly independent replicates, results in 195 overconfident estimates and hence is one of the leading causes of false-positive conclusions

196	(Forstmeier, Wagenmakers & Parker 2017). Gaussian models, in contrast, allow us to easily control
197	for pseudoreplication by specifying the random effects that cause non-independence of data points
198	(mixed-effects models).
199	
200	Finally, there is much to be gained when researchers follow a standardized way of reporting effect
201	sizes (Lumley et al. 2002). For instance, a study that examines the effect of a single treatment on
202	multiple dependent variables (e.g. health parameters) may often switch forth and back between
203	reporting parametric and non-parametric test statistics depending on how strongly the trait of interest
204	deviates from normality, rendering a comparison of effect sizes difficult. Methods of converting effect
205	sizes for discrete traits (e.g. odds ratio from a 2×2 contingency table) into effect sizes for continuous
206	traits (e.g. Pearson correlation coefficient) already work by violating the normality assumption (e.g.
207	fitting a Pearson correlation through the binary data of a 2×2 table; Nakagawa & Cuthill 2007), so
208	why not always report the Gaussian model to begin with, if the primary purpose of the test is to obtain
209	a reliable <i>P</i> -value?
210	

211 **Practical advice (for referees)**

212 In order to effectively guard against false-positive claims entering the scientific literature, violations

213 of the normality assumption in linear models are much less of a problem than violations of the

214 independence of data points (pseudoreplication; Schielzeth & Forstmeier 2009; Forstmeier,

215 Wagenmakers & Parker 2017). To avoid the negative consequences of strong deviations from

216 normality that may occur under some conditions (see Figure 1) it may be most advisable to apply a

217 rank-based inverse normal (RIN) transformation (aka rankit scores Bliss 1967) to the data, which can

218 approximately normalize most distributional shapes and which effectively minimizes type I errors and

219 maximises statistical power (Bishara & Hittner 2012).

220

221 In practice, we recommend the following to referees:

222	(1) When a test assumes Gaussian errors, request a check for outliers, particularly if very small P-
223	values are reported. Consider recommending a RIN-transformation for strong deviations from
224	normality.
225	(2) For Poisson, binomial and negative binomial errors, always check whether the issues of
226	overdispersion and resampling are addressed, otherwise request an adequate control for type I errors
227	or verification with Gaussian models.
228	(3) Requesting a switch to non-parametric statistics is not advised, and requests for switching from lm
229	to glm (or from lmm to glmm) should be accompanied with sufficient advice (e.g. R-code) to ensure a
230	safe implementation.
231	
232	Conclusion
233	If we are interested in statistical hypothesis testing, linear regression models with Gaussian error
234	structure are generally robust to violations of the normality assumption. Judging P-values at the
235	threshold of $\alpha = 0.05$ is nearly always safe, but if both Y and X are skewed, we should avoid being
236	overly confident in very small <i>P</i> -values and examine whether these result from outliers in both X and
237	Y (see also Osborne & Overbay 2004). With this caveat in mind, violating the normality assumption is
238	relatively unproblematic. Alternative solutions like Poisson models and non-parametric tests may bear
239	a greater risk of yielding anti-conservative P-values when applied by scientists with limited statistical
240	expertise.
241	
242	Data availability
243	All functions are bundled in an R package named "TrustGauss". The R package and all
244	supplementary figures are accessible through the Open Science Framework (osf.io/r5ym4).
245	
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250 Author contributions

- 251 WF and UK conceived of the study. UK wrote the simulation code. UK and WF prepared the
- 252 manuscript.

253

254 Competing interests

255 The authors declare no competing financial interests.

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