CNN explains tuning properties of anterior, but not middle, face-processing areas in macaque IT

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Abstract

Recent computational studies have emphasized layer-wise quantitative similarity between convolutional neural networks (CNNs) and the primate visual ventral stream. However, whether such similarity holds for the face-selective areas, a subsystem of the higher visual cortex, is not clear. Here, we extensively investigate whether CNNs exhibit tuning properties as previously observed in different macaque face areas.   While simulating four past experiments on a variety of CNN models, we sought for the model layer that quantitatively matches the multiple tuning properties of each face area. Our results show that higher model layers explain reasonably well the properties of anterior areas, while no layer simultaneously explains the properties of middle areas, consistently across the model variation. Thus, the CNNs may have some similarity with the primate face-processing system in the near-goal representation, but differ in the intermediate computational process, thus requiring a more comprehensive model for understanding the entire system.

Introduction

Recently, the neuroscience community has witnessed the rise of the deep convolution neural network (CNN)[1], a family of feedforward artificial neural networks, in computational modeling of the primate visual system. CNN models trained for behavioral goals have exhibited remarkable similarity to ventral visual areas in terms of stimulus-response relationship despite that the network itself was not directly optimized to fit neural data. For

example, CNN models optimized for image classification were highly predictive of single-site and population-level neural responses in the inferotemporal (IT) cortex[2,3]. Parallels along the hierarchy have been discovered between layers of CNN and the intermediate[3-5] or lower visual areas[6]; analogous parallels have also been reported in a decoding study of fMRI signals[7]. Such predictive CNN model has further been used to generate "optimal" stimuli for model validation[8]. A natural question arises here: if CNN explains overall responses in IT, then does it also explain responses in a subsystem of IT?

Among various subsystems of IT[9-11], the most well-studied is the macaque face-processing system[12,13]. The subsystem forms a network consisting of multiple face-selective patches with anatomically tight inter-connections[14]. The network putatively has a functional hierarchy from the middle to the anterior patch areas with a progressive increase of selectivity to facial identities and invariance in viewing angles[15]. For each patch area, a number of tuning properties to specific facial features have been documented in a clear and detailed manner[15-18]. Given these experimental facts, the macaque face processing system emerges as an ideal testbed to examine our question regarding the generality of CNN as a model of higher visual processing. However, this direction has previously been touched on only in restricted cases, involving one experiment, one face-processing patch, or one CNN model, as a side question in other main experimental or theoretical investigation[18,19].

In this study, we have asked, as the main question, whether CNN explains previously reported tuning properties of face neurons in macaque IT, and have undertaken a much larger-scale investigation (Figure 1). More specifically, we explored a variety of CNN models that were trained for classification with different architecture and dataset settings. We incorporated four major physiological experiments that had been conducted on the middle lateral (ML), anterior lateral (AL), and anterior medial (AM) patches: (1) view-identity tuning in ML, AL, and AM[15], (2) shape-appearance tuning in ML and AM[18], (3) facial geometry tuning in ML[16], and (4) contrast polarity tuning in ML[17]. While simulating these experiments on each model, we attempted to make a correspondence between the model layers and the macaque face patches by matching the population-level tuning properties. Our particular aim here is to exploit the available multiple experimental results on the same face patch and thereby perform a strong plausibility test on each model layer. Our results show that higher layers give a reasonably good match with the tuning properties of AM, while no layer gives a

good match simultaneously with the multiple tuning properties of ML, consistently across the explored CNN models. Thus, although the near-goal representation in face processing may be somewhat similar between CNN and macaque, the intermediate representation may be rather different, thus calling for a more comprehensive model to understand the computation in the primate face-processing system.

Figure 1: Schema of our investigation to compare the macaque face-processing network and a CNN model. We simulate previous four experiments (experiments (left image sets; top left face was obscured due to bioRxiv policy on the inclusion of human faces/identifiable information within research manuscripts)) on a CNN model (bottom middle) to identify tuning properties (bottom right). We quantitatively compare the tuning properties between each macaque face patch (from the past experiment) and each CNN layer (from the present simulation) to find out their correspondence.

Results

To investigate whether CNN can explain known tuning properties of the macaque face-processing network, we started with a representative CNN model optimized for classification of face images. Our model adopted an architecture similar to AlexNet[20], following recent studies relating CNNs with the ventral stream[2,4,7]. The AlexNet architecture has seven layers in total. The first five 'convolutional' layers perform multi-channeled local linear filters that are replicated across the visual field. Repetition of such layers progressively increase the size of visual receptive fields, mimicking the general structure of the visual cortex. Then, two 'fully connected' layers follow and cover the entire visual field. (The network ends with a special layer representing the class, which is ignored throughout our analysis.) We trained our CNN model on a large number of natural face

images for classifying facial identities (using the VGG-Face dataset with data augmentation for size variation; see **Methods**). From here on, we refer to this network as 'AlexNet-Face.'

For our AlexNet-Face model thus constructed, we first identified a population of face-selective units in each layer (**Methods**); we call face-selective population simply 'population' and face-selective unit simply 'unit' from here on. We then ran the protocols (stimulus set and data analysis) of previous four monkey experiments[15-18] on our model and thereby investigated whether each model layer replicated similar population-level tuning properties to the corresponding published experimental data (Figure 1). Note that, in this approach, we need no raw experimental data.

View-Identity Tuning

In the first study that we consider[15], it has been reported that different macaque face patch areas (ML, AL, and AM) have different joint tuning properties to the facial view and identity. Accordingly, we incorporated the same set of face images as used experimentally, which consisted of 25 identities and 8 views (frontal, left and right half-profiles, left and right profiles, up, down, and back). For each layer of our CNN model, we first recorded the responses of all model units to those images. We then calculated the correlation between the population responses to each pair of face images and constructed a population response similarity matrix (RSM) of such correlations (**Methods**). Figure 2 shows RSMs for layers 1, 3, 5, and 7, where the face numbers are grouped according to the view (forming sub-matrices of size 25×25) and sorted by identity in the same way within each group. (For succinctness, we present, here and hereafter, comparison results only for the odd-numbered layers since the remaining layers generally give more or less interpolated results of the presented layers.) In the intermediate layers (layers 3 to 5), the RSMs had strong block-diagonal patterns, indicating that most units had selectivity to a specific view, similarly to ML[15]. In the top layer (layer 7), such block-diagonal structure disappeared, but para-diagonal lines instead became prominent, indicating that most units had selectivity to facial identity with some degree of view invariance, similarly to AM[15]. However, at a closer look, the correlations between the profile and frontal views were weaker than those between the half-profile and frontal views, which is likely due to our training image set including fewer images in profile views than half-profile views (see relevant results in Supplementary Figure 5). In addition, a mirror-symmetric pattern in view can be seen from layers 3 to 7,

somewhat similarly to AL[15], though high correlations were observed only between the left and right profile views, not the half-profile views. In sum, the intermediate-to-top layers gradually shifted from view-specific to view-invariant and identity-selective, which is reasonably consistent with the idea of functional hierarchy in the macaque face patches[15].

Figure 2: View-identity tuning. Each plot shows the population response similarity matrix for each layer. The pixel values of the matrix indicate the pairwise correlation coefficients (legend) for the population responses to face images. The elements of the matrix are grouped according to the view (indicated by the images along the axes; images were obscured due to bioRxiv policy) with the same order of identities in each group.

The same experimental study has also reported invariance property in stimulus size[15]. Thus, we recorded the model unit responses to a set of face and non-face object images of various sizes (illustrated in Figure 3a). Then, for each layer and for each image size, we calculated the response, $\bar{R}_{\text{face}}^{\text{size}}$, to face images averaged over the population and the stimulus set; similarly, we calculated the average response, $\bar{R}_{\text{object}}^{\text{size}}$, to object images. We quantified the degree of size invariance by how much robustly the population-level selectivity to faces over objects retained for different sizes: size-invariance index (SII) is defined as the minimal fraction of image sizes at which the average response to faces is reasonably larger than that to objects ($\bar{R}_{\text{face}}^{\text{size}} > 1.4\bar{R}_{\text{object}}^{\text{size}}$); thus, a lower SI-index indicates a stronger size invariance (**Methods**). Not surprisingly, size invariance in our CNN model strengthened along with its depth (Figure 3b). In particular, the top layer (layer 7) had the strongest size invariance (SII equal to $1/4$), where the average response to faces (red) was always larger than to objects (blue) for all tested sizes. The top layer also quantitatively came closest, of all layers, to the face patches (ML/AL/AM), which all give SII around $1/8$[15]. (The experimental study also investigated position invariance, but we did not since position-shifted images extruded the image frame in our setting.)

Figure 3: Size invariance. (a) Examples of face (faces were obscured due to bioRxiv policy) and non-face object stimuli of various sizes (the numbers beneath). (b) The average responses to the face images (red) and to the object images (blue) for each image size (x-axis) in each model layer. The 'bline' stands for the average baseline response to the blank image.

Shape-Appearance Tuning

In the second experimental study[18], coding of facial shapes and appearances in the macaque face patches (ML and AM) has been investigated. Similarly to their method, we constructed a face space based on the active appearance model[21]. The face space was described by 50-dimensional feature vectors, consisting of 25 shape and 25 appearance dimensions, defined as follows. Using a set of natural frontal face images with coordinates annotated on pre-defined facial landmarks, the shape dimensions were the first 25 principal components (PC) of the landmark coordinates and the appearance dimensions were the first 25 PCs of the original face images that were morphed so that the landmarks matched to their mean coordinates (**Methods**); Figure 4a illustrates the first shape and first appearance dimensions. We then randomly sampled a set of face images from this space and used it for all the subsequent analyses.

Shape-appearance preference. Following the experimental study[18], we examined whether and how much each model unit preferred shape or appearance. We first recorded the responses to the face images and estimated the 50-dimensional vector of spike-triggered average (STA), i.e., the average of feature vectors of the face images weighted by the

responses. We then computed the shape preference index (SPI), $(S - A)/(S + A)$, where S is the vector length of the shape dimensions and A is the vector length of the appearance dimensions of the STA; a unit is considered to prefer shape when SPI is positive and prefer appearance when SPI is negative (**Methods**). Figure 4b shows the distribution of SPIs for each layer (blue). In the intermediate-to-higher layers (layers 5 to 7), most units had appearance preference, with a similar distribution to the corresponding experimental data on AM (pink). However, the lower layers (layers 1 to 3) broadly mixed both shape-preferring and appearance-preferring units, thus not particularly similar to either AM (pink) or ML (gray). We also examined shape-appearance preference by counting the number of significantly tuned units to each feature dimension; the tendency was similar (Supplementary Figure 1a).

Decoding performance. Following again the experimental study[18], we investigated how much information on the face space was contained in each layer. We first decoded feature vectors from the population responses to each face image by linear regression with leave-one-out. We then measured the performance of the decoding by the ratio of explained variance in the actual feature values by the predicted feature values for each feature dimension (Figure 4c, blue). The results for the top layer (layer 7) had a good match with the data from AM (red). However, all lower-to-intermediate layers (layers 1 to 5) gave results far from both AM (red) and ML (gray). In particular, no layer showed higher performance for shape dimensions and lower performance for appearance dimensions like ML (opposite to AM). We also measured the decoding performance in terms of accuracy of nearest-neighbor classification in the feature space; we observed a similar tendency (Supplementary Figure 1b). Thus, in contrast to the comparison regarding the view-identity tuning experiment[15], the results here reveal the lacking of ML-like properties in the CNN model.

It is somewhat unintuitive that lower layers yielded higher decoding performance (Figure 4c) despite that their representations would be less face-related. In addition, we found that, in all layers, most units showed ramp-shaped tuning curves along the STA and flat tuning curves along orthogonal axes to the STA (Supplementary Figure 2), consistently with both ML and AM[18]. We continue to discuss these points in **Discussions**.

Figure 4: Shape-appearance tuning. (a) Illustration of the first shape and first appearance dimensions for frontal faces. It shows how varying these dimensions changes the image. The shown images correspond to the feature vectors with all zero except the indicated dimension is set to -3, 0, or 3. (b) The distribution of shape-preference indices for each model layer (blue), in comparison to the corresponding distributions for ML (gray) and AM (pink) replotted from Figure 1F of the experimental study[18]. (c) Decoding performance measured by the ratio of explained variance in the actual feature values by the decoded feature values for each feature dimension (x-axis; 1–25: shape, 26–50: appearance). Each plot compares the results from a model layer (blue) with those from AM (pink) and ML (gray), replotted from Figure 2C of the experimental study[18].

View tolerance. The same experimental study also investigated view tolerance in the face space representation in AM[18]. Accordingly, we first constructed the feature representation for profile faces in a way compatible with frontal faces. Namely, we built another shape-appearance face space from left profile face images, similarly to frontal faces, and established a mapping between the frontal and profile face spaces via linear regression; we hereafter always used feature vectors for profile faces that were mapped to the frontal face

space, which allowed us to use the same feature vectors for both views of the same identity (**Methods**). Figure 5a illustrates the first shape and appearance dimensions for profile faces; note their compatibility with the frontal faces in Figure 4a. For each unit, we estimated the STA from profile faces, similarly to frontal faces, and calculated the correlation between the frontal and the profile STAs at each feature dimension across all units in each layer (Figure 5b, red and blue). As a result, the STA correlations at the first half of the appearance dimensions (blue) increased from lower to higher layers, indicating a gradual progression of view tolerance along with the depth. In particular, the correlations in the top layer (layer 7) came closest, of all layers, to the corresponding data on AM (black). Note that this result is consistent with the view-identity tuning in the top layer (Figure 2). We also conducted a decoding analysis using a mixed set of frontal and profile faces; only the top layer showed similar decoding performance between both views (Supplementary Figure 3), consistently with AM[18].

To gain further insight, we repeated the above analysis for all available 10 non-frontal views including half-profile views. The result for a left half-profile view (Figure 5c) shows a similar tendency to the left full-profile, but the overall STA correlations were slightly higher, indicating stronger tolerance for the half-profile view than the full-profile view. This result is again consistent with Figure 2, in which the frontal view is more strongly correlated with the half-profile view than the full-profile view. Finally, Figure 5d plots the mean STA correlation between the frontal and the non-frontal STAs (averaged over the feature dimensions) for all non-frontal views and for all layers. The mean STA correlation increased, thus view-tolerance became stronger, in a higher layer and in a view closer to the frontal view.

Figure 5: View tolerance. (a) Illustration of the first shape and first appearance dimensions for profile faces. The images correspond to the feature vectors with all zero except the indicated dimension is set to -3, 0, or 3. (b) The correlation between the frontal and the profile STAs across units for each dimension (x-axis; 1–25: shape, 26–50: appearance). Each plot compares the result from a model layer (red and blue) and AM (black) replotted from Figure 6D of the experimental study[18]. The shaded region indicates the 99% confidence interval of randomly shuffled data from the model. (c) Analogous result for the left half-profile view. (d) The mean STA correlation (averaged over the feature dimensions) for each non-frontal view (x-axis) against frontal view, for each layer (color; see legend).

Facial Geometry Tuning

In the third experimental study[16], tuning of ML neurons to local and global features in cartoon face stimuli has been documented. Thus, we incorporated their stimulus design of cartoon face images, which were parametrized by 19 different facial features, each ranging

from −5 to +5 with ±5 corresponding to the extreme features and 0 corresponding to the mean features (Figure 6a). We randomly generated a set of cartoon face images. From the responses of each unit to those images, we estimated a tuning curve for each feature parameter and determined its statistical significance (**Methods**).

Figure 6b (blue) shows how many features each unit was significantly tuned to (features-per-unit) in each model layer. Analogously, Figure 6c (blue) shows how many units in each layer were significantly tuned to each feature (units-per-feature). In both plots, the intermediate-to-top layers (layers 5 to 7) showed very different distributions from ML (gray), accommodating more units tuned to larger numbers of features and to more remaining features absent in ML.

Figure 6: Facial geometry tuning. (a) Examples of cartoon face images varying a feature parameter (inter-eye distance in this case). (b) The distribution of the number of features that each unit is significantly tuned to. (c) The distribution of the number of units significantly tuned to each feature. Each plot compares the result from a model layer (blue) with ML (gray) replotted from Figure 3 of the experimental study[16].

Curiously, the lower layers (layers 1 to 3) gave results somewhat closer to ML: most units were tuned to a small number of features, which were mostly geometrically larger features (i.e., face aspect ratio, face direction, feature assembly height, and inter-eye distance) rather than smaller features (related to mouth and nose). In addition, in all layers, a majority of units had ramp-shaped tuning curves with peaks and troughs at the extreme values (Supplementary Figure 4), similarly to ML[16]. We come back to these points in **Discussions**.

Contrast Polarity Tuning

The last experimental study[17] has reported that ML units had preference for contrast polarities between face parts in mosaic-like cartoon face stimuli[17]. Thus, we again used their stimulus design of cartoon face images, which consisted of 11 distinct face parts that were each assigned a unique intensity value varying from dark to light (Figure 7a). We randomly generated a set of such face images and analyzed the responses of each unit to those images for identifying its contrast polarity tuning. That is, for each pair of face parts, A and B, out of 55 pairs in total, we determined whether the unit prefers part A lighter than part B (part A > part B) or the opposite (part A < part B); see **Methods**. As summarized in Figure 7b (blue), in all layers, most of the units had preferences for contrast polarities mainly related to the forehead, the largest geometrical area in the mosaic-like face. This result is inconsistent with the experimental finding in ML (gray), where most neurons were tuned to eye- or nose-related contrast polarities and the polarity directions were consistent across the neurons.

Figure 7: Contrast polarity tuning. (a) Examples of mosaic-like cartoon face images with various intensity assignment to each face part. The first three have a larger intensity on the forehead than the left eye; the last three have the opposite. (b) The distribution of contrast polarity preferences in each model layer (blue and red) in comparison to ML (gray) replotted from Figure 3A of the experimental study[17]. In each plot, the upper half gives the positive polarities (part A > part B), while the lower half gives the negative polarities (part A < part B). The binary table at the bottom indicate the 55 part-pairs; for each pair, the upper black block denotes A and the lower block denotes B.

Summary of Correspondence

To see more clearly which model layer corresponds to each macaque face patch, we next quantify the similarities of tuning properties. Figure 8 summarizes the results for our AlexNet-Face model. For each tuning property, we use a different metric to quantify similarity between the results from the model and the experiment. For view-identity tuning

(Figure 8a), we use the correlation between the response similarity matrices from each layer (Figure 2) and each face patch[15]. For size invariance (Figure 8b), we compare the size invariance indices obtained from each layer (Figure 3b) and each face patch[15]. For shape-appearance preference (Figure 8c) or view tolerance (Figure 8d), we compare the averages of shape-preference indices (Figure 4b) or mean STA-correlations (Figure 5b) from each layer and the corresponding experimental data[18]. For facial geometry tuning (Figure 8e) and contrast polarity tuning (Figure 8f), we use the cosine similarity between the distributions from each layer (Figure 6 and Figure 7, respectively) and each face patch[16,17].

Comparing between layers, AM data favor higher model layers consistently across different tuning properties (Figure 8a–d). However, ML data favor different layers depending on each tuning property: intermediate layers in view-identity tuning (Figure 8a), higher layers in size invariance (Figure 8b), and lower layers in other tunings (Figure 8c, e). Comparing between face patches, higher model layers also generally favor AM (Figure 8a, c). However, intermediate layers are somewhat inclined to ML in view-identity tuning (Figure 8a) but to AM in shape-appearance preference (Figure 8c). In sum, AM clearly has the best match with higher layers, while ML has no such clear correspondence since no layer is simultaneously compatible with all the compared experimental data on ML.

Model variation

How much robust are the results so far against the training condition? To address this question, we investigated various model instances while varying the architecture and the dataset.

First, we examined three publicly available pre-trained networks: (1) VGG-Face network[22], a very deep 16-layer CNN model trained on face images, (2) AlexNet[20], trained on general natural images, and (3) Oxford-102 network, an AlexNet-type model trained on flower images (**Methods**). Figure 9 summarizes the layer-patch comparisons for all three models (shown in different line styles), overlaid with the plots for AlexNet-Face already given in Figure 8. For VGG-Face network, we selected the layers that had the closest receptive field sizes as the layers of AlexNet (**Methods**). Generally, the results for all four models are similar: AM data tend to match with higher layers, while ML data do not match with any particular layer simultaneously for all the tuning properties. It is rather surprising that

consistency can be found even in the cases of non-face training images like flowers, though the tendency is overall weaker, in particular, view tolerance in Figure 9d. The different strength of size invariance in the top layer of different models (Figure 9b) likely reflects the variety in image size in the training dataset (AlexNet-Face incorporated data augmentation for size, while VGG-Face model did not; other models used a dataset that had size variation in itself).

Second, to further explore the architecture space, we modified the AlexNet architecture to construct six additional networks, where four networks had five, six, eight, or nine layers and two networks changed the number of convolution filters in every layer to either half or double (Supplementary Table 1). We trained each model on the same face image dataset (**Methods**). Figure 10 summarizes the results from these six models in addition to AlexNet-Face, where the layer numbers are normalized. Again, the general tendency is similar across the architectures: AM corresponds to higher layers but ML has no corresponding layer. The weak view tolerance for the model with five layers or with half numbers of filters (Figure 10d) is probably because the depth or the filter variety was not sufficient for gaining strong invariance.

Figure 8. Summary of comparison between layers of AlexNet-Face and face-patches. (a) The correlation between the response similarity matrices from each layer (Figure 2) and each

face patch (AM/AL/ML) in Figure 4D–F of the corresponding experimental study[15]. (b) The size invariance index for each layer (Figure 3b) and for face patches (equal for AM/AL/ML) from Figure S10C of the corresponding experimental study[15]. (c) The mean shape-preference index for each layer (Figure 4b) with the mean indices for AM and ML from Figure 1F of the corresponding experimental study[18]. (d) The mean STA correlation for each layer (Figure 5b) and AM from Figure 6D of the corresponding experimental study[18]. (e) The cosine similarity between the distributions of the number of tuned units per feature or the number of tuned features per unit for each layer (Figure 6) and ML from Figure 3 of the corresponding experimental study[16]. (f) The cosine similarity between the distributions of contrast polarity preferences for each layer (Figure 7b) and ML from Figure 3A of the corresponding experimental study[17].

Figure 9. Summary of layer-patch comparisons for pre-trained networks in addition to AlexNet-Face (in different line styles; see the legend at the bottom). The format of each plot is analogous to Figure 8. In the view-identity tuning plot (a), we omit comparison with AL data for visibility. In the size invariance plot (b), we slightly shift each curve vertically for visibility. For VGG-Face, the seven layers were those with the closest receptive field sizes to the corresponding layers in AlexNet.

Figure 10. Summary of layer-patch comparisons for different architectures changing the depth or the number of convolution filters, indicated by different colors or line styles; AF-5 to 9 varied the depth; AF-h halved and AF-d doubled the number of filters in each layer; see the legend at the bottom. The format of each plot is similar to Figure 8, except that x-axis shows the normalized depth (0 corresponds to the lowest layer and 1 to the highest layer).

Discussions

In this study, we have investigated whether CNN can serve as a model of the macaque face-processing network. While simulating four previous physiological experiments[15-18] on a variety of CNNs trained for classification, we examined whether the results quantitatively match between each model layer and each face patch. As a result, we found that higher model layers reasonably replicated the multiple tuning properties of AM, while none of the layers simultaneously captured those of ML. The observation was largely consistent across the model variation. Thus, despite the prevailing view linking CNNs and IT, the similarity with the macaque face-processing system may be present mostly in the last stage achieving various types of invariance, but not in the intermediate computational process, and thus a more refined model is required for clarifying the underlying computational principle.

Some previous studies have also compared CNN and face patches, in a smaller scale, to relate with their main experimental findings or computational model. In one study[18], the

authors tested shape-appearance tuning on a face-classifying CNN model to investigate a potential computational mechanism explaining their experimental data on face patches. While they showed AM-like tuning properties in the top layer (appearance preference and ramp-flat tuning) similarly to our results (Figure 4b and Supplementary Figure 2, layer 7), they did not consider other part of the same experiment (decoding performance and view tolerance), other layer than the top, comparison with ML, different experiment, or other model instances. In another study[19], the authors tested view-identity tuning on several CNN models to compare with their novel generative model (see below). Although they showed RSM results similar to ours (Figure 2), they incorporated a more sophisticated quantitative comparison with experimental data[15] and thereby revealed notable dissimilarity in the intermediate computation from the macaque face patches, which is generally compatible with our conclusion. However, they did not incorporate any other experiments on face patches (except for some behavioral experiments). Thus, although these studies have somewhat anticipated our perspective on CNNs in relation to the face patches, our study has added a substantial assurance through the scale of the comparisons undertaken with the variety of considered face-patch experiments and CNN models.

What insight did we gain from our results? First, later stages in both CNNs and the macaque face-processing system have similarity in terms of strong invariance properties in size and view (Figure 2, Figure 3b, and Figure 5b). Although invariance properties in CNN are generally well-known, such fine-grained similarity to physiology in the view-tolerant appearance code goes beyond expectation (Figure 5b). Second, appearance representation is dominant in later stages in both systems (Figure 4), whereas shape representation conspicuously lacks in intermediate-to-higher stages in CNN (Figure 4 and Figure 6) and is dominant only in intermediate stages in macaque. This may be because shapes are in fact relatively unimportant features for classification and thus neglected during the model training[23]. This implies that the goal of the face-processing system may not be merely classification. Third, several results in lower layers were somewhat unintuitive: (1) facial shape tuning (Figure 4b and Figure 6), (2) higher decoding performance than higher layers (Figure 4c), and (3) ramp-shape tuning along STA axis and flat tuning along the orthogonal axis (Supplementary Figures 2 and 4). These may be partly because lower-layer units, although simple, localized feature detectors (e.g., Gabor filters), can in fact easily interact

with stimulus parameters controlling shape feature dimensions or local facial geometry. Also, lower layers have much weaker nonlinearity so that linear decoding would become easier. One could argue that such low-level units should not be qualified as face-selective from the first place, but might have been misjudged so by the standard criterion due to the specific image statistics of face images (e.g., emphasis on eyes). This point also suggests that each single experiment generally has limitation in discriminating between plausible and implausible models, which underscores the importance of taking multiple experiments into account.

In general, relationship between artificial and biological neural networks has been a recurring question. Since the brain has a number of sub-networks with a hierarchical structure, it is tempting to hypothesize that such sub-network is optimized for some behavioral goal. Indeed, a classical study has shown that a neural network trained for a coordinate transformation task exhibits, in the intermediate layer, properties related to spatial location similar to primate parietal area 7a[24]. As mentioned in Introduction, more recent studies have argued that CNNs trained for image classification have layers similar to higher[2-4,7], intermediate[3-5], or lower[6] areas in the monkey or human visual ventral stream. Analogously, layer-wise correspondence has been found between CNNs trained for audio classification and the human auditory cortex[25] or the monkey peripheral auditory network[26]. Although all these studies are positive in the generality of explanatory capabilities of goal-optimized neural networks, the same story might not go all the way through. For the macaque face-processing network, our study here could not find a CNN layer corresponding to the intermediate stage (ML). In addition, some recent studies have pointed out potential representational discrepancies between CNN and the ventral stream from behavioral consideration[19,23,27-29]. (See also the related discussion on the 'computational gap' below.)

One should note that there are, in general, two fundamentally different approaches for comparing a model with the neural visual system. In one approach, which is more traditional and taken in our study, a given model is tested whether it exhibits tuning properties compatible with prior experimental observations ('tuning approach'). In the other approach, which is recently more popular[2,3,25], a given model is used as a basis function and a linear regression fitting is conducted from model responses to actual neural

responses for predicting new neural responses ('prediction approach'). In the tuning approach, although the comparison is arguably more direct in the sense of involving no fitting, tuning experiments have often been criticized for biased and subjective stimulus design and for use of degenerate summary statistics. Therefore showing consistency with experimentally observed tuning may not be sufficiently supportive evidence for the model. Note that, nevertheless, showing clear inconsistency is strongly falsifying evidence, from the logical contraposition of 'if the model behaves similarly to the neural system, then it should reproduce a similar tuning property.' Our comparison with ML is one such example. In the prediction approach, on the other hand, the aforementioned criticism would not occur since an arbitrary (randomly selected) set of stimuli can be used.   However, the necessity of linear fitting makes the comparison somewhat more indirect: correspondence is made between an actual neuron and a 'synthetic neuron,' i.e., the output of a linear model after fitting[2-4,30]. Indeed, one example of computational gap between CNN and IT neural responses has been raised in Fig. 7 of the study by Cadieu et al.[2], where the population similarity matrices from IT and the CNN top layer were strikingly different without fitting, although very similar with fitting. One might therefore argue that it is a CNN plus a linear regression, not a CNN itself, that has predicted neural responses. Thus, both tuning and prediction approaches are complementary to each other and neither is significantly better than the other.

If CNN does not fully explain all the facial tuning properties, then what can be alternative models? Some hints can be found in prior theoretical studies. First, although unsupervised learning of feature representations from the image statistics has traditionally been used for early vision[31-34], recent studies have raised its possible contributions in facial tuning properties. For example, sparse coding of facial images can produce facial-part-like feature representations, which explains surprisingly well most of the facial geometry tuning properties found in ML[35]. Also, PCA-based learning of face images can produce global facial feature representations, which exhibit monotonic and mirror-symmetric view tuning as in ML and AL[36]. Second, feedback processing is ubiquitous in the visual system and therefore likely important, but crucially missing in CNN. One standard theoretical approach to incorporating feedbacks is to use a generative model. Although such theory has been typical for modeling early vision[37-39], some recent studies have pointed out potential

importance in higher vision. For example, a particular generative model, called mixture of sparse coding models, has been employed to represent an organization of multiple modules of model units with competitive interaction[35], which can endow the units with a global face detection capability similar to the neural face selectivity. In a completely different approach, a novel generative model assumes a computer graphics algorithm that generates face images from certain facial and scene feature parameters, while employing a feedforward deep convolutional network trained on those feature parameters[19]. Notably, certain three layers in the feedforward network exhibited view-identity tuning properties each similar to ML, AL, and AM in a way quantitatively better than standard CNN models[19]. Third, invariance properties can be explained not only by supervised learning as in CNN but also by image statistics. While spatial statistics can explain well position or phase invariance in early vision[32,40,41], temporal coherence[42] for learning the most slowly changing features has been commonly used for explaining more complex invariance properties in higher vision[36,43,44] and experimentally tested[45]. Although combining such invariance learning into a generative model is theoretically not so obvious, one approach extending variational autoencoders[46] has been developed[47] and led to a novel deep generative model explaining multiple tuning properties in ML and AM[48]. Taken together, for clarifying the computational principle underlying the primate face-processing system, it seems crucial to view this system as not merely a classifier but having a richer repertoire of visual processing, for which the present work would offer a solid motivation.

Methods

Convolutional Neural Network (CNN)

CNN is a family of feedforward, multi-layered computational models[49], which has originally been inspired by the mammalian visual system. CNN allows for a variety of architecture design, stacking an arbitrary number of layers with different structural parameters. Each layer in CNN undergoes several operations. The layer typically starts with convolutional filtering, which applies an identical multi-channel linear filter to every local subregion throughout the visual field. Then, the results are given to a nonlinear function, $\mathrm{ReLU}(x) = \max(0, x)$, at each dimension, for ensuring non-negative outputs. The layer is optionally

preceded by pooling and normalization. Pooling gathers the incoming inputs within a local spatial region by taking the maximum. Normalization normalizes the outputs by dividing the incoming inputs by their squared norm. Generally, a CNN architecture consists of multiple such layers, by which it progressively increases the effective receptive field sizes and eventually achieves a non-linear transform of the input from the whole image space to a space of interest (i.e., class). Often, the last several layers of a CNN architecture have convolutional filters covering the entire visual field, thus called fully-connected layers.

Each layer operation is closely related to some neural computation discovered in neurophysiology. Convolutional filtering mimics V1 simple cells, which replicate their receptive field structures across the visual field[50]. The nonlinear function proxies for neural thresholding giving rise to non-negative values of firing rates. Pooling comes from the classical notion that V1 complex cells gather the outputs from V1 simple cells to achieve position or phase invariance[50,51]. Normalization stems from a gain-controlling phenomenon that is widely observed in the cortex and often explained by the well-known divisive normalization theory[52]. Further, the repetition of layers of similar processes is inspired by the hierarchy of the visual cortex, for which the gradual increase of receptive field sizes and the congruent micro-circuit structures are well known[53]. To dive deep in CNN, see introductory materials[54,55].

Trained CNN Models

We show, most in detail, the results from a representative CNN model called 'AlexNet-Face.' This CNN model has the same architecture as AlexNet[20] with five convolutional layers followed by two fully connected layers. (The network ends with a special layer for representing classes, but we ignore it in our analysis.) The architecture parameters are given in Supplementary Table 1. We trained it for the classification task using the VGG-Face dataset[22], which contains millions of face images of 2622 identities. We augmented the dataset with size variation, allowing four-times downsizing. (Note that four-times downsizing was limit in our case with full image size 224×224 since further downsizing would make the images too small and impossible to discriminate and thus considerably degrade the classification performance of the model.) We performed the training by minimizing the cross-entropy loss function, a commonly used probabilistic approach to measure the error between the computed and given outputs[54]; we used the stochastic

gradient descent method with momentum (SGDM) as optimizer. The resulting CNN model gave classification accuracy 72.78% for held-out test data. (This score is somewhat lower than state-of-art face recognizing deep nets, which typically go over 90% of accuracy. This is likely because our size-varied data augmentation yielded very small images that would be difficult to classify, e.g., Figure 3a).

To test robustness of our results against structural change to the model, we incorporated a set of six additional model instances modifying the architecture of AlexNet. Four of them changed the number of layers to five, six, eight, and nine. We designed the specific architectures for these by changing only the convolutional layers, keeping the overall structure of increasing receptive field sizes. The remaining two models changed the number of filters in every layer, one halved and one doubled. The architecture parameters of the additional models as well as their classification accuracies are given in Supplementary Table 1.

For all implementation, we used Matlab with Deep Learning Toolbox (https://www.mathworks.com/products/deep-learning.html) as well as Gramm plotting tool[56] for visualization.

Pre-trained CNN Models

To further test robustness, we included three publicly available pre-trained CNN models using very different architecture or dataset, namely, VGG-Face network[22], AlexNet[20], and Oxford-102 network. The VGG-Face network is a very deep 16-layer CNN model that has been trained on VGG-Face database for face classification (with no data augmentation for size variation). For analysis of the VGG-Face network, we chose the layers that had the closest receptive field sizes as the layers of AlexNet (Supplementary Table 2). Also, since lower layers of VGG-Face were too large, we analyzed a subpopulation of randomly sampled 30,000 (face-selective) units whenever the full population exceeded this number. AlexNet is the well-known, original network trained on ImageNet database[57] for natural image classification. Oxford102 is an AlexNet network that has been 'fine-tuned' for the classification of flower images in Oxford-102 dataset[58]. We imported these three network models from a public repository (https://github.com/BVLC/caffe/wiki/Model-Zoo).

Experiments

On each CNN model, we first identified face-selective units and then proceeded to simulation of four macaque experiments on these face-selective units. The specific procedures are summarized as follows.

Face-Selective Population Estimation

We determined the face-selectivity of a unit by following the general approach used in experiments on IT[15,16]. That is, we first recorded the responses of the unit to a set of 50 natural frontal faces from the FEI image database (http://fei.edu.br/~cet/facedatabase.html) and to a set of 50 non-face object images obtained from the Web. Then, from the average responses to the faces, $\overline{R}_{\text{face}}$, and non-face object images, $\overline{R}_{\text{object}}$, above the baseline response to the blank image (all zero pixel-values), we estimated the Face Selective Index, $\text{FSI} = \left(\overline{R}_{\text{face}} - \overline{R}_{\text{object}} \right)/\left(\overline{R}_{\text{face}} + \overline{R}_{\text{object}} \right)$. FSI was set to 1 when $\overline{R}_{\text{face}} > 0$ and $\overline{R}_{\text{object}} < 0$, and to -1 when $\overline{R}_{\text{face}} < 0$ and $\overline{R}_{\text{object}} > 0$. We judged a unit as face-selective if $\text{FSI} > \frac{1}{3}$, that is, the unit responded to face images, on average, twice as strongly as to non-face object images. (Zero FSI, for instance, implies an equal average response to face and non-face images.) For the simulation of shape-appearance tuning experiment described below, we used profile faces in addition to frontal faces for selectivity determination. Below, 'unit' or 'population' always refer to the face-selective ones.

View-Identity Tuning Experiment

To simulate the experiment on view-identity tuning[15], we used the same set of 'face-view' (FV) images as in the experimental study, which consisted of 200 images of 25 identities and 8 views (left full profile, left half profile, straight, right half profile, right full profile, up, down, and back; see the images along the axes in Figure 2). To determine the view-identity tuning, we first recorded the responses of the units to these images and calculated the correlation between the population responses to each pair of FV images; we then constructed a population response similarity matrix (RSM) from those values. The authors of the experiment provided us the FV image set and the RSMs obtained from the experiment (the data corresponding to the back view was missing).

Size-Invariance Experiment

To simulate the experiment on size invariance[15], we took frontal as well as right and left profile face images of 8 individuals (24 face images in total) from FEI face database, and 16 non-face object images obtained from the Web. We then resized these images from the original size 224×224 pixels down to 196×196, 168×168, 140×140, 112×112, 84×84, and 56×56 pixels (see Figure 3a), forming a set of 280 images in total. For each layer, we recorded the responses of the units to those images and calculated the average across the population and the image set, $\bar{R}_{\text{face}}^{\text{size}}$ or $\bar{R}_{\text{object}}^{\text{size}}$, separately for faces or objects, and separately for each size. To quantify the degree of size-invariance, we define size-invariance index (SII) as the minimal fraction of sizes at which the mean population response to faces is reasonably larger than objects: ($\bar{R}_{\text{face}}^{\text{size}} > 1.4 \bar{R}_{\text{object}}^{\text{size}}$).

Shape-Appearance Tuning Experiment

To simulate the experiment on shape-appearance tuning[18], we followed their approach to create a face space based on the active appearance model[21]. For this, we employed 200 frontal face images from FEI face dataset, on which we annotated the coordinates of pre-defined 95 facial landmarks. We here used the Face++ tool (https://www.faceplusplus.com) to automatically annotate the landmarks supported by this tool and resorted to manual annotation for the other landmarks. Our set of landmarks were in fact a superset of the ones used experimentally (58 landmarks) since the automatic tool happened to provide richer annotations, which would not (at least) impoverish our result.

From the above annotated image dataset, we constructed a 50-dimensional face space as follows. We first performed principle component analysis (PCA) on the landmark coordinates of the 200 images, of which the first 25 principal components provided the first 25 dimensions of the face space, called shape dimensions or features. Thereafter, we normalized each image by morphing the original image so that the warped landmark coordinates match the mean landmark coordinates (across all images). We again performed PCA on the resulting normalized images, of which the first 25 principal components provided the last 25 dimensions of the face space, called appearance dimensions or features. We then generated a set of 2000 face images by randomly sampling feature vectors from the 50-dimensional isotropic Gaussian distribution and reconstructing images

by reversely following the above process. Figure 4a shows examples of generated frontal face images by varying the first shape and appearance dimensions.

To identify shape-appearance preference of each unit, we first recorded the responses to the generated 2000 face images and calculated the spike-triggered average (STA) as the average of the 50-dimenisonal feature vectors of those images weighted by the corresponding responses. To quantify the preference to shape or appearance, we defined shape preference index (SPI):

$$\text{SPI} = \frac{(S - A)}{(S + A)}$$

where S is the vector length of the 25 shape dimensions and A is the vector length of the appearance dimensions of the STA[18].

We conducted the same decoding study as in the experimental study[18]. Since the size of unit population affects the performance of decoding, we randomly selected a subpopulation of 100 units from each layer, which is comparable to the size in the experiment. To decode a feature vector from the population responses for a chosen face image, we trained a linear regression model from the population responses to the remaining 1999 face images and predicted the feature vector for the chosen image. Using the leave-one-out approach, we continued this process for each of the 2000 images to decode the feature vectors for all images. We evaluated the performance of decoding in terms of ratios of explained variance in the actual feature vectors by the decoded feature vectors for each feature dimension.

To further investigate view tolerance, we repeated the aforementioned face space generation process for the profile view. That is, we created a profile face space from 200 profile face images from FEI database with manually annotated landmark coordinates and randomly generated 2000 profile face images. We established a mapping between the frontal and profile face spaces by linear regression between the frontal and profile feature vectors of the same identities. From then on, we always used the profile feature vectors mapped to the frontal face space. Figure 5a shows examples of generated left profile face images by varying the first shape and appearance dimensions. We thereafter calculated the STA and performed decoding for profile face images in similar ways to frontal face images. We also repeated the same process for all remaining non-frontal views (10 views in total). See the original experimental study[18] for details.

Facial Geometry Tuning Experiment

To simulate the experiment using cartoon face stimuli[16], we used the same cartoon face design, where each face image had seven elementary parts (hair, face outline, eyes, irises, eyebrows, mouth, and nose) and the geometry of the parts were parameterized by 19 feature parameters (face aspect ratio, face direction, height of assembly, hair length, hair thickness, eyebrow slant, eyebrow width, eyebrow height, inter-eye distance, eye eccentricity, eye size, iris size, gaze direction, nose base, nose altitude, mouth-nose distance, mouth size, mouth top, and mouth bottom). Each of these parameters held values between -5 to $+5$ (11 values), where zero corresponded to the average features (e.g., normal inter-eye distance) and ±5 corresponded to the extreme features (e.g., large or no inter-eye distance). Figure 6a shows example cartoon face images that vary the inter-eye distance parameter over 11 different values.

Using the same method as in the experimental study[16], we estimated a tuning curve for each unit and for each feature. For this, we first generated a set of 5000 cartoon face images with random values for the 19 parameters. From the responses to those images, we estimated a tuning curve for each feature parameter by taking the average of the responses corresponding to each value that the feature parameter takes, regardless of the values of the remaining features; we smoothed the curve by a Gaussian kernel of unit variance. We then determined the statistical significance of the tuning curve using the same criterion as in the experimental study[16].

Contrast Polarity Tuning Experiment

To simulate the experiment using mosaic-like parameterized cartoon faces images[17], we used the same stimulus design, where each face image consisted of 11 face parts (forehead, left eye, right eye, nose, upper lip, left cheek, right-cheek, lower-left cheek, lower-right cheek, mouth, chin) based on a manual fragmentation of a mean face. Following the experimental procedure[17], we generated a set of 432 faces images by randomly giving a unique intensity value to each part ranging between dark and bright (11 values), while ensuring that, for every possible part-pair (55 part-pairs in total, e.g. forehead and left-eye, forehead and right-eye) and every possible intensity level, the set included at least one exemplar in which that part-pair had that intensity level. Figure 7a shows some

examples of generated mosaic-like cartoon face images in the case of forehead lighter than left eye or the opposite.

Following the experimental method[17], we used the responses of each unit to the above set of images to determine preference on the contrast polarity for each of the 55 part-pairs. More specifically, for each part-pair (A and B), we compared the average response between the condition where intensity of part A was greater than part B (part A > part B) and the condition where intensity of part A was lesser than part B (part A < part B) irrespective of what intensity value the remaining 9 parts held. We then determined the significance of the contrast polarity preference for each part-pair using the same criterion as in the experimental study[17].

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Author Contributions

H.H. designed the study. R.R. and H.H. created software required for the study. R.R. performed simulation and analysis. R.R. and H.H. wrote the manuscript.

Competing interests

The authors declare no competing financial interests.

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