1	STATIC LOADING OF THE KNEE JOINT RESULTS IN MODIFIED SINGLE LEG
2	LANDING BIOMECHANICS
3	
4	Running Title: Single Leg Landing Biomechanics
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15 ABSTRACT

- 16
- 17 **Background:** External loading of the ligamentous tissues induces mechanical creep, which
- 18 modifies neuromuscular response to perturbations. It is not well understood how ligamentous
- 19 creep affects athletic performance and contributes to modifications of knee biomechanics during
- 20 functional tasks.
- 21 Hypothesis/Purpose: The purpose of this study was to examine the mechanical and
- 22 neuromuscular responses to single leg drop landing perturbations before and after passive
- 23 loading of the knee joint.
- 24 Study Design: Descriptive laboratory study
- 25 Methods: Male (n=7) and female (n=14) participants' $(21.3 \pm 2.1 \text{ yrs}, 1.69 \pm 0.09 \text{ m}, 69.3 \pm 13.0 \text{ m})$
- kg) right hip, knee, and ankle kinematics were assessed during drop landings performed from a
- 27 30 cm height onto a force platform before and after a 10 min creep protocol. Electromyography
- 28 (EMG) signals were recorded from rectus femoris (RF), vastus lateralis (VL), vastus medialis
- 29 (VM), semimembranosus (SM), and biceps femoris (BF) muscles. The creep protocol involved
- fixing the knee joint at 35° during static loading with perpendicular loads of either 200 N (males)
- or 150 N (females). Maximum, minimum, range of motion (ROM), and angular velocities were
- 32 assessed for the hip, knee, and ankle joints, while normalized average EMG (NAEMG), average
- vertical ground reaction forces (aVGRF), and rate of force development (RFD) were assessed at
- landing. Rate of force development (RFD) was calculated during the landings using ANOVAs.
- 35 Alpha was set at 0.05.
- **Results:** Maximum hip flexion velocity decreased (p < 0.01). Minimum knee flexion velocity
- increased (p < 0.02). Minimum knee ad/abduction velocity decreased (p < 0.001). Ankle ROM
- decreased (p < 0.001). aVGRF decreased (p < 0.02). RFD had a non-significant trend (p =
- 39 0.076). NAEMG was significant between muscle groups (p < 0.02).
- 40 **Conclusion:** Distinct changes in velocity parameters are attributed to the altered mechanical
- 41 behavior of the knee joint tissues and may contribute to changes in the loading of the leg during
- 42 landing.
- 43

44 INTRODUCTION

Knee joint injuries greatly affect athletic and recreational sport populations. Sex-related 45 46 and sports based factors are the leading determinants of knee injuries [17,21,32,37]. The loading 47 of the knee joint in dynamic sporting activities influences the stresses and strains which the tissues within and surrounding the knee joint capsule tolerate. The ligaments of the knee joint 48 49 provide structural integrity to the joint during both passive and active movements [25]. The incidence of injuries to the passive viscoelastic tissues, such as the anterior cruciate ligament 50 (ACL), posterior cruciate ligament (PCL), medial collateral ligament (MCL), lateral collateral 51 ligament (LCL), and menisci are well documented in the literature [4,37,38] as well as the 52 predictive factors leading to injury [1,43]. 53

The injury mechanisms at the knee joint are multifactorial and are complicated due to the 54 requirements of specific movement activities performed in dynamic environments (i.e., athletics 55 venues). Both contact and non-contact activities play critical roles in determining how the knee 56 57 joint responds to the given loading conditions. The type of training, task, fatigue level of the individual, and anatomic structure all contribute to the potential injury of the knee joint [15,34]. 58 In particular, when landing from a given height, the knee biomechanics are modified to absorb 59 energy to reduce the impact of the contact forces upon the lower extremities [41]. Females are 60 reported to have greater knee valgus – a potential sign of knee injury at landing – compared to 61 males, and thus a greater potential for knee injury [18,19,20]. Training individuals to land 62 without excess knee valgus has been documented and may contribute to reduced knee joint 63 injuries [7,31]. Nilstad et al. [26] used static laxity of the ligamentous tissues as a predictor 64 65 variable for knee valgus, but could not conclude this was a factor responsible for increasing likelihood of knee injuries. Others, however, have determined the laxity of the knee joint 66

ligaments contribute to modifications of the neuromuscular control of the knee joint [8,9,28].
The musculotendonous units contribute much more to the stability of the knee joint during
dynamic tasks as the forces generated via the muscle are actively engaged in movement of the
joint, as well as resistance to external forces acting upon the knee [30].

Neuromuscular fatigue of the muscles surrounding the knee joint and other lower 71 72 extremity muscles are believed to be a contributing factor to knee injury. Lower extremity 73 kinematics and myoelectric activity, collected with electromyography (EMG), is reported to 74 significantly change at landing from a jump or drop after fatigue has been induced [29]. When 75 the muscles become fatigued the ability to generate force is diminished and the internal moments have reduced capacity to resist the external moments applied [5]. The contribution of 76 77 neuromuscular fatigue to knee joint injury is significant [34], however, it is unclear how the laxity of the ligamentous tissues contributes to the inability of the joint to maintain its integrity 78 [26]. Neuromuscular fatigue requires the passive ligamentous tissues to be strained further to 79 compensate for the deficiencies of the neuromuscular control. These ligamentous tissues are 80 further loaded during the dynamic activities as tension-relaxation or mechanical creep are 81 induced in parallel with neuromuscular fatigue [35]. Further assessment of the contribution of the 82 83 passive ligamentous tissues during loading tasks is necessary to understand the mechanisms of injury. 84

Reductions in both force generating capacity and myoelectric activity of the musculature about the knee joint have been documented during isometric knee actions following passive loading of the knee joint capsule [9,28,33]. These tests serve to isolate the knee joint and provide a foundational understanding of the influence of loading schemes to the response of the neuromuscular and musculoskeletal systems. Functionally, little is known how passive loading 90 of the knee joint capsular tissues affects the movement of the joint during dynamic (athletic)91 activities.

The purpose of this study was to examine the mechanical and neuromuscular responses of the lower extremities to landing perturbations before and after passive loading of the knee joint capsule. It was hypothesized that passive static loading of the knee joint capsule would elicit a reduced myoelectric amplitude response from the surrounding musculature at landing. Further, it was also hypothesized that joint kinematics of the landing leg would compensate for the passive loading applied at the knee joint capsule during landing through changes in kinematics parameters.

99 METHODS

100 Participants

University students enrolled in kinesiology classes volunteered to participate in this 101 study. Male (n = 7) and female (n = 14) participants (21.3 ± 2.1 years old, 1.69 ± 0.09 m in 102 height, and had a mass of 69.3 ± 13.0 kg) were required to be healthy individuals with no 103 medical conditions which would prevent physical activity, involved in regular physical activity 104 105 (recreational activities at least 3 times/week), not have any trunk or lower extremity disorders, not have an injury to the head, trunk, and lower extremities within the previous 12 months of 106 participation, and if female not be pregnant. Participants were provided an informed consent 107 document approved by the university's Human Subjects Committee prior to the study. 108 Participants agreed to voluntarily participate after reading the informed consent document. 109 Additional verbal instructions were provided during the study. Participants were informed that 110 they could withdraw without penalty at any time during the study. 111

112 Instrumentation

A 6-camera motion capture system (Qualisys, Gotenborg, Sweden) with Oqus 100 113 114 camera sampling at 120 Hz was used to collect movement data. Palpation was used to place 115 individual marker spheres of 14 mm diameter bilaterally over the acromion processes, posterior superior iliac spines (PSIS), and anterior superior iliac spines (ASIS). Unilateral markers were 116 117 positioned over the sacrum at the S1, and the right leg at the greater trochanter, lateral femoral epicondyle, medial femoral epicondyle, lateral malleolus, medial malleolus, calcaneus, 1st and 5th 118 119 metatarsophalangeal joints. Two four-marker clusters were position on the right leg at the 120 midline of the lateral thigh and the proximal third of the lower leg and secured with Coband © wrapping tape. 121

122 Surface electromyography (EMG) (Motion Lab System, Baton Rouge, LA, USA) was used to collect muscle activity from the right thigh musculature surrounding the knee. The skin 123 was abraded and then cleaned with isopropyl alcohol. The 0.02 m diameter stainless steel 124 electrodes have a fixed center to center distance of 0.02 m and bipolar configuration, and were 125 positioned distal to the motor point of each muscle group and aligned parallel with the muscle 126 fibers. Myoelectric signals were collected from the muscles rectus femoris (0.10 m distal from 127 the right ASIS), vastus lateralis (0.10 m proximal and lateral form the patella), vastus medialis 128 (0.10 m proximal and medial to the patella), semimembranosis (~0.20 m proximal to the medial 129 femoral epicondyle), and the biceps femoris (~0.20 m proximal to the lateral femoral 130 epicondyle). Surface EMG signals were bandpass filtered at 20-500 Hz with a common mode 131 rejection ratio of > 100 dB at 60 Hz, an input impedance of $> 100 \text{M}\Omega$, and collected at 1200 Hz. 132 Kinetic data were collected with a 6 degree of freedom force platform (OR-6, AMTI, 133 Watertown, MA, USA) with dimension $0.45 \text{ m} \times 0.5 \text{ m}$ embedded and flush with the laboratory 134

floor. Force data were collected at 1200 Hz. Kinematic, EMG, and kinetic data were collected 135 using the Qualisys Tracking Manager (QTM) software interfaced with a USB 2533 12 bit A/D 136 board (Measurement Computing, Inc., Norton, MA, USA) and save for future processing. 137 138 Protocol Participants warmed up by walking on a motorized treadmill at their self-selected speed 139 for 10 min. Kinematic markers and EMG electrodes were placed upon the participants after the 140 warm-up. Participants performed single leg drop landings from a height of ~ 0.30 m using the 141 142 right leg. Leg dominance was determined by asking the participants which leg they would use to kick a ball. All participants indicated right leg dominance. Participants began by standing on two 143 legs on top of a box situated 0.10 m horizontal from the force platform. They were instructed to 144 145 lean forward leading with the right leg in order to drop onto the force platform. Once they landed, the participants were instructed to maintain their one-legged stance and stand erect for 5 146 s. The hands were positioned on the iliac crests to control arm movements. Participants were 147 given up to 10 practice trials to acclimate to the drop landing task. Participants performed up to 148 10 trials of drop landings before and after the knee joint capsule was loaded. At least 1 min of 149 rest was provided between trials to reduce the influence of fatigue. Landing trials where the 150 participants either jumped, stepped down, or could not maintain balance at landing were 151 discarded and additional trials were performed until 5 sufficient trials were recorded. 152 153 After the initial drop landing trials, participants were positioned into a high-back chair of a Biodex system 3 dynamometer (Shirley, NY, USA). Participants were positioned with their 154 trunk in an upright erect position with the hips in 90° flexion. Then an attachment arm was 155 156 secured to the dynamometer axis, which was aligned with the lateral femoral epicondyle of the

right leg. The attachment arm was secured to the leg 0.05 m proximal to the lateral malleolus.

Ramped maximal voluntary isometric efforts (MVIE) of 5 s were performed 3 times each with 158 the knee at 90° flexion for extension trials and 45° flexion for knee flexion trials (full knee 159 extension is 0°), respectively, with a 60 s rest between efforts. A 10 min rest period was 160 performed after the last MVIE. The leg was then positioned so that the knee was flexed to 35° 161 with reference to the anatomical position [9]. A cuff was secured 0.03 m distal to the femoral 162 163 epicondyle and surrounded the proximal leg. A pulley system was configured to allow a cable to fit perpendicular to the leg and around the cuff. The cable was used to pull the leg anterior 164 relative to the femur with a load of either 200 N (men) or 150 N (women). This protocol has 165 166 been reported to increase laxity of the tissues surrounding the knee joint capsule and potentially the ligaments within the capsule [9]. The knee joint was statically loaded for 10 min. Surface 167 EMG was used to ensure a low level of muscle activity relative to the MVIE was maintained 168 169 during knee loading. Immediately after the loading protocol was completed, participants performed additional drop landing trials. 170

171 Data Processing

The EMG signals collected during the static loading were centered, full wave rectified, and low pass filtered at 3 Hz with a fourth order zero-lag Butterworth filter. The EMG signals collected during drop landing trials were centered, rectified, and then low pass filtered at 5 Hz with a fourth order zero-lag Butterworth filter. All EMG data were then normalized to the maximum EMG value attainted during MVIE.

Force data were processed with a low pass Butterworth filter set at 60 Hz using the
MotionMonitor System software (MotionMonitor, Chicago, IL, USA). A vertical ground
reaction force (VGRF) threshold of 20 N was establish to determine the onset of load acceptance
at landing. Force data were reduced to 120 Hz to coincide with the kinematics data.

181	Kinematics data were processed using the MotionMonitor software (MontionMonitor,
182	Chicago, IL, USA). Kinematics data were smoothed with a fourth order low pass zero-lag
183	Butterworth filter set at 10 Hz. A static reference file was used to determine lower extremity
184	segment and joint angles using the right-hand configuration (x-anteroposterior, y-mediolateral, z-
185	vertical axes, respectively). Based upon the static reference file, segmental coordinate systems
186	were established and used in determining relative angles of adjacent segments. Further, Euler
187	angle calculations were performed to determine segment orientations, which contributed to joint
188	angular rotations (X – frontal plane, Y – sagittal plane, and Z – transverse plane) of the distal
189	segments relative to the proximal segments.

190 Data Analysis

Kinematics data were evaluated in all three planes of movement during the landing phase 191 of the drop landing. Landing phase during the drop landing was assessed as the onset of the force 192 platform threshold until the maximum knee flexion angle was attained. Joint angle parameters 193 194 (maximum, minimum, and range of motion) were assessed using the right-hand rule as follows: at the knee joint, flexion-extension (about the y-axis), internal-external rotations (about the z-195 axis), and mediolateral rotations (about the x-axis). At the hip joint, hip flexion-extension (about 196 the y-axis) and hip adduction/abduction (about the x-axis) were evaluated. Ankle plantarflexion 197 and dorsiflexion movements were assessed as these movements have been reported to align with 198 maximum knee joint flexion at landing (Fong et al., 2011). Angular velocities (maximum and 199 minimum) of the three knee joint rotations were also calculated to determine differences between 200 pre and post loading single leg landing trials. 201

Kinetic variables of concern were the maximum VGRF, force profile of the first 200 ms
of landing, and the rate of force development (RFD). The RDF was calculated as the difference

in maximum VGRF and the VGRF at landing divided by the time between the maximum VGRFand VGRF at landing.

206 Surface EMG recordings during the static knee loading protocol were averaged the first 207 30 s of each minute of the 10 min loading period. This was performed to ensure minimal muscle activity during the loading. Additionally, processed EMG signals were assessed during the first 208 209 200 ms of the landing phase, as well as 200 and 100 ms prior to initiation of the landing to compare pre-loading and post-loading conditions. Pre-landing EMG signals were used to 210 211 determine the preparation of the muscles surrounding the knee joint to the landing (feed-forward 212 control). The 200 ms after landing was compartmentalized into four 50 ms intervals (0-50, 51-100, 101-150, and 151-200 ms) which were used to average the normalized EMG signals for 213 evaluating the trend of the neuromuscular activity at landing. In addition, co-activation ratios of 214 the average quadriceps and hamstring muscles EMG (O:H) at landing were performed. Overall 215 average and maximal EMG values from each muscle group were calculated during this 200 ms 216 landing period. 217

218 Statistical Analyses

All statistical testing was performed with SPSS v 22.0 (Chigaco, IL, USA). Kinematics 219 variables were analyzed using a one-way (condition) analysis of variance (ANOVA). A one-way 220 ANOVA was performed to assess average muscle activity at each minute of static loading. 221 222 Average and maximal EMG values during landing were analyzed with a 2 factor (condition x 223 muscle) ANOVA. A three-factor, muscle x condition x time interval (5 x 2 x 4), ANOVA was 224 performed on the average EMG, while a ratio x condition x time interval (6 x 2 x 5) ANOVA 225 was performed on the Q:H ratio data. A 2 factor ANOVA was performed to assess the overall average and maximal Q:H ratios. Average and peak forces and RFD data were each analyzed 226

227 v	with a one-way	ANOVA	(condition)). A 2-way	y ANOVA	(condition x	k time interv	val) was	used to
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- assess VGRF data during the landing phase, while one-way ANOVAs were used to compare
- 229 maximal and normalized maximal VGRF values between conditions. Tukey post-hoc
- 230 comparisons were performed when significant effects were present. A Mauchly's test of
- 231 Sphericity was performed to assess the normality of the data. A Greenhouse Geisser test was
- applied when normality was not attained. The level of significance was set at $p \le 0.05$.
- 233 RESULTS
- 234 Electromyography
- Average EMG values did not significantly change during the 10 min of static loading.

The average activity for each minute was under 5% of the MVIE, indicating minimum active

237 neuromuscular response to the external load (Table 1).

Table 1. Mean $(\pm sd)$ of normalized surface electromyography as a percentage of MVIC from the three quadriceps and two hamstring muscles during static loading of the knee joint capsule.

		Mus	scle Group (% MV	/IC)	
Time (min)	RF	VL	VM	SM	BF
1	3.72 (3.8)	4.15 (2.6)	3.59 (4.1)	4.87 (4.3)	2.80 (2.0)
2	3.67 (4.2)	3.79 (2.0)	2.67 (1.4)	4.46 (4.0)	3.45 (2.7)
3	3.57 (4.3)	3.92 (2.5)	2.78 (1.5)	4.06 (3.4)	3.09 (2.5)
4	2.99 (3.2)	4.08 (2.4)	2.73 (1.5)	3.52 (2.5)	2.82 (2.3)
5	3.00 (3.2)	4.03 (2.7)	2.73 (1.5)	3.71 (2.9)	2.71 (2.4)
6	2.95 (3.1)	3.74 (2.1)	2.66 (1.4)	3.49 (2.5)	2.56 (2.2)
7	2.79 (2.9)	4.11 (2.9)	2.60 (1.4)	3.53 (2.5)	2.79 (2.3)
8	2.76 (2.9)	3.90 (2.1)	2.89 (1.5)	3.49 (2.5)	2.57 (2.1)
9	2.75 (2.9)	4.25 (2.8)	2.71 (1.5)	3.43 (2.4)	2.50 (2.0)
10	2.74 (3.0)	3.84 (1.8)	3.06 (2.3)	3.32 (2.4)	2.34 (1.8)

240 RF = rectus femoris; VL = vastus lateralis; VM = vastus medialis; SM = semimembranosus; BF
 241 = biceps femoris

242

243

245 Overall Average and Maximal EMG during Landing

246	Average EMG values did not change between conditions ($p > 0.55$), but were significant
247	between muscles ($F_{4,199} = 5.347$, p < 0.01). There was no significant condition x muscle
248	interaction effect ($p > 0.87$) (Table 2). Peak EMG values were not significant between conditions
249	(p > 0.34), but were significant between muscles ($F_{4,180} = 9.553$, p < 0.01) (Table 2). There were
250	no significant interaction effects present ($p > 0.97$).

Table 2. Mean (sd) peak and average NEMG as a percentage of MVIC from the three quadriceps and two hamstring muscles during drop landings.

	Peak 1	NEMG	Overall	Average	NEMG	Overall
Muscle	Pre	Post		Pre	Post	
RF	115.1	117.5	116.3	45.1	47.7	46.4
	(62.0)	(55.0)	(57.9)	(30.1)	(28.3)	(28.9)*
VM	43.3	45.2	44.2	28.4	24.1	26.2
	(44.9)	(54.9)	(49.3)^	(32.3)	(22.9)	(27.7)
VL	98.3	104.2	101.3	50.6	61.9	56.3
	(61.6)	(50.3)	(55.2)	(36.9)	(55.1)	(46.6)†
BF	86.5	97.4	92.2	38.5	39.1	38.8
	(56.2)	(61.8)	(58.7)	(28.3)	(28.0)	(27.8)
SM	64.0	80.9	73.1‡	30.7	34.2	32.4
	(30.6)	(55.5)	(46.0)	(15.3)	(29.1)	(23.0)

*indicates RF significantly greater than VM (p < 0.01)

 254 †indicates VL significantly greater than VM, BF, and SM muscle groups (all p < 0.02)

 $^{\text{indicates VM}}$ significantly less than all other muscle groups (all p < 0.03)

256 \ddagger Indicates SM significantly different than RF, VL, and VM (all p < 0.03)

257

A significant time interval x muscle interaction was present ($F_{20, 1189} = 1.951$, p < 0.01)

when observing the average EMG signals at landing. Post-hoc analysis indicated a significant

difference between time intervals (p < 0.001) and muscle groups (p < 0.001). There were no

significant condition effects (p > 0.27), nor condition x time interval (p > 0.99) or condition x

muscle interaction (p > 0.99) effects present (Figure 1).

Figure 1 here

Figure 1. Mean (sd) normalized EMG from pre and post-landing conditions for rectus femoris (RF), vastus lateralis (VL), vastus medialis (VM), biceps femoris (BF), and semimembranous (SM) muscle groups. EMG activity is provided in 50ms intervals during the first 200ms of

landing. Pre-landing ratios are provided 200ms and 100 ms prior to the landing.

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269 EMG ratios during Landing

The average EMG ratio values were not significant between conditions (pre: 1.34 ± 1.2 ,

post: 1.47 ± 1.2 , p > 0.66), but were different between muscle ratios (F_{5,231} = 4.919, p < 0.01)

(Table 3). There was no significant condition x ratio interaction effect (p > 0.96). Peak EMG

ratios were not significant between conditions (p > 0.87), but were significant between muscle

ratios ($F_{5,187} = 6.806$, p < 0.01) (Table 4). There were no significant condition x muscle ratio

interaction effects (p > 0.58).

Table 3. Mean (sd) average muscle ratios during the landing phase between pre and post landingconditions.

			Muscl	e Ratio			
Condition	RF/BF	VL/BF	VM/BF	RF/SM	VL/SM	VM/SM	Total
Pre	1.27 (0.9)	0.78 (0.7)	1.50 (1.0)	1.50 (0.9)	1.05 (1.0)	1.91 (1.7)	1.34 (1.1)
Post	1.35 (0.9)	0.78 (0.6)	1.84 (1.6)	1.86 (1.7)	1.05 (1.0)	1.92 (1.7)	1.46 (1.4)
Overall	1.31 (0.9)‡	0.78 (0.6)*	1.67 (1.4)	1.68 (1.3)†	1.05 (1.0)	1.92 (1.7)#	1.40 (1.5)

278 RF = rectus femoris; VL = vastus lateralis; VM = vastus medialis; SM = semimembranosus; BF
 279 = biceps femoris

*indicates VL/BF is significantly less than VM/BF, RF/SM, and VM/SM (all p < 0.01)

281 \dagger indicates RF/SM is significantly greater than VL/SM (p < 0.01)

282 \ddagger indicates RF/BF is significantly less than VM/SM (p < 0.04)

#indicates VM/SM is significantly less than VL/SM (p < 0.01)

				N /	la Dati-			
	Condition	RF/BF	VL/BF	VM/BF	le Ratio RF/SM	VL/SM	VM/SM	Total
	Pre	1.47 (0.6)	1.01 (0.8)	1.64 (1.3)	2.34 (1.5)	0.75 (0.7)	1.88 (1.15)	1.48 (1.2)
	Post	1.67 (1.5)	0.57 (0.6)	1.98 (2.0)	1.73 (1.1)	0.69 (0.7)	2.25 (2.3)	1.47 (1.6)
	Overall	1.59 (1.2)	0.78 (0.7)*	1.82 (1.7)	2.01 (1.3)	0.72 (0.7)†	2.09 (1.9)‡	1.47 (1.4)
287	RF = rectus	3 femoris; V	L = vastus la	teralis; VM	= vastus m	edialis; SM =	= semimembr	anosus; BF
288	= biceps fer	moris						
289	*indicates	VL/BF is sig	gnificantly les	ss than RF/I	BF, VM/BF	, and RF/SM	l (all p < 0.01)
290	†indicates	VL/SM is si	gnificantly le	ess than RF/	BF, VM/BI	F, and RF/SN	A (all p < 0.02)	2)
291	‡indicates	VM/SM is s	ignificantly g	reater than	VL/BF and	VL/SM (all	p < 0.04)	
292								
293	A si	ignificant di	fference was	present bet	ween muscl	e ratios ($F_{5,1}$	$_{317} = 38.182,$	p < 0.001)
294	and betwee	n time inter	vals (F _{5,1317} =	9.87, p < 0	.001) (Figu	re 2). There	were no signi	ficant
295	condition e	ffects ($p > 0$).88), nor wer	e there con	dition x rati	o (p > 0.99),	condition x t	iming
296	interval (p ²	> 0.44), or c	condition x tim	ning interva	al x muscle	ratio (p > 0.9	99) interaction	n effects
297	present.							
200				***	- 7 hara***	*		
298				··· rigui	e 2 here***			
299	Figure 2 M	lean (sd) au	adricens to h	amstring rat	ios from pr	e and nost-la	nding conditi	ons (rectus
300	-	· · -	teralis (VL),	-	-	-	-	ions (reetus
301	· · · ·		(),		(),	-)ms intervals	during the
302			-				ns prior to th	-
302	11150 2001115	of failuting.	1 IC-landing l	anos are pr	Ovided 200			c landing.
303								
304	Kinematics	1						
504	- cinematics							
305	Max	ximum and r	minimum ang	gular displa	cement data	from the hip	o, knee, and a	nkle joints
306	are provide	d in Table 5	. Although n	ot significat	nt, a trend w	vas present b	etween condi	tions for

Table 4. Mean (sd) maximal muscle ratios during the landing phase between pre and post landingconditions.

- ankle flexion maximum (p > 0.071). All other maximum and minimum displacement data were
- 308 not significant between conditions.
- Table 5. Mean (sd) maximum and minimum angular displacements (°) at the hip, knee, and ankle
- 310 joints during drop landings before (Pre) and after (Post) static passive loading of the knee joint 311 capsule.

	Max	Maximum		Minimum		p-value
	Pre	Post	Î.	Pre	Post	<u>^</u>
Hip flexion	22.0 (6.8)	19.7 (9.2)	0.38	9.2 (3.0)	6.2 (6.6)	0.15
Knee flexion	60.8 (7.8)	60.9 (8.3)	0.97	16.4 (4.8)	15.7 (9.7)	0.67
Ankle flexion	1.9 (16.9)	-1.9 (12.6)	0.071	-52.7 (14.5)	-51.4 (15.4)	0.61
Hip Abduction	14.0 (8.9)	11.3 (8.6)	0.13	-7.6 (13.9)	-6.4 (11.0)	0.59
Knee abduction	-4.0 (8.3)	-4.2 (6.2)	0.94	-30.5 (11.9)	-32.7 (14.1)	0.29
Knee rotation	16.2 (5.8)	16.7 (9.5)	0.77	1.7 (6.9)	2.8 (2.4)	0.48

312

313	Table 6 provides a	ngular velocity data	measured from the hip	, knee, and ankle joints. Hip
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abduction maximum velocity was significant between conditions ($F_{1,3} = 43.5$, p < 0.007). A

significant difference between conditions was present ($F_{1,9} = 7.963$, p < 0.02) for minimum knee

flexion velocity. Minimum knee abduction velocity was significant between conditions ($F_{1,9}$ =

19.35, p < 0.002). All other angular velocities in sagittal, frontal, and transverse planes were not

318 statistically different between conditions.

320 joints during drop landings before (Pre) and after (Post) static passive loading of the knee joint

321 capsule.

	Maxi	mum	p-value	Minii	num	p-value
	Pre	Post		Pre	Post	_
Hip flexion	204.9 (76.4)	227.0 (46.5)	0.43	-60.9 (62.2)	-65.5 (73.5)	0.78
Knee flexion	527.9 (131.6)	544.1 (168.7)	0.59	-14.9 (25.2)	-27.9 (34.2)	< 0.02
Ankle flexion	792.3 (104.9)	544.1 (168.7)	0.66	-4.7 (21.3)	-17.0 (41.5)	0.21
Hip	87.1 (56.9)	56.9 (63.4)	< 0.007	-304.2 (101.2)	-291.7 (62.6)	0.57
Abduction						
Knee	90.0 (48.4)	99.7 (50.5)	0.53	-528.5 (127.5)†	-399.9 (129.3)	< 0.002
abduction						
Knee rotation	306.3 (99.9)	276.4 (89.5)	0.30	-125.9 (51.4)	-141.5 (45.2)	0.46

322 p < 0.05 is indicated in bold

Table 6. Mean (sd) maximum and minimum angular velocities ($^{\circ}$ /s) at the hip, knee, and ankle

Table 7 provides ROM data for the hip, knee, and ankle joints. Ankle ROM was

significant between conditions ($F_{1,166} = 7.904$, p < 0.006). No other ROM variables were

Table 7. Mean (sd) values of ROM of the hip, knee, and ankle joints before (Pre) and after (Post) static passive loading of the knee joint capsule.

Pre	Post	p-value
15.9 (8.6)	16.6 (8.8)	0.64
46.3 (9.8)	46.8 (9.8)	0.73
56.2 (8.5)	52.6 (8.5)	< 0.006
19.3 (11.1)	18.5 (11.4)	0.71
21.5 (13.0)	21.9 (12.8)	0.82
14.5 (8.1)	14.2 (8.1)	0.79
	15.9 (8.6) 46.3 (9.8) 56.2 (8.5) 19.3 (11.1) 21.5 (13.0)	15.9 (8.6) 16.6 (8.8) 46.3 (9.8) 46.8 (9.8) 56.2 (8.5) 52.6 (8.5) 19.3 (11.1) 18.5 (11.4) 21.5 (13.0) 21.9 (12.8)

332 Kinetics

Absolute peak VGRFs were not different between conditions (pre 1550.5 \pm 84.6 N, post 1548.1 \pm 55.8 N, p > 0.91). No significant condition effects were present for normalized peak forces (pre: 2.25 \pm 0.3, post: 2.24 \pm 0.2, p > 0.76). Similarly, the rate of force development was not significantly different between conditions, but did have a trend (pre: 16,602.0 \pm 1057.0 N/s, post: 17,368.0 \pm 1447.6 N/s, p > 0.076).

- 338 Force timing
- Significant main effects for condition ($F_{1,787} = 5.593$, p < 0.02) and time interval ($F_{3,787} =$
- 128.217, p < 0.001) were present. The average force over the first 200ms of contact at landing
- 341 was 1297.1 (\pm 392.4) N before and 1231.3 (\pm 392.4) N after knee loading. There were no
- significant condition x time interval interaction effects (p > 0.56, Figure 3).

³²⁵ significantly different between conditions.

344

Figure 3 here

Figure 3. Mean (sd) vertical ground reaction forces measured at 50 ms intervals from initiallanding to 200ms during each condition (pre and post).

347

348 DISCUSSION

The aim of this study was to assess the neuromuscular and kinematics responses of the 349 landing leg during single-leg drop landings before and after passive static loading of the knee 350 joint capsule. Based upon previous research involving passive loading of the knee joint capsule, 351 it was believed that neuromuscular and biomechanical behaviors would be modified in the lower 352 extremity at landing. The reasoning for this study was twofold: 1) mechanical loading of the 353 354 viscoelastic passive tissues is known to influence mechanical behavior changes of the affected (loaded) tissues, as well as the EMG response of the surrounding muscles, and 2) in the absence 355 of neuromuscular fatigue it is not known how the lower extremity will respond to a perturbation 356 357 given during a functional activity once passive loading of the knee joint is performed. The initial 358 hypothesis predicted a reduction in EMG amplitude of the muscles surrounding the knee joint at 359 landing after passive knee joint loading. However, this hypothesis was not supported based upon the results. There were no significant neuromuscular changes between conditions, however, the 360 361 EMG ratios provide information indicating specific relationships between the quadriceps and 362 hamstrings muscle groups. It was also assumed that the neuromuscular system would compensate for the reduced mechanical tension within the passive connective tissues to increase 363 364 coactivation in the drop phase prior to landing. This, however, was not substantiated in the data and cannot be considered a control mechanism of the leg at landing in this study. The second 365 hypothesis regarding compensation of joint motion due to the passive loading at the knee joint 366

367 capsule was partially supported. Distinct modifications to hip, knee, and ankle kinematics during
368 landing resulted from the static loading. Further, the overall average VGRF decreased after static
369 loading, while no changes in the maximal force was evident.

370 Electromyography

Neuromuscular control determined the response of the landing leg during the drop 371 landing. Low level myoelectric activity from both hamstrings and quadriceps muscles groups 372 assisted in preparing the leg for landing. This feed-forward mechanism allows the neuromuscular 373 374 system to engage immediately once contact with the support surface is initiated to prevent the leg from buckling. Once landing occurred, greater muscle responses were observed to reduce joint 375 angular motions. There were significant differences between the muscles groups at landing. 376 377 Overall peak EMG values were greatest in the RF group and least in the VM muscles group. However, average EMG values were greatest from the VL group, and least in the VM group. 378 379 This is expected as the VL muscles group has been reported to be activated at higher relative 380 levels during similar tasks [30].

The descent phase of landing requires knee extensor muscles to perform eccentric actions 381 to diminish flexion of the knee joint. The EMG signals of all muscles examined increased as the 382 knee approached maximum flexion. The contribution of the VL and RF muscles were much 383 greater than that of the VM, indicating differential control within the knee extensors. This may 384 385 indicate the inability of the VM muscle group to provide a primary role in joint stability, which 386 may be due to architectural factors [10]. The increased myoelectric amplitudes are expected from the knee extensors, but not necessarily from the knee flexor muscles. The SM muscle group 387 388 showed high activation levels in both conditions indicating that this muscle group was more actively involved in the control of leg mechanics compared to the BF muscle. There are two 389

explanations which exemplify the activation of the hamstrings at landing: 1) the hamstring
muscle activities are indicative of control at the hip joint to reduce hip joint flexion motion
during the landing phase, and 2) sufficient hamstring muscle activity is required to compensate
for anterior translation of the tibia [3].

The ratios of quadriceps to hamstrings muscle groups were assessed to identify changes 394 395 in the coactivation of the thigh musculature. The largest Q:H EMG ratio was observed in the VL/BF relationship during the entire preparation and landing phases. Reduced BF muscle 396 397 activity is suggested to increase knee internal rotation in a small sample of female athletes [14]. 398 In patients who have undergone ACL reconstruction, modifying landing instruction to increase 399 knee flexion at landing was reported to also reduce BF activity [11]. Although the BF activity was relatively lower than other muscles surrounding the knee, this did not influence overall knee 400 rotation at landing (Table 5). 401

402 Kinematics

Compensatory changes in the movement velocities at the knee and hip during the landing 403 phase highlight the modified control which the musculoskeletal system uses to respond to the 404 dynamic loading. First, the rate of hip abduction at landing was significantly reduced even 405 though the displacement of the hip joint during landing did not change between landing 406 conditions (Table 4). Reduced hip abduction angular velocity suggests potential increase in hip 407 408 adductor contribution during the landing. This reduced hip abduction velocity may compensate 409 for the mechanics observed at the knee joint. The ability of the leg to absorb the shock at landing 410 may have been due to greater emphasis of control at the knee as greater negative knee flexion 411 angular velocity was observed. In addition, a reduced knee abduction negative velocity would indicate a greater control of frontal plane knee rotations and less mechanical energy being 412

absorbed. Norcross et al. [27] reported knee landing kinematics differences between ACL injury
risk groups and noted greater increased ligament loading with greater energy absorption. It is
possible that the mechanical energy absorbed by each joint at landing was modified and could
explain how control at each joint was performed.

The knee joint kinematics may have influenced the range of motion observed from the 417 418 ankle joint after the passive loading. Overall ankle joint range of motion decreased, while no 419 maximum or minimum angular displacement measures were different between the landing conditions. Fong et al. [13] noted that passive ankle joint range of motion was related to greater 420 421 knee flexion at landing leading to reduced stress in the ACL, specifically. Although greater range of motion can reduce the forces acting upon the joints at landing, Butler et al. [6] suggest 422 423 increased joint stiffness is important for successful landing mechanics. However, increased limb stiffness is also a factor in potential lower extremity injury, particularly in female athletes 424 [22,24]. Additionally, maximal hip abduction velocity decreased, minimum knee flexion angular 425 426 velocity increased in magnitude, and knee abduction velocity decreased indicating potential neuromuscular control enhancement of the muscles surrounding the joints. 427

428 Kinetics

Significant reductions in the average VGRF after static loading of the knee joint was present. Initially, it could be suggested that the landing style changed between conditions, however, there was no kinematics evidence to suggest foot position changed at the initial contact with the support surface. Although a reduced range of motion at the ankle joint in plantardorsiflexion was observed, this was not believed to influence the landing, especially within the first 10 ms of the landing, which is a critical time period of knee injuries at landing. Kernozek et al. [19] observed a non-significant trend of reduced peak VGRF, as well as reduced internal joint

reaction forces during drop landings performed after fatiguing the thigh musculature. Similarly,
Laughlin et al. [23] reported reduced peak VGRFs and peak ACL forces when female
participants were instructed to land with greater knee flexion during drop landing. They observed
kinematics differences at initial contact and peak ACL force from the hip and knee joints which
explained their findings.

441 Although not tested, the stiffness of the leg influences the ability of the system to resist external loads applied. In particular, the musculotendonous stiffness influences the knee joint 442 loading and ability to dissipate mechanical energy. Greater joint stiffness at landing when the 443 knee is more extended leads to increased injury potential [12,16]. Hamstring musculotendonous 444 stiffness has been reported to reduce the loading of the ACL and limit frontal plane rotations [2]. 445 This is significant as the current study was implemented to reduce stiffness in the tissues within 446 and surrounding the knee joint. In addition, joint stiffness has been reported to be greater in 447 females compared to males at landing [24]. This may serve as an initial protective mechanism for 448 the joint at landing, but may act to increase the chances of knee ligament injury. 449

450 Knee Joint Loading

Isolation of the knee joint utilizing specific loading schemes to assess the neuromuscular 451 responses of the surrounding joint musculature provides biomechanical information of the 452 factors associated with knee joint injury mechanisms, in the absence of neuromuscular fatigue. 453 454 When muscles become fatigued more of the load/stress is transferred to the passive viscoelastic tissues to maintain joint integrity during functional movements. Although not a functional 455 loading scheme, the passive loading implemented in the current study has been shown to elicit 456 457 creep behavior of the tissues within and surrounding the knee joint capsule [8,9]. Evidence of the influence of these mechanical creep experiments has provided mixed information, but this is also 458

dependent upon the specific intentions of each study. Cheng et al. [8] initiated posterior loading 459 of the tibia to elicit posterior cruciate ligament creep and reported reduced co-activation of the 460 antagonist thigh muscles during knee extension activities. Chu et al. [9], however, noted 461 increased force and agonist activation during maximal effort knee extension exercises with no 462 changes in antagonist (hamstring) activities. Further evidence of passive tissue loading within 463 464 and surrounding the knee joint demonstrates reduced agonist and antagonist muscle activities in maximal efforts [28,33], indicating a potential neuromuscular inhibition which may impede 465 function of the muscle during activity. Specifically, Nuccio et al. [28] report significant 466 467 reductions in the biceps femoris muscle activity after cyclic loading during both knee flexion and knee extension static efforts. 468

It must be emphasized that isolated loading of specific tissues, such as the ACL or PCL 469 in the knee joint capsule, are not directly linked in *in vivo* studies. Unlike animal models where 470 tissues can be isolated for perturbation/loading to determine the effects of mechanical 471 manipulation of the specimen [36,39,40], there are factors which constitute how human models 472 can be interpreted. Loading of the knee joint involves applying mechanical creep to the 473 surrounding musculotendonous units, ligamentous tissues, meniscus, and other connective 474 475 tissues which assist in maintaining the functional dynamics of the knee during physical activity. Particularly when applying these anteriorly directed loads, the musculotendonous units of the 476 477 hamstrings muscle group can be strained leading to potential modifications in the activation level and stiffness of the muscle [2]. Shear stress of the meniscus during anterior loading is reported to 478 differ between femoral and tibial anterior and posterior attachments, as well as medial and lateral 479 attachments leading to an overall disparity in load distribution in ACL-deficient knees [42]. 480

481

482 CONCLUSIONS

483	Implementation of a static load to the knee joint capsule modified movement parameters
484	during a drop landing performance. Tissue-level behavioral changes may be present to influence
485	how the lower extremity joints respond to dynamic loading. Neuromuscular modifications were
486	not present between the landing conditions indicating that this loading scheme does not result in
487	altered neuromuscular control. Additional research is warranted to examine potential
488	modifications to the loading schemes to further understand how the neuromechanics of the lower
489	extremities are modified when controlling for fatigue.

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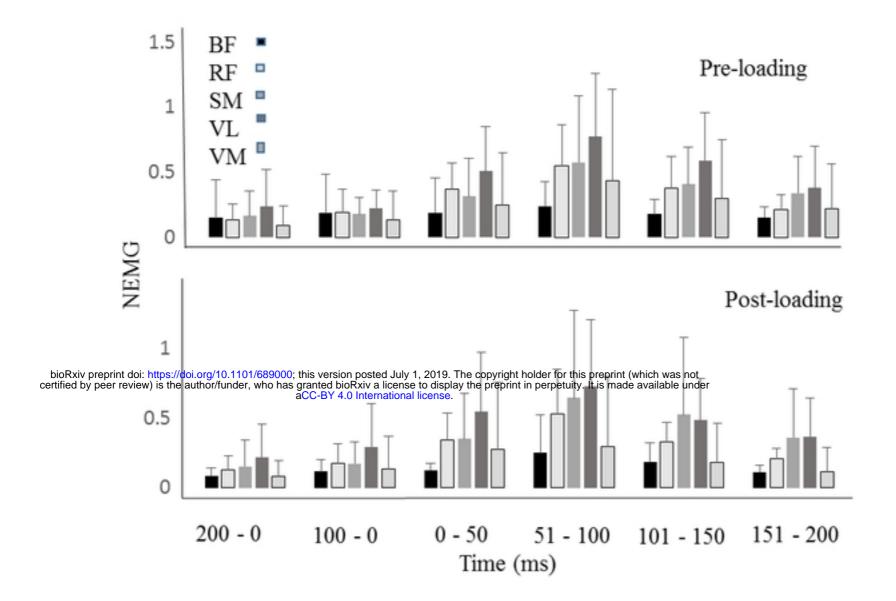


Figure 1. Mean (sd) normalized EMG from pre and post-landing conditions for rectus femoris (RF), vastus lateralis (VL), vastus medialis (VM), biceps femoris (BF), and semimembranous (SM) muscle groups. EMG activity is provided in 50ms periods during the first 200ms of bioRxiv preplice polymore landing the first 200ms of certified by peer review) is the autorfunder, who has granted bioRxiv a license to display the preprint in perpetuity. It is made available under acC-BY 4.0 International license.

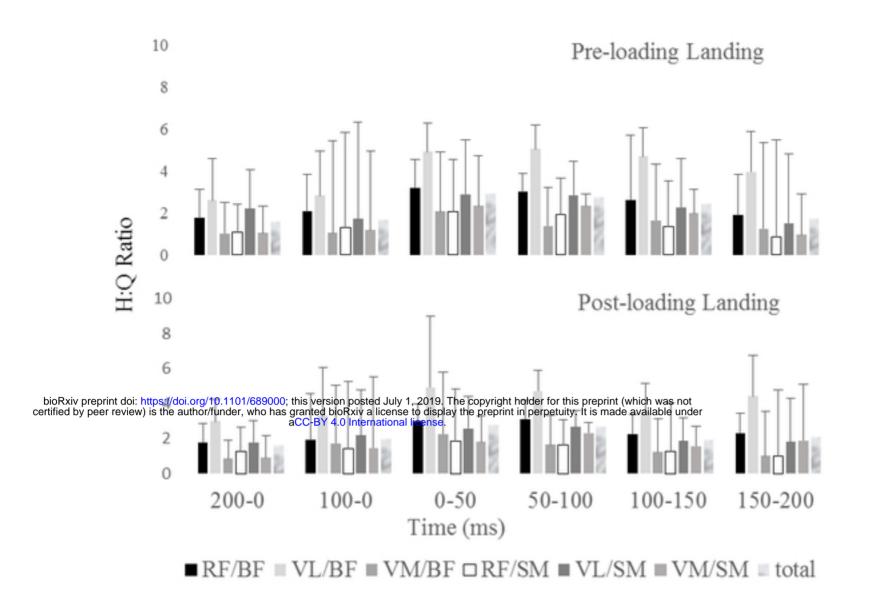


Figure 2. Mean (sd) quadriceps to hamstring ratios from pre and post-landing conditions. Prelanding ratios are provided 200sm and 100 ms prior to the landing.



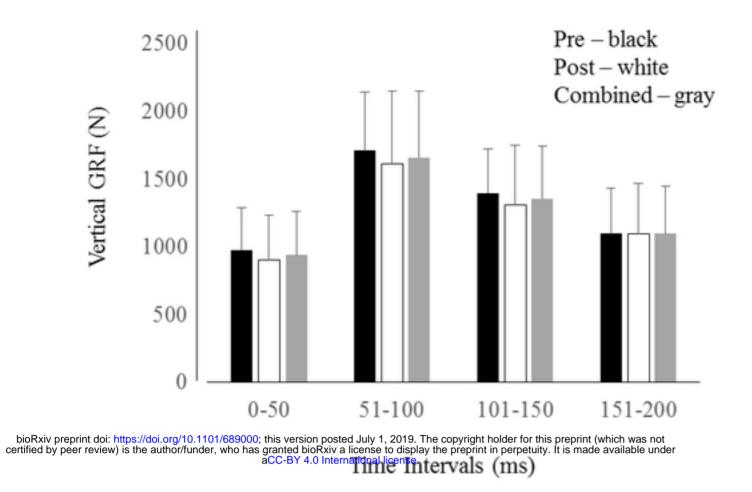


Figure 3. Mean (sd) vertical ground reaction forces measured at 50 ms intervals from initial landing to 200ms during each condition (pre and post).

Figure 3