Ecotone formation through ecological niche construction: the role of biodiversity and species interactions

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Abstract

Rapid changes in species composition, also known as ecotones, can result from various causes including rapid changes in environmental conditions, or physiological thresholds. The possibility that ecotones arise from ecological niche construction by ecosystem engineers has received little attention. In this study, we investigate how the diversity of ecosystem engineers, and their interactions, can give rise to ecotones. We build a spatially explicit dynamical model that couples a multispecies community and its abiotic environment. We use numerical simulations and analytical techniques to determine the biotic and abiotic conditions under which ecotone emergence is expected to occur, and the role of biodiversity therein. We show that the diversity of ecosystem engineers can lead to indirect interactions through the modification of their shared environment. These interactions, which can be either competitive or mutualistic, can lead to the emergence of discrete communities in space, separated by sharp ecotones where a high species turnover is observed. Considering biodiversity is thus critical when studying the influence of species-environment interactions on the emergence of ecotones. This is especially true for the wide range of species that have small to moderate effects on their environment. Our work highlights new mechanisms by which biodiversity loss could cause significant changes in spatial community patterns in changing environments.

1   Introduction

Whether species composition changes gradually, or forms discrete zones along environmental gradients has been the subject of a long-standing debate in ecology (Clements, 1916; Gleason, 1926; Braun-Blanquet, 1928; Hedberg, 1955; McIntosh, 1967). Observational studies have found both gradual (Whittaker, 1956; Vazquez G. and Givnish, 1998; Ellison et al., 2010; Lieberman et al., 1996) and discrete patterns (Kitayama, 1992; Hemp, 2006; Tuomisto and Ruokolainen, 1994; Kessler, 2000). Rapid changes in community composition along gradients, also termed ecotones (Kent et al., 1997), have been observed in a wide range of ecosystems, such as alpine treelines (Germino et al., 2002), tropical mountain forests (Martin et al., 2007) and coastal environments (Sternberg et al., 2007; Walker et al., 2003). Hereafter, a transition will be termed "rapid" when its scale is much smaller than the spatial scale of the landscape, even though the transitional area may show mixing of species.

While rapid changes can be blurred by species dispersal (Liautaud et al., 2019) or stochasticity in nature, it is important to understand the theoretical conditions under which rapid community changes can emerge. These rapid changes in species composition can coincide with rapid changes in environmental conditions, such as the frost line (Kitayama and Mueller-Dombois, 1992) or discontinuities in edaphic conditions (Tuomisto and Ruokolainen, 1994; Kessler, 2000). In these cases, it is often assumed that changes in abiotic conditions are responsible for the change in species composition (McIntosh, 1967; Kent et al., 1997). This assumption is supported in many cases, but it may obscure the possibility that, in other settings, the two boundaries emerge together from the influence of species on their abiotic environment. The mechanisms that can lead to such transitions are poorly known, and in particular the respective contributions of species-environment feedbacks and interspecific interactions.

Species that are able to modify their abiotic environment are often called "ecosystem engineers" (Jones et al., 2010). Classical examples range from beavers that impact water flow and habitat heterogeneity (Wright et al., 2002), to cushion alpine plants that buffer extreme temperatures and increase soil moisture (Badano et al., 2006). Ecological niche construction is a particular case in which engineers modify the environment to their own benefits (Kylafis and Loreau, 2008, 2011), creating a feedback with the environment (an example in which engineers can instead create succession is presented in the Appendix). This ecological process should be distinguished from

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56   the related concept of niche construction in evolutionary theory in which we would also expect

57   species traits to evolve over time (Odling-Smee et al., 2003, 1996). Examples of ecological niche

58   construction range from plant-water feedbacks in arid environment (Dekker et al., 2007) to increases

59   in nutrient inputs by trees in tropical ecosystems (De longe et al., 2008). Such feedbacks can govern

60   species distributions (Wilson and Agnew, 1992), particularly under harsh environmental conditions

61   (Kéfi et al., 2007; Gilad et al., 2004; Meron et al., 2004; von Hardenberg et al., 2001), and lead

62   to the emergence of ecotones (Bearup and Blasius, 2017; Jiang and DeAngelis, 2013). Classical

63   studies on ecosystem engineers, however, have generally focused on the effects of a particular

64   species having strong effects on the abiotic environment (Jones et al., 2010; Bouma et al., 2010;

65   Prugh and Brashares, 2012). But many more species have small or moderate impacts on their

66   environment. Such species, which are often neglected individually, might substantially affect their

67   environment when aggregated. Furthermore, previous studies have scarcely explored what types

68   of interactions can arise between multiple species that engineer their shared environment. We

69   thus propose to focus on the role of diversity and species interactions in the emergence of ecotones

70   through ecological niche construction.

71   Biodiversity can have two main effects on the emergence of species-environment feedbacks : a

72   cumulative effect of species number, and a heterogeneity effect due to variations in species' pref-

73   erences and engineering ability. Cumulative effects are similar to complementarity in biodiversity-

74   ecosystem functioning relationships (Loreau and Hector, 2001; Hooper et al.). The fact that species

75   coexist with weak or no competition implies the existence of different niches, i.e. other factors be-

76   yond the environmental preference modelled here. This cumulative effect arises when there is

77   no single identifiable engineer, but where community acts collectively to create an ecotone. A

78   potential example is the occurrence of ecotones between mangroves and hardwood forests, where

79   several mangrove tree species can modify water salinity in synergy (Sternberg et al., 2007). In

80   contrast, the heterogeneity effect of biodiversity arises when there are differences in species' pre-

81   ferred environmental states. We investigate the effect of these differences on emergent competition

82   or facilitation between ecosystem engineers, and how this could play a role in ecotone emergence.

83   In this study, we build a theoretical model that couples the dynamics of a community and

84   of its abiotic environment to assess the role of ecosystem engineers and of their diversity in the

85   emergence of ecotones in space. In our model, ecotones are represented by abrupt changes, in-

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86 cluding discontinuities. In the presence of multiple interacting species, we show that ecological

87 niche construction can lead to the emergence of indirect interspecific interactions -which can be

88 either positive or negative - through environmental modifications. Similarly, we show that even

89 species with different preferences can act synergistically as a single community. We then assess

90 the consequences of these different interaction types for community patterns in space, and identify

91 the conditions under which ecotone formation is predicted to occur.

2 Model and methods

2.1 Species growth and niche construction

94 We model the dynamics of a community of n species, each of which obeys a logistic growth along

95 a gradient of an arbitrary environmental factor E. We consider independent locations along this

96 environmental gradient, assuming no fluxes between the locations [1] . For a given location k, the

97 population dynamics of species i is given by:

$$\frac{dN_{i,k}}{dt} = r_i N_{i,k} \left(1 - \frac{N_{i,k}}{K_i(E_k)} \right) \tag{1}$$

98 where E_k represents the value of the environmental factor at location k, N_{i_k} is the abundance of

99 species i at that location, and r_i is its intrinsic growth rate, assumed to be equal for all species,

100 $r_i = r$. The fundamental niche of each species is defined by its carrying capacity $K_i(E)$, which is

101 assumed to depend on the environmental value E according to a Gaussian function:

$$K_i(E) = K_i^{\max} \exp\left[-\frac{(E - C_i)^2}{2T_i^2} \right] \tag{2}$$

102 The classical Hutchinsonian niche (Hutchinson, 1957) would instead be defined in terms of growth

103 rate, but these two assumptions are equivalent in the case of logistic growth as considered here.

104 The above function is characterized by the species' fundamental niche centre C_i, i.e. the value of

105 the environmental factor for which its carrying capacity reaches its maximum value $K_i^{\max}$, and

106 its tolerance range T_i. This unimodal, continuous distribution ensures a gradual response of each

107 species to changes in the environment.

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[1]But see Liautaud et al. (2019) for the role of dispersal in smoothing abrupt transitions.

At each location k on the gradient, the environmental factor has a distinct physical baseline value B_k representing its state in the absence of environment modification. Species, however, can affect the environmental value E_k by pushing it toward their preferred value C_i at a maximum rate m_i, which we call the niche construction rate. These species will be called "ecosystem engineers". The environment tends to return spontaneously to its baseline value B_k at a rate μ. The dynamics of the environmental factor at location k is therefore:

$$\frac{dE_k}{dt} = \mu(B_k - E_k) + \sum_i m_i \frac{N_{i,k}}{K_i^{\mathrm{max}}}(C_i - E_k) \tag{3}$$

where abundance $N_{i,k}$ is rescaled by its maximum K_i^{max} so that m_i is the maximum rate at which species i can affect the environment. In this study, we assume that species' carrying capacities are only influenced by a single factor E, although we recognize that many abiotic factors can also affect K in nature. The presence of direct competition between species can also have an influence on species distributions in space (Liautaud et al., 2019), we describe this case in Appendix A3. In this simplified model, the only role played by growth rates is to determine how fast species reach their carrying capacities, and which equilibrium is reached from given initial conditions when there are multiple equilibria. The identification of alternative equilibria in described in the next section.

2.2   Potential landscape and alternative equilibria

To predict the long-term spatial patterns created by dynamics (1) and (3), we propose a simple method for finding their equilibria at each location k along the gradient. This method is based on the notion of potential landscape, whose role in ecology was pioneered by Holling (1973).

Let us consider a local community at a given location k with baseline environmental state B_k. If species population dynamics are much faster than that of the environment ($r \gg \max(m_i, \mu)$) we expect that species quickly reach their carrying capacity for a given environment value, $N_{i,k} = K_i(E_k)$, while E_k changes over longer time scales according to :

$$\frac{dE_k}{dt} = \mu(B_k - E_k) + \sum_i m_i \frac{K_i(E_k)}{K_i^{\mathrm{max}}}(C_i - E_k) \tag{4}$$

We show in the Appendix A2.1 that this can be expressed as a gradient descent dynamics,

$$\frac{dE_k}{dt} = -\frac{d}{dE_k}U(E_k) \tag{5}$$

where $U(E_k)$ is a potential function. This equation imposes that, from any initial condition, the variable $E_k(t)$ always moves over time toward the closest minimum of $U(E)$, and then stays there at equilibrium. This potential takes the form:

$$U(E_k) = U_E(E_k) + U_{sp}(E_k) \tag{6}$$

where $U_E(E_k)$ represents the contribution of abiotic processes returning the environment to its baseline state, with

$$U_E(E_k) = \frac{\mu}{2}(E_k - B_k)^2 \tag{7}$$

and $U_{sp}(E_k)$ represents the species' contribution

$$U_{sp}(E_k) = -\sum_i m_i T_i^2 \exp\left[-\frac{(E_k - C_i)^2}{2T_i^2}\right] \tag{8}$$

which we illustrate in Fig.1 for a single species. The relative effect of abiotic and biotic factors in encapsulated in the ratio :

$$\gamma_i = \frac{m_i}{\mu} \tag{9}$$

such that niche construction is weak for $\gamma \ll 1$ and strong for $\gamma \gg 1$. This parameter will be termed "niche construction strength".

This potential landscape provides an intuitive interpretation of the action of engineer species. In the absence of niche construction ($m_i = 0$), the only minimum of $U(E_k)$ is at the physical baseline $E_k = B_k$. When present, ecosystem engineers "dig" in that landscape, creating wells of width T_i centered on their preferred value C_i. As we see in Fig.1, weak engineering only slightly

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145 displaces the equilibrium, while strong engineering can create an alternative equilibrium, or even

146 overcome abiotic dynamics entirely.

147 We also show in the Appendix A2.1 that, for arbitrary values of the rates r, m_i and μ, the

148 dynamics of $E_k(t)$ become more complex than a gradient descent (i.e. the function $U(E_k)$ can

149 increase for part of the time), but all possible equilibria are still given by the minima of the

150 potential $U(E_k)$ defined in (6).

151 ## 2.3   Numerical simulations

152 In the presence of a single ecosystem engineer, the niche construction strength (γ) is expected to

153 be the main driver of the dynamics. We thus study the influence of this parameter on the shape

154 of potential landscape, and the consequences for species' distribution in space.

155 In diverse communities, the similarity of species in their ressource use or environmental require-

156 ments has been shown to influence species interactions (Abrams, 1983; MacArthur and Levins,

157 1967; Levin, 1970), and species distribution in space (MacArthur, 1972). Therefore, we study how

158 the difference in the environment optimum of the various species (ΔC) and the niche construction

159 strength (γ), can influence the nature and intensity of species interactions (I) in a two-species

160 system. To do this, we compute the abundance of a species 1 when alone (N_{1a}), or in the presence

161 of a second species 2 (N_{1b}), for different values of (γ, ΔC). We use the relative change in the

162 abundance of species 1 as a measure of the net effect of species 2 on species 1 :

$$I_{12} = \frac{N_{1b} - N_{1a}}{N_{1a}} \tag{10}$$

163 In our study, the two species have equal niche construction abilities, but distinct environment

164 optima. In the case where bistability is observed, we only study the equilibrium for which species

165 1 predominates ($C_1 = 40$, $C_2 = C_1 + \Delta C$, $E_{t=0} = B = 50$). We then extend these results to a

166 larger number (S) of engineer species.

167 To address the role of these different factors - ($\gamma, \Delta C$, S) - on community pattern in diverse

168 communities, we study an environmental gradient of 101 cells ranging from $k = 100$ to $k = 200$ in

169 arbitrary units, with a step size of 1. The baseline value of the environment gradually increases

170 along the gradient, as $B_k = k$. The centres of the fundamental niches of the various species, C_i,

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171 are randomly assigned following a uniform distribution between 0 and 300, so that species may

172 have their niche centre in or outside the studied zone initially.

173 The model is run independently on each cell. The initial value of the environment at each

174 location equals its baseline value($E_k(t = 0) = B_k$). For all simulation results in the main text,

175 species were given equal maximal carrying capacity $K^{\max} = 1$ and tolerance range $T \leq 10$.

176 Environmental return rate is set to $\mu = 1$, and species intrinsic growth rate is set to $r = 10$. Under

177 these conditions, with $r \gg \mu$, species quickly reach their carrying capacity, with $N_{i,k} = K_{i,k}(E)$

178 (see 2.2). Initial species abundances are set equal for all species in all locations. We run the model

179 with different values of the different parameters of interest (γ, ΔC, S) until $t = 1000$, and verify

180 that the equilibrium is reached.

3 Results

3.1 Effects of niche construction strength on local equilibria

183 In the case where niche construction is weak ($\gamma = 0.1$, Fig. 1), the dynamics goes towards the

184 environmental baseline value B. However, when the niche construction strength of a species in-

185 creases ($\gamma = 5$), it becomes able to influence the environment. With increasing niche construction,

186 the species becomes able to create an alternative stable equilibrium, which corresponds to an envi-

187 ronment value close to its optimum ($\gamma = 10$). For a very high niche construction ability ($\gamma = 100$),

188 the species environment optimum becomes the single stable equilibrium in the system.

189

3.2 Engineer similarity, attractors and species interactions

191 Here we study the influence of the difference in engineers' environment optima (ΔC) on the po-

192 tential landscape. For 2 species with a high niche construction rate ($\gamma \to +\infty$, Fig. 2, a) ΔC

193 determines the number of attractors in the system. We can calculate a threshold θ of ΔC that

194 separates cases in which species' contributions to the potential (U_{sp}, Eq 6) create a single attrac-

195 tor, from cases where two attractors are observed. When $\Delta C > \theta$, there are two minima in U_{sp} .

196 As we have assumed that the abiotic contribution $U_E(E)$ is negligible, the species create distinct

197 minima in the potential $U(E)$ (red curve) that correspond to distinct attractors (i.e alternative

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stable states), in which the environment is optimal for either of the two species (Fig. 2, a, I). By contrast, when $\Delta C < \theta$, there is a single minimum in U_{sp}. In this case, the two species create a common well in the potential landscape, which corresponds to a single equilibrium in between the two species' optima (Fig. 2, a, II). We show in the Appendix A2.2 that $\theta = 2T$ for species with equal tolerance ranges T and maximal carrying capacities K_{max}.

The similarity (ΔC) of engineers therefore influences the nature and intensity of species net interactions. When niche construction is weak and the similarity in environmental optima is high, the abundance of species 1 is increased when associated with species 2 (Fig. 3, red). The relative increase in species 1's abundance in association with species 2 can reach 8% when compared with its abundance when alone, indicating a positive net interaction between the two species ($I > 0$). By contrast, when niche construction is high and dissimilarity in environment optima is high, species 1 has a lower abundance in the presence of species 2 (Fig. 3, blue, indicating a negative net interaction ($I < 0$)). The relative decrease in the abundance of species 1 in the presence of species 2 can reach more than 30%, and is maximal for $\Delta C \approx \theta$. For a given niche construction rate γ, indirect interactions can thus be alternatively positive or negative, depending on the species' similarity ΔC.

The diversity of ecosystem engineers also has an influence on system properties. In the case where species have weak niche construction abilities ($\gamma = 1$, Fig. 2, b), a single species is unable to create a well in the potential. Instead, the environment controls the dynamics and the only equilibrium corresponds to the environment baseline B. By contrast, when several weak engineer species with close optima are present, they are able to dig a common well in the potential landscape (Fig. 2, b, II). This leads to the emergence of an alternative stable equilibrium, in which the environment lies between the various species' optima.

3.3 Influence of engineer similarity on species distribution and environmental changes in space

As described in section 3.2, the similarity of species environment optima (ΔC) influences the number of stable equilibria. When two ecosytem engineers are present along an environmental gradient, different community patterns can emerge, depending on ΔC. In the case where $\Delta C > \theta$ (Fig. 4, I), each species pushes the environment to its own optimum. Along an environmental

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gradient, this leads to the emergence of distinct zones where the environment is driven close to the respective species optima. These zones are separated by abrupt changes in both the environment (Fig. 4,I,b) and species abundances (Fig. 4,I,c). Within these zones, each species is dominant in the spatial extent over which it controls the environment (Fig. 4,II). A distinct pattern emerges in the case where $\Delta C < \theta$, with the two species pushing the environment between their respective optima. This leads to the emergence of a single spatial zone where the environment is modified, and allows species coexistence at high abundances (Fig. 4, II, b-c). The transition between zones where the species can or cannot modify the environment is abrupt, with a discontinuity in both the environment and species abundances.

3.4 Spatial community patterns in diverse communities

We now extend these results to many-species communities. In the case where several strong ecosystem engineers are present ($\gamma_i = 10$), we observe discrete communities in space, separated by sharp boundaries where important changes in both the abundance of ecosystem engineers (blue curves, Fig. 5, I) and in the environment (Fig. 5, I, b) occur. Non-engineers species ($\gamma_i = 0$, black curves) follow this pattern, with abrupt changes in their abundances. The bifurcation diagram shows the existence of alternative stable states, with different environment equilibria for a given location in space (Fig. 5, I, b). Similar patterns are observed when there are numerous weak ecosystem engineers ($\gamma = 2$), with the coincidence of abrupt changes in both the environment and species abundances in space. We observe much fewer discrete zones than there are engineers, because of the fusion of their potential wells (see section 3.2).

4 Discussion

In this work, we investigated the role of biodiversity and species interactions in the emergence of ecotones through ecological niche construction. In particular, we studied the respective contributions of niche construction strength (γ), similarity in the environment optimum of the species (ΔC) and diversity (S). Our results show that, depending on the engineering strength γ, the contribution of biodiversity to ecotone emergence will be either through the similarity of species' environmental optima ΔC, or through the diversity of engineering species S.

In the case of a single ecosystem engineer acting on the environment, discontinuities occur when a high niche construction rate (γ) allows the engineer to control its environment. These abrupt shifts are explained by the presence of two alternative stable states in the system that correspond to: 1) a modified state, with the environment close to the engineer's optimum, and 2) a non-modified state, corresponding to the baseline value of the environment. A small change in the environmental conditions can thus lead to an abrupt shift from one attractor to the other.

In the case where species are strong ecosystem engineers, the difference in environmental optima (ΔC) is the main contribution of biodiversity to the emergence of ecotones. The presence of various engineers with distinct environment optima leads to the emergence of indirect interactions that influence the community patterns. We showed in a two-species system that these indirect interactions can be competitive or mutualistic, depending on the value of the difference ΔC.

When engineers have distant environmental optima and strong engineering abilities, their net interaction is competitive. At a given location, a species has a lower abundance when associated to a second engineer, as compared with its abundance when alone. Indirect competition through the environment can be observed in cases where there is multistability in the system, but also when a single equilibrium exists. In the extreme case where the modified environmental conditions are outside the other species' fundamental niche, the latter can be excluded. By contrast, when the species' environmental optima are close, with weak engineering abilities, we observe the emergence of net mutualistic interactions. In these cases, the two species are able to improve their carrying capacities, by modifying the environment to their mutual benefit. The abundance of a species is thus higher when associated with another engineer. In our study, the more species differ in their environmental optima, the stronger the negative effect they have on each other. This differs from classical limiting similarity theory (Abrams, 1983; MacArthur and Levins, 1967). Considering limiting resources such as water or light, limiting similarity theory predicts an increase in competition strength as the similarity in the resource requirements of the various species increases. By contrast, when species modify the abiotic environment to their own benefit, we showed that competition decreases, and then can turn into a net mutualistic interaction as the similarity of species' environmental optima increases.

With more than two strong engineers along the gradient, engineers with close optima will tend to modify the environment to their collective benefit. When the ability of a community to modify

the environment becomes higher than the ability of another one, the former will replace the latter along environmental gradients. This can be interpreted as a situation where there is competition between communities. In this case, the community shows a high level of integration (Clements, 1916; Wilson and Sober, 1989). This type of community organization tends to create particular species abundance patterns in space, with discrete communities separated by sharp boundaries.

In the case where the species are weak ecosystem engineers, the main contribution of biodiversity to community organization is through the number of engineering species. In this case, a weak ecosystem engineer alone is not able to substantially modify the environment and create a species-environment feedback. But when numerous weak engineers with similar optima are present, we do observe the emergence of species-environment feedbacks. In these cases, species jointly modify the environment to their collective benefit, as described above. In our model, an increase in species diversity can lead to an increase in each species' biomass, through facilitation. The collective action of a large number of different ecosystem engineers can thus lead to the emergence of discrete communities along an environmental gradient, associated with sharp changes in the environment. In this study, the effect of several weak ecosystem engineers on the environment is not qualitatively different from the effect of a single strong engineer, but the spatial extent of the environmental change may be larger. The existence of several species may indeed broaden the spectrum of abiotic conditions under which the environment is modified, as seen in the case of positive interactions between two engineers. Biodiversity is potentially a key factor influencing the emergence of species-environment feedbacks in nature, and thus the emergence of sharp ecotones separating discrete communities. This might be the case in mangrove ecosystems, where several species can have similar effect on water salinity (Sternberg et al., 2007). As shown in this study, a certain level of biodiversity in ecosystem engineers might be necessary to maintain species-environment feedbacks. Likewise, Gonzalez et al. (2008) showed that the accumulation of small environmental changes by weak engineers can ultimately lead to a substantial change in the abiotic environment, and thus allow an ecosystem engineer to invade. A decrease in biodiversity, as currently observed worldwide (Pimm et al., 2014; Ceballos et al., 2015), might thus have important consequences, not only for community composition and organization, but also for the abiotic environment and for ecosystem functioning.

Species that do not modify their environment can also be influenced by ecological niche con-

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struction. By changing the environment, ecosystem engineers can promote species that benefit more from the modified state than the baseline conditions. In this case, ecosystem engineers indirectly facilitate other species through environmental modification. Facilitation has been shown to occur, particularly under harsh environmental conditions, such as in arid ecosystems (Soliveres and Maestre, 2014; Vega-Álvarez et al., 2018; Armas and Pugnaire, 2005) or in cold environments (Choler et al., 2001; Callaway et al., 2002). When an engineer facilitates another species, it can be considered as a "nurse species" (Niering et al., 1963) that modifies the environment and allows the growth of species that would not have the ability to grow otherwise. Nevertheless, ecosystem engineering can also have negative effects on other species. For example, van Breemen (1995) showed how *Sphagnum* species can depress the growth of vascular plants by changing the environmental conditions in peat bogs ecosystems. A sharp ecotone can thus be explained by the appearance or disappearance of an engineer along the gradient, facilitating or preventing the growth of other species. In the case where species do not modify the environment to their own optimum, succession in time can be observed. In this case, the engineer can foster the growth of its successors, thus having a negative impact on its own performances (Appendix A4).

Species interactions - such as competition or mutualism - have been identified as drivers of species abundance along environmental gradients (Terborgh and Weske, 1975; Choler et al., 2001). We have shown in this paper that interactions between species and the abiotic environment can have unexpected consequences on species interactions themselves. These interactions can lead to the emergence of discontinuities in the environment, associated with sharp ecotones where important species turnover are observed . Explicit consideration of species-environment feedbacks is thus likely to increase our understanding of species distributions along environmental gradients. It may similarly be essential when studying the responses of species or communities to temporal changes in their environment. Finally, we have also shown that biodiversity can influence community organization along an environmental gradient. Current biodiversity loss can have major consequences for species distributions, abiotic environmental conditions, and ecosystem functioning.

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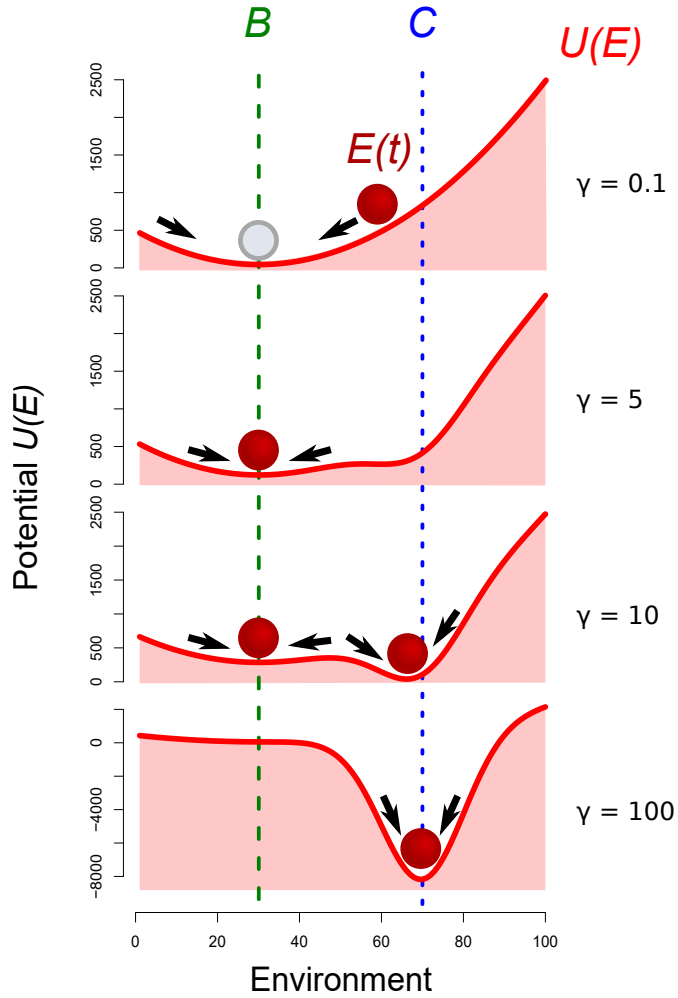
Figure 1: Representation of the environment as a potential under the action of physical processes and an ecosystem engineer. The ball representing the environmental state $E(t)$ follows the arrows down the slope until it reaches an equilibrium value, corresponding to a minimum of the potential function $U(E)$ (denoted by the solid curve). B is the baseline environment value, and C is the species' environmental optimum. Four parameter conditions are depicted, from weak engineering ($\gamma = 0.1$) to strong engineering ($\gamma = 100$).
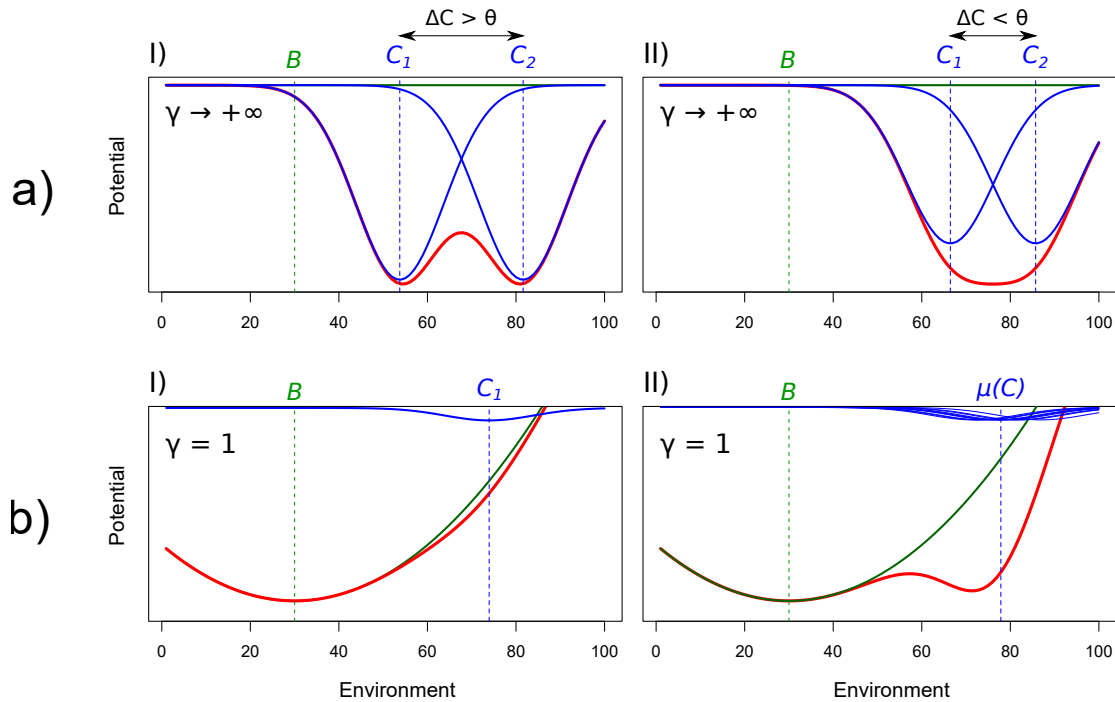
Figure 2: Influence of the similarity in species' environmental optima (ΔC) and diversity (S) on the potential landscape. Blue and green curves show the contributions of species ($U_{sp}(E)$) and environment ($U_E(E)$), respectively, to the potential $U(E)$ (red curve). a) : Influence of strong ecosystem engineers ($\gamma = +\infty$) on the potential landscape for two values of optimum similarity ΔC. θ represents the threshold in ΔC that separates cases in which species' contribution to the potential ($U_{sp}(E)$) show one or two minima. b) : Influence of diversity in engineering species on the potential landscape for two levels of diversity : $S = 1$ (I) and $S = 10$ (II), for low niche construction strength ($\gamma = 1$).
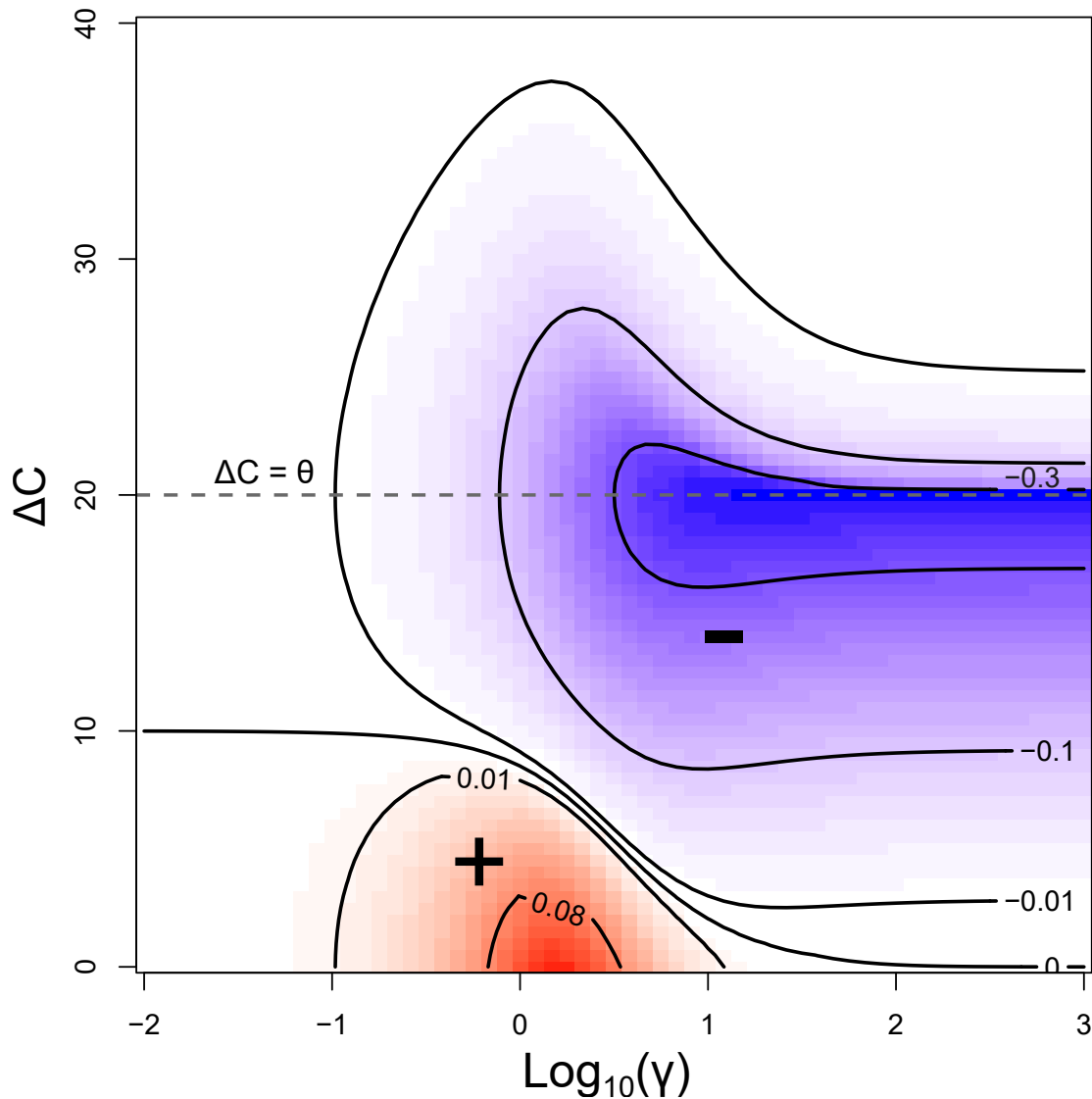
Figure 3: Emerging net species interactions as a function of the similarity of species' environment optima (ΔC), and niche construction strength (γ). Parameter values for which net competitive interactions (-) are observed are depicted in blue, whereas net mutualistic interactions (+) are depicted in red. Interaction strength is measured by the relative change in the abundance of species 1 when associated with species 2, compared with its abundance when alone (Eq. 10). **Dashed line** $\Delta C = \theta$ represents the threshold in environment optimum similarity that separates cases in which species' contribution to the potential shows one or two minima. In the case where bistability is observed, we only study the equilibrium for which species 1 predominates ($C_1 = 40$, $C_2 = C_1 + \Delta C$, $E_{t=0} = B = 50$).
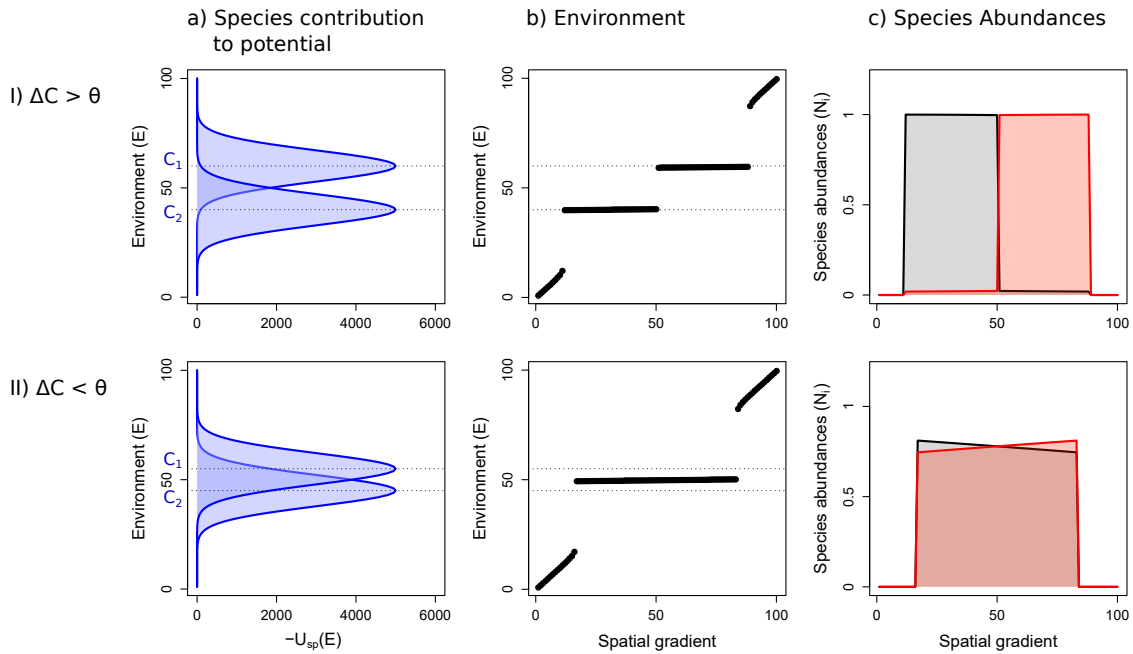
Figure 4: Influence of the similarity in ecosystem engineers on species distributions and the environment along a spatial gradient. We show results for : I) a difference in species' environmental optima ΔC larger than the threshold θ, II) a difference in species' environmental optima ΔC smaller than the threshold θ. (a) : Species contribution - $U_{sp}(E)$ - to the potential $U(E)$. (b) : Value of the environment along the spatial gradient . (c) : Species abundances along the spatial gradient at equilibrium. In the two depicted cases, species are strong ecosystem engineers ($\gamma = 10$).
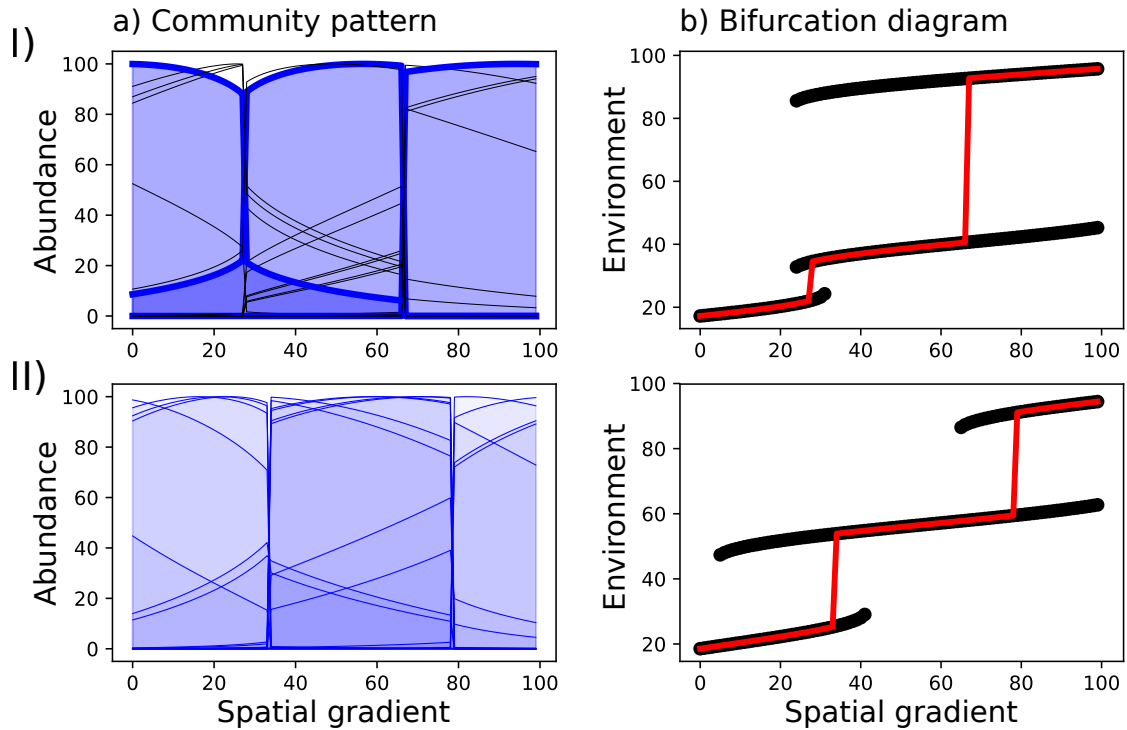
Figure 5: Species abundances along a spatial gradient (a) and bifurcation diagrams (b) in the case where: I) both strong ecosystem engineers ($\gamma = 10$, bold blue curves) and non-engineers ($\gamma = 0$, black curves) are present, II) numerous weak ecosystem engineers ($\gamma = 2$, blue curves) are present. In bifurcation diagrams (b), black curves represent all potential stable equilibria, and red lines represent equilibria observed in depicted cases in (a). Many weak engineers create fewer zones than there are engineers, and a pattern similar to the case where there are a few strong engineers.