

1 **embarcadero:**
2 Species distribution modelling with Bayesian
3 additive regression trees in R

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7 Submitted to *Methods in Ecology and Evolution* on September 18, 2019

8 **Abstract**

9 1. Classification and regression tree methods, like random forests (RF) or
10 boosted regression trees (BRT), are one of the most popular methods of
11 mapping species distributions.

12 2. Bayesian additive regression trees (BARTs) are a relatively new alterna-
13 tive to other popular regression tree approaches. Whereas BRT iteratively
14 fits an ensemble of trees each explaining smaller fractions of the total vari-
15 ance, BART starts by fitting a sum-of-trees model and then uses Bayesian
16 backfitting with an MCMC algorithm to create a posterior draw. So far,
17 BARTs have yet to be applied to species distribution modeling.

18 3. **embarcadero** is an R package of convenience tools for researchers in-
19 terested in species distribution modeling with BARTs. It includes function-
20 ality for spatial prediction, an automated variable selection and importance
21 procedure, and other functionality for rapid implementation and data visu-
22 alization.

23 4. To show how **embarcadero** can be used by ecologists, we re-map the distri-
24 bution of Crimean-Congo haemorrhagic fever and a likely vector, *Hyalomma*
25 *truncatum*, in Africa.

26 **Keywords:** Bayesian additive regression trees, species distribution model-
27 ing, ecological niche modeling, Crimean Congo haemorrhagic fever
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32 1 Introduction

33 In the last two decades, over a dozen statistical and machine learning methods have
34 been proposed for species distribution modeling (SDM). Over time, a handful of
35 methods have risen to predominance due to ease of implementation, computational
36 speed, and strong predictive performance in rigorous cross-validation. Some meth-
37 ods are especially popular for specific applications, mostly because of disciplinary
38 tradition. For example, maximum entropy (MaxEnt) models are widely popular
39 for studies of global ecological responses to climate change. (VanDerWal *et al.*,
40 2013; Warren *et al.*, 2013) In disease ecology, boosted regression trees (BRTs) have
41 become the dominant tool for mapping vectors, reservoirs, and transmission risk of
42 infectious zoonoses and vector-borne diseases (Carlson *et al.*, 2019; Pigott *et al.*,
43 2014; Messina *et al.*, 2016), largely due to an influential 2013 paper on dengue
44 virus. (Bhatt *et al.*, 2013)

45 Boosted regression trees are easily implemented as an out-of-the-box machine
46 learning method, are powerful for ecological inference, and consistently perform
47 well in rigorous tests of SDM performance. The classification tree approach is also
48 more intuitive than the complex fitting procedures “under the hood” of MaxEnt
49 or Maxlike methods. However, BRTs also have downsides: they can be prone
50 to overfitting, and fitting procedures are largely handed down as anecdotal best
51 practices, with most studies choosing learning rates and tree depth based on the de-
52 fault settings recommended by early work (Elith *et al.*, 2008), with very few studies
53 selecting parameters from formal cross-validation with packages like `caret`. Fur-
54 thermore, uncertainty is usually measured by generating an unweighted ensemble
55 of BRT submodels over subsetted training data, generating a confidence interval
56 from data permutations rather than formal assumptions about model uncertainty.

57 In this paper, we propose the use of a Bayesian alternative to boosted regression
58 trees, called *Bayesian additive regression trees* (BARTs), for the problem of species
59 distribution modeling. In computer science, BARTs are used for everything from
60 medical diagnostics to self-driving car algorithms (Sparapani *et al.*, 2018; Tan
61 *et al.*, 2018); however, they have yet to find any widespread application in ecology.
62 A study from 2011 used BARTs as a tool to examine habitat selection data on
63 birds (Yen *et al.*, 2011); a 2017 study used BARTs to evaluate performance data of
64 other species distribution modeling methods. (Farley, 2017) But so far, they have
65 not been used for the purpose of predicting species distributions. We introduce an
66 R package, `embarcadero`, as a convenience tool for running SDMs with BARTs.

67 **2 Bayesian additive regression trees**

68 Whereas BRTs fit an ensemble of trees each explaining smaller fractions of unex-
69 plained variance, BART starts by fitting an initial sum-of-trees model, and then
70 uses Bayesian backfitting with an MCMC algorithm to create a posterior draw.
71 The Bayesian component of BART is designed to have minimal user input, making
72 it an unusually out-of-the-box algorithm as Bayesian SDM methods go. The priors
73 set for covariates and for the distribution of splitting rules are both uniform by
74 default. (Chipman *et al.*, 2010) The remaining priors, which govern tree depth and
75 the error distribution, are given a set of default hyperparameters that are robust
76 enough for the developers of the method to have recommended automated tuning.
77 The number of trees is the main free parameter; a default of 200 is recommended,
78 though cross-validation can be used to tune this very easily.

79 **3 SDMs with BARTs**

80 **3.1 Using dbarts and embarcadero**

81 At least four R packages currently exist that can implement BARTs: `BayesTree`
82 (Chipman & McCulloch, 2016), `bartMachine` (Kapelner & Bleich, 2013), `BART`
83 (McCulloch *et al.*, 2018), and `dbarts` (Chipman *et al.*, 2014). Their functionality
84 differs in important ways, and not all of them are currently capable of important
85 features like partial dependence plots that are important for SDMs. Our package
86 is an SDM-oriented workflow wrapper for `dbarts`, which includes most of the
87 basic functionality needed for species distribution modeling: BART models with
88 binary response variables, multithread model training, easy generation of partial
89 dependence surfaces (including two-predictor plots and spatial projections), and
90 simple prediction including full posteriors. Compared to other packages, `dbarts`
91 only has one major limitation. In future versions, we hope to make `embarcadero`
92 flexible for work with any underlying engine.

93 **3.2 Variable selection**

94 Variable importance can be measured in BART models by counting the number
95 of times a given variable is used by a tree split across the full posterior draw of
96 trees. (This is similar to variable importance in BRTs, which is calculated from

97 the number of tree splits and the corresponding improvement they cause in the
98 model.) Because the trees are weak learners, in models with higher numbers of
99 trees, the difference in variable importance becomes less pronounced, and less in-
100 formative variables become more commonly represented. Consequently, variable
101 selection can be performed by observing variable importance in models with pro-
102 gressively fewer trees, and selecting variables that have improved performance in
103 progressively smaller ensembles. (Chipman *et al.*, 2010) In our package, variable
104 importance can be calculated with `varimp`, and variable selection diagnostic plots
105 can be generated with `varimp.plot`.

106 As a way to standardize inclusion rules across workflows, we implemented an
107 automatic variable elimination procedure in `variable.step`, which (1) fits a full
108 model with all predictors and a small tree ensemble (default $m = 10$), a fixed
109 number of times ($n = 50$); (2) eliminates the least informative variable across all
110 50 runs; (3) re-runs the models again ($n = 50$), recording the root mean square
111 error; (4) repeats steps 2 and 3 until there are only three covariates left; and (5)
112 finally selects the model with the lowest average RMSE is selected. The variable
113 sets recommended by this procedure are almost always nearly identical to the sets
114 generated from a subjective reading of the diagnostic plots.

115 We recommend careful analysis of all diagnostic information, but include a
116 full automated variable selection pipeline in `bart.var`, which (a) produces the
117 initial multi- m diagnostic plot, (b) runs automated variable selection, (c) returns
118 a model trained with the optimal variable set, (d) plots variable importance in the
119 final model, and (e) calculates the AUC of the final model. Despite automation,
120 this procedure is not a fail-safe against the inclusion of uninformative predictors,
121 or false inference on them; this is true of almost all methods, and predictors
122 should always be chosen based on at least some expert opinion about biological
123 plausibility. (Fourcade *et al.*, 2018) Similarly, validation of partial dependence
124 curves against biological knowledge should be treated as an additional level of
125 model validation, potentially more informative than measuring predictive accuracy.
126 (Warren *et al.*, 2019)

127 3.3 Visualizing model results

128 BART model predictions can be visualized several ways using `embarcadero`. Un-
129 fortunately `dbarts::bart.predict` cannot handle spatial data in its native for-
130 mat. For spatial prediction, we provide `bart.map` as a wrapper, which can also

131 pull the 5% and 95% credible interval layers from the posterior distribution. These
132 raster layers can be exported to other spatial data packages in R, or external soft-
133 ware like ArcGIS or QGIS, for more professional visualization.

134 We include several methods for generating partial dependence plots. The func-
135 tion `partial` is written as a wrapper for `dbarts::pdbart`, and can be used to
136 generate partial dependence plots with a customizable aesthetic, including multi-
137 ple ways of visualizing uncertainty. (As with overall predictions, credible intervals
138 on partial plots are true Bayesian credible intervals.) Two-dimensional partial de-
139 pendence plots (interactions among two predictor variables) can also be generated
140 using `dbarts::pd2bart`. Finally, we designed a new visualization called *spatial*
141 *partial dependence plots*, which reclassify predictor rasters based on their partial
142 dependence plots, and show the relative suitability of different regions for an in-
143 dividual covariate. The `spartial` function can be used to generate these maps,
144 and answer questions like “What desert regions are too arid, even in their wettest
145 month, for spadefoot toads?” or “Where are the soils with the best pH for redwood
146 growth?” We illustrate some of these visualization options in Figure 1.

147 3.4 Notes on model performance

148 The strength of a given SDM method is very rarely resolved in a single study, and is
149 challenging to understand in the context of “real world” datasets. Simulation stud-
150 ies have become common practice as a way to unpack model performance relative
151 to confounding factors, such as sample size and bias, pseudoabsence design, and
152 colinearity among predictors; each of these is usually worth testing in isolation.
153 Moreover, the definition of “performance” is subjective, and SDMs are used for
154 several (sometimes conflicting) purposes in ecology (Guillera-Arroita *et al.*, 2015);
155 for example, methods that usually perform well in overall accuracy may not nec-
156 essarily handle variable importance well. (Smith & Santos, 2019) Ultimately, the
157 most comprehensive “bake-off” studies, with dozens of methods tested by dozens
158 of authors, have usually found that more recent and popular methods like MaxEnt
159 or BRTs are more sensitive to poor calibration than they are discrepant with each
160 other. (Norberg *et al.*, 2019)

161 In this descriptor, we did not compare the performance of BARTs to other
162 methods using AUC or comparable accuracy metrics, because our aim was not
163 to produce a method that universally outperforms `gbm` or more distantly related
164 methods. Instead, we aimed to produce an accessible environment for explor-

165 ing BARTs, and to propose their use for SDMs as an approach with different
166 conceptual strengths than existing methods. BART is a nice compromise be-
167 tween Bayesian prediction—which works well in SDM, but has yet to become
168 widely popular—and the conceptual familiarity and strengths of regression tree
169 approaches like BRTs. Some other Bayesian methods for SDMs have been pro-
170 posed, but are not widely adopted (Golding & Purse, 2016; Redding *et al.*, 2017),
171 possibly due to the dominance of more familiar model families. Most importantly,
172 BARTs handle uncertainty with formal Bayesian logic, and generate a posterior
173 from a single model implementation. We argue this is more coherent than how
174 uncertainty is usually generated for BRTs, with several hundred BRTs trained
175 as a usually-unweighted ensemble on randomly-subsetted training data. This in-
176 herently reduces the training sample size and amplifies within-sample biases (es-
177 pecially geographic biases) fed into every submodel, and produces a “confidence
178 interval” that lacks a formal statistical definition as such. We believe the structure
179 of BART makes it easier to include uncertainty in applied tasks using SDMs, like
180 estimating the population at risk from a given pathogen.

181 4 Example: Crimean-Congo Haemorrhagic Fever

182 Crimean-Congo haemorrhagic fever virus (CCHFV) is a tick-borne Bunyavirus
183 that causes extremely severe, and often fatal, illness in humans. Very little is
184 known about CCHFV, compared to other cosmopolitan tick-borne illnesses like
185 Lyme disease or tularemia. The definitive reservoir of CCHFV is unknown but
186 likely ungulates (Babayan *et al.*, 2018); outbreaks frequently affect sheep and other
187 domestic ruminants, and other members of the Nairoviridae infect similar hosts.
188 The vectors of CCHFV are better known, and are presumed to almost always be
189 *Hyalomma* ticks, which are widespread throughout Africa and Eurasia; other tick
190 vectors have been suspected, but evidence for their competence is limited. (Papa
191 *et al.*, 2017) In Africa, *Hyalomma truncatum* in particular is common throughout
192 rangeland and is one of the strongest candidates for a primary vector. (Logan
193 *et al.*, 1989; Wilson *et al.*, 1991)

194 A global map of Crimean-Congo haemorrhagic fever has been previously been
195 produced with boosted regression trees; a significant amount of the Black Sea
196 region was suitable, while areas outside had highly localized predictions of suit-
197 ability, presumably because of data sparsity in Africa especially. (Messina *et al.*,

2015b) However, some major areas of presence appeared under-predicted, such as
the western Congo Basin. To demonstrate the use of BARTs, we re-mapped trans-
mission risk in Africa using the same original CCHF occurrence dataset (Messina
et al., 2015a). Just as studies of dengue have included suitability for *Aedes aegypti*
as a covariate, our model included a suitability layer for *Hyalomma truncatum*,
which we created using the canonical dataset on African tick distributions. (Cum-
ming, 1998); all code for these models and their visualization is available as a
detailed 30-page vignette with the package.

Both the *Hyalomma* model and the CCHF model were also run with 11 envi-
ronmental covariates: eight average and monthly variables from WorldClim (BIO
1, 2, 5, 6, and 12–15; Hijmans *et al.* 2005), layers for mean and amplitude of
NDVI previously used to map anthrax (Carlson *et al.*, 2019), and a layer of per-
centage cropland. (Ramankutty *et al.*, 2010) For both models we ran a BART
with default `dbarts` settings using the full variable set. We then ran automated
variable set reduction, made spatial predictions using the recommended variables,
and recorded the accuracy (*Hyalomma*: AUC = 0.911; CCHF: AUC = 0.898).
Our final model of Crimean-Congo risk included six variables: *H. truncatum* suit-
ability, mean and amplitude of NDVI, mean annual precipitation (BIO12), and
precipitation of wettest month (BIO13). The variable importance diagnostic for
the CCHF model is shown in Figure 2.

Our model predicts that the distribution of CCHF may be more geographically
expansive than previous studies have indicated (Figure 3). Areas of the highest
risk are still heavily concentrated in Sahel rangeland and east African highlands,
but also far more extensive in southern Africa and along the Atlantic coast than
previously believed. Although *H. truncatum* had a high importance in the final
model, and scaled positively with CCHF risk, our model still predicted some areas
outside of its range. In particular, our final CCHF map captured an area in
Gabon and the western Congo basin where occurrences have been recorded but *H.*
truncatum is likely absent, and another vector may be involved. This may raise
some interesting questions for future research.

5 Next steps

The `embarcadero` package is designed as a beginning framework for using BART
as a species distribution modeling method. Currently, `embarcadero` version 1.0.1

231 is available open source on Github, at github.com/cjcarlson/embarcadero and soon
232 it will be available on CRAN. We hope to continue to expand the package based
233 on user input and collaborative coding. The top priority for development is faster
234 (multithread) prediction, which remains computationally limiting for global map-
235 ping projects.

236 **Acknowledgements**

237 Thanks to Shweta Bansal and Jason Blackburn for research support, to Ethan Bea-
238 man for telling me about BARTs in the first place, to Zack Susswein for helpful
239 comments on design of Bayesian models, and to Tad Dallas for helpful comments.
240 This work was supported with a Georgetown Environment Initiative (GEI) post-
241 doctoral fellowship.

Figures

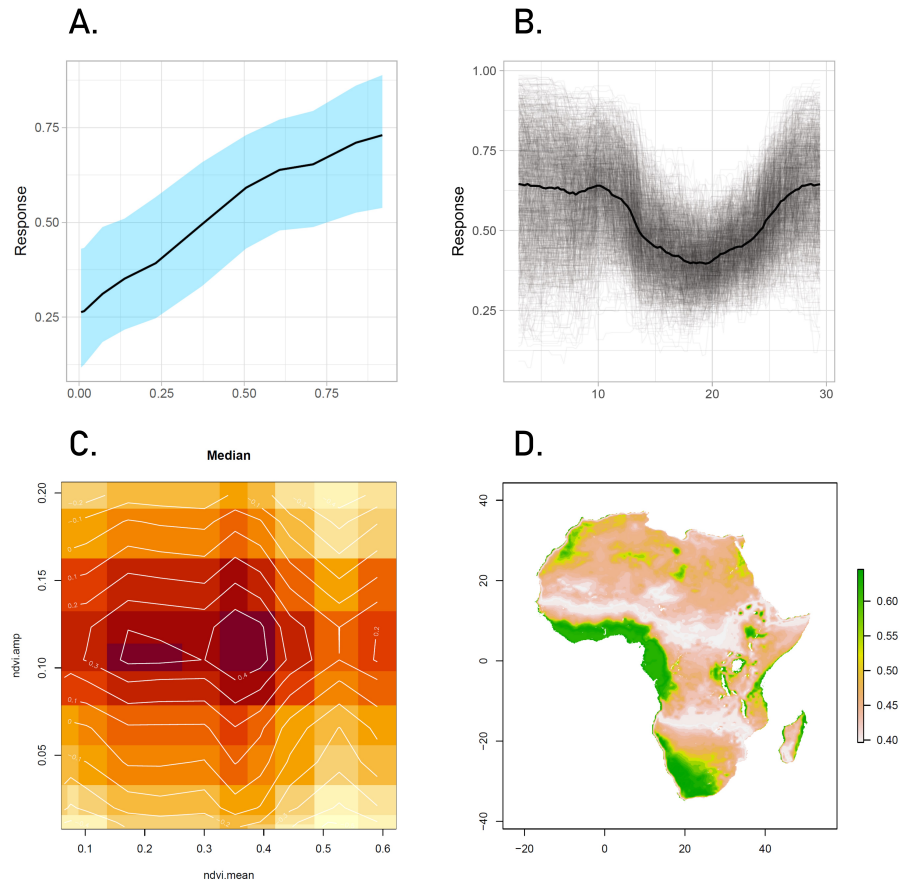


Figure 1: Partial dependence plots from the CCHF model (see Section 4), as examples of four different model visualization styles. (A) Partial dependence plot for *Hyalomma truncatum* suitability, blue bars show 95% posterior CI; (B) partial plot for BIO2 (mean diurnal range), where individual traces show every posterior draw; (c) a two-predictor partial plot for mean and amplitude of NDVI; and (d) a “spatial” plot for BIO12 (annual precipitation).

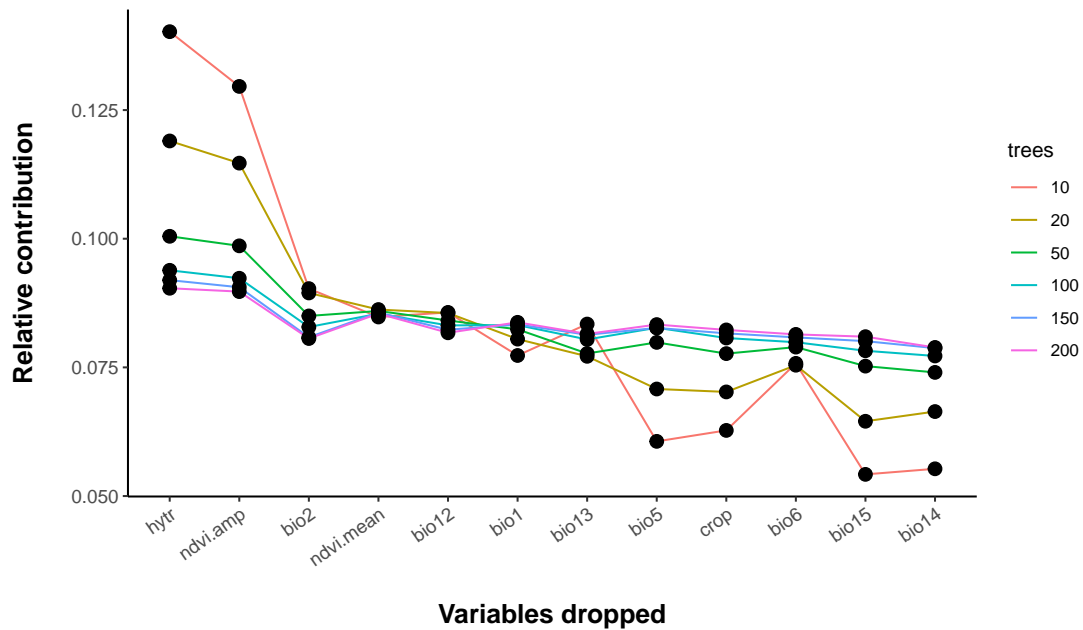


Figure 2: The variable selection diagnostic plot for the CCHF model, in the style of Chipman *et al.* (2010). Variables that are included more often in decision splits (the relative contribution) as the number of trees becomes smaller are more likely to be influential, real predictors. Variables that have increasing contributions as the number of trees increases, on the other hand, should be dropped.

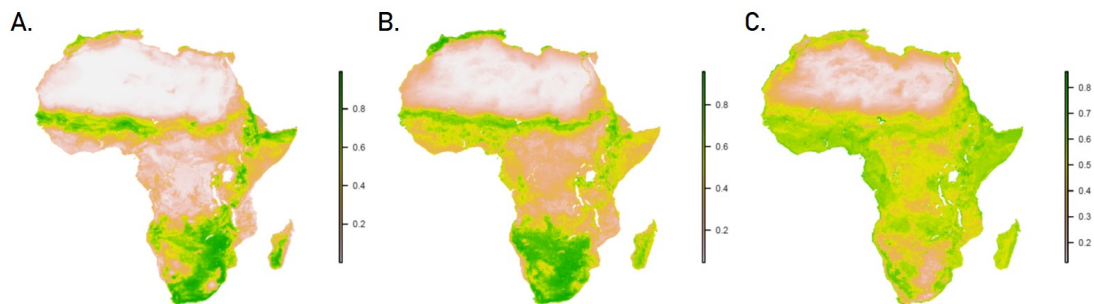


Figure 3: (A) Final posterior mean map of suitability for *Hyalomma truncatum*. (B) Final posterior mean map of suitability for Crimean-Congo haemorrhagic fever virus. (C) The 95% posterior credible interval width for the CCHF model.

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