Temperature shapes movement and habitat selection by a heat-sensitive ungulate

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Abstract

Context

20 Warmer weather caused by climate change poses increasingly serious threats to the persistence

21 of many species, but animals can modify behavior to mitigate at least some of the threats posed

22 by warmer temperatures. Identifying and characterizing how animals modify behavior to avoid

23 the negative consequences of acute heat will be crucial for understanding how animals will

24 respond to warmer temperatures in the future.

Objectives

27 We studied the extent to which moose (*Alces alces*), a species known to be sensitive to heat,

28 mitigates heat on hot summer days via multiple different behaviors: (1) reduced movement, (2)

29 increased visitation to shade, (3) increased visitation to water, or (4) a combination of these

30 behaviors.

Methods

33 We used GPS telemetry and a step-selection function to analyze movement and habitat selection

34 by moose in northeastern Minnesota, USA.

Results

Moose reduced movement, used areas of the landscape with more shade, and traveled nearer to

mixed forests and bogs during periods of heat. Moose used shade far more than water to

ameliorate heat, and the most pronounced changes in behavior occurred between 15˚C and 20˚C.

Conclusions

Research characterizing the behaviors animals use to facilitate thermoregulation will aid

conservation of heat-sensitive species in a warming world. The modeling framework presented

in this study is a promising method for evaluating the influence of temperature on movement and

habitat selection.

Key words

climate change, habitat selection, habitat use, lidar, moose (*Alces alces*), resource selection, step-

selection function, thermal refugia

Introduction

Physiological performance peaks within a limited range of body temperatures in which molecular, cellular, and systemic processes operate optimally. Body temperatures outside this range impose functional constraints on these processes, including reductions in growth, reproduction, activity, and immune function (Pörtner and Farrell 2008). Nevertheless, animals routinely operate in environmental conditions that trigger suboptimal body temperatures (Boyles et al. 2011; Sunday et al. 2014). This conundrum underlies two long-standing questions in biological research: (1) How do animals mitigate suboptimal thermal conditions, and (2) how effective are those efforts at mitigation? Rapid and ongoing responses to global climate change by a multitude of animal species (Walther et al. 2002; Parmesan 2006; Hoegh-Guldberg and Bruno 2010) increase the urgency of answering these questions.

Animals can relax the constraints of limited ranges of thermal tolerance by modifying their behavior to reduce heat gain and dissipate heat at high temperatures. Such behavioral thermoregulation has a long history of study in biological research (Cowles and Bogert 1944), but this idea still offers fresh insight today. Animals can restrict movement to produce less metabolic heat (Stelzner 1988; Broders et al. 2012), alter posture to reduce heat gain from insolation or increase surface area to shed heat (Luskick et al. 1978; Bartholomew and Dawson 1979), pant to lose heat via evaporation (Campos and Fedigan 2009; McCann et al. 2013), or visit thermal refugia (spaces that provide refuge from thermal stress caused by extreme temperatures [e.g., burrows, wallows, shade cover]; van Beest et al. 2012; Hovick et al. 2014; Kurylyk et al. 2015), among other behaviors. Identifying exactly which of these strategies animals use to behaviorally thermoregulate, how much these strategies buffer against adverse impacts of hot weather, and what costs animals incur to use these strategies is crucial for

understanding their ability to increase ranges of thermal tolerance, which in turn increases our

understanding of how animals may adapt (or not) to increasing temperatures in a warmer future.

Recent advances in statistical modeling techniques provide opportunity to study

behavioral thermoregulation in new ways. Step-selection functions (hereafter "SSFs") are an

extension of the resource selection function modeling framework that explicitly incorporates

spatial and temporal animal movement characteristics to enable examination of fine-scale habitat

selection and movement behavior at biologically realistic scales (Forester et al. 2009; Thurfjell et

al. 2014; Duchesne et al. 2015; Signer et al. 2019). SSFs have primarily been used to model

habitat selection (Thurfjell et al. 2014), but recent theoretical development has demonstrated that

they can also be used to explicitly model movement behavior that changes in both space and time

in relation to landscape features (Avgar et al. 2016; Prokopenko et al. 2017; Ladle et al. 2019;

Signer et al. 2019). By including interaction terms between temperature, habitat covariates, and

movement rates within SSFs, the relative importance of temperature-dependent animal

behaviors—including both resource selection and movement rates—can be quantified in a single

model.

We used the SSF modeling framework to examine behavioral thermoregulation in moose

(*Alces alces*), a species known to be sensitive to heat. Moose have undergone substantial

population declines across much of their southern range due in part to climate change (Lenarz et

al. 2010; van Beest et al. 2012; Dou et al. 2013; Monteith et al. 2015). Moose experience heat

stress starting at temperatures as low as 14˚C (Renecker and Hudson 1986) or 17˚C (McCann et

al. 2013) during the summer. Moose prevent heat stress on hot days by using water, shade, and

decreased activity to shed heat via conduction and reduced exposure to radiation from the sun

(Belovsky 1981; Dussault et al. 2004; Broders et al. 2012; Street et al. 2015; McCann et al.

2016). At coarse spatial and temporal scales, moose select for thermal cover (e.g., dense canopy

in conifer forests) during periods of high temperatures (Schwab and Pitt 1991; Demarchi and

Bunnell 1995; van Beest et al. 2012; Melin et al. 2014; Street et al. 2016; but see Lowe et al.

2010). However, earlier studies have not established the relative importance of multiple different

heat amelioration strategies (e.g., seeking shade vs. reducing movement vs. visiting water) or

identified thresholds at which behavioral thermoregulation alters habitat selection.

To evaluate how moose modify fine-scale habitat selection and movement patterns as

temperatures increase, we used an SSF to assess the effects of temperature on movement and

resource selection. We examined empirical support for a single model consisting of temperature

and interactions with variables likely to be important for moose thermoregulation. This model

enabled us to quantify the importance of several ways moose may alter behavior to

thermoregulate when it is hot: moose (1) decrease movement rates to decrease metabolic heat

production, (2) increase use of shade to decrease heat gain from solar radiation, (3) increase use

of water to increase heat loss via conduction, convection, and evaporation, or (4) use some

combination of each of these.

Materials and Methods

Study area

We conducted our study in northeastern Minnesota, USA. Federal, state, county, and

tribal public lands managed for timber harvest and recreation make up >80% of property

ownership in the area. The region is a sub-boreal transition zone between northern hardwood

forests in the south and Canadian boreal forests in the north (Pastor and Mladenoff 1992).

Upland forests are primarily composed of white, red, and jack pine (*Pinus strobus*, *P. resinosa*,

and *P. banksiana*), aspen (*Populus tremuloides*), paper birch (*Betula papyrifera*), and balsam fir

(*Abies balsamea*). Black spruce (*Picea mariana*), tamarack (*Larix laricina*), and northern white

cedar (*Thuja occidentalis*) dominate wet lowland forests. Mean minimum and maximum

temperatures, respectively, are -16.5˚C and -5.5˚C for the month of January and 12.6˚C and

24.0˚C for the month of July at the Beaver Bay weather station on the southern edge of our study

area (National Oceanic and Atmospheric Administration). Snow cover is typically present from

December to April, with mean annual snowfall ranging between 150 – 240 cm (Minnesota

Department of Natural Resources).

Animal Capture and GPS Telemetry

We captured moose by darting them from helicopters (Quicksilver Air, Inc., Fairbanks,

Alaska, USA) during the winters of 2011 and 2012. Darts used to sedate moose contained 1.2 ml

(4.0 mg ml^{-1}) carfentanil citrate (ZooPharm, Laramie, Wyoming, USA) and 1.2 ml (100 mg ml^{-1})

xylazine HCl (Midwest Veterinary Supply, Inc., Burnsville, Minnesota, USA), and we used

7.2 ml (50 mg ml^{-1}) naltrexone HCl (ZooPharm) and 3 ml (5 mg ml^{-1}) yohimbine HCl (Midwest

Veterinary Supply) as antagonists (Roffe et al. 2001; Lenarz et al. 2009). We fitted immobilized

moose with global positioning system (GPS) collars (Lotek Wireless, Inc., Newmarket, Ontario,

Canada). Animal capture and handling protocols met American Society of Mammalogists

recommended guidelines (Sikes et al 2011) and were approved by the University of Minnesota

Animal Care and Use Committee (Protocol Number: 1309-30915A).

Collars were programmed to record locations every 20 minutes and to drop off moose at

the end of expected battery life (2 years). We retained GPS locations with 3-D fixes or 2-D fixes

with dilution of precision values ≤ 5 (Lewis et al. 2007) and removed locations that resulted in

movement rates > 30 km / hour. Data used in this analysis include only locations between May 1

and September 31—dates that coincide with average daily maximum temperatures above the

threshold believed to induce heat stress for moose (Renecker and Hudson 1986). Location and

activity data within 2 weeks of death or collar failure were censored from our data, and only full

months of data were used in analysis. Our analysis included 153 moose-months from 24 moose.

Moose were adults at capture except for one moose that was a yearling (1.8 years old), and 17 of

24 moose were females.

Model Covariates

Because shade is difficult to directly calculate over large areas at fine scales and varies at

any given location on daily and seasonal cycles, we used canopy vegetation density as a proxy

for shade. Canopy vegetation density was estimated using airborne lidar data. Lidar is an active,

laser-based remote sensing technology that provides detailed information on topography and

vegetation structure (Vierling et al. 2008; Davies and Asner 2014). Lidar data were collected

over our entire study area during leaf-off conditions in May 2011 as part of the Minnesota

Elevation Mapping project (Minnesota Geospatial Information Office). Lidar data were collected

from a fixed wing airplane at an altitude of 2,000-2,300 m above ground level using discrete-

return laser scanning systems (ALS60, ALS70, or Optech GEMINI). Side overlap was 25% with

a scan angle of $\pm 20°$. Nominal point spacing and pulse density varied due to incomplete overlap

of adjacent flight-lines. Average nominal pulse density was 1 pulse/m^2. We calculated height of

discrete returns above ground by subtracting ground elevation based on a lidar-derived Digital

Elevation Model from the return elevation. Lidar data met the National Standard for Spatial

Database Accuracy (Federal Geographic Data Committee 1998) and had a vertical accuracy

RMSE of 5.0 cm and a horizontal accuracy of 1.16 m.

We estimated canopy vegetation density as the proportion of all returns that were ≥ 3 m

above ground. Canopy vegetation density is typically estimated with LiDAR as the ratio of

returns originating from the canopy to the total number of returns (Vierling et al. 2008; Merrick

et al. 2013; Davies and Asner 2014). We used a threshold of 3 m to estimate canopy vegetation

density because this corresponds to canopy over a moose's head. Lidar-derived canopy

vegetation density estimates were summarized in a 30 x 30 m grid that aligned with 2011

National Land Cover Database (NLCD; Homer et al. 2015) raster data to ensure consistency

across data layers in GIS. We used FUSION software (McGaughey 2016) to create the lidar-

derived canopy vegetation density raster. For the sake of simplicity, we hereafter refer to lidar-

derived canopy vegetation density as "shade".

Vegetation cover types were determined using the 2011 NLCD (Homer et al. 2015).

NLCD is a remotely sensed dataset of 16 land cover classes created from Landsat Thematic

Mapper with 30 m spatial resolution. We extracted 5 vegetation cover types that may offer

thermal refuge—woody wetland, hereafter called bog; emergent herbaceous wetland, hereafter

called marsh; open water; conifer forests; and mixed forests. Each of these cover types offers

different amounts of thermal refuge via different mechanisms (Table 1). Each cover type also

offers different amounts of forage. Since moose primarily eat the leaves of deciduous shrubs and

saplings < 3 m tall during summer (Peek et al. 1976), forage quantity decreases as the amount of

shade and proportion of conifers increases. Selection of cover types may be dependent on

proximity to other cover types, and GPS error may lead to underestimation of selection of cover

types covering small areas (Conner et al. 2003; Martin et al. 2018). We therefore calculated the

Euclidean distance of each pixel in our study area from each of our chosen vegetation cover

types using ArcMap 10.4 (Esri, Redlands, California, USA). Euclidean distances were 0 when an

animal was within the land cover type of interest.

Temperature data were obtained from two weather stations within our study area (KBFW

in Silver Bay and KCKC in Grand Marais; MesoWest). These stations are operated by the

National Oceanic and Atmospheric Administration according to national standards and report

temperatures at 20-minute intervals. Moose locations were individually matched with the nearest

weather station (by distance) and nearest temperature recording (by time). Moose locations were

on average 33 km from the nearest weather station and 7 minutes from the closest recorded

weather observation in time.

Statistical Analysis

We used a step-selection function (SSF) to model moose resource selection and

movement behavior. For our SSF, we selected available points using a parameterized Weibull

distribution of step lengths and the observed distribution of turn angles of the animals in our data

set. We paired 20 available locations to each used location (i.e., 21 points per stratum). Our final

data set contained 311,521 steps taken by 24 moose. We used conditional logistic regression (via

the 'clogit' function in the 'survival' package; Therneau 2019) to fit the SSF containing our

variables of interest (extracted at the end of each step; listed in Table 1) and interactions between

each variable and ambient temperature. We included step length (i.e., distance between

consecutive fixes) both to reduce bias in selection estimates (Forester et al. 2009) and to

explicitly model its interaction with another variable of interest (Avgar et al. 2016; Prokopenko

et al. 2017; Ladle et al. 2019). Interaction coefficients detail how temperature influences step

length and selection of cover types at differing temperatures. Because step lengths vary in a

regular pattern over the course of each 24-hour period (Fig. A2), we adjusted step lengths prior

to inclusion in the model by subtracting the observed step length from the average step length at

each given time of day. Because moose move more during crepuscular periods than at other

times of day regardless of temperature (Cederlund 1989; Lowe et al. 2010; Eriksen et al. 2011;

Vander Vennen et al. 2016), failure to adjust for crepuscular activity peaks could lead to

consistent positive bias in movement rates at low (morning) and intermediate (evening)

temperatures. We included one-way interactions between each covariate and temperature (˚C).

Because temperature was constant within strata, it was considered only as an interaction term.

The full final model is listed below:

Use ~ Shade + dBog + dMarsh + dWater + dConifer + dMixed + StepLength + Temp*Shade +

Temp*dBog + Temp*dMarsh + Temp*dWater + Temp*dConifer + Temp*dMixed +

Temp*StepLength,

where "*" denotes interactions between variables. We used generalized estimating equations

(GEEs) to obtain robust standard errors among animal-days that reduce Type I error caused by

pseudoreplication (Fortin et al. 2005; Craiu et al. 2008; Duchesne et al. 2010), and checked that

variance inflation factors (VIFs) between main effects were < 3 to ensure multicollinearity was

not a problem in our model (O'Brien 2007; Dormann et al. 2013). We calculated VIFs using the

'vif' function in the 'car' package (Fox and Weisberg 2019). We then conducted k-fold (k=5)

cross-validation on our final model and calculated Spearman rank correlation (mean of 50

replications) to evaluate model fit based on the methods of Fortin et al. (2009). Finally, we

rarified data to 1-, 2-, and 4-hour intervals to demonstrate the impact of less frequent GPS

location data on our ability to detect biologically significant interactions. All analyses were

conducted using R statistical software (R Core Team 2018). Effect sizes are reported as relative

selection strength (RSS) for one location on the landscape relative to another, given the

difference in a variable of interest between the two locations while holding the values of all other

variables in the model constant (Avgar et al. 2017).

Results

Moose Movement and Resource Selection

We found empirical support for four interaction terms (StepLength*Temp, Shade*Temp,

dBog*Temp, dMixedForest*Temp) in our step-selection function (Table 2), indicating that

temperature significantly altered movement rate and selection for shade, bog, and mixed forest.

We did not detect empirical support for interactions between temperature and distance to marsh,

temperature and distance to open water, or temperature and distance to conifer forest. Of these

variables with interaction terms whose 95% CIs overlapped zero, only the main effect for

distance to conifer forest was significant. Regardless of temperature, moose selected areas

further from conifer forest (Relative Selection Strength [RSS] = 1.553; 95% CI = 1.133-2.130).

Moose neither selected nor avoided areas near marsh or open water. Habitat use by moose was

consistent throughout our study period (i.e., month-to-month changes in distance to vegetation

cover types were small; Fig. A3).

Moose decreased movement rates at hotter temperatures (Fig. 2A). At each standardized

step length > 0 m (i.e., steps that were longer than average for a given time of day), the odds of

moose taking a step of that length was higher at 0˚C than at 15˚C, and higher at 15˚C than at

30˚C. At 0°C, the odds that moose would move 100 m more than average in 20 minutes were

substantially higher (RSS = 1.074; 95% CI = 1.025-1.126) than at 15˚C (RSS = 0.849; 95% CI =

0.777-0.928), which were in turn substantially higher than at 30˚C (RSS = 0.672; 95% CI =

0.590-0.765). Furthermore, the mean step length at all temperatures above 20˚C was below the

overall mean step length controlling for time of day.

Moose spent more time in shade at hotter temperatures (Fig. 2B). Relative selection

strength increased with increasing vegetative cover at 30˚C, while it decreased with increasing

vegetative cover at 0˚C and 15˚C, indicating that moose sought shade at high temperatures while

avoiding it at lower temperatures. At 0˚C, the odds that moose would move into a pixel with

75% vegetative cover were substantially lower (RSS = 0.265; 95% CI = 0.239-0.295) than at

15˚C (RSS = 0.640; 95% CI = 0.523-0.782), which were in turn substantially lower than at 30˚C

(RSS = 1.542; 95% CI = 1.148-2.073).

Despite avoiding bogs at colder temperatures, moose traveled closer to bogs at hotter

temperatures (Fig. 2C). The odds that moose were far from bogs was higher at 0˚C (RSS =

1.180; 95% CI = 0.988-1.410 at 500 m) than at 15˚C (RSS = 0.686; 95% CI = 0.484-0.973 at 500

m), and higher at 15˚C than at 30˚C (RSS = 0.399; 95% CI = 0.237-0.672 at 500 m).

Moose selected for shorter distances to mixed forest when it was hot than when it was

cold (Fig. 2D). The odds that moose were far from mixed forest were higher at 0˚C (RSS =

0.909; 95% CI = 0.756-1.088 at 500 m) than at 15˚C (RSS = 0.679; 95% CI = 0.478-0.963 at 500

m) or 30˚C (RSS = 0.507; 95% CI = 0.302-0.852 at 500 m), though only the difference between

0˚C and 30˚C was statistically significant.

Model validation

K-fold cross-validation of our model demonstrated that our model was substantially better than

random at predicting where moose moved—the mean Spearman rank correlation coefficient was

0.47 for observed steps.

Effects of temporal scale on interactions

The interactions we found between temperature and step length, shade, distance to bog, and

distance to mixed forest diminish substantially if GPS locations are rarified so that locations

occur at longer intervals. When 20-min interval GPS data are rarified to 1-hr, 2-hr, and 4-hr

intervals and used to fit the same SSF, interactions become progressively less biologically

meaningful (Fig. A4). As the length of time intervals between locations increases, differences

across temperatures for step length, shade, and distance to bog become minimal. Differences

across temperatures for distance to mixed forest shrink, but more gradually.

Discussion

In this paper, we developed a modeling framework to test multiple competing (but not

mutually exclusive) hypotheses on behavioral responses by animals to heat. We used this

framework to model behavioral responses by moose, an ungulate known to be sensitive to heat

(Renecker and Hudson 1986; McCann et al. 2013; Melin et al. 2014). Moose altered both

movement and habitat selection to behaviorally thermoregulate during hot periods. Moose

reduced movement and moved nearer to or stayed within shade, bogs, and mixed forest at high

heat, even while avoiding shade and bogs at cooler temperatures (Fig. 2). This pattern links

previous findings of separate studies. First, moose prefer to forage in areas with low canopy

cover, likely because canopy cover is generally inversely related to forage availability (Lone et

al. 2014). Second, moose prefer to use bed sites under dense forest canopy in wet lowland forests

during the day (McCann et al. 2016), where moose have access to less forage but more

protection against heat gain from solar radiation and more capacity to lose heat to wet ground via

conduction. Moose therefore face a steep tradeoff during periods of heat—areas that are good for

foraging may not be good for avoiding heat. Selection for shade and shorter step lengths as

temperatures increase indicates that moose forego foraging in favor of bedding down under

shade as temperatures increase. Earlier studies have documented moose shifting activity to

cooler evenings and nights on hot days (Dussault et al. 2004; Montgomery et al. 2019), which is

consistent with this trade-off.

The vegetation cover types used more by moose during warm weather further indicate

that moose face a tradeoff between foraging and thermoregulation during periods of heat. In

general, moose are more likely to find greater quantities of forage in cover types that do not

provide thermal cover, while cover types that provide thermal cover are less likely to provide

forage. For example, upland mixed forest has some available forage, but forage availability is

highest in this cover type in young forests with little canopy cover. Similarly, bogs in Minnesota

are largely populated by black spruce, tamarack, and alder, all of which can provide thermal

cover but are very rarely eaten by moose (Peek et al. 1976). Birch (*Betula* spp.), willow (*Salix*

spp.), and red-osier dogwood (*Cornus sericea*) are eaten by moose and occasionally grow in

bogs in Minnesota, but rarely at densities high enough to compensate for unpalatable species

dominating the canopy layer.

Further studies would be helpful for demonstrating how common trade-offs between

thermoregulation and foraging are among ungulates. Reductions in activity during periods of

heat are widespread among ungulates, having been documented in a diverse array of ungulates

that include moose, mule deer (*Odocoileus hemionus*; Sargeant et al. 1994), white-tailed deer (*O.*

virginianus; Wolff et al. 2020), bighorn sheep (*Ovis canadensis*; Alderman et al. 1989), Alpine

ibex (*Capra ibex*; Aublet et al. 2009; Mason et al. 2017), Alpine chamois (*Rupicapra*

rupricapra; Mason et al. 2014), common eland (*Taurotragus oryx*; Shrestha et al. 2014), black

wildebeest (*Connochaetes gnou*; Vrahimis and Kok 1993), blue wildebeest (*Connochaetes*

taurinus; Shrestha et al. 2014), impala (*Aepycerus melampus*; Shrestha et al. 2014), and greater

kudu (*Tragelaphus strepsiceros*; Owen-Smith 1998). Nevertheless, the relative importance of

reducing activity is not often compared directly to other strategies used by ungulates to reduce

heat stress, and reductions in activity may not always result in reduced foraging opportunity,

which depends on landscape structure (i.e., distance between foraging sites and bed sites with

adequate thermal cover).

Studies on the contexts in which tradeoffs between foraging and thermoregulation

become particularly acute will also be important in a warming future. Environment and

nutritional condition may play a role in shaping such tradeoffs. For example, North American elk

(*Cervus canadensis*) prioritize reducing thermoregulatory costs over forage quality in low-

elevation desert populations but not in high-elevation mountain populations, and individuals with

low fat reserves prioritize reducing thermoregulatory costs over forage quality most strongly

(Long et al. 2014). Body size may also play a role in modulating tradeoffs between foraging and

thermoregulation. Adult male Alpine ibex, which are substantially larger than females, reduce

time spent foraging more than females when it is hot (Aublet et al. 2009). Common eland and

blue wildebeest reduce afternoon activity all year round, but smaller impala reduce afternoon

activity only during the summer (Shrestha et al. 2014). The effects of environmental variation,

nutritional condition, or body size on thermoregulatory behavior could be answered in larger data

sets using our modeling framework by building SSFs for each individual and testing for

statistical effects of a variable of interest (e.g., fat reserves, body size) on the RSS of a variable

of interest (e.g., step length at a given high temperature).

Determining the relative importance of features on the landscape for mitigating heat

stress will also be important in a warming future. In our study, moose used shade far more than

water to ameliorate heat during hot weather. Moose are commonly observed in bodies of water,

and anecdotal evidence suggests that moose use water to shed heat (Schwab and Pitt 1991;

Demarchi and Bunnell 1995). Our analysis, however, indicates that moose do not often use open

water and marsh to mitigate heat stress; they prefer to seek shadier vegetation cover types.

Nevertheless, they do increase use of woody bogs—where both shade and some water are

usually available—as temperatures increase. This is consistent with a previous study (McCann et

al. 2016) that found that moose prefer bed sites with both canopy cover and relatively high soil

moisture. Other ungulates may use different features of the landscape to mitigate heat stress. For

example, mountain goats (*Oreamnos americanus*) may move closer to persistent snow cover

during hot weather rather than seeking shade (Sarmento et al. 2019). Step-selection functions

that include interactions with temperature offer a simple way to test for the relative importance

of a wide variety of different landscape features for thermoregulation.

Frequent GPS locations enabled us to detect responses to heat by moose and may explain

why previous attempts to characterize moose movement patterns failed to reveal a strong

relationship between temperature and movement rates (Dussault et al. 2004; Montgomery et al.

2019). Moose spend about half of the day foraging during the summer, with foraging bouts

interspersed by periods of rumination at bed sites. Periods of rest and rumination are typically

distinct and occur at regular intervals of roughly 2 hours (Renecker and Hudson 1989; Moen et

al. 1996). As the interval between GPS locations increases, the chance that both ambulatory

foraging bouts and stationary ruminating bouts are aggregated into a single GPS fix increases,

which homogenizes step lengths (Moen et al. 1996). Frequent GPS locations reduce the

probability of this happening. Indeed, when our location data was rarified to 1-, 2-, and 4-hour

intervals, effect sizes of interactions between temperature and movement rates were

progressively reduced (Fig. A4). Because many species have idiosyncratic movement behaviors,

movement studies may require intervals between GPS locations within a specific range to best

answer research questions concerning animal movement. This is an important consideration for

researchers planning studies of animal movement. Researchers should carefully consider the

frequency of GPS locations before deploying GPS collars and recognize that GPS data that is too

sparse may result in Type II error.

Our analysis can directly inform management and conservation actions for wildlife.

Many moose populations at the southern edge of their distribution (including our study area)

have undergone substantial declines in the past decade (Lenarz et al. 2010; van Beest et al. 2012;

Dou et al. 2013; Monteith et al. 2015). Our results suggest that in a warmer future proximity to

shade will strongly influence habitat suitability for moose in areas with abundant forage due to

timber harvest and other anthropogenic disturbance. Moose will likely benefit from management

action to explicitly promote maintenance of shade near large patches of forage. Because moose

prioritize shade over forage when it is hot, moose will likely not feed in large forest openings on

hot days (though moose may feed in unshaded forest openings at night; Dussault et al. 2004).

Moose will likely spend more time foraging in forest openings with patches of canopy cover than

in large homogeneous forest openings. For example, most of the forage in large clearcuts may be

inaccessible to moose during hot periods unless the clearcuts contain "reserve patches", or

interior islands or fingers of forest extending into the clearcut. These reserve patches will likely

be most helpful for moose if they consist of bog or mixed forest.

Some measure of fitness (or a proxy for fitness) would make it possible to directly link

behavioral strategies to a population-level response to large-scale drivers like climate change.

Although behavioral thermoregulation mitigates some metabolic costs of hot weather, forgoing

foraging to avoid high body temperatures may result in decreased fat reserves, lower fitness, and

ultimately in population declines compared to a cooler baseline scenario where moose do not

need to behaviorally thermoregulate. Although we did not link behavior to fitness in this study,

identifying and quantifying patterns of behavior allows researchers to explicitly test for effects

on fitness in subsequent studies. For example, development of conceptual and modeling

frameworks to identify and quantify "green wave surfing" behavior (by which animals migrate

along paths of rapidly greening forage) in migratory ungulates (Bischof et al. 2012; Merkle et al.

2016; Aikens et al. 2017) allowed researchers to later quantify a connection between green wave

surfing and fitness (Middleton et al. 2018). Our study could be used as a foundation for further

analyses along these lines, or to parameterize mechanistic models of moose energetic balances

under various climate scenarios, land management strategies, or disturbance regimes to project

the outcomes of conservation actions taken to benefit moose.

Our analysis demonstrates that advances in animal tracking, remote sensing, and

modelling techniques allow us to study responses by free-ranging animals to weather in the field

at finer scales than previously possible. SSFs in particular are a valuable tool to answer questions

concerning behavioral responses by free-ranging animals to changes in weather in a relatively

simple and intuitive way. Because SSFs estimate selection conditionally at each GPS location,

each location or step can be connected with a distinct time and spatial location, enabling

inference on how animals change movement and habitat selection in space and time in response

to specific stimuli. SSFs have been used to characterize animal movements in relation to

landscape features, such as grizzly bear (*Ursus arctos*) response to human activity (Ladle et al.

2019) and North American elk, African wild dog (*Lycaon pictus*), and wolverine (*Gulo gulo*)

response to roads (Abrahms et al. 2016; Prokopenko et al. 2017; Scrafford et al. 2018). Likewise,

SSFs that incorporate interactions between temperature and other variables of interest can

characterize changes in movement behavior and habitat use in response to differences in

temperature.

In conclusion, moose altered both movement and habitat selection to behaviorally

thermoregulate during hot periods by reducing movement rates and increasing use of shaded

vegetation cover types that they avoided at cooler temperatures. Moose did not regularly use

water sources that lack canopy cover to shed heat. Moose face a tradeoff between forage and

thermal cover at high temperatures and forego foraging in favor of seeking thermal cover.

Behavior changed at thresholds near (though somewhat above) previously documented heat

stress thresholds (Renecker and Hudson 1986; McCann et al. 2013): step lengths decreased at

temperatures above 20˚C, and selection patterns for shade reversed above 15˚C. Future research

characterizing strategies for behavioral thermoregulation and consequences of those strategies

for fitness will aid conservation in a warming world, for both moose and other heat-sensitive

species.

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Author Contributions

JA and RM conceived and designed the study; RM collected the data; JA, MJ, and JM analyzed

the data; JA led the writing of the manuscript. All authors contributed critically to manuscript

drafts and gave final approval for publication.

Data Availability

Data and R scripts are archived on *Zenodo* at: http://doi.org/10.5281/zenodo.3872407.

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Figures

Fig. 1 The physical characteristics of the surrounding environment greatly influence the thermal landscape for animals. Fig. 1A

represents an environment (conifer forest) where heat gain may be decreased by reducing exposure to radiation, Fig. 1B represents an

environment (marsh) where heat loss may be increased by conduction, and Fig. 1C represents an environment (clear cut) that offers

neither relief from radiation nor opportunities to disperse heat via conduction. Moose likely face tradeoffs between forage availability

and thermal relief.

Fig. 2 Interaction plots showing relationships for significant interactions between temperature and relative selection strengths (RSS) of

variables of interest (A: Step length and temperature, B: Shade and temperature, C: Distance to bog and temperature, D: Distance to

mixed forest and temperature). High temperatures decrease the odds of longer step lengths, increase the odds of seeking shade, and

increase the odds of traveling in bogs and mixed forest. In some cases (A, B, and C), patterns of behavior at low temperatures reversed

into patterns of the opposite behavior at high temperatures (e.g., moose strongly avoid shade at 0°C while strongly selecting for shade

at 30°C).

Tables

Table 1 Variables incorporated in the step-selection function of moose movement and habitat selection in response to changes in

temperature and justification for inclusion in the model.

Name	Variable	Description
Shade	Canopy Vegetation Density	Proportion of all lidar returns above 3 meters; analogous to canopy vegetation density, a proxy for shade
dBog	Distance to Bog	Distance to woody wetlands; included in analyses because bogs have both canopy cover and ground moisture
dMarsh	Distance to Marsh	Distance to emergent herbaceous wetlands; included in analyses because moose are often observed in marshes, and water can disperse heat via conduction, convection, and evaporation
dWater	Distance to Open Water	Distance to open water; included in analyses because moose are often seen in bodies of water, which can disperse heat via conduction, convection, and evaporation
dConifer	Distance to Conifer Forest	Distance to conifer forest; included in analyses because conifer forest contains localized thick canopy cover
dMixed	Distance to Mixed Forest	Distance to mixed forest; included in analyses because conifers offer localized thick canopy cover while deciduous trees offer foraging opportunities
StepLength	Step Length	Distance between a moose location and the location immediately prior; included in analyses to account for bias in the parametric distribution of step lengths used to characterize available points and to estimate how temperature affects movement rates
Temp	Temperature	Temperature at the nearest NOAA weather station at the time of a location; included in analyses to estimate how temperature affects habitat use and movement rates

Table 2 Coefficient estimates, standard errors (SE), relative selection strengths (RSS), 95% confidence limits (lower, LCL; upper, UCL), and p-values for a step-selection function of moose habitat selection and movement in response to changing temperature. Bold lettering denotes variables with confidence limits that do not overlap 1 (the dividing line between selection and avoidance). Variables are described in detail in Table 1.

Variable	Coefficient	SE	RSS	LCL	UCL	p
Shade	**-0.174**	**0.007**	**0.840**	**0.829**	**0.852**	**<0.001**
dBog	**0.728**	**0.182**	**2.071**	**1.450**	**2.956**	**<0.001**
dMarsh	-0.055	0.108	0.947	0.767	1.169	0.612
dWater	0.057	0.106	1.058	0.860	1.302	0.592
dConifer	**0.440**	**0.161**	**1.553**	**1.133**	**2.130**	**0.006**
dMixed	0.169	0.184	1.184	0.825	1.699	0.359
StepLength	**3.025**	**0.242**	**20.603**	**12.831**	**33.082**	**<0.001**
Shade*Temp	**0.008**	**0.000**	**1.008**	**1.007**	**1.009**	**<0.001**
dBog*Temp	**-0.072**	**0.012**	**0.930**	**0.909**	**0.952**	**<0.001**
dMarsh*Temp	0.004	0.007	1.004	0.990	1.019	0.558
dWater*Temp	-0.004	0.007	0.996	0.982	1.010	0.589
dConifer*Temp	-0.009	0.010	0.991	0.972	1.011	0.388
dMixed*Temp	**-0.039**	**0.012**	**0.962**	**0.940**	**0.984**	**0.001**
StepLength*Temp	**-0.156**	**0.014**	**0.855**	**0.832**	**0.879**	**<0.001**

Appendix A: Supplementary Data

Fig. A1 Comparison of temperatures at the two weather stations used in this study (KCKC in Grand Marais and KBFW in Silver Bay). The red line indicates a 1:1 relationship. Temperatures at KCKC followed the regression line 1.74 + 0.821*KBFW, where "KBFW" indicates the temperature at the KBFW station. $R^2 = 0.881$ for the regression equation. Temperatures were thus slightly warmer at KCKC at very low temperatures (less than ~2˚C), but usually slightly cooler (e.g., when it was 30˚C at KBFW, the expected temperature at KCKC was 26.4˚C). Variation in temperature across our study area was thus much smaller than temperature across the day or summer.

Fig. A2 Lowess regression of mean step length across times of day (20 min. increments). The gray ribbon represents the 95% confidence interval for the regression line. Moose movement rates varied slightly but consistently over the course of the day, with movement rates peaking during crepuscular periods. The area within the dotted rectangles represents the range of civil sunrise and sunset at the centroid of our study area during our study period (determined using the NOAA Solar Calculator tool [https://www.esrl.noaa.gov/gmd/grad/solcalc/]).

Fig. A3 Boxplots showing monthly changes in distance to cover types of interest (A: Distance to bog, B: Distance to marsh, C: Distance to water, D: Distance to conifer forest, E: Distance to mixed forest). Month-to-month differences in habitat use are small, indicating that patterns observed from our SSF reflect habitat selection throughout our study period and are not influenced by one-time phenological events occurring during our study period (e.g., parturition movements by females during May, or the emergence of aquatic plants during June).

Fig. A4 Interaction plots showing relationships for significant interactions between temperature and relative selection strengths (RSS) of variables of interest (A: Step length and temperature, B: Shade and temperature, C: Distance to bog and temperature, D: Distance to mixed forest and temperature) at progressively longer intervals between GPS locations (1: 20-minute, 2: 1-hour, 3: 2-hour, and 4: 4-hour). Patterns in the selection strength of interactions progressively weaken as the interval between GPS locations increases, in part explaining why other studies have not found consistent effects of temperature on moose movement.