Title :

Oscillation-driven memory encoding, maintenance and recall in an

entorhinal-hippocampal circuit model

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Abstract

Coherent neuronal activity phase-locked to theta and gamma oscillations is thought

to be crucial for information processing across multiple brain regions. However, the

network mechanisms underlying the oscillation-driven multi-area computation

remains largely unclear. To explore such mechanisms, we constructed a hippocampal-

entorhinal neural network model involving parvalbumin-positive, somatostatin-

positive and vasoactive intestinal polypeptide interneurons in the hippocampal area

CA1 and the superficial and deep layers of the entorhinal cortex. We examined the

model behavior by using neural activity data recorded during delayed nonmatching

to place tasks. Our model shows that experimentally observed relative phases of

theta oscillation ensure working memory performance. Moreover, the model

predicts that acetylcoline concentrations in these areas modulate the balance

between intra-area and inter-area information processing according to cognitive

demands emergent at encoding, maintenance and recall epochs of a working

memory task. Our model suggests the active role of theta-phase-locked firing and

cholinergic modulations for multi-area memory processing.

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Spatial navigation is a fundamental cognitive function that requires the processing of

spatial memory by the hippocampus and entorhinal cortex. During a spatial navigation

task, spatial information relevant to the task has to be encoded into, maintained in and

recalled from spatial working memory at adequate times. How these operations are

coordinated by the cortico-hippocampal neural circuits during a spatial working

memory task has to be yet explored.

A spatial working memory task is processed by several cortical areas such as the medial

prefrontal cortex (mPFC) (Benchenane et al., 2010; Jones and Wilson, 2005; Spellman

et al., 2015), medial entorhinal cortex (MEC)(Suh et al., 2011; Yamamoto et al., 2014)

and the hippocampal area CA1 (Benchenane et al., 2010). These anatomically

connected areas (Eichenbaum, 2017; Swanson and Cowan, 1977; Witter et al., 2000)

are thought to mutually communicate information necessary to accomplish the task.

Interestingly, the degree of functional importance of different inter-area connections

varies during the task. This is suggested because the impairment of these connections

at different behavioral phases differentially influenced task performance (Spellman et

al., 2015; Suh et al., 2011; Yamamoto et al., 2014). For instance, in a delayed

nonmatching to place task (DNMP), the maintenance of spatial memory during a delay

period does not require synaptic connections from the layer 3 of the MEC (MECIII) to

CA1, but these connections are necessary for memory recall(Yamamoto et al., 2014).

Connections from CA1 to the mPFC play a crucial role in memory encoding but not in

memory recall (Spellman et al., 2015). These results indicate that information flows via

the hippocampal circuit are not static but are dynamically regulated depending on the

behavioral demands.

Coherence in neuronal activity between different areas likely reflects dynamic

information routing across multiple areas (Spellman et al., 2015; Yamamoto et al.,

2014), which leads to the hypothesis called "communication through coherence"(Fries,

2015). Many theoretical (Akam and Kullmann, 2010; Buehlmann and Deco, 2010;

Palmigiano et al., 2017; Vogels and Abbott, 2005; Yang et al., 2016) and experimental

(Letzkus et al., 2015; Womelsdorf et al., 2014) studies have explored the gating

functions for this dynamic processing. However, how the computations installed at

multiple cortical areas are integrated to execute a spatial working memory task

remains largely unclear. In addition, the mechanistic role of theta and gamma

oscillations in this process has not been fully understood.

Here, we elucidated the underlying mechanisms of multi-area dynamic information

processing during spatial navigation. In so doing, we constructed a biologically

plausible model of the entorhinal-hippocampal circuit consisting of MECIII, CA1 and

MEC layer V (MECV). We show that the model successfully reproduces a wide range of

behavioral and electrophysiological observations reported from a DNMP task

(Yamamoto et al., 2014). We further confirmed the validity of the model by using data

from another DNMP task (Fernández-Ruiz et al., 2017; Mizuseki et al., 2013).

Importantly, our model predicted the crucial role of cholinergic modulations in

regulating information flow dynamics of the MECIII-CA1-MECV circuit. Acetylcholine

(ACh) is related to cognitive states (Hasselmo and Sarter, 2010; Parikh et al., 2007) in

many behavioral tasks including fear conditioning (Letzkus et al., 2011; Pi et al., 2013),

sensory discrimination (Hangya et al., 2015; Pinto et al., 2013), associative memory

(Sabec et al., 2018), and spatial (Croxson et al., 2011; Okada et al., 2015) and non-

spatial working memory tasks (Furey et al., 2000; Hasselmo, 2006; McGaughy et al.,

2005). Consistent with the regulatory role, cholinergic inputs from the medium septum

(MS) project broadly to distinct cortical areas including the hippocampus. In our

model, cholinergic modulations were necessary to perform the three important stages

of memory processing, i.e., encoding, storing, and decoding spatial information and

were implemented by disinhibitory mechanisms.

Results

Hippocampus-entorhinal cortex circuit model

To understand the circuit mechanisms to control flexibly spatial information in the

hippocampus and MEC, we built an inter-areal cortical network model (Figure 1A, see

Supplemental materials for details). The network comprises three main areas CA1, MEC

layer 3 (MECIII) and layer 5 (MECV), and additional areas CA3, MEC layer 2 (MECII) and

medial septum (MS) as external inputs. All main areas have excitatory (E) and

parvalbumin (PV)-positive interneurons. In addition to these neurons, the model CA1

has somatostatin (SOM)-positive oriens-lacunosum moleculare (OLM) and vasoactive

intestinal polypeptide (VIP) neurons. We built synaptic connections in our model based

on anatomical observations (Gonzalez-Sulser et al., 2014; Unal et al., 2015; Witter et

al., 2000). In addition, we assumed that E neurons in MECII project to PV neurons in

MECIII, as previously suggested (Mizuseki et al., 2009).

Exc, PV and OLM neurons constitute the core circuits of the present network model

and were modeled as Hodgkin-Huxley-type conductance-based neurons according to

previous models (Middleton et al., 2008; Rotstein et al., 2006; Wang and Buzsáki, 1996;

Wulff et al., 2009). VIP neurons were modeled as Poisson firing neurons with the

probability density of spikes described and their outputs mediate the modulatory

effect of acetylcoline (ACh). We described CA3 excitatory neurons projecting to CA1,

MECII E neurons projecting to MECIII, and GABAergic neurons in MS projecting to CA1

and MECV as external Poisson spike trains. As shown in Figure 1B, the firing

probabilities of these neurons were modulated at the theta frequency (10Hz) to induce

theta rhythmic activities in the core circuits. The relative preferred phases of the theta

rhythm of the external inputs were adjusted based on experimental observations

(Klausberger and Somogyi, 2008; Mizuseki et al., 2009). Furthermore, from these

phases and experimental observations, we set the theta phase of the local field

potential (LFP) to be observed in the stratum pyramidale (SP) of CA1. Although this LFP

was not directly calculated from the modeled CA1 activities, the quantity was used as a

reference to measure the degree of agreement between the preferred phases of model

neurons and experimental observations. The preferred phases of GABAergic neurons in

MS were dependent on their target neuron types (ECV PV, CA1 PV and CA1 OLM). In

experiment, GABAergic neurons projecting to OLM and those projecting to PV in CA1

have different preferred phases (Borhegyi, 2004).

Acetylcholine is known to modulate activity of VIP neurons (Albuquerque et al., 2009)

and the conductance of a calcium-sensitive non- specific cation current (CAN) in MECV

excitatory cells (Fransen et al., 2002; Fransén et al., 2006) in a manner depending on

the concentration of ACh ([ACh]). In this study, we test the hypothesis that [ACh] varies

in correlation with cognitive demands to perform encoding, maintenance and decoding

spatial working memory. We demonstrate that the cholinergic modulations of

disinhibition of CA1 E neurons and calcium dynamics in MECV E neurons enable the

flexible processing of spatial working memory. Cholinergic neurons in MS ((Newman et

al., 2012; Zhang et al., 2010) were not explicitly modeled.

For Poisson neurons in CA3, MECII and MS, their preferred phases of theta oscillation

for the default [ACh] (Figure 1D) were chosen to be consistent with experimental

observations (Borhegyi, 2004; Klausberger and Somogyi, 2008; Mizuseki et al., 2009).

Given this condition, all neurons in CA1, MECIII and MECV fired in theta-rhythmic

manners (Figure S1A). As observed in experiments, E and OLM neurons in CA1 showed

preferred phases around the troughs of theta oscillation, whereas PV neurons around

the peaks (Klausberger and Somogyi, 2008). In MECIII, E and PV neurons fired

preferentially around the peaks and troughs of theta oscillation, respectively (Mizuseki

et al., 2009). In MECV, PV neurons preferred the troughs, but E neurons did not show

strong phase preferences (Mizuseki et al., 2009). These results show that theta phase-

locked firing in our model is biologically plausible.

Encoding spatial information into theta rhythmic firing

The central question of this study is to clarify how spatial information is encoded,

maintained and recalled in the entorhinal-hippocampal circuits. To study this problem,

we asked whether our model can replicate the task-related activities reported in

previous experiments. In particular, we considered a DNMP task on a T-maze

(Yamamoto et al., 2014). In this experiment, one arm of the T-maze was closed during

a sample run and the rat was forced to choose another arm. After a delay period, the

rat was set to a test run in which both arms were open and the rat had to choose the arm opposite to the one chosen in the preceding sample run (that is, if the rat chose the right arm in the sample run, it had to choose the left arm in the test run). For a successful test run, the rat had to remember the previously chosen arm. This task requires at least two types of memory, namely, rule-based memory and spatial working memory. The former memory is thought to be encoded in the prefrontal cortex (Durstewitz et al., 2010; Guise and Shapiro, 2017; Preston and Eichenbaum, 2013). However, in this study we did not model the prefrontal circuits and focused on the processing of spatial working memory in the entorhinal-hippocampal circuits.

Figure 1C shows the organization of sample and test runs in our model together with the connectivity patterns between the neural ensembles encoding different locations on the maze. We monitored the activity of sample runs along the center arm (sample-C) and left arm (sample-L), and that of test runs at the home position (delay) and center arm (test-C) up to the junction (decision point) of the T-maze. For the sake of simplicity, we implemented four subgroups L, R, C and H of place cells in CA3, each of which represented the current position of the model rat on the left, right, center arms and at the home position, respectively. For instance, neurons belonging to the subgroup L were given a higher firing probability when the model rat traveled across the left arm (Figure 1D; also see "Neuron models" in STAR methods). Accordingly, E neurons in CA1 were also divided into four subgroups L, R, C, and H, each of which was strongly projected to by the corresponding subgroup in CA3. In contrast, MECIII and MECV had two subgroups denoted as L and R, and these subgroups were assumed to form closed loop circuits with the corresponding CA1 subgroups. The other positions on the maze that are not shown in Figure 1C were not modeled.

Role of theta oscillation in coordinating activities in the CA1-MECV-MECIII loop circuit
Experimental results showed that theta-phase-locked firing in MECIII is highly correlated with the task performance (Yamamoto et al., 2014). Therefore, we hypothesized that the L and R subgroups in MECIII contributes to the success of spatial

working memory task and defined task performance as difference in neural activity
between these subgroups at the test-C period. The larger the difference is, the more
robust the memory encoding is. Below, we consider the case, without loss of
generality, that the rat chooses the left arm in every sample trial. In Figure 1D, we
demonstrated activities of E neurons in CA3, CA1, MECV and MECIII together with
[ACh] during (1) sample-C, (2) sample-L, (3) home (delay) and (4) test-C runs.
Depending on the rat's position, the corresponding subgroup was activated in CA3.
During the sample-L run, [ACh] was increased, which disinhibited CA1 PV neurons and
accordingly strongly activated the CA1-MECV-MECIII loop circuit of the L subgroups to
encode a choice memory in MECIII. Then, in the delay period, [ACh] was slightly
decreased, which strongly suppressed neural activities in all L subgroups including the
CA1 subgroup L. We note that a similar suppression arose in experiment as if spatial
memory had not been maintained during delay periods (Yamamoto et al., 2014).
During the test-C run, the CA1 subgroup C was activated driven by the CA3 subgroup C.
Importantly, as the model rat approached to the decision point, the subgroups L were
gradually reactivated in the loop circuit to retrieve the memory of the previous choice.
This activation-suppression-reactivation pattern is clearly seen in the firing rate of
MECIII neurons. Average firing rates during the test-C period were significantly
different (p=3.071x10^{-6}, t test on two related samples) between the subgroups L and R
in MECIII (Figure 1E), implying that the network model successfully recalled the stored
spatial memory.
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The successful encoding of memory required theta-phase-locking of neural firing along
the CA1-MECV-MECIII loop circuit. As mentioned previously, the theta phases of
external sources (i.e., CA3, MECII and MS) entrain neurons in these areas in theta-
phase-locked firing with the preferred phases that are consistent with experimental
observations. In the normal situation, MECIII PV neurons are activated by input from
MECII at the bottoms of theta oscillation and consequently MECIII E neurons tend to
fire at the peaks. Then, CA1 E neurons are strongly activated in non-linear
manner(Bittner et al., 2015; Takahashi and Magee, 2009) by near-coincident inputs

from MECIII and CA3: spikes from CA3 arrive at CA1 at the descending phases of theta

oscillation just after spikes from MECIII (see STAR Methods).

The theta phases of inputs from different sources need to be well coordinated for

successful working memory function. To examine this, we shifted the preferred phases

of MECII neurons by 180 degrees from the troughs to the peaks of the reference theta

oscillation of CA1 LFP (Figure S1B). Figure S1C shows the phase preferences of CA3,

CA1 E, CA1 PV, and MECIII E neurons after this change. MECIII PV neurons dramatically

reduced spikes at the descending phases of theta oscillation, which shifted the firing of

MECIII E neurons to the troughs of theta oscillation. Consequently, the peak activities

of MECIII and CA3 were separated by about one half of theta cycle and did not

coincidently innervate CA1. The timing deviation impaired the encoding of spatial

information into the loop circuit, as indicated by significantly reduced rate differences

between L and R subgroups (Figure S1D, p= 2.679×10^{-16}, t test on two related samples),

resulting in a degraded task performance (Figure 1F, p= 2.334×10^{-8}, t test on two

related samples). Thus, theta oscillation is crucial for the appropriate temporal

coordination of neuronal firing in the entorhinal-hippocampal circuit.

Figure 1. Entorhinal-hippocampal network model. (A) The structure of the network

model is schematically illustrated. (B) Theta-modulated firing probabilities of input

neurons are shown during the sample-center run. The preferred firing phases were

determined with respect to a reference theta oscillation (black) reported in the CA1

stratum pyramidale (SP) layer. (C) Left; Schematic illustrations of task periods during

the sample and test trials of the DNMP T-maze task: (1) sample-C, (2) sample-L, (3)

home (delay), (4) test-C periods. Right; Synaptic connectivity is shown between the

neuron subgroups encoding the specific locations of the maze (left, right, center arms

and home position). Connections (bold) are stronger within the loop circuit of MECV,

MECIII and CA1 than other modest connections (solid). (D) Raster plots of E neurons in

different cortical areas are shown together with the time evolution of ACh

concentration. (E) The average firing rates of MECIII L and R subgroups were calculated

for the test-C period in five different networks with five different initial conditions

(black lines). Unless otherwise stated, average firing rates were evaluated in a similar

fashion throughout this study. (F) Probability of left choice (P_L) and average of P_L was

calculated in the normal and modified conditions. Gray dots show P_L of different

networks for different initial conditions. Here, $P_L = e^{-r_L}/(e^{-r_L} + e^{-r_R})$, where r_L, r_R

are firing rate of L and R subgroups in test-C period, respectively. Chance level is 0.5.

Figure S1 (related to Figure 1). Activity of various types of neuron during task. (A)

Preferred phases of various neuron types during the sample-C period. The firing rates

were calculated by numerical simulations for excitatory and inhibitory neurons in the

entorhinal-hippocampal circuit. The reference theta oscillation presumed in the SP

layer of CA1 is also shown (solid lines). (B) Theta-modulated firing probabilities of ECII

neurons for the normal and preferred phase shift conditions are shown. (C)

Modulations of spike counts by theta oscillation are shown for CA1 E, MECIII E and

MECIII PV neurons during the sample-L period. Neuronal activities in the normal and

preferred phase shift conditions of theta oscillation are shown with dark and light

colors, respectively. (D) Differences in the firing rate between the L and R subgroups of

CA1 E neurons were calculated during the sample-L period and compared between the

normal and the phase shift conditions. Simulation results for the same initial conditions

are connected with lines.

The role of disinhibition in regulating the activity of the CA1-MECV-MECIII loop circuit

We show that the ACh-mediated disinhibitory mechanisms regulate cross-area

communications within the entorhinal-hippocampal circuit during different task

periods. We first analyzed how CA1 neurons selectively encode spatial information

from CA3. We consider the default state (i.e., 0 to 1 sec in Figure 1D) in which [ACh] is

low (Figure 2A). In this state, output from VIP neurons is weakened and, consequently,

PV neurons are strongly activated around the peaks of theta oscillation (Figure 2B).

Accordingly, CA1 E neurons rarely fire around the peaks (but they can generate a small

number of spikes driven by external noise after the troughs of theta oscillation at

which inputs from both PV and OLM are weakened: see Figure S1A). In contrast, during

the epochs of high [ACh] (Figure 2D, the sample-L period: the test-C period also

corresponds to the high [ACh] epoch, but will be discussed later), CA1 E neurons show

strong activation immediately after the peaks of theta oscillation because PV neurons

are suppressed around the peak (Figure 2E). OLM neurons are also suppressed, but

their inhibitory effect on E-neuron firing around the peak is relatively weak since the

preferred phase of OLM neurons is the trough of theta. Thus, the cholinergic

modulation advances the preferred phase of CA1 E neurons from the troughs to the

peaks of theta oscillation. Later, we will examine the model's prediction in

experimental data.

Information on the current position of the rat can be transferred from CA3 to CA1 only

when [ACh] is sufficiently high. Throughout the task, CA1 E neurons constantly receive

position information from CA3 which changes as the rat moves on the maze. During

encoding epoch, a certain mechanism is required to enable CA3 inputs to activate CA1

neurons in the sample-L period (see the CA1 L subgroups in Figure 1D). ACh-induced

disinhibition provides this mechanism: at the sample-C period [ACh] is low and the

sensitivity of CA1 E neurons to CA3 input remains low, consequently the position

information is not transferred to CA1; at the sample-L period [ACh] is increased and

accordingly the sensitivity is also enhanced, resulting in an information transfer

(Figures 2C and 2F).

The disinhibition mechanism further explains why the blockade of MECIII-to-CA1

connections impaired task performance in experiment (Yamamoto et al., 2014). When

the model rat is sampling left or right arm, the disinhibition mechanism enables the

activation of the corresponding subgroups in the CA1-ECV-ECIII loop: highly activated

CA1 neurons activate MECV E neurons, which in turn activate MECIII E neurons. MECIII-

to-CA1 projections further activate CA1 E neurons, thus completing a positive feedback

loop within the activated subgroups. However, the blockade of MECIII-to-CA1

connections reduces neural activity in CA1 and hence in MECIII, disabling the storage of

the current position.

To confirm the crucial roles of disinhibition (i.e., VIP-PV-E and VIP-OLM-E connections)

in the working memory task, we studied two cases. In the first case, PV neurons were

inactivated in CA1 during the entire trial period without changing the other conditions

(Figure S2A). Due to the lack of inhibition from PV neurons, CA1 E neurons were

strongly activated at any ACh concentration. In the encoding epoch, E neurons

exhibited higher activity in the L subgroup than in the R subgroup in both CA1 (Figure

S2B) and ECIII (Figure S2C, 1 to 3 sec). However, after this epoch E neurons immediately

lost selectivity to spatial information because they were too strongly activated in both

subgroups. During some intervals firing rate was higher in the L subgroup than in the R

subgroup, but it was opposite during other intervals (Figure S2C, after 3 sec). Thus, the

spatial information recalled randomly varied from trial to trial, and working memory

performance was unreliable (Figure S2D).

In the second case, the cholinergic modulation of PV neurons (but not that of OLM

neurons) was terminated during the entire trial period. In this case, PV neurons were

not inactivated even at high [ACh] (Figure S2E) and the encoding of spatial information

into CA1 was largely impaired (Figure S2F). Consequently, spatial information could not

be stably maintained in MECIII (Figure S2G) and probability of left choice, P_L, was

significantly decreased (Figure S2H, p=1.542×10^{-9}, t test on two related samples). Thus,

in both cases, spatial information in CA3 was not successfully transferred into the CA1-

MECV-MECIII loop circuit.

Figure 2. Gating of CA3-to-CA1 signaling by disinhibition mechanism. (A) The

operation mode of disinhibitory circuit is schematically illustrated in low [ACh] states.

(B) Theta phase preferences of spiking during the sample-C period are shown for CA1

neurons. Only for VIP neurons, the firing rate normalized by [ACh], which corresponds

to output from VIP neurons to other inhibitory neurons (see the STAR method), is

plotted. Solid curves show the reference theta oscillation. (C) Average firing rates of

the L, R, C and H subgroups in CA3 and CA1 are shown during the sample-C period. (D)

The operation mode of disinhibitory circuit in high [ACh] states. (E, F) Similar to (B) and

(C) during the sample-L period.

Figure S2 (related to Figure 2). Effect of inactivation of disinhibition mechanism. (A)

Firing rates of CA1, CA3 and MECIII neurons during sample-L periods are shown. During

the simulations, CA1 PV neurons were inactivated. Solid curves indicate the reference

theta oscillation. (B) Average firing rates of CA1 E neurons in different subgroups are

plotted during sample-L periods in the same inactivating condition. (C) Raster plots are

shown for the L (blue) and R (orange) subgroups of MECIII E neurons. (D) Probability of

left choice is plotted in the normal and inactivating conditions. Lines connect two data

points obtained from simulations of a normal network and its impaired version with

the same initial conditions. (E, F, G, H) same as (A) to (D) , but for the network models

with disabled VIP-to-CA1 PV connections.

Covert activation by calcium dynamics

An unexpected experimental finding was that neural activities in MECIII were strongly

suppressed during delay periods (Yamamoto et al., 2014). This observation challenges

our hypothesis that either MECV or MECIII, or both, serve for working memory in the

spatial decision making task, raising the question about how the entorhinal-

hippocampal circuit recalls the encoded spatial information after the delay periods. To

explore the underlying circuit mechanisms of memory recall, we implemented calcium-

sensitive non-specific cation current (CAN current in STAR Methods) in our cortical

neuron models.

The CAN current was originally proposed to explain persistent activity of single cortical

neurons in MECV (Fransen et al., 2002; Fransén et al., 2006), and a similar persistent

activity was later shown in the layer V of various cortical areas (Rahman and Berger,

2011). The CAN current is activated in the presence of ACh with the intensity

depending on the activation rate of high conductance channels, r_H. The conductance r_H

is linearly increased when the calcium concentration $[Ca^{2+}]$ is beyond a critical value d_P

and decreased when $[Ca^{2+}]$ is below another critical value d_D. Because $d_D < d_P$, a

hysteresis effect or bistability appears for $d_D < [Ca^{2+}] < d_P$. Thus, once $[Ca^{2+}]$ exceeds d_P,

the value of r_H remains high until $[Ca^{2+}]$ again decreases below d_D (Figure 3A). Neurons

with high r_H respond to input more sensitively than those with low r_H and, thus,

memory of previous high activity is stored in r_H through calcium dynamics.

In the sample-L period, an increased activity of the CA1 subgroup L enhanced spike

firing of MECV E neurons in the subgroup L (Figure 3B). During the enhanced firing,

$[Ca^{2+}]$ was elevated in these neurons by calcium influx through the voltage-dependent

calcium channel. This increase of $[Ca^{2+}]$ occurred only in the MECV subgroup L but not

in the MECV subgroup R (Figure 3C). After the sample-L period, [ACh] was decreased

and, consequently, the CAN current was also decreased. Because lowering [ACh]

decreased the output of VIP neurons, that of PV neurons was increased and

consequently that of CA1 E neurons was suppressed. Thus, the changes in neural

activity resulted in a decreased firing rate of MECV E neurons. Nevertheless, the

fraction of high conductance state remained high in the subgroup L (but not in the

subgroup R) of MECV E neurons (Figure 3C).

The CAN current plays a crucial role in the maintenance of working memory. To explain

this, we divided the test-C period into early and late periods: in the early period CA1

neurons were selectively activated in the subgroup C but not in the subgroup L (and

subgroup R); in the late period they were strongly activated in the subgroup L (Figure

3B). During the test-C period, [ACh] was again increased, so was the activity of CA1 E

neurons through the disinhibition mechanism. Although MECV neurons in both

subgroups L and R received synaptic input from the CA1 subgroup C, MECV neurons

were selectively activated in the subgroup L because the high conductance rate

remained high in these neurons. The activity of the MECV subgroup L neurons

gradually increased in the early test-C period, and eventually became sufficiently

strong to activate MECIII subgroup L neurons. Accordingly, the test-C period entered

the late period and the spatial information stored in MECV could be decoded by CA1

neurons. The onset time of the late period depends on the realization of neural

networks and initial conditions. Thus, the covert activation of CAN current enables the

retrieval of persistent activity in the MECV subgroup L neurons for the decoding of

spatial information in the test-C period.

Figure 3. Role of CAN current in memory encoding and maintenance. (A) Single trial

evolution of the membrane potential (top), $[Ca^{2+}]$ (middle) and the ratio of high

conductance state of CAN current (bottom) are plotted in an MECV excitatory neuron.

Dots above the membrane potential represent spikes. Broken lines denote two

threshold values, d_P and d_D, in the middle panel and the upper and lower critical values

of the high conductance ratio in the bottom panel (See STAR method). (B) Firing rates

are shown for E neurons in CA1, MECIII and MECV. Colors indicate different neuron

subgroups. (C) Time evolution of $[Ca^{2+}]$ (top) and the high conductance ratio (bottom)

are plotted for randomly-chosen five MECV E neurons belonging to L (blue) or R

(orange) subgroup during the same trial as in B.

Comparison of MECIII neural activity between the model and experiment

We compared the responses of our model with those of the rat entorhinal-

hippocampal circuit. For this comparison, we analyzed E neuron activity in MECIII after

dividing each of the sample-L, delay and test-C periods into early and late portions,

respectively. As in experiment (Yamamoto et al., 2014), we first quantified the intensity

of theta oscillation in these task periods by computing periodicity index. As shown in

Figure 4A, this index was high during the late sample-L, early delay, and late test-C

periods, but it was low during delay period (i.e., late delay and early test-C periods).

Periodicity index exhibited similar task period-dependence in the model and

experiment (c.f. Figure 5C and Figure S5 in (Yamamoto et al., 2014)).

We next analyzed how the blockade of MECIII-to-CA1 projection affects the behavior of

our model in different task periods. In the experiment, this blockade significantly

impaired working memory performance of the rat. When MECIII-to-CA1 projection was

blocked during the encoding epoch (sample-L period), MECIII activity and the firing rate

difference between L and R subgroups were suppressed during both sample-L and the

subsequent late test-C periods (Figure 4B, blue), meaning that task performance was

impaired. When the blockade was during the recall epoch (late test-C, 5.5-7.5 s), the

inter-subgroup difference was reduced and task performance was also impaired (green

line in Figure 4B). In contrast, when the blockade was imposed during sample-C (3-4.5

s) or early test-C period (4.5-6 s), MECIII activity was not greatly affected (Figure S3).

Figure 4C summarizes the resultant task performance of the model. In three of the four

conditions (blockade in sample-C, early and late test-C), results were well consistent

with experimental observations (c.f., Figure 6F in (Yamamoto et al., 2014)). In addition,

our model predicts that the blockade in sample-L period significantly impairs working

memory performance (p=3.175x10^{-10}), suggesting that the CA1-MECV-MECIII loop

circuit maintains neural activity in the MECIII and plays a pivotal role in the spatial

working memory task. This prediction should be experimentally validated.

Figure 4. Blockade of MECIII-to-CA1 connections during sample-L and late test-C

periods. (A) Periodicity index (Yamamoto et al., 2014) was calculated for the activity of

MECIII E neurons (STAR methods). The labels L, D, C refer to sample-L, delay, test-C

periods, respectively, and the numbers 1 and 2 label the early and late portions,

respectively, of these periods. (B) Average differences in firing rate between the L and

R subgroups of MECIII E neurons were calculated under the blockade of MECIII-to-CA1

connections: normal condition (black); the blockade during sample-L periods (blue);

the blockade during late test-C periods (green). In each condition, the differences were

averaged over five networks and five initial states. By definition, green and black lines

overlap with one another before the blockade. Boxes above the traces indicate the

periods of blockade. (C) P_L (same as in Figure 1F) were calculated for different periods

of the blockade.

Figure S3 (related to Figure 4). Blockade of MECIII-to-CA1 connections during sample-
C and test-C periods. Connections from MECIII to CA1 were blocked during sample-C
(blue) and early test-C (green) periods. Differences in firing rate between the L and R
subgroups of MECIII E neurons are shown in the same manner as in Figure 4B. Similar
evolutions are also shown in the normal condition (black).

Experimental validation of period-dependent preferred theta phases
Our model predicts that CA1 E neurons shift their preferred theta phases from the
troughs to the peaks when [ACh] is high (Figures 2B and 2E). In Figure 5A, we present
the phase preference of CA1 E neurons during sample-C, sample-L, delay, early test-
center (test-C1) and late test-center (test-C2) periods of the DNMP task. Their spikes
preferred the troughs of theta oscillation during sample-C periods but, owing to the
disinhibitory mechanism, the preferred phase was shifted to the peaks during sample-L
periods (Figure 2B). When the model rat returned to the home position (delay period),
[ACh] was decreased to reactivate PV neurons in CA1, which reduced the sensitivity of
CA1 to inputs from MECIII and CA3 and selectively suppressed spike generation at the
peaks of theta oscillation (but not at the troughs). In test-C1 periods, [ACh] was again
increased to allow the activation of CAN current (Figure 3C), which shifted the
preferred phase to the descending phase of theta oscillation. During test-C2 periods,
our model predicts a progressive advance of preferred theta phase in CA1 due to an
enhanced synaptic drive by MECIII (Figure 3B).

We confirmed these predictions in the data of a DNMP task in T-maze (Yamamoto et
al., 2014). Figure 5B shows the distributions of preferred phases of spikes in rat CA1
during different task periods, i.e., sample-C, sample-L (corresponding to the reward
arm), delay, test-C1, and test-C2 periods (see STAR Methods). In rats, spikes were
generally not modulated by theta oscillation as strongly as in the model. In particular,
oscillatory modulations were weak in sample-C periods. Nonetheless, the preferred
theta phases in the various task periods are well consistent between rats and models.

The average preferred phase is delayed during delay periods compared to other task

periods in both rats and models (Figure 5C). In addition, our model predicts that the

preferred phase is progressively advanced during test-C2 (i.e., late test-center) period

due to an increased synaptic drive by MECIII (Figure 3B).

Next, we asked whether preferred theta phase behaves similarly in an alternating

figure-eight task (Mizuseki et al., 2013). We were particularly interested in examining

the hypothesized role of cholinergic control of working memory function. In the

alternating figure-eight task, rats were trained to alternately change the turn direction

at a junction point of an eight-shape maze, meaning that the rats had to remember the

turn direction of the preceding run. This task is similar to the previous DNMP task, but

one difference is that sample and test trials are not clearly separated in the alternating

figure-eight task. Nevertheless, we may correlate the behavioral epochs of the two

tasks to each other. When rats traverse the center arm, they had to retrieve memory of

the preceding choice to prepare for the next choice. Therefore, traveling along the

center arm may correspond to test-C period in the DNMP task. Then, we can define

three distinct areas on the eight-shape maze (Figure 5D): early center, late center and

reward arms, which may correspond to test-C1, test-C2 and sample-L periods,

respectively. Below, we follow these rules.

Figure 5E shows the preferred phases of excitatory neurons in the deep layer of CA1. It

has been reported that for some unknown reason these neurons only exhibit phase

shifts in early trials (Fernández-Ruiz et al., 2017; Mizuseki et al., 2013). Therefore, we

only used data of initial ten trials in the following analyses. On the early center arm

(test-C1 period), neurons fired more frequently around the troughs of theta oscillation

than the peaks. However, on the late center arm (test-C2 period), neurons fired slightly

more often at the peaks, generating two peaks per theta cycle in the spike density

distribution. On the reward arm (sample-L period), neurons fired most frequently at

the peaks, which is consistent with the previous study(Fernández-Ruiz et al., 2017).

These results seem to be consistent with the model's prediction that the preferred

firing phase of CA1 neurons changes from the troughs to the peaks of theta oscillation

during the epochs of high [ACh]: in the alternating figure-eight task, high level of

attention, or high [ACh], is likely to be required on the reward arm (for encoding

reward information) and the late center arm (for recalling the previous choice).

Figure 5. Preferred theta phases in model networks and rats. (A) Phase preferences

are shown for CA1 E neurons in model networks during given task periods (top). (B)

Phase preference curves of CA1 neurons were calculated for data obtained in

(Yamamoto et al., 2014). (C) Preferred theta phases of the models (filled circles) and

rats (empty circles) were averaged over multiple theta cycles during given task periods.

The average phase $\bar{\theta}$ is computed as $\bar{\theta} = \arg\left(\Sigma_k \exp(i\theta_k)\right)$, here, k is index of spikes

for all neurons and i is imaginary unit. The same average phases are shown for two

theta cycles (one in darker colors and one in light colors) for the clarity of the plots. (D)

Schematic illustration of the figure-eight maze used in (Fernández-Ruiz et al., 2017;

Mizuseki et al., 2013). Colored rectangles indicate early-center, late-center, and reward

periods from which data were resampled. (E) Phase preference curves of CA1

excitatory neurons were calculated by using the data of (Mizuseki et al., 2013). For

comparison, we divided the task periods of center arm and reward arm into early and

late epochs.

Task performance depends on acetylcholine concentrations in the model

In our model, two ACh-regulated mechanisms, that is, disinhibitory circuit in CA1 and

CAN current in MECV excitatory cells, play crucial roles in encoding, maintenance and

recall epochs of working memory tasks. Therefore, we examined whether these core

mechanisms work robustly when [ACh] is varied. We changed the default levels of

[ACh] with other parameter values unchanged. Lowering the default [ACh], which

weakens disinhibition, during the encoding epoch (sample-L) disenabled the CA1 L and

R subgroups to exhibit large enough activity differences to encode spatial information

in the CA1-MECV-MECIII loop circuit (Figure 6A, blue). Task performance was severely

impaired, contrasting to intact performance at higher default [ACh] levels (Figure 6B,

left). Lower default [ACh] levels during delay period had almost no effects on task performance (Figure 6B, center). Finally, lower default [ACh] levels during the recall epoch (test-C2) eliminated the reactivation of the subgroup L (Figure 6A, green) and task performance was severely impaired (Figure 6B, right), but performance remained intact at higher [ACh] levels. These results show that default [ACh] levels should be sufficiently high during the encoding and recall epochs, but fine tuning of [ACh] is unnecessary.

Next, we explored whether theta-phase-locked firing has anything to do with the success of the working memory task. To this end, we compared the theta preference of CA1 neurons during the test-C2 period between successful and failure trials in both models and rats (Figure 6C). [ACh] was at the default levels. In both models and rats, neurons preferentially fired around the peaks of theta oscillation in success trails, but firing phases were somewhat delayed in failure trials.

Figure 6. Cholinergic modulations in the network model. (A) In CA1 (left) and MECIII (right), differences in firing rate between the subgroups L and R were calculated at the normal (black) and reduced levels of [ACh] during encoding (sample-C, blue) and recall (test-C2, green) epochs. (B) Probability of left choice averaged over different networks and initial conditions are shown at different levels of [ACh] during sample-L (left), delay (center) and test-C2 (right) periods. Thick lines indicate results for the default [ACh] levels. (C) Frequency of spikes in CA1 excitatory neurons during test-C2 periods (top) are shown in the model (left) and rats (right). In the model, [ACh] was set to the normal level and spike counts are shown separately for the subgroups L and C. Only the total spike count is shown for rats. Bottom panels show the differences in firing rate between successful and failure trials.

Role of high-gamma oscillation in memory in MECIII and CA1

Decision making in rats was accompanied by a rapid increase in coherent high-gamma oscillations (60 -120 Hz) between MECIII and CA1 (Yamamoto et al., 2014). However,

we did not model the mechanism to generate prominent gamma oscillations to keep

our model mathematically simple and minimal. Actually, the simplified mathematical

description was sufficient for accounting for many findings on neural activity and rat

behavior reported in the experiment. Then, the question arises about the role of

coherent high gamma oscillation in the working memory task. To answer this question,

we applied a common oscillatory input in the high-gamma range (80 Hz) to E neurons

in MECIII and CA1 (Figure 7A: also see the STAR Methods). In the experiment, high

gamma oscillations of LFPs were synchronized between MECIII and the lacunosum

molecule layer of CA1, to which MECIII-to-CA1 connections project, indicating a

common source of high gamma oscillations projecting to both areas.

High gamma oscillation improved the decoding of memorized information from the

entorhinal-hippocampal loop circuit in the model. To show this, we built a virtual

decoder of excitatory and inhibitory neurons receiving inputs from MECIII and CA1

(Figure 7A, see the STAR method for details). Stimulated by the high gamma input, E

neurons in both areas tended to fire in the high-gamma frequency range (Figure7B).

Spike bursts were delayed in CA1 by about 10 ms from those in MECIII, which is

consistent with experimental observation (Yamamoto et al., 2014). Because this delay

is approximately equal to the period of high gamma oscillation, synaptic inputs from

the two areas coincidently arrived at the decoder in each high-gamma cycle. The

coincident input amplified the evoked responses and facilitated spike firing of the

decoder (see bursting of CA1, MECIII and decoder neurons around 7.7 sec in Figure 7B).

In contrast, without the high gamma input, inputs from MECIII and CA1 did not arrive

coherently to the decoder. Feedforward inhibition, which is a ubiquitously found motif

of cortico-cortical synaptic connections (Isaacson and Scanziani, 2011), further

attenuated the impact of incoherent spike input on decoder neurons. Thus, coherent

high gamma activity in MECIII and CA1 may facilitate the readout of spatial information

from MECIII by other cortical areas.

To generalize this observation, in Figure 7C, we quantified decoding performance while

changing burst size (the number of spikes per burst) in MECIII and CA1. The

performance was measured by the probability that coincident bursts in CA1 and MECIII

generate a spike burst in a decoder neuron. Without gamma oscillation, even a large

burst in MECIII and/or CA1 could not evoke a burst in the decoder. In contrast, in the

presence of gamma oscillation a small burst in MECIII and/or CA1 was sufficient for

evoking a burst in the decoder with high fidelity. These results further support the role

of coherent high gamma oscillation in facilitating the decoding performance. It is noted

that an increased high gamma coherence between CA1 and MECIII enhanced the

performance even if the input burst size was reduced.

Figure 7. Role of high-gamma oscillation in information decoding. (A) Decoding of

choice information from MECIII and CA1 is schematically illustrated. (B) Raster plots are

shown for CA1 and MECIII E neurons in the subgroup L and excitatory and inhibitory

neurons in the decoder. From 7.5 [s] to 8 [s], a common coherent high-gamma input

was applied to MECIII E and CA1 E neurons. (C) Decoding performance (upper) and the

average number of output spikes evoked from a decoder neuron by a single burst in

MECIII (left), CA1 (middle) or both (right) are plotted against the input burst size

(bottom). Spike counts obtained with (blue) and without (red) the high-gamma

oscillatory input are displayed. The decoding performance was defined as the

probability that the number of output spikes in a burst exceeds a threshold value

(dotted lines in bottom panels) for a given input burst size.

Discussion

In this study, we developed a model comprising MECV, MECIII and CA1 to explore how

these local circuits process and communicate information with each other during

DNMP tasks. Our model indicates that ACh concentration is modulated in a task-period

dependent manner to coordinate local network computation for encoding,

maintenance and recalling spatial information across the multiple cortical areas. With

636 these modulations, our model successfully replicates the various features of neural

637 activity observed in MECIII and CA1 (Yamamoto et al., 2014). In particular, the model

638 predicts that CA1 neurons change their preferred theta phases depending on cognitive

639 demands, which was also supported by experimental data (Fernández-Ruiz et al., 2017;

640 Mizuseki et al., 2013; Yamamoto et al., 2014).

642 **Relevance of MEC-CA1 loop to spatial working memory tasks**

643 The hippocampal area CA1 is a central locus for spatial information processing, and

644 stores the concurrent position of the rat (O'Keefe and Dostrovsky, 1971) as well as

645 retrospective and prospective representations of position information (Dragoi and

646 Buzsáki, 2006; Ferbinteanu and Shapiro, 2003; Foster and Wilson, 2006; Gupta et al.,

647 2010; Pastalkova et al., 2008; Zheng et al., 2016). Based on the hypothesis that the

648 CA1-MECV-MECIII loop circuit is involved in spatial working memory (van Strien et al.,

649 2009; Witter et al., 2000), we demonstrated how the spatial information of the

650 selected arm is encoded in CA1 during a sample trial (Figure 2), maintained in MECV

651 during delay period, and transferred to MECIII and reloaded on CA1 for decision

652 making (Figure 3). Consistent with the hypothesis, connections from MECIII to CA1 are

653 crucial for the success of spatial working memory tasks (Suh et al., 2011; Yamamoto et

654 al., 2014). Our model demonstrated this role of MECIII-to-CA1 connections in spatial

655 working memory, predicting their crucial contribution to memory encoding (Figure S3).

656 This prediction can be tested experimentally.

658 Sequence of spikes with theta phase precession, that is, "theta sequence" (Ferbinteanu

659 and Shapiro, 2003; Middleton and McHugh, 2016; Pfeiffer and Foster, 2013; Schlesiger

660 et al., 2015; Zheng et al., 2016), has been observed in the hippocampus and the MEC

661 during cognitive tasks requiring episodic memory. The blockade of MECIII-to-CA1

662 connections causes modulation of theta activity in MECIII (Suh et al., 2011; Yamamoto

663 et al., 2014). Similarly, inactivation of the MEC disrupts the temporal organization of

664 spikes and impairs information maintenance (Robinson et al., 2017). These results

665 imply that the temporal coordination of theta-phase-locked neuronal firing along the

CA1-MECV-MECIII loop circuit is crucial for the success of spatial working memory

tasks. We showed an example case in which the disruption of this temporal

coordination in MECIII led to a significant increase of failure trials (Figure S1B, C).

Our model hypothesizes that [ACh] changes in time during a working memory task,

which generates shifts of preferred theta phase in CA1 E neurons: higher [ACh]

advances the preferred phase towards the peak of theta oscillation (Figure 5). Based on

this hypothesis, the model predicts that phase advances occur during the encoding

epoch in sample trials (i.e., on the reward arm) and during the recall epoch in test trials

(i.e., on the center arm). We validated this prediction with the results of two

experiments (Fernández-Ruiz et al., 2017; Mizuseki et al., 2013; Yamamoto et al.,

2014). Phase advances in the encoding epoch have been known previously and can be

accounted for by temporal separation between CA3 input and MECIII input to CA1

(Colgin et al., 2009; Cutsuridis et al., 2010; Hasselmo et al., 2002; Lasztóczi and

Klausberger, 2016; Milstein et al., 2015)(Mizuseki et al., 2009). Input from CA3

preferentially arrives at CA1 on the descending phase of theta oscillation of LFP

(Klausberger and Somogyi, 2008) (Mizuseki et al., 2009)whereas input from MECIII

arrives at the peaks of theta oscillation (Colgin et al., 2009; Fernández-Ruiz et al., 2017;

Hasselmo et al., 2002) (Mizuseki et al., 2009). Because MECIII input, which presumably

carries sensory information, seems to dominate CA3 input during encoding

(Hasselmo2002), CA1 neurons likely fire at the peaks rather than the troughs of theta

oscillation (Fernández-Ruiz et al., 2017).

Phase advances on the later central arm (i.e., in the recall epoch) represent a novel

finding of this study. CA1 neurons were previously shown to fire at the troughs of theta

oscillation during memory recall (Fernández-Ruiz et al., 2017), and this was consistent

with the view that CA3 input dominates MECIII input during this epoch. Challenging the

conventional view, our model predicts that CA1 neurons retrieve spatial memory from

the MECIII, hence firing at the peaks of theta oscillation. Possibly consistent with this

prediction, if we divide the center arm into early and late portions in (Mizuseki et al.,

2009), preferred theta phases show a second (and advanced) peak in the late portion

of recall epoch (Figure 5D). This peak was absent in the previous analysis (Fernández-

Ruiz et al., 2017) because the center arm was treated as a single entity. The consistency

between the model and experiment requires further clarification.

Reflection of cognitive demands on the MEC-CA1 loop circuit through ACh

ACh is involved with several cognitive functions such as sensory discrimination (Hangya

et al., 2015; Pinto et al., 2013), associative learning (Sabec et al., 2018), and spatial

(Croxson et al., 2011; Okada et al., 2015) and non-spatial working memory (Furey et al.,

2000; Hasselmo and Stern, 2006; McGaughy et al., 2005). In correlation with cognitive

states, ACh concentration changes to modulate activity of the specific types of neurons

(Muñoz et al., 2017; Womelsdorf et al., 2014) through muscarinic and nicotinic

receptors (Parikh et al., 2007; Teles-Grilo Ruivo et al., 2017; Zhang et al., 2010). In

associative learning, ACh was suggested to facilitate MECIII-to-CA1 input during the

encoding epoch and CA3-to-CA1 input during the decoding epoch (Hasselmo, 2006).

We propose a novel role and mechanism of ACh for the functions of the entorhinal-

hippocampal loop circuit according to the cognitive demands arising during a spatial

working memory task, namely, memory encoding, maintenance and recall. Consistent

with the proposal of our model (Figure 1D), it has recently been shown in a DNMP task

(Teles-Grilo Ruivo et al., 2017) that [ACh] is significantly higher on the reward arm than

in other positions in both sample and test trials, that on the center arm [ACh] tends to

be larger in test trials than in sample trials, and that [ACh] is low in delay periods (c.f.,

Figure 6B).

We assumed that a change in cognitive demands is reflected in a phasic change in

[ACh] on the timescale of seconds. However, [ACh] is thought to change in a diffusive

and tonic manner on much slower timescales of minutes or hours. Importantly, recent

studies have revealed that [ACh] undergoes phasic changes at sub-second and second

timescales (Parikh et al., 2007; Teles-Grilo Ruivo et al., 2017; Zhang et al., 2010), and

such a phasic change in [ACh] is associated with reward or aversive signals (Hangya et

al., 2015). Further, task performance is correlated with slower tonic increases in [ACh]

during the task period (Parikh et al., 2007), but uncorrelated with phasic changes in

[ACh] in the reward arm (Teles-Grilo Ruivo et al., 2017). In our model, task performance

saturates above a certain level of [ACh] in the reward arm (Left panel in Figure 6B). Our

results suggest that the tonic level of [Ach] expresses an overall bias during each trial

and a phasic increase in [Ach] gives a more elaborate modulation reflecting a specific

cognitive demand.

Dynamic processing across multiple areas

Coherence in neural activity between different cortical areas varies with the cognitive

state of the brain (Benchenane et al., 2010; Fries, 2015). Furthermore, disruption of a

cortico-cortical interaction at different behavioral states can impair task performance

differently (Spellman et al., 2015; Yamamoto et al., 2014). These results imply that

information flows between cortical areas are differentially routed according to the

demand of the on-going cognitive process through the dynamical regulation of

corticocortical coherence. Theoretical studies have proposed several mechanisms of

information routing based on a balance control between excitatory and inhibitory

synaptic inputs (Vogels and Abbott, 2009), disinhibitory circuits (Yang et al., 2016),

spontaneous bursts (Palmigiano et al., 2017), and band-pass filtering by a feed-forward

inhibitory circuit (Akam and Kullmann, 2010). While these studies focused on the

circuit mechanisms of information routing, we addressed how such mechanisms are

integrated to perform a spatial working memory task through different cognitive

demands (Benchenane et al., 2010; Spellman et al., 2015; Yamamoto et al., 2014). We

demonstrated that cholinergic inputs coordinate the encoding and recall functions by

modulating the cortical disinhibitory circuit and Ca^{2+}-dependent cationic channels in

excitatory cells.

Accumulating evidence suggests that disinhibitory circuits play a crucial role in

cognitive tasks such as fear conditioning (Letzkus et al., 2011; Pi et al., 2013) and

sensory discrimination (Hangya et al., 2015; Pinto et al., 2013). VIP, SOM and PV

inhibitory neurons are dominant interneuron types of the disinhibitory circuit (Donato
et al., 2013; Francavilla et al., 2018; Kamigaki and Dan, 2017; Zhang et al., 2014) VIP
neurons express muscarinic receptors and are depolarized by cholinergic input (Bell et
al., 2014). VIP neurons project more strongly to SOM neurons than to PV neurons in
cortical areas (Kamigaki and Dan, 2017; Zhang et al., 2014), but some studies have
shown stronger modulations of PV neurons in the hippocampus (Donato et al., 2013;
Francavilla et al., 2018). PV neurons innervating the perisomatic area of CA1 excitatory
neurons preferably spike in the descending phase of theta oscillation (Klausberger and
Somogyi, 2008) to weaken CA3 input. In contrast, SOM (OLM in CA1) neurons
projecting the distal dendrites of CA1 excitatory neurons preferably spike at the
troughs of theta oscillation (Klausberger and Somogyi, 2008)(Royer et al. Buzskai, 2012
Nature Neuroscience) to weaken MECIII input. Because MECIII input rarely arrive at the
troughs of theta oscillation, the suppression of MECIII input by disinhibited OLM
neurons exerts a smaller effect on excitatory neuron firing compared to disinhibited PV
neurons. Therefore, we mainly focused on the effect of PV neurons on neural circuit
functions. In line with our model's prediction (Figure S2), optogenetic inhibition of PV
neurons impairs performance in spatial working memory (Murray et al., 2011).
However, the actual spikes delivered by the MECIII are distributed broadly over a theta
cycle in rats (Mizuseki et al., 2009), implying that disinhibition of PV and SOM neurons
can modulate activity of excitatory neurons in parallel. Indeed, our model predicts that
inactivation of PV or VIP neurons impairs task performance in different ways (Figure
S2). This prediction can be examined by a selective inhibition of either neuron types in
the spatial working memory task.
779
Covert memory state for maintenance of information
Recent studies showed that dynamically evolving neuronal activity can maintain
information during a delay period in working memory tasks (Murray et al., 2017;
Stokes, 2015; Wolff et al., 2017)(Pastalkova et al., 2008). In the DNMP task we studied
(Yamamoto et al., 2014), theta phase-locked firing of MECIII neurons was correlated
with the success of the task. Nevertheless, this neuronal activity temporarily vanished

during a delay period, implying that a non-spiking activity maintains information on the

previous choice. We hypothesized that the conductance of a specific ionic channel, i.e.,

calcium-dependent cationic current, remains in an elevated state to preserve spatial

information during delay period. This elevated state is not accompanied by neuronal

firing, hence is consistent with experimental observations. This mechanism was

originally proposed to account for persistent activity of isolated single neurons

(Fransen et al., 2002; Fransén et al., 2006) and suggested to be engaged in temporal

association memory (Kitamura et al., 2014). Our model demonstrates that the same

mechanism can generate a covert memory state necessary in spatial working memory.

This and other mechanisms of covert memory state, for instance, short-term synaptic

plasticity (Mongillo et al., 2008), are not mutually exclusive. However, our mechanism

has an important advantage that working memory maintenance is turned on and off

by cholinergic modulation depending on the cognitive demand. Thus, our results

suggest that neuromodulators are crucial for the flexible control of memory processing

by the brain.

Limitation of the model

We showed that coherent activations of CA1 and MECIII at high-gamma frequencies

facilitate decoding of information about the previous choice from CA1 and MECIII

(Figure 7). However, gamma oscillation is not absolutely necessary in our model for

performing spatial working memory tasks. Theta-phase-locked neuronal firing alone

could sufficiently facilitate information transfer along the MECIII-CA1-MECV loop circuit

without gamma oscillation. This result may somewhat contradict the experimentally

suggested role of gamma oscillation in information transfer between the hippocampus

and entorhinal cortex (Colgin et al., 2009; Yamamoto et al., 2014). The role of gamma

oscillation needs to be further explored.

Secondly, we did not model any mechanism to translate the decoded information into

a correct choice behavior under a given rule of decision making (e.g., the alternate

choice of left or right turn). The mPFC is projected to by CA1 and projects back to it via

reuniens (Dolleman-Van Der Weel and Witter, 1996; Ito et al., 2015), and is engaged in

spatial working memory (Bolkan et al., 2017; Jones and Wilson, 2005; Spellman et al.,

2015). Furthermore, some mPFC neurons exhibit rule-related activities. However, the

delay-period activity of mPFC neurons is specific to neither previous nor present

location in a DNMP task (Bolkan2017) and the rule-related activities are not location-

specific (Durstewitz et al., 2010; Guise and Shapiro, 2017; Preston and Eichenbaum,

2013). Where and how decision rules are processed and how spatial working memory

and rule-related activities are integrated are open to future studies.

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1053

1054

1055

1056   *STAR Methods*

1057

Neuron models

Our model has two classes of neurons: i) Poisson neurons; ii) Hodgkin-Huxley type (HH)

neurons.

i) Poisson neurons

There are four types of theta-oscillating neurons (excitatory neurons in CA3 and MECII,

VIP neurons in CA1 and GABAergic neurons in MS) and noise neurons. Other types of

neurons, that is, excitatory (E) neurons, fast spiking (PV) neurons and OLM neurons in

CA1, E and PV neurons in MECIII and E and PV neurons in MECV, are modeled as HH

neurons. 40 excitatory and 40 inhibitory noise neurons project to all HH neurons. Firing

rates of noise neurons are different depending on the cortical areas modeled: 35 [Hz]

in CA1 and in MECIII and 30 [Hz] in MECV.

For theta-oscillating Poisson neurons, we described the theta-oscillating (10Hz)

probability of spiking per unit time $P_x(t_1 < t < t_1 + \Delta t)$ (x=E in CA3 and MECII, VIP in

CA1, GABA in MS) as

1072
$$P_x(t_1 < t < t_1 + \Delta t) = (\Theta (A_x (sin (2\pi (\tfrac{t}{T} - \theta_x)) + B_x)) + C_x)\Delta t,$$

where $\Theta(s)$ = s when $s>0$ or otherwise 0. $T = 100$ ms and Δt = 0.02 ms is the step size

of our numerical simulation. A_x and B_x are the amplitude and preferred phase of

oscillating firing rate, respectively, and θ_x is the preferred phase of theta oscillation for

the neuron type x, whereas C_x is the amplitude of background noise for inactive

subgroups outside of their place fields. We set the preferred phases based on previous

experimental studies (Borhegyi, 2004; Klausberger and Somogyi, 2008; Mizuseki et al.,

2009) as follows:

1080

x = CA3:

CA3 neurons in the model are divided into four groups according to their spatial

preferences (Figure 1 and Circuit structure in STAR Methods). Their firing patterns are

changed depending on the present location of the model rat. When the model rat is in

Center ($0 < t < 1000$ ms, sample-C and $4500 \leq t < 7500$ ms, test-C), sample-Left

($1000 \leq t < 3000$ ms) and Home ($3000 \leq t < 4500$ms) positions, Center, Left, and

Home subgroups are activated, respectively.

1088
$$A_x = 30 \text{ [Hz]}, B_x = 1, C_x = 0 \text{ [Hz]}, \theta_x = -0.2$$

1089   for neurons in an active subgroup, and

$$A_x = 0 \text{ [Hz]}, C_x = 3 \text{ [Hz]}$$

1090   for neurons in inactive subgroups.

1091

1092 x = ECII:

1093 During the entire trial period, we set the parameters as
$$A_x = 5 \text{ [Hz]}, B_x = 0.6, C_x = 0 \text{ [Hz]}, \theta_x = -0.2$$
1094

1095 *x* = GABAergic in MS:

1096 Three groups exist in the model, those projecting to PV in CA1, to OLM in CA1 and to
1097 PV in MECV. The preferred theta phase of MECV PV-projecting GABAergic neurons is
1098 the same as that of CA1 OLM-projecting GABAergic neurons,
$$A_x = 5[Hz], B_x = 0.8, C_x = 0[Hz], \theta_x = -0.1,$$
1099
1100 whereas the preferred phases of CA1 PV-projecting neurons are different from the
1101 above ones (Borhegyi, 2004) and given by
$$A_x = 5[\text{Hz}], B_x = 2.0, C_x = 0[Hz], \theta_x = -0.5.$$
1102

1103

1104 *x*=VIP:

1105 During the entire trial period, we set the parameters as
$$A_x = 20[Hz], B_x = 0.3, C_x = 0[Hz], \theta_x = -0.4.$$
1106

1107 Finally, we set a reference theta oscillation in CA1 SP as
$$A_x = 1, \theta_x = 0.5, B_x = 0, C_x = 0,$$
1108 which is a virtual oscillatory component used only for determining the relative
1109 oscillation phases of other brain regions to theta oscillation in CA1 SP, but not for
1110 numerically simulating the network model.

1111

ii) HH neurons

In our model, there are seven types of neurons; E, PV and OLM in CA1, and E and PV in
MECV and MECIII. PV neurons are modeled identically in all areas (Wang and Buzsáki,
1996). In the following equations, I_i is synaptic input from other neurons as described
in Circuit structure in STAR Methods. Dynamics of each type of neurons is described
below.

1118

1119 a) Excitatory neurons in CA1

1120 We modeled excitatory neurons in CA1 based on (Wulff et al., 2009). We additionally
1121 included an afterhyperpolarization (AHP) and h currents in the model for generating a
1122 weak subthreshold oscillation of the membrane potentials through interplay between
1123 AHP (Middleton et al., 2008) and h current (Rotstein et al., 2006).

$$V_{Na} = 50[mV], V_K = -100.0[mV], V_{AHP} = -100.0[mV], V_h = -20.0[mV], V_L$$
$$= -67.0[mV]$$
$$g_{Na} = 100.0[mS/cm^2], g_K = 80.0[mS/cm^2], g_{AHP} = 0.2[mS/cm^2], g_h$$
$$= 0.1[mS/cm^2], g_L = 0.1[mS/cm^2]$$
$$C = 1, I_{cnst} = -0.1$$

$$C\frac{dV_i}{dt} = g_{Na}m_\infty(V)^3 h(V_{Na} - V_i) + g_K n^4(V_K - V_i) + g_{AHP}w(V_{AHP} - V_i)$$
$$+ g_h(0.65hf + 0.35hs)(V_h - V_i) + g_L(V_L - V_i) + I_i + I_{const}$$

1124   The channel variable h is determined as

1125 $$h = \max(1 - 1.25n, 0).$$

1126   Other channel variables evolve according to

1127 $$\frac{dx}{dt} = \frac{x_\infty(V) - x}{\tau_x(V)},$$

1128   where x = m, n, w, hf and hs. Among these variables, m and n are determined by

1129

1130 $$x_\infty(V) = \frac{\alpha_x(V)}{\alpha_x(V) + \beta_x(V)},$$

1131 $$\tau_x(V) = 1/(\alpha_x(V) + \beta_x(V)),$$

1132   where x stands for either m or n, and

1133 $$\alpha_m(V) = -0.32(V + 54)/(\exp(-0.25 * (V + 54)) - 1,.$$

1134 $$\beta_m(V) = 0.28(V + 27)/(\exp(0.2 * (V + 27)) - 1),$$
$$\alpha_n(V) = -0.032(V + 52)/(\exp(-0.2 * (V + 52)) - 1),$$

1135 $$\beta_n(V) = 0.5\exp(-0.025(V + 57)).$$

1136   Other variables are determined by

$$w_\infty(V) = \frac{1}{\exp(-0.1(V + 41)) + 1}$$

$$\tau_w(V) = \frac{500}{3.3\exp(0.05(V + 41)) + \exp(-0.05(V + 41))}$$

$$hf_\infty(V) = 1/(1 + \exp\left(\frac{V + 79.2}{9.78}\right))$$

$$\tau_{hf}(V) = \frac{0.51}{\exp((V - 1.7)/10) + \exp(-(V + 340)/52)} + 1$$

1137 $$hs_\infty(V) = 1/\left(1 + \exp\left(\frac{V + 2.83}{15.9}\right)\right)^{58}$$

1138 $$\tau_{hs}(V) = \frac{5.6}{\exp\left(\frac{V - 1.7}{14}\right) + \exp\left(\frac{-(V + 260)}{43}\right)} + 1.$$

1139

1140   b) PV in CA1, MECIII, MECV

1141   We modeled PV neurons in CA1 as well as those in MECIII and MECV as described in

1142   (Wang and Buzsáki, 1996).

$$V_{Na} = 55[mV], V_K = -90.0[mV], V_L = -65.0[mV]$$
$$g_{Na} = 35.0[mS/cm^2], g_K = 9.0[mS/cm^2], g_L = 0.1[mS/cm^2]$$
$$C = 1$$
$$C\frac{dV_i}{dt} = g_{Na}m_\infty(V)^3 h(V_{Na} - V_i) + g_K n^4(V_K - V_i) + g_L(V_L - V_i) + I_i$$

$$\frac{dx}{dt} = \frac{x_\infty(V) - x}{\tau_x(V)}$$

$$x_\infty(V) = \frac{\alpha_x(V)}{\alpha_x(V) + \beta_x(V)}$$

1143 $$\tau_x(V) = 1/(\alpha_x(V) + \beta_x(V)),$$

1144 where the index $x = n$, h and m.

$$\alpha_m(V) = 0.1(V + 35)/(1 - \exp(-0.1(V + 35)))$$

$$\beta_m(V) = 4\exp\left(-\frac{V + 57}{40}\right)$$

$$\alpha_n(V) = 0.01(V + 34)/(1 - \exp(-(V + 34)))$$

$$\beta_n(V) = 0.125\exp(-(V + 44)/80)$$

$$\alpha_h(V) = 0.07\exp(-(V + 58)/20)$$

$$\beta_h(V) = 1/(\exp(-0.1(V + 28)) + 1)$$

1145

1146   c) OLM in CA1:

1147 We modeled OLM neurons as described in (Wulff et al., 2009).

$$V_{Na} = 60[mV], V_K = -100.0[mV], V_L = -70.0[mV], V_A = -90.0[mV], V_h = -32.0[mV]$$

$$g_{Na} = 40.0[mS/cm^2], g_K = 23.0[mS/cm^2], g_A = 16.0[mS/cm^2], g_h = 6.0[mS/cm^2], g_L = 0.05[mS/cm^2]$$

$$C = 1.3, I_{cnst} = 0.2$$

$$C\frac{dV_i}{dt} = g_{Na}m^3h(V_{Na} - V_i) + g_K n^4(V_K - V_i) + g_A ab(V_A - V_i) + g_h r(V_h - V_i) + g_L(V_L - V_i) + I_i + I_{cnst}$$

1148 $$\frac{dx}{dt} = \frac{x_\infty(V) - x}{\tau_x(V)},$$ (Eq.2)

1149 where $x = m,\ h, n, a, b$ and r. The channel variables are determined by

1150

$$x_\infty(V) = \frac{\alpha_x(V)}{\alpha_x(V) + \beta_x(V)},$$

1151 $$\tau_x(V) = \frac{1}{\alpha_x(V) + \beta_x(V)}.$$

1152 for m, h and n with

$$\alpha_m(V) = -\frac{0.1(V + 38)}{\exp\left(-\frac{v + 38}{10}\right) - 1}$$

$$\beta_m(V) = 4\exp\left(-\frac{V + 65}{18}\right)$$

$$\alpha_h(V) = 0.07\exp\left(-\frac{V + 63}{20}\right)$$

$$\beta_h(V) = 1/(\exp(-0.1(V + 33)) + 1)$$

$$\alpha_n(V) = \frac{0.018(V - 25)}{1 - \exp\left(-\frac{V - 25}{25}\right)}$$

$$\beta_n(V) = \frac{0.0036(V - 35)}{\exp\left(\frac{V - 35}{12}\right) - 1}$$

1153   For $x = a$, b and r, variables in Eq.2 are determined by

$$a_\infty(V) = 1/(1 + \exp(-(V + 14)/16.6))$$
$$\tau_a(V) = 5$$
$$b_\infty(V) = 1/(1 + \exp((V + 71)/7.3))$$
$$\tau_b(V) = 1/\left(\frac{0.000009}{\exp\left(\frac{V - 26}{18.5}\right)} + \frac{0.014}{0.2 + \exp\left(-\frac{V + 70}{11}\right)}\right)$$
$$r_\infty(V) = 1/(1 + \exp((V + 84)/10.2))$$
$$\tau_r(V) = 1/(\exp(-14.59 - 0.086V) + \exp(-1.87 + 0.0701V))$$

1154

d) Excitatory neurons in MECIII

We modeled excitatory neurons in MECIII based on an excitatory neuron model of
MECII (Middleton et al., 2008), with some modifications of parameter values. These
neurons have an AHP current in addition to the standard sodium, potassium and leak
currents. The model is described as

C=1.0 [uF/cm^2],
$$V_{Na} = 50[mV], V_K = -90.0[mV], V_{AHP} = -100.0[mV], V_L = -65.0[mV]$$
$$g_{Na} = 100.0\left[\frac{mS}{cm^2}\right], g_K = 80.0\left[\frac{mS}{cm^2}\right], g_{AHP} = 0.3\left[\frac{mS}{cm^2}\right]$$
$$g_L = 0.5[mS/cm^2]$$

1161 $C\frac{dV_i}{dt} = g_{Na}m^3h(V_{Na} - V_i) + g_Kn^4(V_K - V_i) + g_{AHP}w(V_{AHP} - V_i) + g_L(V_L - V_i) + I_i$

1162 $$\frac{dx}{dt} = \alpha_x(V)(1 - x) - \beta_x(V)x,$$

1163   where $x = m$, n and h.

$$\alpha_m(V) = -0.32(V + 54)/(\exp(-0.25 * (V + 54)) - 1)$$
$$\beta_m(V) = 0.28(V + 27)/(\exp(0.2 * (V + 27)) - 1)$$
$$\alpha_n(V) = -0.032(V + 52)/(\exp(-0.2 * (V + 52)) - 1)$$
$$\beta_n(V) = 0.5\exp(-0.025(V + 57))$$
$$\alpha_h(V) = 0.128\exp(-(V + 50)/18)$$
1164 $$\beta_h(V) = 4.0/\exp(-0.2(V + 27) + 1).$$

1165   The channel variable w is determined by

1166 $$\frac{dw}{dt} = (w_\infty(V) - w)/\tau_w(V),$$
$$w_\infty(V) = \frac{1}{\exp(-0.1(V + 41)) + 1},$$

$$\tau_\infty(V) = \frac{500}{3.3 \exp\big(0.05(V+41)\big) + \exp\big(-0.05(V+41)\big)}.$$

e) Excitatory neurons in MECV

excitatory neurons in MECV are modeled based on (Egorov et al., 2002; Fransén et al., 2006) with simplification of conductance of nonspecific calcium-sensitive cationic, g_{CAN} (see Disinhibitory system in STAR Methods). Ca flux is regulated through CaL channel.

$$V_{Na} = 50[mV], V_K = -100[mV], V_{CAN} = -20[mV], V_{Ca} = 140[mV], V_L = -65[mV]$$

$$g_{Na} = 100.0\left[\frac{mS}{cm^2}\right], g_K = 80.0\left[\frac{mS}{cm^2}\right], g_{AHP} = 0.05, g_{K,C} = 195\left[\frac{mS}{cm^2}\right], g_{K,C}$$

$$= 195\left[\frac{mS}{cm^2}\right], g_M = 3.5, g_{CaL} = 0.15, g_{Na,p} = 0.2, g_{K,A} = 0.5, g_L$$

$$= 0.5[mS/cm^2]$$

$C\frac{dV_i}{dt} = g_{Na}m^3h(V_{Na} - V_i) + g_K n^4(V_K - V_i) + g_{AHP}w(V_{AHP} - V_i) + g_M s_M(V_K - V_i) + g_{Na,p}s_{Na,p}h_{Na,p}(V_{Na} - V_i) + g_{K,A}s_{K,A}h_{K,A}(V_K - V_i) + g_{CAN}(t)s_{CAN}(V_{CAN} - V_i) + g_{K,C}s_{KC}(V_K - V_i) + + g_{CaL}s_{CaL}(V_{Ca} - V_i) + I_i$ (Eq.3)

In addition to voltage dynamics, concentration of Ca^{2+}, $[Ca^{2+}]$, in a neuron is modeled according to:

$$\frac{d[Ca^{2+}]}{dt} = \kappa I_{CaL} - [Ca^{2+}]/\tau_{Ca}$$

Here, $\kappa = 0.5181937[Fd^{-1}]$ and $\tau_{Ca} = 250[ms]$.

The standard current of sodium and potassium in Eq.3 are exactly same as in excitatory neurons in MECIII. AHP, KA, KC, M, Na$_p$ and CaL currents follow the standard activation-inactivation forms:

$$\frac{dx}{dt} = \alpha_x(V)(1-x) - \beta_x(V)x$$

$$x = w(=AHP), s_M(=M), s_{K,A}, h_{K,A}, s_{K,C}(=KC), s_{CaL}(=CaL).$$

α and β of each current are according to the following equations.:

$$\alpha_{AHP}(V) = \begin{cases} \min(2.4([Ca^{2+}]-15), 15) & \text{for } [Ca^{2+}] > 15 \\ 0.2[Ca^{2+}] & \text{otherwise} \end{cases}$$

$$\beta_{AHP}(V) = 1$$

$$\alpha_{CaL}(C) = \frac{1.6}{1 + \exp\big(-0.072(V-65)\big)}$$

$$\beta_{CaL}(V) = \frac{0.02(V-51.1)}{\exp\big(0.2(V-51.1)\big)-1}$$

$$\alpha_{KC}(V) = \begin{cases} \dfrac{\exp(0.053782V - 0.66835)}{18.975} & \text{for } V < 50 \\ 2\exp\left(\dfrac{6.5-V}{27}\right) & \text{otherwise} \end{cases}$$

$$\beta_{KC}(V) = \begin{cases} 2\exp\left(\dfrac{6.5 - V}{27}\right) - \alpha_{KC} & \text{for } V < 50 \\ 0 & \text{otherwise} \end{cases}$$

$$\alpha_{S_{KA}}(V) = \frac{0.02(V - 13.1)}{1 - \exp\left(0.1(13.1 - V)\right)}$$

$$\beta_{S_{KA}}(V) = \frac{0.175(V - 40.1)}{\exp\left(0.1(V - 40.1)\right) - 1}$$

$$\alpha_{h_{KA}}(V) = 0.0016\exp\left(-(V + 13)/18\right)$$

$$\beta_{h_{KA}}(V) = 0.05/(1 + 0.2\exp(10.1 - V))$$

1184 Variables for M, Na$_p$ and CAN channels follow the form:

1185
$$\frac{dx}{dt} = \frac{x_\infty(V) - x}{\tau_x(V)},$$

1186 where $x = s_{Na,p}, h_{Na \cdot p}, s_M (= M), s_{CAN} (= CAN)$. x_∞ and τ_x for each variables are
1187 according to

$$s_{M,\infty}(V) = 1/(1 + \exp(-V + 35)/5)$$

$$\tau_M(V) = \frac{1000}{3.3\exp((V + 35)/40) + \exp(-(V + 35)/20)}$$

$$s_{Na,p\infty}(V) = 1/\left(1 + \exp\left(-\frac{V + 48.7}{4.4}\right)\right)$$

$$\tau_{S_{Nap}}(V) = \frac{1}{\left(\dfrac{0.091(V + 38)}{1 - \exp\left(\dfrac{V + 38}{5}\right)} - \dfrac{0.062(V + 38)}{1 - \exp\left(\dfrac{V + 38}{5}\right)}\right)}$$

$$h_{Na,p\infty}(V) = \frac{1}{1 + \exp\left(-\dfrac{V + 48.8}{9.98}\right)}$$

$$\tau_{h_{Na,p}}(V) = \frac{1}{-\dfrac{0.00000288(V - 49.1)}{1 - \exp\left(-\dfrac{V - 49.1}{4.63}\right)} + -\dfrac{0.00000694(V + 44.7)}{1 - \exp\left(-\dfrac{V + 44.7}{2.63}\right)}}$$

$$s_{CAN,\infty}(V) = 48 \times \frac{10^2[Ca^{2+}]^2}{48 \times 10^2[Ca^{2+}]^2 + 0.03}$$

1188
$$\tau_{S_{CAN}}(V) = 1/(48 \times 10^2[Ca^{2+}]^2).$$

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1192 **Synaptic Inputs**
1193 Synaptic input I_i to neuron i includes excitatory I_i^E and inhibitory I_i^I currents. Only in
1194 CA1 neurons, OLM currents, which are from OLM neurons, are modeled as another
1195 type of inhibitory currents based on (Wulff et al., 2009).

$$I_i(t) = I_i^E + I_i^I = g_i^E(V_E - V) + g_i^I(V_I - V) + g_i^{OLM}(V_i - V)$$

$$g_i^{E,I,OLM}(t) = \Sigma_k \int_0^t G_{ik} \Sigma_s \alpha^{E,I,OLM}(t' - t_k^s - d_{ik})dt' \text{ (Eq.4),}$$

where k is index of pre-synaptic neuron. For the excitatory current, k corresponds to
index of excitatory neurons in all cortical areas and excitatory noise neurons projecting
to post-synaptic neuron i. For the inhibitory currents, k corresponds to index of
inhibitory neurons (PV, OLM, VIP, GABA) in all cortical areas and inhibitory noise
neurons projecting to post-synaptic neuron i. Connections G among these neurons are
described in Circuit model in STAR Methods. s is index of spikes in k neuron. d_{ik} is
transduction time lag. When neurons i and k are within a same area, d is chosen
randomly from (0,2) ms, while d is chosen from (10,15) ms for neurons in different
areas. Double exponential functions, α, are described as:

$$\alpha^{E,I,OLM}(t) = (e^{-\frac{t}{\tau_{E,I,OLM}^r}} - e^{-\frac{t}{\tau_{E,I,OLM}^d}})/(\tau_{E,I,OLM}^r - \tau_{E,I,OLM}^d) \text{ (Eq.5)}$$

Rise time constant t^r is 0.05,0.07 and 2.0 ms for E, I, and OLM, respectively, while decay
time constant t^d is 5.3, 9.1 and 22.0 ms for E, I, and OLM, respectively.
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1210

1211 **Circuit structure**
1212 Our model has three cortical areas (Figure1A) and external oscillating neurons in MECII,
1213 CA3 and MS. excitatory neurons in each cortical area are divided into two or four
1214 subgroups (Table1). CA1 has four groups denoted as Left (L), Right (R), Center (C) and
1215 Home (H). MECIII and MECV have two groups denoted as L and R.
1216

1217 Table1: number of neurons in each are

	CA1	ECIII	ECV	CA3
E	120x4	120x2	200x2	120x4
PV	240	160	120	
OLM	240			

1218
1219
1220
In addition, a model has 240 VIP neurons in CA1, 120 excitatory neurons in MECII and
360 GABAergic neurons in MS. The GABAergic neurons are divided into three groups
projecting to different types of neuron each of which has 120 neurons; groups to OLM,
to PV in CA1 and to PV in MECV.
Structure of a circuit is given by a matrix G in Eq. 4, which represents efficacy of
synaptic connections. Connection between presynaptic neuron j and postsynaptic
neuron I, G_{ij} is determined by

$$G_{ij} = \begin{cases} G_{XY}^{AB}/\rho_{XY}^{AB} N_Y^B & \text{with probability } \rho_{XY}^{AB} \\ 0 & \text{otherwise} \end{cases} \text{(Eq.6)},$$

where X and Y are neuron types that i and j neurons belong to, respectively. A and B
refer subgroups (L,R,C,and H) that i and j neurons belong to, respectively. Because only
excitatory neurons in each area are divided as the subgroups, A and B are neglected for
other types of neurons. N_Y is the number of type Y neurons. If the type Y neurons are
divided into the subgroup, N^B_Y indicates the number of type Y neurons in subgroup B. G
and ρ for each connection are as follows:

1235

1236 i) Connection from noise neurons
1237 Connections G from noise neurons to the neurons in cortical areas are shown in Table2.
1238 A postsynaptic neuron receives inputs from 40 excitatory and 40 inhibitory neurons
1239 ($\rho_{XY} = 1, N_{XY} = 40$).

1240

1241 Table2 Connection G_{XY} from noise neurons to each type of neurons.

Post-synaptic X Pre-synaptic Y	CA1			ECIII		ECV	
	E	PV	OLM	E	PV	E	PV
Excitatory noise neurons	.32	.8	3.2	.8	.2	.2	.4
Inhibitory noise neurons	.6	.2	.4	.6	.8	.2	.6

1242
1243
1244 ii) Connection from excitatory neurons in MECII, MS and CA3
1245 a) connection from excitatory neurons in MECII to PV in MECIII
$$G_{XY} = 0.4$$
$$\rho_{XY} = 1$$
1246 b) from GABAergic neurons in MS
1247 to PV in MECV
$$G_{XY} = 0.1$$
1248 to PV in CA1
$$G_{XY} = 3.7$$
1249 to OLM in CA1
$$G_{XY} = 3.7$$
1250 For all connections,
$$\rho_{XY} = 1$$
1251 c) from CA3 to E in CA1
1252 for $A \neq B$
$$G_{XY}^{AB} = 0, \rho_{XY}^{AB} = 0$$

1253   For $A = B$

$$G_{XY}^{AB} = 2.0\xi, \rho_{XY}^{AB} = 0.3$$

1254   here, ξ is chosen randomly from (0,1).

1255   d) from CA3 to PV in CA1

1256 $G_{XY} = 0.1 \ \rho_{XY} = 0.5.$

1257   e) from VIP to PV and OLM in CA1

1258   Efficacy of these connections are modified by [ACh] (Tremblay et al., 2016) as follows:

1259   For X=PV,

$$G_{XY} = 0.012[Ach], \rho_{XY} = 1$$

1260   For X=OLM,

$$G_{XY} = 0.02[Ach], \ \rho_{XY} = 1$$

1261   f) Connections between E neurons within the same cortical areas

1262   For $A \neq B$

$$G_{XY}^{AB} = 0.01, \rho = 0.025 \text{ (in MECIII)}$$
$$G_{XY}^{AB} = 0, \rho = 0 \text{ (in MECV)}$$

1263   For $A = B$

$$G_{XY}^{AB} = 14.4, \rho = 0.15 \text{ (in MECIII)}$$
$$G_{XY}^{AB} = 0.216, \rho = 0.03 \text{ (in MECV)}$$

1264   There is no connections between excitatory neurons in CA1 in our model.

1265

1266   g) Connection between neurons within the same cortical areas (except E-E
1267   connections)

1268   There is no connections between OLMs(Wulff et al., 2009). Connections from OLM to E
1269   neurons in CA1 are described in h), since OLM is observed to be attached on proximal
1270   dendrite of excitatory neurons in CA1 and regulate inputs from MECIII.

1271

1272   Other connections within cortical areas are shown in Table 3.

1273

1274   Table 3: connection parameters in CA1, MECIII, MECV

	CA1					
(X,Y)	E,PV	PV,E	PV,PV	PV,OLM	OLM,E	OLM,PV
G_{XY}	2.2	0.2	0.3	0.5	0.5	0.2
ρ_{XY}	0.5	0.5	0.5	0.5	0.3	0.5

1275

MECIII			MECV		
E,PV	PV,E	PV,PV	E,PV	PV,E	PV,PV

2.5	0.5	0.01	0.2	0.3	0.01
0.5	0.3	0.3	0.5	0.3	0.3

1276

1277 h) connections from neurons in CA1 to those in MECV

1278 For X=excitatory neurons in MECV, Y=excitatory neurons in CA1,

1279 $$G_{XY}^{AB} = \begin{cases} 0.27 & \text{for } B \in \{H, C\} \\ 0.36 & \text{for } (A, B) \in \{(L, L), (R, R)\} \\ 0.00125 & \text{otherwise} \end{cases}, \rho_{XY}^{AB} = \begin{cases} 0.075 & \text{for } B \in \{H, C\} \\ 0.075 & \text{for } (A, B) \in \{(L, L), (R, R)\} \\ 0.0125 & \text{otherwise} \end{cases}$$

1280 For X=PV neurons in MECV, Y=excitatory neurons in CA1,

$$G_{XY} = 0.01, \qquad \rho_{XY} = 0.3$$

1281

1282 i) connections from neurons in MECV to those in MECIII

1283 For X= excitatory neurons in MECIII, Y=excitatory neurons in MECV,

1284 $$G_{XY}^{AB} = \begin{cases} 0.01 & \text{for } A \neq B \\ 1.44 & \text{otherwise} \end{cases}, \rho_{XY}^{AB} = \begin{cases} 0.0125 & \text{for } A \neq B \\ 0.075 & \text{otherwise} \end{cases}$$

1285

j) connections from neurons in MECIII to those in CA1

For X=excitatory neurons in CA1, Y=excitatory neurons in MECIII,

$$G_{XY}^{AB} = \begin{cases} 0.003 & for A \neq B \\ 0.216 & otherwise \end{cases}, \rho_{XY}^{AB} = \begin{cases} 0.01 & for A \neq B \\ 0.06 & otherwise \end{cases}$$

In addition, effect of OLM is implemented for modulating inputs from MECIII as
follows:

Up to 5 ms after a spike from OLM to a E neurons in CA1, efficacy of connections from
E neurons in MECIII to this E neurons in CA1 is reduced with multiplication by 0.1.

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Nonlinear interaction of excitatory neurons in CA1 with input from MECIII and CA3

E neurons integrate spikes from CA3 and MECIII (Bittner et al., 2015). We introduced
this effect in our model. A prolonged EPSC I_{prol} is supposed to be generated, when the
following conditions are satisfied:

● A excitatory neuron in CA1 receives a burst (three spikes within 15ms) from MECIII
and it does not receive any inhibitory input from OLM within 15ms at time t_1.

● This excitatory CA1 receives a burst (three spikes within 10ms) from CA3 within
20ms from t_1 (denoted t_2).

● Previous prolonged EPSC is 100ms earlier than t_2.

If these conditions are satisfied, a prolonged (100ms) EPSC in E neuron in CA1 is
generated according to:

$$\alpha_{prol}(t) = \begin{cases} \dfrac{t}{5} \ \text{for } 0 < t < 5\,[ms] \\[2mm] 1 - \dfrac{t-5}{60} \ \text{for } 5 < t < 35 \\[2mm] 0.5\exp\left(-\dfrac{t-35}{30}\right) \ \text{for } 35 < t < 100 \\[2mm] 0 \quad \text{otherwise} \end{cases}$$

$$I_{prol}(t) = 0.01\alpha_{prol}(t)$$

1306

1307

1308 **Disinhibitory system and modulated conductance of nonspecific calcium-sensitive**
1309 **cationic (CAN) current through ACh.**

1310 We assume concentration of ACh represents cognitive states and changes dependent
1311 of current locations:

$$[ACh] = \begin{cases} 0.2 \ \text{for } t < 1\,[s] \ (\text{a rat on sample-C}) \\[2mm] 1 - 0.8 exp\left(-\dfrac{t - T_{LS}}{200}\right) \ \text{for } 1[s] \leq t < 3[s] \ (\text{a rat on sample-L}) \\[2mm] 0.8 - 0.2 exp\left(-\dfrac{t - T_H}{200}\right) \ \text{for } 3[s] \leq t < 4.5[s] \ (\text{a rat on sample-L}) \\[2mm] 1.1 - 0.3 exp\left(-\dfrac{t - T_{CT}}{200}\right) \ \text{for } 4.5[s] \leq t \ (\text{a rat on test-C}) \end{cases}$$

1312 [ACh] modifies neural behavior in a circuit in two pathways. Efficacy of connections
1313 from VIP is modified with [ACh] (Circuit structure in STAR Methods) as well as
1314 conductance of I_{CAN}. Maximum conductance g_{CAN} is dependent on history of [Ca2+]
1315 and [ACh] (Fransén et al., 2006) as follows:

$$g_{CAN}(t) = 0.02[Ach]r_{high}(t)$$

$$r_{high}(t + \Delta t) = \begin{cases} r_{high}(t) + 1.5\Delta t \ \text{for } [Ca^{2+}] > 0.004 \\[2mm] r_{high}(t) - 0.2\Delta t \ \text{for } [Ca^{2+}] < 0.0003 \\[2mm] r_{high}(t) \quad \text{otherwise} \end{cases}$$

1316 We also set upper and lower bounds for r_{high} at 2.5 and 0.3, respectively.

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1318

An additional decoder
To examine how high gamma coherence between MECIII and CA1 observed in
(Yamamoto et al., 2014) is utilized for detection of previous memories, we applied
stimuli with high gamma oscillation to these areas and implemented an additional
circuit as a decoder. The decoder circuit composes 100 excitatory (exc) and 100
inhibitory (inh) neurons (Figure 7A) which receive synaptic inputs from excitatory
neurons in MECIII and CA1. For the high gamma stimuli, we applied coherent current
input $I_{high\,\gamma}$ to excitatory neurons in CA1 and ECIII with f=80 Hz as follows:

$$r_t = \sin{(2\pi f t/1000)}, \text{ here } t{=}t[\text{ms}],$$

$$I_{\text{high } \gamma} = \begin{cases} 0.02 m r_t \text{ for } m r_t > 0 \\ I_0 r_t \text{ for } r_t \leq 0 \end{cases},$$

$I_0 = 0.18$ for CA1 neurons, 0.216 for ECIII neurons.

1330

1331 Excitatory neurons are modeled as a normal HH neuron model:

$$C = 1.0[\mu F/cm^2]$$
$$V_{Na} = 50[mV], V_K = -90.0[mV], V_L = -65.0[mV]$$
$$g_{Na} = 100.0[mS/cm^2], g_K = 80.0[mS/cm^2], g_L = 0.5[mS/cm^2]$$
$$C\frac{dV_i}{dt} = g_{Na}m^3h(V_{Na} - V_i) + g_K n^4(V_K - V_i) + g_L(V_L - V_i) + I_i + 0.1$$

1332 $$\frac{dx}{dt} = \alpha_x(V)(1 - x) - \beta_x(V)x,$$

1333 where x=m,n,and h.

$$\alpha_m(V) = -0.32(V + 54)/(\exp(-0.25 * (V + 54)) - 1)$$
$$\beta_m(V) = 0.28(V + 27)/(\exp(0.2 * (V + 27)) - 1)$$
$$\alpha_n(V) = -0.032(V + 52)/(\exp(-0.2 * (V + 52)) - 1)$$
$$\beta_n(V) = 0.5\exp{(-0.025(V + 57))}$$
$$\alpha_h(V) = 0.128\exp{(-(V + 50)/18)}$$

$$\beta_h(V) = 4.0/\exp{(-0.2(V + 27) + 1)}.$$

Inhibitory neurons are modeled same as PV neurons in CA1, MECIII and MECV. Neurons
in the decoder receive noisy excitatory and inhibitory synaptic inputs same as those in
the main circuit (inputs from noise neurons in Synaptic structure). Excitatory and
inhibitory neurons spike with 35[Hz]. Connection strength from 40 excitatory noise
neurons to excitatory and inhibitory ones in the decoder, $G_{EE}, G_{IE} = 0.005, 0.05$, while
those from 40 inhibitory noisy neurons to excitatory and inhibitory ones in the decoder,
$G_{EI}, G_{II} = 0.02, 0.0015$. For alpha function in Eq.5 for both of the excitatory and
inhibitory neurons in the decoder, we set $\tau_{dcy} = 4$ ms and other parameters are same
as the main circuit.

1344

In the decoder circuit, 100 excitatory neurons are divided into two sub groups, L (50
neurons) and R (50 neurons), as well as 100 inhibitory neurons. Synaptic inputs from
these neuron and excitatory neurons in CA1 and MECIII are modeled as Eq.4. Circuit
structure of the decoder is set according to Table 4. We also set time-lag d through
synaptic inputs; d from MECIII and CA1 to the excitatory neurons is chosen randomly
from (35,50) and (10,15) ms, respectively. d from those to the inhibitory neurons is
chosen randomly from (22.5,27.5) and (10,15) ms, respectively.

1352

1353 Table 4: circuit structure of the decoder

pre / post	E	I	E in CA1	E in MECIII
E	0 0	2.5 0.8	0.4 0.1	0.02 0.1
I	0 0	0.05 0.6	0.45 0.4	0.3 0.2

1354 For each cell, upper and lower values are $G_{post,pre}$ and $\rho_{post,pre}$ in Eq.6, respectively.

1355

1356 We implemented nonlinear amplifications of inputs from MECIII and CA1 as similar to

1357 that in the excitatory neurons in CA1. To be specific, when both inputs arrive to the

1358 neuron in the decoder within 1 ms, input currents are amplified by 4.5-fold and 2.0-

1359 fold in excitatory and inhibitory neurons, respectively.

1360

1361

Experimental data in rats

Spiking activities and LFP data in CA1 are obtained from previously published data in

(Yamamoto et al., 2014) for Figures 5B and 6C and that in (Mizuseki et al., 2013) for

Figures 5D and 5E. Experiments were approved by the Institutional Animal Care and Use

Committee of Rutgers University. All procedures for animal care and use were performed in

accordance with the National Institutes of Health *Guide for the Care and Use of Laboratory*

Animals. Detailed conditions on data recording are described in these papers.

1369

LFP activities were band-pass filtered (6-12Hz) as theta wave and instantaneous phase

of the filtered theta wave were derived from Hilbert transform. For spiking activities,

we dropped a part of spikes to analyzed as follows:

Spiking activities in (Yamamoto et al., 2014) were recorded with the silicon linear

probes and were analyzed as multi-unit activities. In this paper, however, we roughly

distinguish putative excitatory neurons from inhibitory ones in order to show clear

theta preference. According to (Mizuseki et al., 2009), we sorted spikes by trough to

peak latency. Due to short length of single spike profile in the data, we cannot identify

baseline before spike and consequently cannot compute peak amplitude asymmetry.

We assigned spikes with the latency larger than 0.5ms to putative excitatory neurons.

For Figure 5B, we have the sorted spikes in three out of five rats because spikes of the

rest two rats do not show clear theta preference due to small number of spikes.

For spiking activities in (Mizuseki et al., 2013), we used sessions

"ec014.12","ec014.16","ec014.17","ec014.27","ec014.28","ec013.44","ec013.46","ec0

16.30". Because phase shift in the side arm was observed only in deeper neurons in

(Fernández-Ruiz et al., 2017), we only used spikes of deeper neurons according to
(Mizuseki et al., 2011).
1387
1388

Figure 1

Figure 2

A

B

C

D

E

F

Figure 3

Figure 4

A

periodicity index

C L1 L2 D1 D2 C1 C2
sample | delay | test
location

B

sample-C sample-L delay test-C
normal = no block
[Hz]
block block
$r_L - r_R$
10

0 2 4 6
Time [s]

C

P_L
1
*** ***

C L C1 C2 normal
sample | test
block location

Figure 5

Figure 6

Figure 7