Repetita iuvant: repetition facilitates online planning of sequential movements

Abbreviated title: Sequence repetition facilitates online planning

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Word count. Abstract: 247 / 250; Significance Statement: 102 / 120; Introduction: 649 / 650; Discussion: 1498 / 1500. 32 pages, 7 figures, 0 tables.

Author contributions. G.A. and J.D. designed research; G.A. and Y.K. performed research; G.A. analyzed data; G.A., Y.K., and J.D. wrote the paper.

Acknowledgements. This work was supported by a James S. McDonnell Foundation Scholar award, an NSERC Discovery Grant (RGPIN-2016-04890), and the Canada First Research Excellence Fund (BrainsCAN). The authors wish to thank Jonathan A. Michaels for comments on the manuscript.

Disclosures. The authors declare no conflicts of interest.

Abstract

Beyond being essential for long-term motor-skill development, movement repetition has immediate benefits on performance, increasing the speed and accuracy of a second execution. While such repetition effects have been reported for single reaching movements, whether they apply to movement sequences, or whether they affect planning or execution processes, has yet to be determined. We addressed these questions in two behavioral experiments using a discrete sequence production (DSP) task in which human volunteers had to perform short sequences of finger movements. In Experiment 1, participants were presented with random sequences and we manipulated whether participants had to execute the sequence (Go), or not (No-Go), and whether the sequence was repeated on the next trial. We establish that repeating a sequence of movements led to immediate improvements in speed without associated accuracy costs. The biggest benefit was observed in the middle part of a sequence, suggesting that the repetition effect likely results from facilitated online planning. This claim was further supported by Experiment 2, in which we kept a set of sequences fixed allowing participants to develop sequence-specific learning: once learning reduced the need for online planning, the benefit of repetition disappeared. Finally, we found that repetition-related improvements only occurred for the trials that had been preceded by sequence production, suggesting that action selection and sequence pre-planning may not be sufficient to reap the benefits of repetition. Together, our results highlight the importance of motor practice for enhancing our ability to link individual sequence elements into skilled sequential behavior.

Key words:

Significance Statement

Even for overlearned motor skills such as reaching, repeating the same movement improves subsequent performance. How exactly brain processes associated with motor planning and execution might benefit from repetition, however, remains unclear. Here we report the novel finding of repetition effects for sequential movements. Our results indicate that this benefit of repetition is tied to faster and more accurate online planning of upcoming sequence elements. We also highlight how recent movement experience appears to be required to observe the repetition effect, suggesting that actual practice might be more beneficial to the human sensorimotor system than mental rehearsal for producing short-term performance improvements.

Introduction

Repeated practice is an essential ingredient for successful learning. However, even immediate repetition of the same stimulus or response often leads to better performance (i.e., "repetition effect"). Stimulus repetition enhances perceptual processing (Eichelman, 1970; Bentin and McCarthy, 1994) and improves stimulus-response (S-R) mapping (Bertelson, 1961, 1963, 1965). Conversely, switching usually incurs a performance cost (Hyman, 1953; Adams, 1961; Smith, 1968; Eimer et al., 1995; Kleinsorge, 1999). Within the motor domain, repetition can provide short-term benefits to motor output, even for a well-learned skill (Ajemian et al., 2010). As a common example, athletes and musicians rehearse action sequences moments before a big match or performance. Previous research on reaching has shown that movements are biased towards the direction experienced in the recent history, and repeated movements can be executed with less variability (Chapman et al., 2010; Diedrichsen et al., 2010; Verstynen and Sabes, 2011; Marinovic et al., 2017). Yet, the mechanisms by which movement repetition facilitates subsequent task performance remain elusive.

A recent study (Mawase et al., 2018) provided some insight into the possible origin of this effect. The authors argue that repetition accelerates response preparation of the same movement, and present some evidence that this effect is not caused by speeding up perceptual or selection processes. Together, these results suggest that repetition effects for simple, ballistic movements are mediated by an improved ability of the nervous system to reach a well-prepared state and trigger a movement more quickly. However, many real-life motor skills are more complex than single, point-to-point reaches – they tend to involve the production of sequential movements. If repetition only improves the preparation of individual movements, we should not find a repetition effect at the sequence level – that is, switching between two different orderings of the same movement elements should be as good as repeating the same ordering.

Conversely, if repetition accelerates planning at the level of a sequence, we would expect to observe a repetition effect only when the ordering remains consistent.

Using a discrete sequence production (DSP) task, we have recently shown that faster sequential performance with learning relies on improvements in online planning – the ability to plan future elements in parallel with the execution of preceding sequence elements (Ariani and Diedrichsen, 2019). Given the hypothesis that repetition improves movement planning (Mawase et al., 2018), we would therefore expect to observe a repetition benefit not only on reaction time, which depends on pre-planning, but also on sequence movement time, which depends on online planning. To test these ideas, here we used a DSP task in which participants were explicitly cued to execute short sequences of finger movements. On any given trial, with equal probability (0.5), the sequence could either be the same as in the previous trial (Repetition), or a different sequence (Switch). Participants were given enough time (2.5 s) to complete stimulus identification and action selection before the go-signal (Exp. 1). The use of such a delayed-movement paradigm ensured that repetition effects were not caused by improved perceptual processes. Our findings indicated that sequence repetition improved both reaction times (the time between go-signal and the first key-press) and sequence movement times (the time between first and the last key-press in the sequence).

Next, we asked whether these benefits could be achieved by the act of planning alone, or whether sequence production was required. While our design encouraged participants to pre-plan each sequence during the preparation phase, we manipulated whether they would perform the sequence, or not, with a Go/No-Go paradigm. This allowed us to compare Repetition and Switch trials, depending on the whether the previous (N-1) trial involved pre-planning alone (No-Go condition), or included also the initiation and production of the sequence (Go condition).

Finally, in a separate behavioral experiment on an independent sample, we explored how the repetition effect changed with sequence-specific learning by monitoring the effect over the course of 2 days of training on a fixed set of sequences (Exp. 2).

Methods

Participants. Forty-nine right-handed volunteers participated in Experiment 1 (33 F, 16 M; age 18–39, mean 22.73 years, SD 5.04). An independent sample of 40 right-handed volunteers participated in Experiment 2 (24 F, 16 M; age 18–36, mean 22.28 years, SD 3.44). Handedness was assessed using the Edinburgh Handedness Inventory (Exp. 1: mean 86.33, SD = 15.67; Exp. 2: mean 78.59, SD = 16.74). While some participants had musical training, none of them was a professional musician (musical experience, Exp. 1: mean 4.67 years, SD 6.01; Exp. 2: mean 3.14 years, SD 3.77). None of the participants had a history of neurological disorders. Experimental procedures were approved by the ethics committee at Western University (London, Ontario, Canada). All participants gave written informed consent and received monetary compensation for their participation. Four participants withdrew from Exp. 1 before study completion and were thus excluded from data analysis (final N = 45). In Exp. 2, one participant failed to follow the instructions. The session was terminated before completion and the data excluded from successive analysis (final N = 39).

Apparatus. Sequences of finger presses were executed on a custom-made keyboard device comprised of five keys corresponding to each finger of the right hand. The isometric force exerted by each finger was continuously recorded by force transducers under each key (FSG-15N1A, Sensing and Control, Honeywell; dynamic range, 0-25 N) at a rate of 500 Hz. To account for sensor drifts, we recalibrated the zero-force baseline at the beginning of each block of trials. Each key was independently deemed to be *pressed* when the force exceeded a threshold of 1 N, and *released* as soon as the force returned below 1 N. (Fig. 1C; P = press, R = release).

Figure 1. The discrete sequence production (DSP) task. A. *Exp. 1 example trial: a sequence cue (white numbers on the computer screen) is followed by an execution cue (outline changes color, numbers are masked). Online visual feedback about key-presses was given during the response window (green asterisks for correct presses, red for incorrect presses), followed by reward points depending on performance. 30% of the trials in a block were No-Go trials (red outline + low-pitch sound, top), 70% were Go trials (green outline + high-pitch sound, bottom).* ***B.*** *The next trial could be either a Repetition of the same sequence (0.5 probability), or a Switch to a new sequence.* ***C.*** *Example trial in Exp. 1 with the following trial timing: preparation phase: 2.5 sec; response window: 2 sec; ITI: 0.5 sec. Dashed horizontal line indicates force threshold (1 N) to determine the moment of each key-press and release (dotted lines). P1 = press of first key; R4 = release of fourth key; IPI 1 = first inter-press interval. Total time (TT) = RT + MT.* ***D.*** *Exp. 2 design: repeating sequences, trial structure and timing. Note that the go-signal here is given via white box around the sequence cue.*

Visual stimuli to instruct one sequence of finger presses were presented on a computer monitor and consisted of a string of 4 numeric characters displayed in white on black background (Sequence cue), and framed by a white rectangle (Fig. 1A; character height 1.5 cm, visual angle approx. 2˚).

Task. We used a discrete sequence production (DSP) task in which participants were required to produce sequences of key-presses with the five fingers of their right hand (Fig. 1A). Each sequence was cued by 4 numbers ranging from 1 to 5, instructing which fingers had to be pressed (e.g., 1 = thumb, 2 = index, … 5 = little). The sequence had to be executed by sequentially pressing the fingers corresponding to the numbers on the screen, from left to right. On each trial, participants were presented with a 4-item sequence and asked to prepare for the corresponding finger presses (preparation phase). After a fixed delay of 2.5 seconds, an audio-visual execution cue would mark the beginning of the sequence response window (a fixed 2 seconds). On Go trials, the execution cue was a green frame accompanied by a high-pitch tone (Fig. 1A, bottom), indicating that participants had to perform the planned sequence of finger presses as quickly and accurately as possible (Go condition). On other trials, the execution cue was a red frame accompanied by a low-pitch tone (Fig. 1A, top), instructing the participants to remain as still as possible without pressing any key until the end of the response window (No-Go condition). To encourage sequence pre-planning before the Execution cue, at the beginning of the response window the sequence cue was replaced by 4 asterisks masking the numbers. Moreover, the sequence of key-presses had to be completed within 2 seconds from the execution cue (timeout error after that). With each key-press, the corresponding asterisk turned either green (correct press) or red (wrong press). Performance was evaluated in terms of both execution speed and press accuracy. Speed was defined in terms of total time (TT), which consisted of the reaction time (RT: from the onset of the Sequence cue to the first key-press)

plus the movement time (MT: from the onset of the first key-press, P1, to the release of the last key-press, R4). A single press error invalidated the whole trial, so accuracy was calculated as percent error rate (ER) per block of trials (number of error trials / number of total trials x 100). At the end of the response window, during the 500 ms inter-trial interval (ITI), participants were presented with performance points appearing in place of the asterisks.

Feedback. To motivate participants to improve in speed (TT = RT + MT) and accuracy (1 - ER) of sequence production, we gave participants performance feedback on each trial. The performance score was based on the following point system: -1 points for timing errors (i.e., anticipation of the execution cue, or movement initiation in No-Go trials); 0 points for correct timing but wrong finger press (any one wrong key-press); +1 points for correct timing and press (i.e., movement initiation in Go trials, or no movement in No-Go trials); and +3 points for correct timing, correct press, and TT 2% or more faster than TT threshold. TT threshold would decrease by 2% from one block to the next if both of the following performance criteria were met: median TT in the current block faster than best median TT recorded hitherto, and mean ER in the last block < 25%. If either one of these criteria was not met, the thresholds for the next block remained unchanged. At the end of each block of trials, the median TT, mean ER, and points earned were displayed to the participants. At the end of the session, monetary compensation corresponded to the amount of performance points accumulated (points < 750 = 10 \$; 750 ≤ points < 1000 = 12 \$; points ≥ 1000 = 15 \$).

Penalizing timing errors (-1 points) more than press errors (0 points) might have made participants more cautious and increased their RTs. Thus, to encourage full preparation of the sequence, for the last 20 participants of Exp. 1 we gave equal weight to timing and press errors (both 0 points). Successive analyses showed no difference in performance between the two groups (with or without penalty for timing errors), suggesting that participants adopted a similar strategy regardless of the penalty.

The scoring system in Exp. 2 was identical to the one in Exp. 1 without any additional

penalty for eventual timing errors (0 points). Furthermore participants in Exp. 2 were paid a flat

hourly rate (7 $), regardless of the specific amount of points accumulated.

Design.

Exp. 1. To investigate the nature of the repetition effect, we used a 2-by-2 design independently

manipulating whether a particular sequence was repeated or whether the previous trial was a

Go or No-Go trial. Sequences in Exp. 1 were randomly determined (see below). On any given

trial, there was a 0.5 probability that the sequence was the same as the previous trial

(Repetition) or that it was different (Switch; Fig. 1B). Independently, we varied whether each trial

was a Go trial (70%) or a No-Go trial (30%). We designed a majority of the trials to be go-trials

to encourage full sequence pre-planning before the execution cue. The order of trials was

randomly interleaved, creating all possible combinations of the factors repetition type and

execution type of the previous trial. Note that, given that the trial structure was kept fixed across

all experimental conditions (i.e., 2.5 sec preparation phase + 2 sec response window + 0.5 sec

ITI), there was no difference in time elapsed after a Go, or No-Go trial. Each block was

composed of 48 trials (12 repetitions for each of the 4 sequences), and participants underwent 1

session of 12 blocks each. In order to limit strong learning effects that might lead to ceiling

performance, for each block of trials, we randomly selected four different 4-item sequences from

a large pool of all permutations with repetition of the numbers 1 to 5, taken 4 items at a time.

Moreover, to keep sequences of a similar level of difficulty, we removed from the permutation

pool all sequences in which any number repeated (i.e., each number could only appear once

per sequence), or that included "runs" (more than 2 fingers in either increasing or decreasing

order; e.g., 1-2-3, or 3-2-1).

Exp. 2. To explore how sequence learning affects the repetition effect, we designed a second experiment where the set of sequences remained fixed over two consecutive days of testing following overnight consolidation. We used 8 4-item sequences including all fingers of the right hand except for the ring finger. The sequences were selected according to the following criteria: 1) each finger was used only once per sequence; 2) each finger started 2 of the 8 sequences; 3) each finger was pressed in every ordinal position twice across sequences; and 4) no more than 2 neighboring fingers pressed in a row (i.e., as in Exp. 1, we excluded "runs").

In contrast to Exp. 1, Exp. 2 did not contain any No-Go trials and the preparation phase was shortened to a fixed 1 s. Also, the execution cue was presented only visually (white box around the sequence cue), the sequence cue was not masked, and the duration of the response window was not fixed (i.e., TT dictated the actual duration of the trial, with the ITI occurring right after the last key-press). Finally, sequence repetition was not randomized, but counter-balanced across sequences. Each sequence was executed from a minimum of once (i.e., a Switch) to a maximum of five times in a row (i.e., executing once and repeating four times). To ensure a comparable number of trials per each repetition condition, we manipulated the proportion of same-sequence executions in a row as follows: .33 one-execution trials (Switch), .22 two-executions trials (One-repetition), .22 three-executions trials (Two-repetitions), .11 four-executions trials (Three-repetitions), .11 five-executions trials (Four-repetitions). Each of the 8 sequences was presented in each repetition condition the same number of times (balanced design across sequences), and the factors sequence type and repetition condition were then pseudo-randomized within a block of trials. In addition, unbeknownst to the participants, we included a variable number (from 1 to 4) of one-execution trials (Switch) as dummy trials at the beginning (assuming warm-up) and end (assuming tiredness) of each block, which were subsequently excluded from data analysis. Overall, this led to a final proportion of .59 repetition trials (across repetition conditions), and .41 switch trials. Each experimental block consisted of 50 trials (including dummy trials), and participants performed 12 blocks (~ 4-5 min each) per

experimental session per day (i.e., 24 blocks in total per participant). No explicit information

about the sequence types, or instruction to memorize the sequences, was given. Nonetheless,

the extensive repetition (more than 130 trials per sequence) ensured that participants would

learn the finger transitions associated with each sequence, usually already by the end of the first

testing day.

Data analysis. Data were analyzed offline using custom code written in MATLAB (The

MathWorks, Inc., Natick, MA). Statistical analyses for assessing movement repetition effects on

reaction times (RT) and sequence movement time (MT) included two-tailed paired-samples t-

tests (Repetition vs. Switch), and 2-by-2 within-subject repeated measures ANOVAs with factors

repetition type (Repetition / Switch) and previous trial type (No-Go / Go). Error trials (both timing

and press errors), No-Go trials, and dummy trials (Exp. 2 only, see Design section) were

excluded from data analysis. For visualization purposes only, data were normalized by

subtracting from each data point each participant's mean, and adding back the grand mean of

the group. Statistical analyses, computed on raw data, were not affected by this normalization

procedure.

Results

Sequence repetition reduces both reaction and movement times

Our experiment was designed to test whether there are short-term (i.e., trial-to-trial) benefits for the repetition of sequential movements. We compared trials in which the sequence was the same as on the previous trial (i.e., Repetition) to trials preceded by a different sequence (i.e., Switch). We found that RT improved upon repetition of the same sequence (Fig. 2A). Participants could react more quickly to the Go cue when then previous trial contained the same sequence (paired-samples t-test, t_{44} = 2.890, p = 0.006). Notably, this RT advantage was present even though participants had more than enough time (2.5 s) to finish pre-planning of the 4-item sequence before the execution cue (Ariani and Diedrichsen, 2019). These results extend previous insights by Mawase et al. (2018) by showing that repetition facilitates the triggering of a planned movement, an effect that cannot be explained by improved identification of the visual stimuli, or a bias in selection processes. Repetition also accelerated sequence production, as indicated by a significant repetition effect on sequence MT (Fig. 2C). On Repetition trials, the sequence was performed 36 ms (± 5 ms) faster than on Switch trials, a robust effect across participants (paired-samples t-test, t_{44} = 7.473, p = 2.330e-09).

Next we asked whether the repetition effect would increase with further repetitions of the same sequence. For RT, the repetition effect was limited to the first repetition (Switch-Rep1 difference: 15 ± 4 ms; t_{44} = 3.753, p = 5.081e-04; Fig. 2B). After that, no further RT advantage was observed for successive sequence repetitions (Rep1-Rep2 difference: -2 ± 4 ms; t_{44} = -0.537, p = 0.594; Rep2-Rep3+ difference: -4 ± 3 ms; t_{44} = -1.138, p = 0.261). In contrast, for MT the improvements were not limited to the first repetition (Switch-Rep1 difference: 23 ± 4 ms): a second repetition (i.e., performing the same sequence three times in a row) was almost nearly as beneficial to further reduce sequence MT (Rep1-Rep2 difference: 21 ± 4 ms; t_{44} = 4.712, p = 2.478e-05; Fig. 2D). After the second repetition, performance appeared to reach a plateau

289   (Rep2-Rep3+ difference: 4 ± 6 ms; t_{44} = 0.705, *p* = 0.484).

Figure 2. Immediate repetition leads to better performance. A. Distribution of median reaction times (RT) separately for Switch and Repetition trials. Light-gray lines represent individual participants. Dashed black line shows group mean across conditions, with relative standard error. B. Mean RT as a function of repetition number (1 means that a sequence was performed twice in a row, 3+ means the average of a sequence being repeated 4 or more times in a row). Shaded areas represent between-subject standard error of the mean. C. Distribution of median sequence movement times (MT) separately for Switch and Repetition trials. Other conventions as in panel A. D. Mean sequence MT as a function of repetition number. Other conventions as in panel B. *p < 0.05, two-tailed paired-samples t-test.

293   Importantly, faster RT and MT in Repetition trials did not come at the cost of decreased

294   accuracy. In fact, the opposite was true: accuracy increased from 81.8 ± 1.1% correct trials in

295   Switch trials to 85.6 ± 1.2 % in Repetition trials (paired-samples t-test t_{44} = -5.532, *p* = 1.637e-

06). Moreover, timing errors (i.e., false starts by anticipation of the execution cue) decreased from 4 % to 2.9 % (paired-samples t-test t_{44} = 2.777, p = 0.008).

Overall, our results suggest that repetition of a sequence improves both the initiation of a pre-planned movement, as well as the speed by which the repeated sequence can be performed. The accuracy advantage proved that this effect did not arise at the expense of reduced execution accuracy.

Repetition benefit on MT arises from improved online planning, not execution processes

The results so far indicate that sequence repetition improves initiation (RT) and movement (MT). Should this be taken as an indication that repetitions improve execution-related, rather than planning-related processes? Not necessarily so. In a previous study we have demonstrated that sequence MT (the time from first to last key-press) is not only a function of motoric processes, but is also strongly influenced by the speed of online planning (Ariani and Diedrichsen, 2019). Even for short sequences, only the first 2-3 key-presses can be fully pre-planned, whereas later movements appear to be planned online, that is during of the execution of the beginning of the sequence. If movement repetition facilitates online planning, this effect should therefore be more prevalent in latter parts of the sequence. If, however, movement repetition facilitates execution processes, it should influence the speed of all presses in the sequence, no matter if these are performed in the beginning or later.

To examine this issue, we inspected the 3 inter-press intervals (IPIs) between the onsets of the 4 key-presses separately. The second transition was the slowest, while the first and last transition were nearly equally fast (Fig. 3A). This indicates a "2-and-2" rhythm, in which each 4-item sequence begins with two quick presses, followed by a brief pause, and then again by two quick presses. Given that the sequences changed randomly from block to block, all possible finger transitions could occur with equal probability at each position of the sequence. Therefore, this effect cannot be explained by biomechanical factors (e.g., some transitions being harder

 than others). Instead, the pattern or results suggests a clear influence of online planning: the

323 first two key-presses can be fully pre-planned and can therefore be executed quickly; then

324 execution needs to slow down until online planning of the remaining two key-presses is finished.

Figure 3. Sequence repetition benefits online planning of repeating sequence elements. A. *Mean inter-press intervals (IPI) as a function of transition number, separately for Switch (light) and Repetition (dark) trials. Shaded areas represent between-subject standard error of the mean.* ***B.*** *Same data as in A but normalized by mean IPI for each transition separately Dashed gray line denotes group mean across conditions, with relative standard error.* **p < 0.05, two-tailed paired-samples t-test.*

Importantly, we found that the repetition effect was most pronounced on the second

transition (Switch-Repetition difference, 2nd vs 3rd transition: 10 ± 3 ms; t_{44} = 3.205, p = 0.003;

Fig. 3A). After normalizing the Switch-Repetition difference by mean IPI of each transition, we

found that the repetition benefit, expressed as percentage of average IPI (Fig. 3B), was

significantly greater on the second and third transitions than on the first transition (t_{44} = 5.380, p

= 2.729e-06). Taken together, the pattern of IPIs is consistent with the view that repetition

affects sequence movement times by accelerating processes related to online planning, and

does not speed up the actual production of individual key-presses.

Actual movement experience may be required for sequence repetition effects

So far, the results suggest that sequence repetition accelerates subsequent pre- and online

planning processes. We next addressed the question of whether pre-planning of a sequence

would be sufficient to produce a benefit on subsequent trials RT, or whether the execution of the

sequence (involving initiation, motor processes, and online-planning) is required. For this

purpose, we compared Switch and Repetition trials separately for whether the previous trial (N-

1) had been a Go, or a No-Go trial. Our logic was that if the repetition effect resulted from

stimulus processing, selection, and pre-planning, we should see a repetition benefit even if the

previous trial had been a No-Go trial. Conversely, if the repetition effect requires the initiation

and execution of the sequence, then we should only observe it when the previous trial had been

executed (i.e., N-1 was a Go trial). To avoid trials which were preceded both by a Go and by a

No-Go trial of the same sequence, we restricted this analysis to the first repetition of a sequence

(i.e., max two executions in a row).

We found that the repetition effect on RT was significant when the previous trial had

been a Go (t_{44} = 4.534, p = 4.421e-05), but not when it had been a No-Go (t_{44} = 0.986, p =

0.330; Fig. 4A). Importantly, the interaction between repetition type (Switch vs. Repetition) and

previous trial type (No-Go vs. Go) was significant (2-by-2 within-subject ANOVA, $F_{1,44}$ = 5.303, p

= 0.026). The same pattern of results was observed for MT (Fig. 4B): significant repetition effect

only on N-1 Go trials (t_{44} = 5.464, p = 2.055e-06), and significant interaction between repetition

and previous trial type ($F_{1,44}$ = 4.898, p = 0.032). As excepted, the effect was also visible when

we split up the MT into IPIs (Fig. 4C). Only for the second transition did we find a significant

interaction between repetition type and previous trial type ($F_{1,44}$ = 4.271, p = 0.044).

Figure 4. The repetition effect appears to require movement experience. A. *Distribution of median movement times (MT) separately for Switch (light) and Repetition (dark) trials as a function of whether the previous (N-1) trial was a Go, or a No-Go trial. To avoid contamination between Go and No-Go trials in long repetition chains, selected trials were restricted to a maximum of one repetition. Solid light-gray lines represent individual participants. Dashed black lines represent group means across conditions. Black dots are considered group outliers.* ***B.*** *Distribution of median reaction times (RT) separately for Switch (light) and Repetition (dark) trials as a function of whether the previous (N-1) trial was a Go, or a No-Go trial. Other conventions as in panel A;* ***C.*** *Mean inter-press intervals (IPI) as a function of transition number, separately for Switch (light) and Repetition (dark) trials, and split by whether the preceding trial was a No-Go (left) or a Go (right) trial. Shaded areas represent between-subject standard error of the mean. *p < 0.05, two-tailed paired-samples t-test; •p < 0.05, for interaction in 2-by-2 within-subject repeated measures ANOVA.*

Again, faster reaction and movement in repetition trials did not trade-off with sequence

execution accuracy. The strong and consistent improvements in accuracy after a repetition ($F_{1,44}$

= 26.698, p = 5.543e-06) was not different depending on whether the previous trial had been a

Go or a No-Go trial ($F_{1,44}$ = 0.159, p = 0.691), nor it was the decrease in timing errors (main

effect of repetition, $F_{1,44}$ = 6.238, p = 0.016; interaction between repetition and previous trial

execution, $F_{1,44}$ = 0.190, p = 0.665).

Taken together, our results are consistent with the view that the repetition effect relies on

the experience of performing a sequence. The act of processing the visual stimuli, selecting,

and pre-planning the upcoming sequence movements (all processes that we assumed would be

performed on No-Go trials as well) was not sufficient to obtain faster RT or MT on Repetition

trials. Therefore, the benefit of rehearsal in a motor sequence task appears to require processes

that are only activated when the movement is actually executed.

Repetition improves the speed of even the fastest movements and participants

Immediate movement repetition makes participants faster at initiating and producing a motor

sequence. This effect may be caused by an improvement in movement speed across the board

– that is, even the fastest trials should get even faster after repetition. Alternatively, the effect

could be caused by the fact that repetition makes slow trials less likely: such trials could be

caused by errors in planning, lack of concentration or focus on the task. In other words,

repetition may simply ease the computational burden on the subject and make such suboptimal

trials less likely, without actually affecting top-speed in sequence execution. To investigate this

idea, we divided the whole distribution of sequence movement times into 11 bins for each

repetition condition and participant separately. This analysis was performed separately for trials

for which the previous trial (N-1) was a No-Go or a Go trial (Fig. 5A). For Go trials, the repetition

effect was present for the whole range of sequence execution speeds. Importantly, this was true

even for the fastest MTs: the mean repetition difference for the fastest bin was 41 ± 19 ms (one-

sample *t*-test vs. zero t_{44} = 2.124, *p* = 0.039).

Figure 5. The repetition benefit remains constant across a wide range of movement speeds. A.
Sequence MT as a function of MT percentile (11 bins), separately for Switch (light) and Repetition
(dark) trials, and by previous trial No-Go (left), or Go (right). Dashed vertical line denotes the MT bin
that includes the median MT. Shaded areas represent between-subject standard error of the mean. ***B.***
Repetition difference normalized by median MT for each bin separately as a function of MT percentile,
and by previous trial No-Go (light), or Go (dark). Other figure conventions are the same as in A. ***C.***
Repetition difference normalized by median MT plotted against MT for each participant. Solid line
represents linear regression. Dotted line as landmark for lack of repetition difference. R^2 = proportion
of variance in repetition difference explained by execution speed.

To better quantify this difference, we plotted the repetition difference normalized by the MT of

the corresponding percentile bin (i.e., [Switch MT – Repetition MT] / Overall MT for each bin;

Fig. 5B). Again, this analysis confirmed that for N-1 Go trials the percentage repetition effect

was significant (one-sample t-test vs. zero across all percentiles, t_{44} = 4.792, p = 1.908e-05) and

did not differ across the range of speeds (paired-samples t-test first vs. last percentile, t_{44} = -

0.516, p = 0.609). As expected, for N-1 No-Go trials the effect was not significant (t_{44} = 1.064, p

= 0.293). Thus, the repetition benefit was not simply a consequence of preventing occasionally

slow executions (i.e., an attentional effect). Rather, after a repetition, participants were more

likely to beat their currently best speed.

Lastly, we investigated whether repetition was equally beneficial for all subjects, or only

for participants that were relatively slow performers to begin with. Indeed, for participants that

were already faster overall, the benefit of repetition may not have constituted a large proportion

of their movement time. For each participant, we plotted the median Switch-Repetition

difference normalized by MT as a function of median sequence movement time (Fig. 5C). The

correlation between sequence production speed and size of the repetition effect was not

significantly different from zero (r = 0.119, t_{44} = 0.790, p = 0.434), so we found no evidence that

inter-subject variability had a strong influence on the relative repetition benefit. Overall, we

showed that movement repetition enables faster sequence MT across the board – both for fast

and slow trial, and for fast and slow participants.

Sequence-specific learning gradually erases the benefit of repetition

In Exp. 1, sequences varied randomly from block to block, effectively preventing participants

from learning a specific set of key-press transitions. Therefore, it is likely that overall

performance improvements largely reflected sequence-general learning (Fig. 6A). But how does

sequence-specific learning (i.e., extensively practicing a fixed set of sequences) change the

repetition effect? One possibility is that practice may diminish, and eventually erase, the

repetition effect. This would be consistent with our previous finding that sequence-specific

learning reduces the time that participants need to pre-plan and online-plan the sequences

(Ariani and Diedrichsen, 2019).

Figure 6. Sequence-specific learning reduces the repetition effect. A. Sequence movement time separately for Switch (light) and Repetition (dark) trials as a function of block number in Exp.1. Shaded areas represent between-subject standard error of the mean. B. Same as A, but for Exp. 2. Dotted vertical line indicates the break from Day 1 to Day 2. C. Switch-Repetition difference normalized as percentage of MT for each block in Exp. 1. Shaded areas represent between-subject standard error of the mean. Black solid line represents linear regression line. Dashed horizontal line indicates absence of repetition effect. D. Same as C, but for Exp. 2. *p < 0.05, two-tailed paired-samples t-test; ⋅⋅p < 0.05, two-tailed one-sample t-test vs zero.

424   To test this hypothesis, we designed a second study (Exp. 2) in which a set of 8 sequences was

425   kept constant throughout the experiment. We still randomly varied, however, whether a

426   sequence would repeat or change between trials. Participants trained on the sequences for two

consecutive days (12 blocks of 50 trials on each day). We then analyzed how the repetition

effect changed over the course of learning. For illustrative purposes, we re-analyzed the results

of the first experiment (Exp. 1, N = 45, sequence-general; Fig. 6A-6C) in the same format as the

results for the second experiment (Exp. 2, N = 39, sequence-specific; Fig. 6B-6D).

In Exp. 1, where sequence-specific learning was nearly impossible, a clear repetition

benefit was present from the first block (Fig. 6A; Switch-Repetition difference: 49 ± 12 ms, t_{44} =

3.973, p = 2.600e-04) and remained roughly constant despite sequence-general learning, until

the last block (last block Switch-Repetition difference: 35 ± 11 ms, t_{44} = 3.315, p = 0.002; Fig.

6A). Importantly, once adjusted by overall MT for each block (Fig. 6C), there was no difference

in repetition benefit from block 1 to block 12 (paired-samples t-test, t_{44} = 0.214, p = 0.832).

In Exp. 2, we found that the repetition benefit was present in the first few blocks of each

day (one-sample t-test between mean blocks 1-3 vs. zero difference, Day 1: t_{38} = 2.424, p =

0.020, Day 2: t_{38} = 3.168, p = 0.003; Fig. 6D) despite the overall improvement in sequence

execution speed (Fig. 6B). However, this effect quickly vanished after a few blocks of practice

(repetition difference on block 4, Day 1: t_{38} = 1.806, p = 0.078, Day 2: t_{38} = 0.827, p = 0.413; Fig.

6D). Coincidentally, the repetition effect came back at the beginning of day 2, and then

disappeared relatively quickly again.

These results suggest that repetition effects only occur on sequences for which no

strong sequence-specific representation could be learned. Together with our finding that

sequence-specific learning to a large degree reflects improved movement planning (online and

before the movement; Ariani and Diedrichsen, 2019), these findings are consistent with the idea

that the benefit of sequence repetition originates from online planning, rather than motor

execution. The break between the two sessions may induce some forgetting, which could make

online planning being more critical again, leaving room for the benefit of repetition to come back.

Discussion

Repetition of a sequence of finger movements resulted in immediate improvements in speed and accuracy of sequence production. This indicates that repetition affects processes governing the planning or execution of the entire movement sequence, rather than just individual movements. To understand the implications of this finding, it is useful to consider our findings in the framework of neuronal state-spaces (Churchland et al., 2010, Fig. 7). Motor pre-planning is equivalent to bringing the neuronal state into a specific location of the preparatory state-space (Churchland et al., 2006b). Upon movement initiation, the neuronal state changes dramatically (Elsayed et al., 2016; Kaufman et al., 2016) and subsequently evolves mainly in the dimensions that span the movement state-space and generate the patterns required for producing muscular output. Note that preparation and movement state-spaces are thought to be largely independent from each other likely by using orthogonal dimensions in an overlapping neural population (Kaufman et al., 2014).

In this framework, repetition effects for individual movements would be caused by the fact that the correct preparatory state can be reached faster and with more accuracy after repetition (Mawase et al., 2018), possibly by lingering activity in the preparatory network (Fig. 7A). Now consider the production of a short sequence. Here, the preparatory neural state needs to traverse multiple locations, each triggering the corresponding elementary movements in the motor network (Fig 7B). During motor execution, the neural state in the preparatory state space would already start to move to the next movement (i.e., online planning). If movement repetition simply primed one location in the preparatory state-space, then any advantage of preparing the first individual movement element would be washed out after completing the sequence. Thus, the presence of a repetition effect at the level of sequences indicates that movement repetition primes the entire pathway through the preparatory state-space. This is consistent with the hypothesis of an intermediate level between movement selection and execution (Diedrichsen

477 and Kornysheva, 2015).

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A Three individual finger movements (3, 5, 2)   **B** Sequence of three finger movements (3-5-2)

+ Baseline
● Go-signal

Switch trials
Repetition trials

Optimal preparatory state
for each finger movement

*Figure 7. Conceptual visualization of planning and execution in a neural state-space framework. Changes in the pattern of neuronal firing can be characterized by movements of the neuronal state in a low-dimensional state-space. During preparation, these changes mostly occur in the preparatory state-space (lower plane), whereas during execution, these changes are more pronounced in the movement state-space (upper plane). Different finger movements (numbers) are characterized by a unique pattern in preparatory state-space, and a unique trajectory in the movement state-space. Dotted lines indicate temporal correspondence between state-space events across planning and execution planes. **A.** Individual finger movements. During pre-planning (after stimulus onset), the neural state trajectory moves from a baseline location (cross) towards the optimal preparatory state (gray spotlight) until the go-signal (dot) triggers execution dynamics. On repetition trials the correct preparatory state would be reached more quickly and with higher accuracy, enabling faster movement initiation when the go signal is given. **B.** Sequence of finger movements. Note that in this scenario what improves upon repetition is the entire neural state trajectory on the planning plane (i.e., online planning), leaving motor dynamics unchanged on the execution plane.*

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481 **RT advantage does not reflect improved stimulus processing or action selection**

482 In a previous study we found that benefits of increased preparation reach an asymptote after

483 ~1.5 seconds (Ariani and Diedrichsen, 2019). Thus, by using a delayed-response paradigm, we

484 can be relatively confident that our RT measure mainly reflects the initiation of a pre-planned

25

response, as processes of stimulus identification and action selection should have been

completed after 2.5 s. Thus, our study provides stronger evidence than Mawase et al. (2018),

who used a Free-RT/Timed-response paradigm, that the repetition benefit on RT cannot be

explained by faster perceptual processing of the target stimuli. By masking the sequence cue at

the moment of the go-signal, we strongly encouraged participants to complete the perceptual

processing and response selection in the preparatory period. The faster response initiation after

a repetition may reflect that the preparatory state was closer to the ideal state, which allowed for

faster triggering of the desired sequence (Churchland et al., 2006a, 2006b; Ames et al., 2014;

Michaels et al., 2018).

Improved sequence production is consistent with more efficient online planning

Repetition accelerated not only RT, but also MT for repeated sequences. Critically, a detailed

analysis of the inter-press-intervals revealed that the transition between the first two key-

presses, which was likely fully pre-planned, was not influenced by the repetition. Rather, the

repetition advantage was observed for second and, to some degree, third transitions. This

finding is consistent with the view that repetition benefits arose as a consequence of facilitated

online planning (Fig. 7B). Our current design cannot disambiguate whether this was a

consequence of participants splitting the 4-item sequences into 2 chunks, with online planning

between the chunks, or whether the slowing down was caused by the necessity for continuous

online planning in the middle of the sequence. Either way, sequence repetition shortens MT, not

by accelerating how quickly individual movement elements can be executed, but by improving

the speed by which movement elements can be linked into a sequence.

Sequence-specific learning gradually reduces the repetition effect

509   After one day of practice on a fixed set of sequences we observed behavioral improvements

510   consistent with sequence-specific learning (Wiestler et al., 2014; Ariani and Diedrichsen, 2019).

This speed advantage went hand in hand with a decrease, and eventual disappearance, of the repetition effect. This result corroborates the interpretation that repetition benefits on sequence production come from improvements in online planning. More efficient online planning for known sequences allows for faster movement speeds, up to the point where participants are limited not by their ability to quickly plan the next response, but by the ability to motorically implement the response (Ariani and Diedrichsen, 2019). When online planning ceases to be the main limiting factor, the repetition benefit disappears. An alternative and non-mutually exclusive interpretation is that sequences are planned and executed in movement chunks – in the case of our short 4-item sequences, 2 chunks of 2 key-presses each. After extensive training, participants could gradually learn to associate each sequence with a larger chunk of 4. This would enable them to quickly pre-plan the entire short sequence at once, and then execute it as one chunk, again removing the benefit of online planning during sequence repetition.

Interestingly, despite faster movement speed compared to the first blocks of Day 1, the repetition benefit reappeared on the first blocks of Day 2. This result indicates that sequence-specific learning can deteriorate overnight. Consistent with this notion, the speed in the first blocks of Day 2 was slower than the fastest blocks on Day 1, suggesting that the break between the two sessions induced some forgetting. If such decay in skill occurs regardless of the amount of training (Ajemian et al., 2010), then it makes sense from an athlete's perspective to rehearse critical movement sequences before a performance to counteract the forgetting that took place since the last training session.

Is pre-planning sufficient to drive the repetition effect, or is movement required?

The repetition effect was only present when the sequence was actually executed on the previous trial. Sequence pre-planning alone did not appear to be sufficient for the repetition effect. This was slightly surprising given the notion that neural states for planning and execution are very different, both in terms of dynamics and overall levels of activity (Kaufman et al., 2014;

Elsayed et al., 2016). Thus, it was not obvious why executing a sequence would be required to observe the repetition effect, especially on RT. In fact, if repetition facilitates response preparation (Mawase et al., 2018), one may have expected the opposite result: motor planning (or motor imagery) being sufficient for driving repetition effects (and learning) via the formation and retrieval of distinct motor memories for different sequences, even in the absence of execution, similarly to what has been shown in the context of reaching adaptation and brain-machine interface (Sheahan et al., 2016, 2018; Vyas et al., 2018).

A potential explanation for our finding could be that, despite having enough time and information, participants did not fully pre-plan the response during the preparatory period. Indeed, reaction times were relatively long (~400 ms) for triggering a pre-planned sequence. Perhaps participants used time after the go-signal to complete preparation. In this view, the completion of pre-planning would be essential for the subsequent repetition benefit. Nonetheless, our experiment was designed to motivate participants to pre-plan the sequence in advance during the delay. We masked the sequence cue so that they could not rely on that after the go-signal. Go and No-Go trials were pseudo-randomly ordered, and we included a higher proportion of Go trials (70%), such that, more often than not, participants would have to act on the pre-planned sequence. Finally, we rewarded participants on the sum of RT and MT, meaning that an easy way to earn more money would be to shorten RTs. Thus, it is hard to see how more complete pre-planning could be achieved.

Rather, a more likely explanation of our result is that the repetition benefit arises only when the planning trajectory for the entire sequence is complete, something that requires online planning (Fig. 7B). According to this view, neither the pre-planning of the initial part of the sequence, nor the motoric execution of the individual sequence elements would be enough to produce a behavioral advantage with repetition. Instead, it is revisiting the whole trajectory in the preparatory state-space that improves subsequent RTs and MTs.

Conclusions

Our results show clear repetition effects for sequential movements, thereby extending previous

findings that repetition speeds us the preparation of individual movements. The pattern of

results is consistent with repetition facilitating entire trajectories through the preparatory neural

state-space. While sequence production recruits widespread cortical sensorimotor areas

(Wiestler and Diedrichsen, 2013; Kornysheva and Diedrichsen, 2014), our results would predict

that the neuronal origin of repetition effects should not be found in the primary motor cortex,

which mainly appears to be involved in the execution of individual movements (Yokoi et al.,

2018; Yokoi and Diedrichsen, 2019). Instead, we would expect to observe the effects of

repetition in regions involved in (online) motor planning, such as premotor and parietal cortex.

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