Relating the strength of density dependence and the spatial distribution of individuals

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ABSTRACT

Spatial patterns in ecology contain useful information about underlying mechanisms and
processes. Although there are many summary statistics used to quantify these spatial
patterns, there are far fewer models that directly link explicit ecological mechanisms to
observed patterns easily derived from available data. We present a model of intraspecific
spatial aggregation that quantitatively relates static spatial patterning to negative density
dependence. Individuals are placed according to the colonization rule consistent with the
Maximum Entropy Theory of Ecology (METE), and die with probability proportional to
their abundance raised to a power α, a parameter indicating the degree of density
dependence. Our model shows quantitatively and generally that increasing density
dependence randomizes spatial patterning. $\alpha = 1$ recovers the strongly aggregated
METE distribution that is consistent with many ecosystems empirically, and as $\alpha \to 2$
our prediction approaches the binomial distribution consistent with random placement.
In between our model predicts less aggregation than METE, but more than random
placement. We additionally relate our mechanistic parameter α to the statistical
aggregation parameter k in the negative binomial distribution, giving it an ecological

interpretation in the context of density dependence. We use our model to analyze two

contrasting datasets, a 50 ha tropical forest and a 64 m^2 serpentine grassland plot. For

each dataset, we infer α for individual species as well as a community α parameter. We

find that α is generally larger in the tightly packed forest than the sparse grassland, and

the degree of density dependence increases at smaller scales. These results are consistent

with current understanding in both ecosystems, and we infer this underlying density

dependence using only empirical spatial patterns. Our model can easily be applied to

other datasets where spatially explicit data are available.

Keywords

Aggregation, density dependence, macroecology, METE, spatial ecology, theoretical

ecology

INTRODUCTION

Quantitative understanding of spatial patterns in ecosystems can illuminate underlying processes (Levin, 1992; Rosenzweig, 1995; Brown et al., 2016) and allow us to better predict ecosystem response to natural and anthropogenic disturbances (Thomas et al., 2004; Newman et al., 2020). It is also critical in understanding the species-area relationship, a well studied (Arrhenius, 1921; Plotkin et al., 2000; Drakare et al., 2006; Harte and Kitzes, 2015) macroecological pattern, and has applications in reserve designs and conservation (Kitzes and Shirley, 2016).

Many different summary statistics have been used to quantify spatial patterning in ecology (Wiegand et al., 2013), and these summary statistics have been shown to be able to distinguish different ecological mechanisms (Brown et al., 2016). More broadly, there is evidence that emergent spatial patterns contain information about underlying ecological processes (Law et al., 2009; Brown et al., 2011; Münkemüller et al., 2020), meaning that spatial data can be used to infer the importance of various mechanisms. Rather than looking directly at summary statistics, we take a slightly different approach and directly model the impact of intraspecific negative density dependence on the spatially explicit species-level abundance distribution $\Pi(n|A, A_0, n_0)$. This distribution is defined as the probability that if a species has n_0 individuals in a plot of area A_0, then it has n individuals in a randomly selected subplot of area A. We can then quantitatively examine how the degree of density dependence affects the shape of this distribution.

One prediction of this function comes from the Maximum Entropy Theory of Ecology (METE), which successfully and simultaneously predicts many macroecological patterns (Harte, 2011; Harte and Newman, 2014) across a wide range of spatial scales, taxa, and habitats (White et al., 2012; Xiao et al., 2015). For the $\Pi(n|A, A_0, n_0)$ function, METE predicts very strong spatial aggregation consistent with many observed

ecosystems. METE obtains the functional form of $\Pi(n)$ by maximizing entropy while

constraining the mean number of individuals in a subplot, however the same functional

form can be obtained using a colonization rule.

Colonization rules assign spatial locations to new individuals based on the location of

existing individuals. Harte (2011) shows that using the Laplace rule of succession as a

colonization rule results in the same geometric distribution for $\Pi(n)$ that METE predicts.

Because METE agrees well with empirical data, we will use this colonization rule in our

model. This is in contrast to a random colonization rule that would be consistent with the

random placement model (Coleman, 1981). This model predicts no spatial aggregation

and is therefore inconsistent with most observations, given that most species are

aggregated (He and Gaston, 2000; Kitzes, 2019).

Empirically, we see that the degree of aggregation is sometimes less than the METE

prediction (Conlisk et al., 2012). Conlisk et al. (2007) added an extra parameter to the

relevant colonization rule that allows $\Pi(n)$ to vary, but it has no mechanistic

interpretation and is used only as a free fit parameter. Another approach is to fit the

spatial data with a negative binomial distribution (Bliss and Fisher, 1953; He and Gaston,

2000, 2003; Green and Plotkin, 2007), but again this leaves us without any ecological

intuition about the degree of aggregation to expect in different ecosystems as the

additional parameter is a free fit parameter.

We derive a new model that uses the colonization rule consistent with METE and

adds a density dependent death rule. Our model introduces a parameter α which

quantifies the degree of intraspecific negative density dependence. Since this parameter

has an ecological interpretation, we can use our model to infer the underlying density

dependence from observed spatial patterning. This is in contrast to the models mentioned

above, where the parameters have no mechanistic interpretation.

More generally, our model predicts a more random spatial arrangement with stronger

negative density dependence and more spatial aggregation with weaker density

dependence. While empirically there is an apparent qualitative relationship between

species density and aggregation (Condit et al., 2000; Bagchi et al., 2011; Comita et al.,

2014), our aim here is to establish a general quantitative statement relating density

dependence and spatial aggregation.

First, we briefly review the METE and random placement predictions. In Methods,

we derive our new probability distribution and explain how we will compare it to data, as

well as introduce the datasets that we will be using for comparison. In Results, we look at

the shape of this probability distribution and then present aggregate and species-level

statistics for the data. Finally, in Discussion, we place our results for the analyzed

datasets in a broader context, and describe possible applications.

MATERIAL AND METHODS

METE

In METE, the $\Pi(n)$ function is given by (Harte et al., 2008)

$$\Pi(n|A,A_0,n_0) = \frac{e^{-\lambda_\Pi n}}{Z_\Pi} \tag{1}$$

where Z_Π is a normalization factor, and λ_Π is the Lagrange multiplier determined by the

constraint condition

$$\sum_n n\Pi(n|A,A_0,n_0) = \frac{n_0 A}{A_0}. \tag{2}$$

In the case of a bisection, $A = A_0/2$ and the Π function simplifies to

$$\Pi(n|n_0) = \frac{1}{n_0+1}, \tag{3}$$

which is independent of n. This means that given n_0 individuals, any arrangement of

them on the two sides of a bisected plot or quadrat is just as likely as any other.

Ecologically, this is equivalent to very strong spatial aggregation. This is in agreement with many datasets (Harte et al., 2008; Harte, 2011) but fails in others, where the theory over-predicts aggregation (Conlisk et al., 2007). This empirical agreement is why we choose the METE distribution as our starting point.

The prediction from METE is equivalent to the distribution obtained from using the Laplace rule of succession as a colonization rule (Harte, 2011). This rule states that in a colonization process, the probability of placing an individual on one side of the bisected area is roughly proportional to the fraction of individuals already there. This "rich get richer" effect results in strong spatial aggregation. More precisely, the probability for placing an individual on the left half of a bisected plot with n_L individuals on the left and n_R individuals on the right is

$$p_L = \frac{n_L + 1}{n_L + n_R + 2}.$$

To make our notation consistent with that above, let the number on the left be n and the total number to be n_0. The probabilities of a new individual arriving on the left or on the right are then:

$$\begin{aligned}
p_L(n|n_0) &= \frac{n+1}{n_0+2}, \\
p_R(n|n_0) &= \frac{n_0-n+1}{n_0+2}.
\end{aligned} \tag{4}$$

If we place n_0 individuals using this rule, the resulting probability distribution is given by Eq. 3.

Random placement

Another model for spatial ecology, perhaps the simplest, is the random placement model (Coleman, 1981). Instead of the placement rules in Eq. 4, each individual is placed randomly. In a bisected plot this means each individual has a 50 percent chance of being placed on either side, $p_L = p_R = 0.5$. Placing n_0 individuals this way gives the binomial

distribution

$$\Pi_{\mathrm{RP}}(n|n_0) = \binom{n_0}{n} \left(\frac{1}{2}\right)^{n_0} \tag{5}$$

which, if n_0 is large, means we are very likely to have roughly half the individuals on each side. This is equivalent to having no spatial aggregation; there is no preference for any new individual to stay close to any previous individual as each placement is a random coin flip.

Introducing a density dependent death rule

We now introduce an intraspecific density dependent death rule in addition to the METE colonization rule in Eq. 4. To allow for general density dependence, we set the death rate proportional to n^α. The parameter α determines the strength of the density dependence, and can be inferred from the data. Density dependence may result from resource limitation, or some other mechanism (e.g. the Janzen-Connell effect (Janzen, 1970; Connell, 1971)).

In the case of a bisected plot, each death must be on the left or right and the probability of a single death on the left, $p_{D,L}$, or right, $p_{D,R}$, is

$$
\begin{aligned}
p_{D,L}(n|n_0) &= \frac{n^\alpha}{n^\alpha + (n_0 - n)^\alpha} \\
p_{D,R}(n|n_0) &= \frac{(n_0 - n)^\alpha}{n^\alpha + (n_0 - n)^\alpha}.
\end{aligned}
\tag{6}
$$

Deriving the Π distribution

Now that we have the colonization and death rules (Eqs. 4 and 6), we can derive the general $\Pi_\alpha(n|n_0)$ for bisections. At each step in the model, we will have one death followed by the placement of one new individual. Each placement can be interpreted ecologically as a birth or as the immigration of an individual from the same species. This means the population size of the species is constant. Because we assume constant

population size, we implicitly assume some degree of negative density dependence.

However the strength of the density dependence is determined by the magnitude of α,

where stronger density dependence corresponds to larger α. We can solve for the

resulting steady state distribution where we reach an equilibrium in the spatial pattern.

There are several approaches for deriving the steady state solution for such a system.

Here, we equate the rates leaving and entering any individual state $\Pi_\alpha(n|n_0)$. We take

the probability that we start with n individuals on the left, one on the right dies and then

one is placed on the left resulting in $n+1$ individuals on the left, and equate that to the

probability that we have $n+1$ individuals on the left, one on the left dies and then one is

placed on the right resulting in n individuals on the left. We could have equivalently done

the same thing with n and $n-1$. Equating these rates using the probabilities in Eq. 4 and

Eq. 6 leads to a recursion relation. Solving it gives a general stationary solution for Π_α

with a given n_0 and α:

$$\Pi_\alpha(n|n_0) = \frac{n^\alpha + (n_0 - n)^\alpha}{C(n_0, \alpha)n_0^\alpha} \binom{n_0}{n}^{\alpha - 1} \tag{7}$$

where $C(n_0, \alpha)$ is the overall normalization that does not have a closed analytic form. In

the case that $n_0(\alpha - 1)$ is large, an approximate form for the normalization is

$$C = \frac{2^{n_0(\alpha - 1)}\pi n_0}{\sqrt{\alpha - 1}} \left(\frac{1}{2\pi n_0}\right)^{\alpha/2}. \tag{8}$$

See Supporting information S1 for the details of this derivation.

If $\alpha = 2$, we can solve for the normalization explicitly to get

$$\Pi_{\alpha=2}(n|n_0) = \frac{n^2 + (n_0 - n)^2}{2^{n_0 - 1}n_0(n_0 + 1)} \binom{n_0}{n}, \tag{9}$$

and if $\alpha = 1$, we recover the METE prediction $\Pi_{\alpha=1}(n|n_0) = \frac{1}{n_0+1}$.

Beyond the first bisection

Bisecting the plot more than once (into quadrants, then into 8 cells, etc.) when

comparing the model to data allows us to consider how aggregation changes with scale,

as well as obtain multiple data points for individual species. We use the following

method when we discuss bisecting a single plot more than once.

We begin by bisecting the plot in half in one direction, then bisecting each of the

resulting plots in the opposite direction. We alternate this bisection pattern until we have

2^b cells, where b is the number of bisections. We can then compare adjacent cells as if

they were their own bisection to obtain 2^{b-1} points.

When we go beyond the first bisection in the subsequent analysis, we only consider

species that could have at least one individual per bisection ($n_0 > 2^{b-1}$). The smallest

scale we consider in our datasets is $b = 8$, so when we bisect the plot more than once we

will only consider species with more than 128 individuals. This restriction ensures that

we do not have too many plots with only a few individuals present. If n_0 is very small,

$\Pi_\alpha(n)$ is not particularly sensitive to α and it becomes very difficult to reliably infer α

from the data. For $n_0 \leq 2$, $\Pi_\alpha(n)$ does not depend on α.

Inferring density dependence with α

Inferring the degree of intraspecific density dependence in empirical data requires

obtaining a value of α consistent with the data. Bisection predictions can be compared to

data by rank ordering the fraction of individuals present in one half of the plot for each

species (e.g. Harte (2011)). This method, however, obscures trends in species abundance

in the data and the predictions, and can lead to incorrect conclusions about which model

is preferred (see Supporting information S2).

We instead find the maximum likelihood α given the data. Inferring α using this

method gives us the values that are the most consistent with the data, even if they may

not look like they agree with the rank ordered fractions (Supporting information Fig. S1

and Table S1).

For determining α for individual species, we will require multiple bisections and the

sample size p will be roughly the number of cell pairings, $p \approx 2^{b-1}$. There will be fewer

data points in practice as some cell pairings will be empty.

We can also define a community α, assuming each species follows the same death

rule with identical α. In this case, we will have a larger sample size. For a single

bisection, we will have a sample size p equal to the number of species, $p = S_0$. For

multiple bisections where we consider the species on aggregate, the sample size will be

roughly equal to the number of species multiplied by the number of cells, $p \approx S_0 2^{b-1}$.

Again, the equality is not exact as not all cell pairings beyond the first bisection will have

all of the species present at the single bisection level.

The statistical error in estimating α this way goes as $1/\sqrt{p}$ (see Supporting

information S3). We can also get some idea of error from the maximum likelihood

estimate itself by considering the width of the likelihood distribution, however for Fig. 3

and 4, we do not include these error bars as they are smaller than the data points.

Data used

We will compare our results to two contrasting datasets. First, we will use data from a

sparse Californian serpentine grassland site (Green et al., 2003) at the McLaughlin

University of California Natural Reserve censused in 1998. This is a 64 m^2 plot divided

into 256 cells with 24 species and 37 182 individuals. There are 10 species with

abundance greater than 128 individuals that constitute 36 783 individuals. The serpentine

data are available from the Dryad Digital Repository at

`https://doi.org/10.6078/D1MQ2V` Green et al. (2019).

Second, we will use data from Barro Colorado Island (BCI) in Panama (Condit, 1998;

Hubbell et al., 1999, 2005), a 50 ha plot in a moist tropical forest. We will work with the

2005 census and consider plants with a diameter at breast height (dbh) greater than 10

cm. This dataset has 229 species and 20 852 individuals, and 40 species with abundance

greater than 128 individuals that constitue 15 960 individuals. The BCI data can be
found at `https://forestgeo.si.edu/explore-data` and are available from
the Dryad Digital Repository at `https://doi.org/10.15146/5xcp-0d46`
Condit et al. (2019).

RESULTS

Comparison to METE and random placement

Figure 1 compares the bisection predictions for $\Pi(n)$ from METE, random placement, and our density dependent model for various α, at $n_0 = 10$ and 50. In general, our model predicts that increasing negative density dependence (larger α) leads to more random spatial patterning, and less density dependence (smaller α) leads to stronger aggregation.

We can relate our distribution directly to both the METE and random placement distributions for different values of α. $\alpha = 1$ corresponds exactly to the METE solution, which makes sense given that the placement and death rules are both linear in n. As $\alpha \to 2$, our distribution approaches the random placement prediction if n_0 is large enough (Supporting information S4 shows this result analytically). For $1 < \alpha < 2$, we vary continuously between METE and random placement. We can make the distribution even more spatially aggregated than METE with $\alpha < 1$ and even less than random placement (overdispersed) with $\alpha > 2$.

We can also relate this distribution to the commonly used conditional negative binomial distribution (Bliss and Fisher, 1953; He and Gaston, 2000, 2003; Green and Plotkin, 2007) in the limit of large n_0, assuming that matching the peak of the distributions is a good approximation for the entire distribution. In that limit, the aggregation parameter k is approximately related to the density dependent parameter α

241 by

$$k \approx \frac{n_0}{2} \left(\frac{\alpha - 1}{2 - \alpha} \right) + 1. \tag{10}$$

242 Note that this approximation holds for $1 \leq \alpha \leq 2$, which is the ecologically relevant

243 range for most species. See Supporting information S5 for the derivation.

Individual species

Since the Π function is defined on the species level, we can consider each species

separately and find the maximum likelihood α for each. To do this we have to go beyond

the first bisection to get multiple data points for the same species at smaller scales.

For the serpentine data, we exclude *Eriogonum nudum* from the following figures as

an outlier (see Discussion). This leaves 9 species with abundance greater than 128

individuals.

Figure 2 shows the distribution of α values among the species at each scale, for both

the serpentine and BCI data. The median α increases at smaller scales for both datasets,

and is higher overall at the BCI dataset, even though the absolute scale is much larger.

The spread in α is quite large, but this variation is expected considering the small number

of data points, especially for rarer species. Most species have an α between 1 and 2,

which is somewhere between the aggregation predicted by METE and random placement.

Community α

We can instead treat α as a community parameter, using each species as a single data

point to recover a community α. Figure 3 shows the direct comparison between our

model and the serpentine and BCI datasets at the single bisection level. Each data point is

the observed fraction of individuals in one half of the plot versus the species abundance.

The curves in this figure show the 95% contour intervals for $\Pi(n)$ distributions predicted

by METE, random placement, and our density dependent model with the maximum

likelihood α value. The contours narrow at larger n_0 as the distributions narrow.

At the single bisection level, the maximum likelihood result for the serpentine dataset

is nearly indistinguishable from $\alpha = 1$, so the confidence interval curves on the plot for

METE and the density dependent model overlap for most n_0. For the BCI data, the

maximum likelihood value is $\alpha = 1.12$, slightly larger than 1. We can see the contours in

this case are clearly in between those for METE and random placement. The likelihoods

for each of the models are shown in Table 1.

Scale dependence in community α

Going beyond the first bisection allows us to see how α varies depending on the scale of

our plot. Figure 4 shows how α scales with fractional area for both the serpentine and

BCI plots. Density dependence increases at smaller scales in both datasets. The trend in

community α across scales is similar to the median α in the single species analysis,

though the median α is in general slightly larger than the community α. Note that here

we restrict our analysis to species with $n_0 > 128$ for all scales so that we are including

the same species across scales.

DISCUSSION

Our model establishes a quantitative relationship between the spatially explicit

distribution $\Pi(n)$ and the parameter α, which measures the strength of negative density

dependence. This can be seen in Fig. 1, where the $\Pi_\alpha(n)$ distribution flattens with

smaller α, indicating greater aggregation, and broadens as α increases. Importantly, the

parameter α has a direct interpretation. Unlike the models outlined in the introduction

(Bliss and Fisher, 1953; He and Gaston, 2000, 2003; Green and Plotkin, 2007; Conlisk

et al., 2007) where an ad hoc parameter is tuned to fit spatial patterns, our model

introduces a parameter that models the strength of negative density dependence. Further,

our relationship in Eq. 10 allows us to interpret the parameter k in the negative binomial

distribution in the same intuitive way.

Comparing species and community α

In our analysis, we consider α both as a separate parameter for each species (as in Fig. 2,

and as a community parameter where each species has the same α (as in Fig. 3 and

Fig. 4). The community α is harder to interpret ecologically, but we include it to allow

for comparisons with models with community level aggregation parameters (e.g. Conlisk

et al. (2007) and Volkov et al. (2005)). To analyze and compare the accuracy of the

species-level α and the community α, we considered the Akaike Information Criterion

(AIC) in both cases across scales (Table 2). For both serpentine and BCI at all scales

considered, we find that the AIC is lower with species-level α compared to a single

community α, despite the inclusion of 9 more parameters in the case of the serpentine

data and 228 more parameters in the case of the BCI data. This leads us to believe that a

separate α for each species describes the data better than a single community α.

Comparing serpentine and BCI

We use our model to directly compare our results between our two contrasting datasets,

serpentine and BCI. Because the serpentine site was very sparse, whereas the BCI forest

is tightly packed, we expect higher α values and greater density dependence at BCI than

at the serpentine site. This is consistent with our inferred values of α at both the

individual species level and at the community level.

Another difference between the serpentine and BCI sites is how well other

macroecological distributions agree with METE. METE well describes other patterns at

the serpentine site, and does less well at explaining the BCI data. Given that $\alpha = 1$

corresponds to the METE prediction for $\Pi(n)$, we might expect that ecosystems well

described by other METE predictions will have $\alpha \approx 1$, as these systems will generally be

consistent with METE. This could be the case as METE predictions seem to hold for

relatively static and undisturbed ecosystems (Newman et al., 2020). This interpretation is

consistent with our analysis here as the median and community αs for the serpentine data

are approximately 1 at the largest scale, whereas at BCI the median and community αs

are larger than 1.

Scaling

Our scaling results in both Figs. 2 and. 4 make ecological sense. We expect that at

smaller scales, the density dependence would be larger as individuals compete more for

resources at that scale. At large scales, we expect α to be close to 1 as the individuals do

not compete over large distances. This means that the spatial distributions look more

aggregated on large scales than on small scales as the individuals within species broadly

group together, but repel each other at small scales. We see this trend at the individual

level in Fig. 2 as the medians increase at smaller scales, and for the community α in

Fig. 4.

Our repeated bisection analysis also indicates at which scale density dependence

becomes important. This will appear as a shoulder in the data where α moves away from

≈ 1. We could do this for individual species by tracing α and looking for a shoulder in

Fig. 2, but here we will look at the community results in order to compare to Conlisk

et al. (2007) and Volkov et al. (2005). Looking at Fig. 4, we find that the shoulder in

absolute scale corresponds to $< 0.5\text{m}^2$ for the serpentine plot and < 1.6 ha for the BCI

dataset. This again makes sense given that the serpentine grassland is much more sparse

than the BCI forest.

We first compare to Conlisk et al. (2007), who introduce a fit parameter ϕ that

modifies the colonization rule Eq. 4 and allows the Π distribution to vary continuously

between random placement and METE. For the serpentine data, they find that at scales

larger than around 0.5 m^2 (the 8th bisection), ϕ approaches 0.5, which corresponds to the

META prediction. At scales around 0.5 m^2 or smaller, $\phi \approx 0.2$, where $\phi = 0$ corresponds

to random placement. This is consistent with our scaling results in Fig. 4.

Volkov et al. (2005) showed that intraspecfic and symmetric density dependence can

explain different shapes for the species-abundance distribution. Their added parameter c

is interpreted as a measure of the strength of symmetric density dependence, where $c = 0$

corresponds to no density dependence. This parameter is therefore similar to our

community α in that all species have the same degree of negative density dependence.

They then show at what density these effects become important in their Fig. 3. For BCI,

they find $c = 1.80$, and the density dependent effects are visible for species with $n > 27$.

This corresponds to density dependence entering at scales smaller than a fractional area

of $1/27 = 1/2^{4.75}$, which is close to the same scale where we see α increase away from

1 in Fig. 4.

At the individual species level at BCI, Condit et al. (2000) find that individuals are

clustered at small scales and distributed randomly at large scales. Though initially this

result seems to be in conflict with our results, it is explained by a different measure of

aggregation. They use Ω_x, which is the total number individuals found within a radius x

of a single individual, normalized by the average density of individuals. $\Omega_x = 1$

corresponds to random placement, and $\Omega_x > 1$ indicates aggregation. At small scales at

BCI, they find $\Omega_{0-10m} >> 1$, and at large scales $\Omega_{>100m} \approx 1$. We find that for most

species, $\alpha > 1$ at small scales and $\alpha \approx 1$ at large scales (Fig. 2). To see that these results

are consistent, consider a plot with a cluster of individuals on one side where the spatial

structure within the cluster is random. At the single bisection level this would be

consistent with $\alpha = 1$, but within the cluster $\alpha > 1$. That same arrangement of

individuals would give an Ω_x that shows strong aggregation at small scales and random

placement at large scales. This is what we find empirically in the BCI data. This spatial

pattern is also consistent with the Poisson cluster model outlined in Plotkin et al. (2000), where clusters of individuals are placed uniformly with random internal spatial structure.

Trends for individual species at BCI

At the individual species level more broadly, we might expect to find trends in inferred density dependence with species abundance or size. More abundant species may be competing more for the same resources, or larger species may compete over larger distances. For example, Condit et al. (2000) find that both rarer species and smaller individuals tend to be more aggregated, however at a much smaller scale (within a 10 m radius) and with a different metric of aggregation.

In the BCI data, we do not find any species with high α and high abundance (Supporting information Fig. S4), but otherwise we do not see a trend in abundance. We also find no evidence of a trend with species' mean dbh (Supporting information Fig. S5), though it is possible this trend is obscured by variance in individual size within a species, or that the range of mean dbh we considered (about $100 - 500$ mm) is too small to see its effect.

Finally, we looked for an overall energy effect. Considering that the most abundant species tend to be smaller, it may be that density dependence depends on the total metabolic rate of a species. Plotting this relationship (Supporting information Fig. S6) again does not reveal a scaling relationship.

That none of these trends are found in the data might indicate that the operating density dependent mechanism is not resource limitation, in that it doesn't depend on the abundance, size, or metabolic rate of the species. A plausible mechanism for the observed density dependence at BCI is the Janzen-Connell effect (Janzen, 1970; Connell, 1971), whereby areas near parent trees are inhospitable for offspring, resulting in density dependence. Various studies (Harms et al., 2000; Carson et al., 2008; Comita et al., 2014)

have observed this effect at BCI, which is consistent with our result that $\alpha > 1$ for most species at smaller scales there. See Supporting information S6 for more information on these trends.

Notable species

For individual species at the BCI dataset, *Gustavia superba* stood out with an average α of 1.001 across scales. This species is largely limited to 2 hectares of young secondary forest along the edge of the plot, (J. Wright, personal communication, 2019) making it look especially aggregated and resulting in a maximum likelihood α close to 1.

In the serpentine dataset, we excluded *Eriogonum nudum* as an outlier for part of our analysis. The maximum likelihood α was > 6 at the smallest scale and the maximum itself was very shallow. This species has a large canopy compared to the other grassland plants, and tends to be found far from other individuals. It makes sense that it would be overdispersed with $\alpha > 2$.

Implications for the species-area relationship

In METE, the spatial distribution is used together with the species-abundance distribution to predict the species-area relationship (Harte, 2011), and to upscale predictions of biodiversity (Harte and Kitzes, 2015). These predictions should hold in ecosystems like the serpentine grassland analyzed here, as the observed species aggregation agrees with the METE prediction. However, different levels of aggregation will impact the species-area relationship. The impact of aggregation is discussed in Wilber et al. (2015). They find that increasing randomization decreases the predicted slope of the species-area relationship at the same scale, and therefore upscaling METE will overpredict species richness. In addition, they analyze the effect of variation in aggregation among species, which slightly decreases the slope at small scales and increases the slope at larger scales. This results in a species-area relationship that more closely resembles a power law. They

also consider the effect of decreasing aggregation across scale, which results in a species-area relationship that no longer displays scale collapse. We observe both of these effects here.

Limitations and assumptions

Our model considers only bisections, and it would be useful to extend it to be more general. There are many spatial arrangements that can not be accurately captured by dividing plots into bisection, and in general a single functional summary statistic does not completely describe the observed spatial pattern (Wiegand et al., 2013). For example, if we divide our plot into an m by m grid, and have one individual per cell, we would see exactly 0.5 as the fraction for each bisection. This result would be consistent with random placement with a large number of individuals, which does not well describe this exceptionally uniform arrangement. There could also be different degrees of spatial aggregation within a cell that we will not accurately capture with a bisection. Despite these limitations, bisections are useful for understanding commonly observed macroscopic spatial patterns.

A conceptually simple extension to our model is to divide plots into quadrisections rather than bisections. The colonization and death rules then have three unknowns rather than one (the number of individuals in each quadrant, where the fourth is determined by constraining the sum to be n_0). This makes it hard to solve analytically, however we can simulate the birth-death process until it reaches steady state. We find no significant difference in our simulation compared to our prediction from two bisections, and find that a community $\alpha = 1.12$ is still consistent with the BCI data.

Because we consider the steady state solution in our model, we are assuming that the density dependence time scale is longer than the time scale of individual births or deaths. That is, α must not change too rapidly in time. This assumption is justified for many

systems roughly in steady state with their environment and not undergoing rapid change

(Newman et al., 2020).

Solving for the steady state solution also assumes that births and deaths are in

balance. We assume here that there is a single death followed by a placement, however

simulating two deaths followed by two placements gives a probability distribution

consistent with our analytic prediction. We expect our result to hold with other numbers

of deaths and placements. Assuming that births and deaths are in balance also implicitly

assumes some amount of negative density dependence, and here α provides a

quantitative measure of the degree of density dependence.

Another assumption in our model is the choice of colonization rule itself, though if

we had chosen a different colonization rule many of our conclusions would remain the

same. We use the colonization rule consistent with METE because of its good empirical

agreement (Harte, 2011). This allows us to interpret the $\alpha = 1$ case as consistent with

METE. This is useful as METE can be thought of as a null theory that holds in

ecosystems that are undisturbed and relatively static (White et al., 2012; Xiao et al.,

2015; Harte et al., 2017; Newman et al., 2020), and $\alpha \neq 1$ can be thought of as a density

dependent correction.

As an example, we could have chosen the colonization rule resulting in the random

placement distribution, which for a bisection is just $p_L = p_R = 0.5$. In this case, $\alpha = 1$

would recover the binomial distribution which we know does not well describe most

spatial data (He and Gaston, 2000), and so we cannot interpret $\alpha \neq 1$ as a density

dependent correction. As another example, if we had chosen the more general

colonization rule in (Conlisk et al., 2007) we would have two parameters to tune, making

it difficulty to differentiate between colonization and death. In ecosystems where we

suspect a different colonization rule may be in play, we could modify our theory

appropriately. In any of these cases, our general results would remain largely unchanged.

Conclusion

Our model robustly predicts that increased intraspecific negative density dependence leads to more random spatial patterning, and establishes a quantitative relationship between the degree of density dependence described by the parameter α and spatial patterning described by the metric $\Pi(n)$. We predict that this result is general across ecosystems and taxonomic groups. We find that at all but the smallest scales, the serpentine grassland site is consistent with the absence of a density dependent correction and has the strong spatial aggregation predicted by METE. This is true for both the median individual species and at the community level. At the tropical forest site, negative density dependence is important: the median species α and the community α are both greater than 1 at even the largest scales. Both ecosystems show scaling of negative density dependence as we expect with median species α and community α larger at smaller scales, and increasing away from 1 at scales consistent with other analyses. Overall, our results are consistent with current understanding at both sites. Our model allows us to infer this underlying density dependence using only static spatial patterning, and can be applied in any ecosystem with spatially explicit data.

Data availability statement

The serpentine data are available from the Dryad Digital Repository at
`https://doi.org/10.6078/D1MQ2V`. The BCI data can be found at
`https://forestgeo.si.edu/explore-data` and are available from the
Dryad Digital Repository at `https://doi.org/10.15146/5xcp-0d46`.
Relevant code is available at
`https://github.com/micbru/density_dependence_public`.

Declarations

Acknowledgements – JH thanks the Santa Fe Institute for their hospitality. We thank Kaito Umemura for valuable discussion and feedback, and Egbert Leigh and Joseph Wright for their help with the BCI dataset. We thank Jessica Green for the serpentine data. The BCI forest dynamics research project was founded by S.P. Hubbell and R.B. Foster and is now managed by R. Condit, S. Lao, and R. Perez under the Center for Tropical Forest Science and the Smithsonian Tropical Research in Panama. Numerous organizations have provided funding, principally the U.S. National Science Foundation, and hundreds of field workers have contributed.

Funding – This material is based upon work is supported by the National Science Foundation under Grant No. DEB-1751380. MB acknowledges the support of the Natural Sciences and Engineering Research Council of Canada (NSERC), [PGSD2-517114-2018].

Author contributions – Both authors were involved in conceptualization. MB conducted the formal analysis and led the writing of the manuscript.

Conflict of interest – None.

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Serpentine		BCI	
Model	Log-likelihood	Model	Log-likelihood
METE	-114.8	METE	-729
RP	-5188.6	RP	-963
$\alpha = 1.0003$	-114.6	$\alpha = 1.12$	-660

Table 1. Log-likelihood values for the three different models, with α as a community parameter. We can compare our model to METE using the deviance in log-likelihood and obtain a p-value. The deviance is defined as twice the difference in log-likelihood. For the serpentine dataset, the deviance is 0.6 which corresponds to a p-value of 0.45. For the BCI dataset, the deviance is 138 which corresponds to a p-value of $< 10^{-30}$.

Scale (A/A_0)	2^{-8}	2^{-7}	2^{-6}	2^{-5}	2^{-4}	2^{-3}
Serpentine Species α, AIC	474	769	1294	1931	3208	4881
Community α, AIC	485	777	1321	2079	3420	5182
BCI Species α, AIC	10133	7541	5079	3409	2109	1271
Community α, AIC	10207	7621	5148	3522	2171	1307

Table 2. Comparison of the Akaike Information Criterion (AIC) for α defined at the individual species level and at the community level in both the serpentine and BCI data and across scales. The AIC is lower at the species level in all cases.

(a) $n_0 = 10$

(b) $n_0 = 50$

Figure 1. Comparison of the bisection probability distributions $\Pi(n)$ from METE, random placement (RP), and our density dependent model with varying α. At $\alpha = 1$, our model corresponds exactly to METE. At larger n_0, $\alpha \to 2$ approaches the random placement distribution. Our model varies continuously between METE and random placement for $1 < \alpha < 2$.

(a) Serpentine, 10 species

(b) BCI, 40 species

Figure 2. Boxplots for α among the species at different scales. At smaller scales α is larger, and we see a relatively large spread in α across species at the same scale. The boxplots show boxes from quartile 1 (Q1) to quartile 3 (Q3) with a line at the median. The whiskers extend to $1.5\times$(Q3-Q1). The remaining points are plotted as individual circles.

(a) Serpentine

(b) BCI

Figure 3. 95% contour intervals for the different predicted probability distributions overlayed with (3a) the serpentine dataset, and (3b) the BCI dataset. For our density dependent model with a community α, $\alpha = 1.0003$ maximizes the log-likelihood for the serpentine dataset, and $\alpha = 1.12$ maximizes log-likelihood for BCI dataset.

Figure 4. Community α scaling with area for species with abundance $n_0 > 128$. The density dependence again increases at smaller scales and the trend is similar to the single species analysis. The serpentine dataset has 36 783 individuals and the BCI dataset has 15 960 individuals.