Uplift and erosion of genomic islands with standing genetic variation

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Abstract

Details of the processes that generate biological diversity have long been of interest to evolutionary biologists. A common theme in nature is diversification via divergent selection with gene flow. Empirical studies on this topic find variable genetic differentiation throughout the genome, that genetic differentiation is non-randomly distributed, and that loci of adaptive significance are often found clustered together within “genomic islands of divergence”. Theoretical models based on new mutations show how these genomic islands can arise and grow as a result of a complex interaction of various evolutionary and genic processes. In the current study, I ask if such genomic islands can alternatively arise from divergent selection from standing genetic variation and I tested this using a simple two locus model of selection. There are numerous ways in which standing genetic variation can be partitioned (e.g., between alleles, between loci, and between populations) and I tested which of these scenarios can give rise to an island pattern compared to no genomic differentiation or complete genomic differentiation. I found that divergent selection, even without reciprocal gene exchange between populations, following a bout of admixture can relatively quickly produce an island pattern. Moreover, I found two pathways in which islands can form from divergence from standing variation: 1) through the build up of islands and 2) through the breakdown of larger, genome-wide differentiation. Lastly, similar to new mutation theory, I found that the frequency of recombination is an important determinant of island formation from standing genetic variation such that mating behavior of a species (e.g., facultative or obligate sexual) can impact the likelihood of island formation.

Keywords: Genomic Islands of Divergence, Standing Genetic Variation,

Population Genetics, Population Genomics, Divergence with Gene Flow, Adaptation

1. Introduction

It is increasingly evident that phenotypic and taxonomic diversity arises despite ongoing gene flow between populations or incipient species [15]. Predicting the genomic response to divergence with gene flow (DGF) in nature is difficult, however, because several interacting evolutionary and genetic factors can occur simultaneously. Moreover, some of these factors can themselves have multiple levels of interaction. For example, divergent selection contributes to genetic divergence both *directly* by its effect on actual selected loci and *indirectly* by ‘divergent hitchhiking’ (DH) of nearby neutral loci [16].

The metaphor of “genomic islands of divergence” has been used recently to integrate the dynamics of migration and divergent selection affecting selected loci and recombination and selection affecting the degree of genetic hitchhiking [14, 10]. Here, inter-population gene flow homogenizes the neutrally evolving “sea floor” whereas DH creates genomic isolation, reducing the effective migration rate at selected loci as well as loci in tight physical linkage with these selected loci [16]. Such reduction in effective migration owing to DH can further diverge weakly selected, *de novo* mutations at nearby loci [18] that would otherwise be trumped by migration experienced at the sea floor. Thus, over time these divergent islands are hypothesized to grow (widen) with the inverse of the product of migration and recombination whereas height (extent of differentiation) is expected to be proportional to strength of divergent selection.

Mathematical models of GI formation has almost exclusively focused on divergent selection based on new mutations even though many research programs find adaptation from standing genetic variation [SGV; 13, 3, 2, 8, 7, 9]. Adaptation from SGV can lead to faster evolution, fixation of more small-effect alleles, and an increase frequency of beneficial recessive alleles [11] relative to adaptation from new mutations [6, 1]. With regards to GI architecture, however, less is known about the role of SGV in part because such variation can be partitioned several different ways both within and between populations. For example, two populations might be fixed for alternate alleles at all polymorphic loci such that each population is in linkage equilibrium but there is a high degree of cross-population linkage disequilibrium (X-LD)

between loci. In such a case all the SGV is partitioned between populations. In other cases, a varying level of polymorphism can occur within one or more populations at one or more loci. It is reasonable to suspect that varying how SGV is partitioned would likely affect the overall magnitude and localization of genetic differentiation nearby loci under divergent selection.

The arrangement of genetic differentiation that occurs across the genome varies widely in the literature [10] which makes drawing conclusions on the nature of genomic differentiation difficult. It has been postulated that islands form by DH, with growth of such chromosomal regions possible by further divergent selection occurring at loci that are themselves linked to an already established divergently selected locus [10, 18]. I hypothesize that another, perhaps more frequently used mechanism for island formation is from the segregation of existing genetic variation between populations experiencing different selection regimes. Herein I modeled genetic divergence from SGV to explore the parameter combinations likely to give rise to islands versus those that generate either genome-wide divergence or no divergence between populations. I considered seven different demographic scenarios that differ in terms of how SGV is partitioned within and between a pair of populations, the mating type, and the migration frequency between diverging populations. The results highlight how the balance of migration and selection together with meta-population demography can strongly affect short term genome-wide patterns of differentiation.

2. Methods

2.1. Modeling divergence from standing genetic variation

I was interested in identifying the parameter range likely to give rise to islands (i.e., local differentiation only) from those that give rise to other genomic patterns (i.e., no or genome-wide differentiation). I considered scenarios in which 1) a pair of populations were completely isolated for a period of time that affected the partitioning of genetic variation between populations followed by 2) secondary contact and 3) divergence with gene flow. I was concerned here with SGV only and so I assumed that the genomic response to a given demographic scenario occurs without new mutations or that is on a shorter timescale than is relevant for new mutations. I examined the genome-wide and temporal dynamics of differentiation for 7 specific evolutionary scenarios that vary in how SGV is partitioned within and between

populations, the degree of admixture between populations that occurred during secondary contact, the periodicity of migration, and whether individuals are obligate or facultative sexual (Table 1). In all scenarios, the initial type of SGV was a parameter of the model and I explore different levels of migration, divergent selection, and recombination.

The general life-history cycle during the divergence with gene flow following secondary contact is as follows. Migration between populations occurs at rate m between populations every m_f generations. For obligate sexual cases, random mating occurs every generation, following migration if applicable. For facultative sexual cases, random mating occurs following migration only. In other words, for the facultative sexual scenarios, cell division occurs asexually and there are m_f rounds of viability selection occurring between migration and random mating. Viability selection within populations occurs at the last step of the life cycle.

In each evolutionary scenario I tracked genetic differentiation between populations at neutral loci linked to a single locus under divergent selection. Locus A is under divergent selection between these two populations and it is linked to a neutral locus B . The dynamics of neutral divergence between populations can be tracked by following haplotype frequencies through time. Because there is only a single locus under selection, we can obtain genomic patterns of differentiation by varying the recombination rate, r , between loci A and B , migration between populations, and the strength of selection at locus A .

Let $g_{ij}^{(k)}$ be the frequency of haplotypes in population k with allele i at selected locus A and allele j at neutral locus B . For convenience we can summarize the gamete frequencies for each population k as a vector, $\mathbf{p}_k$:

$$\mathbf{p}_k = \begin{pmatrix} g_{11}^{(k)} \\ g_{12}^{(k)} \\ g_{21}^{(k)} \\ g_{22}^{(k)} \end{pmatrix} \quad (1)$$

2.1.1. Migration and random mating

Migration between the two populations experiencing divergent selection follows a simple two-island model with a migration rate m . For example, the vector of new haplotype frequencies following migration for population 1 is:

$$\mathbf{p}_1^{(new)} = (1 - m)\mathbf{p}_1 + m\mathbf{p}_2 \quad (2)$$

Table 1: Evolutionary models of explored in this study. For each scenario, the starting gamete frequencies, within-population LD, cross-population linkage disequilibrium (X-LD), mating mode, and frequency of migration (m_f) is given. Admixture here refers to the number of random mating that occurred during the period of secondary contact.

Scenario	mating	m_f	Admixture	LD	X-LD	$g_{11}^{(1)}$	$g_{12}^{(1)}$	$g_{21}^{(1)}$	$g_{22}^{(1)}$	$g_{11}^{(2)}$	$g_{12}^{(2)}$	$g_{21}^{(2)}$	$g_{22}^{(2)}$
1	obligate	1	none	0	0.25	1	0	0	0	0	0	0	1
2	obligate	1	none	0	0.125	0.5	0.5	0	0	0	0	0	1
3	obligate	1	none	0	0	0.5	0.5	0	0	0	0	0.5	0.5
4	obligate	1	F_1 s	0.25	0.25	0.5	0	0	0.5	0.5	0	0	0.5
5	obligate	1	F_2 s	$0.25 - \frac{r}{4}$	$0.25 - \frac{r}{4}$	$0.5 - \frac{r}{4}$	$\frac{r}{4}$	$\frac{r}{4}$	$0.5 - \frac{r}{4}$	$0.5 - \frac{r}{4}$	$\frac{r}{4}$	$\frac{r}{4}$	$0.5 - \frac{r}{4}$
6	obligate	50	F_2 s	$0.25 - \frac{r}{4}$	$0.25 - \frac{r}{4}$	$0.5 - \frac{r}{4}$	$\frac{r}{4}$	$\frac{r}{4}$	$0.5 - \frac{r}{4}$	$0.5 - \frac{r}{4}$	$\frac{r}{4}$	$\frac{r}{4}$	$0.5 - \frac{r}{4}$
7	facultative	50	F_2 s	$0.25 - \frac{r}{4}$	$0.25 - \frac{r}{4}$	$0.5 - \frac{r}{4}$	$\frac{r}{4}$	$\frac{r}{4}$	$0.5 - \frac{r}{4}$	$0.5 - \frac{r}{4}$	$\frac{r}{4}$	$\frac{r}{4}$	$0.5 - \frac{r}{4}$

99 Mating is assumed to occur at random amongst the individuals within a
100 given population. The change in haplotype frequency after random mating
101 is:

$$\Delta g_{ij} = \pm r D_k \quad (3)$$

102 where r is the recombination rate between loci A and B and D_k is the
103 disequilibrium coefficient ($D_k = g_{11}^{(k)} g_{22}^{(k)} - g_{12}^{(k)} g_{21}^{(k)}$). For the coupling gametes
104 (i.e., $i = j$) the quantity $r D_k$ in Equation 3 is subtracted and it is added
105 otherwise.

106 2.1.2. Viability selection

107 A matrix describing the fitness values for all zygotes in population 1 is
108 given by the matrix $\mathbf{S}_1$:

$$\mathbf{S}_1 = \begin{pmatrix} 1 & 1 & 1 - sh & 1 - sh \\ 1 & 1 & 1 - sh & 1 - sh \\ 1 - sh & 1 - sh & 1 - s & 1 - s \\ 1 - sh & 1 - sh & 1 - s & 1 - s \end{pmatrix} \quad (4)$$

109 where s and h are the selection and dominance coefficients, respectively.
110 For simplicity in the current model I assumed heterozygotes have intermedi-
111 ate fitness between the homozygote genotypes (i.e., $h = 0.5$). In equation 4
112 rows and columns correspond to the elements in $\mathbf{p}_k$. In population 2 the fit-
113 ness matrix is constructed similarly but the quantity $1 - s$ is replaced with 1
114 and *vice versa*. The change in haplotype frequencies for each population can
115 be calculated by considering the marginal fitness values for each haplotype.
116 Following [12], the vector of marginal fitness values is:

$$\mathbf{w}_k^* = \mathbf{p}_k^T \mathbf{S}_k \quad (5)$$

117 The change of haplotype frequencies due to viability selection depends
118 on the mean relative fitness of a given population, the current haplotype
119 frequency, and its marginal fitness. The mean relative fitness is the dot
120 product of the haplotype frequencies and their corresponding marginal fitness
121 values:

$$\bar{w}_k = \mathbf{p}_k \cdot \mathbf{w}_k^{*T} \quad (6)$$

122 Thus, the vector of change of haplotype frequencies after a bout of selec-
123 tion is then:

$$\Delta \mathbf{p}_k = \bar{w}_k^{-1} (\mathbf{p}_k \cdot (\mathbf{w}_k^* - \bar{w}_k)^T) \quad (7)$$

124 2.1.3. Numerical methods

125 Since I was interested in the short-term dynamics of genomic differentia-
126 tion following secondary contact, I ran each scenario for 500 generations for
127 varying migration rates and strengths of selection and recorded the extent
128 genetic differentiation [F_{ST} , 4, 5] at each locus along a simulated chromo-
129 some.

130 3. Results

131 3.1. Genomic differentiation under DGF from secondary contact

132 3.1.1. No admixture during secondary contact

133 Under the evolutionary scenarios in which no admixture during secondary
134 contact occurred (i.e., scenarios 1-3, Table 1) I found that the extent of ge-
135 netic differentiation depended on the relative magnitudes of migration and
136 selection (Figure 1). When initial divergence was strong (i.e., scenario #1)
137 the small increases in the migration rate greatly reduced overall differentia-
138 tion in about 100 generations. Here, under weak to intermediate migration
139 (i.e., $0.001 \geq m \geq 0.01$) and under intermediate to strong selection (i.e.,
140 $s \geq 0.05$) genomic differentiation occurred only under tight linkage, consis-
141 tent with genomic islands. This same general pattern was observed when the
142 initial divergence was weaker (LD=0, X-LD=0.125, scenario #2, Figure 2)
143 but with less overall differentiation. As expected, when SGV was partitioned
144 completely within populations no differentiation occurred in any migration
145 and selection range (scenario #3, Figure 3).

146 3.1.2. Brief admixture during secondary contact

147 I found that brief admixture between diverged, locally adapted popula-
148 tions immediately before DGF strongly promoted island formation. Indeed,
149 when DGF was initiated with F_1 individuals – the parents of which were
150 locally adapted to their respective environment – I found that the only di-
151 vergence that was detected occurred locally within the genome (scenario #4,
152 Figure 4). This island pattern was also observed when two rounds of random
153 mating occurred prior to DGF (scenario #5, Figure 5).

154 I found a strong effect of mating type on the pattern of genetic differentia-
155 tion from SGV. As predicted, for obligate sexual mating and when migration

occurs periodically (e.g., every 50 generations, scenario #6) selection is relatively strong compared to migration resulting in island formation and persistence even under maximum migration ($m = 0.5$; migration per generation = 0.01). When mating type is facultative, however, the joint contribution of selection and migration can create genome-wide differentiation in addition to islands (Figure 7). Here, genome-wide differentiation occurs under strong selection and weak migration.

I identified two pathways in which islands form, depending on the relative strength of selection and migration. First, under strong selection ($s \geq 0.05$) and strong migration ($m \geq 0.2$) islands form from the breakdown of genomic differentiation with time (e.g., upper right panels of Figures 6 and 7). Second, under weak selection ($s=0.01$) and weak to moderate migration ($0.01 < m < 0.05$), neutral genetic differentiation began low and increased (“grew”) over time (e.g., Figures 6 and 7). The size (width) of islands differed between the two mating types – with larger islands found in facultative compared to obligate mating types. Interestingly, migration was not need for island growth to occur when admixture occurred during a single bout of secondary contact ($m = 0$, $s = 0.01$, Figures 4, 5, 6, and 6). This is in stark contrast to scenarios in which no admixture occurred in secondary contact (scenarios 1-3, Figures 1, 2, and 1).

4. Discussion

4.1. Islands from standing genetic variation

I found that localized genetic differentiation can readily occur under a wide range of demographic scenarios, depending on the relative strength of migration and divergent selection. Linkage disequilibrium within and between isolated populations can be generated a number of ways prior to the onset of a divergent selection regime. For example, genetic drift can fix alternative alleles between two isolated populations such that there is no LD within but maximum LD between populations. Of course, the fixation of alternative alleles in each isolated population can occur due to preexisting divergent selection on new mutations. In general, the breakdown of linkage disequilibrium under divergence is required for islands to form.

4.2. Islands uplift and islands erode

Under new mutation theory of island formation, divergent hitchhiking allows for increase establishment probability of new mutations [17] and so

islands can “uplift” from the metaphorical sea when seeded with divergently selected loci. I found that such uplifting can also occur from standing genetic variation. An admixture event between genotypically distinct populations creates a high degree of within population LD [5]. Such a case may occur between hybridizing sister species or through the ephemeral breakdown of a migration barrier. When divergent selection occurs following such an event there are two mechanisms in which islands can form, depending the strength of selection relative to gene flow. During the time in which LD is broken down within a population by random mating, differentiation at both selected and neutral loci increases (though this increase is faster at the selected locus; Figure 8E-F). In the case of no migration between populations (e.g., left column of Figure 8), neutral differentiation will remain steady since no migration (or mutation) is occurring. Islands can also buildup quickly and erode. For example, under strong divergence with moderate gene flow there is a rapid breakdown of LD early with a slower breakdown of LD later (Figure 8D). During the rapid breakdown phase, where the change in haplotype frequencies is dominated by selection and F_{ST} increases with time for both selected and linked neutral sites. During the slow breakdown of LD phase, the change in haplotype frequencies are dominated by migration. Here, differentiation at the selected locus is stable whereas differentiation decreases at the neutral locus (Figure 8F) owing to recombination. With tighter (weaker) linkage the decrease of F_{ST} will be slower (higher). Thus, under divergence with gene flow I would expect islands to erode with time.

Figure 1: Dynamics of divergence with gene flow under scenario #1 – obligate sexual, $m_f = 1$, LD=0, X-LD=0.25. For each panel, the extent of divergence (F_{ST}) at neutral loci are given across time. Rows indicate migration rate, m , between diverging populations and columns indicate the strength of divergent selection, s , at selected locus A.

Figure 2: Dynamics of divergence with gene flow under scenario #2 – obligate sexual, $m_f = 1$, $LD=0$, $X-LD=0.125$. For each panel, the extent of divergence (F_{ST}) at neutral loci are given across time. Rows indicate migration rate, m , between diverging populations and columns indicate the strength of divergent selection, s , at selected locus A .

Figure 3: Dynamics of divergence with gene flow under scenario #3 – obligate sexual, $m_f = 1$, LD=0, X-LD=0. For each panel, the extent of divergence (F_{ST}) at neutral loci are given across time. Rows indicate migration rate, m , between diverging populations and columns indicate the strength of divergent selection, s , at selected locus A.

Figure 4: Dynamics of divergence with gene flow under scenario #4 – obligate sexual, $m_f = 1$, LD=0.25, X-LD=0.25. For each panel, the extent of divergence (F_{ST}) at neutral loci are given across time. Rows indicate migration rate, m , between diverging populations and columns indicate the strength of divergent selection, s , at selected locus A .

Figure 5: Dynamics of divergence with gene flow under scenario #5 – obligate sexual, $m_f = 1$, $LD=0.25 - 0.25r$, $X-LD=0.25 - 0.25r$. For each panel, the extent of divergence (F_{ST}) at neutral loci are given across time. Rows indicate migration rate, m , between diverging populations and columns indicate the strength of divergent selection, s , at selected locus A. Note the change of migration rates investigated in this figure compared to Figure 4

Figure 6: Dynamics of divergence with gene flow under scenario #6 – obligate sexual, $m_f = 1$, $LD=0.25 - 0.25r$, $X-LD=0.25 - 0.25r$. For each panel, the extent of divergence (F_{ST}) at neutral loci are given across time. Rows indicate migration rate, m , between diverging populations and columns indicate the strength of divergent selection, s , at selected locus A .

Figure 7: Dynamics of divergence with gene flow under scenario #7 – facultative sexual, $m_f = 50$, $LD=0.25 - 0.25r$, $X-LD=0.25 - 0.25r$. For each panel, the extent of divergence (F_{ST}) at neutral loci are given across time. Rows indicate migration rate, m , between diverging populations and columns indicate the strength of divergent selection, s , at selected locus A .

Figure 8: Temporal dynamics of genotype frequencies, LD, and differentiation at the selected and linked neutral loci (scenario #4). Two specific examples (left and right columns) of island formation are given. For each example I plotted the results for population #1 only so that genotypes g_{11} and g_{12} are favored and g_{22} and g_{21} are disfavored. Left column, migration is absent. Right column, migration is weak ($m = 0.01$). For each condition the selection coefficient was strong ($s = 0.1$) and the recombination rate between the selected and neutral loci was 0.01.

5. References

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