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Unbiased emission factor estimators for large scale forest inventories: domain assessment techniques

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Abstract Large scale forest inventories are often undertaken following a stratified random or systematic design. Yet the strata rarely correspond to the reporting areas of interest (domains) over which the country wants to report specific variables. The process is exemplified by a country aiming to use national forest inventory data to obtain average biomass estimates per forest type for GHGI international reporting, where activity data (areas of land use or land use changes) and emission factors (carbon coefficients) are typically compiled from disparate sources and estimated using different sampling schemes. This study aims to provide a decision tree for the use of data obtained from forest surveys to draw conclusions about population sub-groups created after (and independently of) the sample selection. While bias can arise whenever activity data and emission factors are calculated independently, it can be eliminated in case of a simple random or simple systematic design if properly weighted estimators are provided. This manuscript describes two unbiased estimators that can be used to estimate reporting-strata means, regardless of the sampling design adopted, and extends the result to the common situation in which the reporting-strata are spatially explicit, where a nested group estimator outperforms in terms of both bias and precision other more traditional estimators. From this estimator, an optimal sample allocation scheme is also derived.

Keywords emission factors · Forest Reference Levels · Greenhouse Gas Inventory · National Forest Inventory · REDD+ · Survey sampling

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1 Introduction

Country-specific estimates of carbon coefficients (aka *emission factors*) are required to compile national greenhouse gas inventories (GHGI) under the United Nations Framework Convention on Climate Change (UNFCCC) and, in the context of REDD+, for developing Forest Reference Levels (FRLs) and for the reporting of REDD+ results-based actions. To this end, in order to account for emissions from land use, land use change and forestry (LULUCF), different emission factors have to be estimated for each of a number of land use categories and of various other land subpopulations, typically defined according to climatic zone, forest type or management practices (cf. IPCC 2003, 2006). Notice that these estimates are required to be unbiased and as precise as possible¹.

IPCC tier 3 methods, which, if well implemented, are supposed to be the most certain and reliable, require these forest carbon coefficients to be obtained from national forest inventories (NFI). Due to the intrinsic variability of biomes and land uses in most of the countries, sampling designs for NFIs tend to rely on stratification as a first step to reduce uncertainties in emission estimates (Köhl et al 2006; Maniatis and Mollicone 2010). But the subpopulations for which the emission factors are needed might differ from those designated at the planning phase of the forest inventory. That is, the requested reporting units or areas of interest for the emission factors might be identified after the definition of the sampling design and/or after the data collection has been carried out. These targeted subpopulations are often called *domains of interest* in the statistical literature (Cochran 1977; Särndal et al 1992; Särndal and Lundström 2005; Köhl et al 2006; Gregoire and Valentine 2008; Mandallaz 2008; Lohr 2009; Schulz et al 2009; Thompson 2012). The lack of congruency between strata and domains usually results in a random and often small number of observations for each emission factor. The situation can be made even more complicated in the presence of complex forest inventory survey designs, often not optimized for all variables of interest involved in multipurpose inventories. In all these cases specific statistical approaches must be adopted in order to ensure that the estimates are precise and unbiased, very often requiring ancillary data or model-, rather than design-based inference (Schreuder et al 2004; Chambers 2011). Similar issues might arise whenever estimates of forest carbon are required not only at the national level, but also for certain provinces or districts of the country (Rao and Molina 2015).

Salient features of the estimation of emission factors for the LULUCF sector are that the domains are often defined spatially over a landscape and that their sizes are usually known but frequently obtained independently of the NFI. The emission factors, in this case, would consist of the average values of carbon or biomass for those specific areas. A detailed review of basic estimation methods for domains is provided in §10.3 of Särndal et al (1992). A compilation of domain estimators used for the analysis of the U.S.A. forest inventory data is presented in Bechtold and Patterson (2005) and for the Swiss National forest inventory by Mandallaz (2008).

Here we aim to provide an overall vision of the different domain estimation techniques applicable to derive LULUCF emission factors from large scale forest inventories. The focus here is particularly on NFI data which are often available to/in REDD+ countries.

¹ From IPCC (2003): “Estimates should be accurate in the sense that they are systematically neither over nor under true emissions or removals, so far as can be judged, and that uncertainties are reduced so far as is practicable”

Table 1 definitions of weights and proportions

Symbol	Definition
P_d	N_d/N
Q_d	$1 - P_d$
W_h	N_h/N
P_{hd}	N_{hd}/N_h
Q_{hd}	$1 - P_{hd}$
W_{hd}	N_{hd}/N_d
p_{hd}	n_{hd}/n_h
f_d	n_d/N_d
f_h	n_h/N_h

Our results apply both to cases in which domain sizes are estimated within or independently of the NFI. In the case where the domains are known and spatially explicit we also derive an unbiased estimator that improves the standard errors typically associated to classical π -weighted (i.e., Horwitz-Thompson) estimators, as well as the optimum sampling sizes per stratum derived from this estimator. Finally, we propose a decision tree, targeted particularly to countries aiming to report emission factor estimates from national forest inventories, to select the most appropriate domain mean estimator.

2 General formulation for domain estimators

Let the population of interest be denoted by $\mathcal{P}$, and the size of $\mathcal{P}$, as measured by the number of areal units of uniform size, be denoted by N , so that $\mathcal{P} = \{u_1, \dots, u_k, \dots, u_N\}$. Let $\mathcal{P}$ be partitioned into H non-overlapping subpopulations $\mathcal{P}_1, \dots, \mathcal{P}_H$. These will be referred to as the sampling strata. Let N_h denote the size of $\mathcal{P}_h$, with $h = 1, \dots, H$ such that $N = \bigcup_{h=1}^H N_h$. The population may also be partitioned alternately into D reporting strata, known widely in literature on survey sampling as *domains*, cf. Särndal et al (1992, Chap. 10). To this end, let $\mathcal{U}_d$ denote the d^{th} domain. Let N_d denote the size of $\mathcal{U}_d$, $d = 1, \dots, D$ such that $N = \bigcup_{d=1}^D N_d$ and let $P_d = N_d/N$ denote the relative size of the domain $\mathcal{U}_d$ (Table 1). In this paper we address the estimation of the domain averages, $\bar{Y}_d$, for some variable on interest indicated by Y . Implicit in the above is that each population unit can be a member of a single sampling stratum and domain.

Let s_d define the part of the sample that happens to fall into $\mathcal{U}_d$, so that: $s_d = s \cap \mathcal{U}_d = \bigcup_{h=1}^H (s_h \cap \mathcal{U}_d)$. Using results that are elaborated in §5.8, 7.6, and 10.3 of Särndal et al (1992) (see also Cochran 1977; Mandallaz 2008; Thompson 2012), an approximately design-unbiased estimator for the domain mean, whether or not the domain size is known, is

$$\tilde{y}_{s_d} = \frac{\sum_{k \in s_d} \frac{y_k}{\pi_k}}{\hat{N}_d} \quad (1)$$

where π_k is the inclusion probability of the k^{th} unit u_k , and $\hat{N}_d = \sum_{k \in s_d} \pi_k^{-1}$.
The approximate variance of $\tilde{y}_{s_d}$ is given by

$$AV(\tilde{y}_{s_d}) = \frac{1}{\hat{N}_d^2} \sum_{k \in \mathcal{U}_d} \sum_{l \in \mathcal{U}_d} \Delta_{kl} \left(\frac{y_k - \bar{y}_{\mathcal{U}_d}}{\pi_k} \right) \left(\frac{y_l - \bar{y}_{\mathcal{U}_d}}{\pi_l} \right) \quad (2)$$

where $\Delta_{kl} = \pi_{kl} - \pi_k \pi_l$ is the covariance between the *sample membership indicators*. An estimator of $AV(\tilde{y}_{s_d})$ is

$$\hat{V}(\tilde{y}_{s_d}) = \frac{1}{\hat{N}_d^2} \sum_{k \in s_d} \sum_{l \in s_d} \check{\Delta}_{kl} \left(\frac{y_k - \tilde{y}_{s_d}}{\pi_k} \right) \left(\frac{y_l - \tilde{y}_{s_d}}{\pi_l} \right). \quad (3)$$

where $\check{\Delta}_{kl} = (\pi_{kl} - \pi_k \pi_l) \pi_{kl}^{-1}$. Specific applications of these general formulas to the most common sampling designs are provided in the next sections. The underlying assumption is that the probability that s_d is empty is negligible.

In the following sections we will assess specific applications of these general formulas to the most common sampling designs: simple random and stratified random sampling.

3 Simple Random Sampling

Let us consider the case in which a simple random sampling (SRS) is carried out on the population $\mathcal{P}$. That is, a sample s of size n is randomly selected from $\mathcal{P}$. Let us define n_d the size of the sample falling in the domain $\mathcal{U}_d$. Under simple random sampling (where $\pi_k = n/N$), given the event $n_d > 0$, the estimator $\tilde{y}_{s_d}$ (Eq. (1)), is approximately design-unbiased for the domain mean and corresponds to the domain sample mean, namely

$$\bar{y}_{s_d} = \frac{\sum_{k \in s_d} y_k}{n_d}. \quad (4)$$

However, when the probability that $n_d = 0$ is not negligible, the bias of $\bar{y}_{s_d}$ may be substantial. The same result applies also to the case in which a systematic sampling is carried out (with $\pi_k = 1/a$, where a is the sampling interval between successively sampled units). From Eq. (2), the approximate variance of $\bar{y}_{s_d}$ is

$$AV(\bar{y}_{s_d}) = \left(\frac{1}{n_d^0} - \frac{1}{N_d} \right) S_{\mathcal{U}_d}^2 \quad (5)$$

where $n_d^0 = n_h \frac{N_d}{N}$ is the expected domain sample size and $S_{\mathcal{U}_d}^2 = (N_d - 1)^{-1} \sum_{k \in \mathcal{U}_d} (y_k - \bar{Y}_d)^2$ is the domain variance. Eq. (5), however, is likely to underestimate the variance of $\bar{y}_{s_d}$, due the fact that, under a simple random sampling, the domain sample size n_d is a random variable, such that $n_d \sim B(n_d^0, \frac{N_d}{N})$. Each time a sample of size n is drawn from the population, the number of sample units that fall in the domain $\mathcal{U}_d$ might differ (or even be zero). The random domain sample size results in a loss of precision, which is inversely proportional to sample size n and to the domain proportion P_d . Conditioning on $n_d > 0$ provides a better approximation of the variance of $\bar{y}_{s_d}$, namely

$$AV^*(\bar{y}_{s_d}) = \left(\frac{1}{n_d^0} - \frac{1}{N_d} \right) \left(1 + \frac{Q_d}{n_d^0} \right) S_{\mathcal{U}_d}^2, \quad (6)$$

where $Q_d = 1 - P_d$, considering binomial probabilities, as shown in §10.4 of Särndal et al (1992). Notice that Eq. (6) requires the domain size to be known.

The variance estimator in Eq. (3) becomes

$$\hat{V}(\bar{y}_{s_d}) = \left(\frac{1}{n_d} - \frac{1}{\hat{N}_d} \right) S_{s_d}^2 \quad (7)$$

where $\hat{N}_d = Nn_d/n$ and $S_{s_d}^2 = (n_d - 1)^{-1} \sum_{k \in s_d} (y_k - \bar{y}_{s_d})^2$ is the domain sample variance.

4 Stratified Random Sampling

Let us consider the case in which a stratified random sampling is carried out on the population $\mathcal{P}$, based on the H sampling-strata. That is, a probability sample s_h , of size n_h , is independently selected from each $\mathcal{P}_h$, according to a design $p_h()$. The total sample set, denoted as s , will be composed as: $s = s_1 \cup s_2 \cdots \cup s_H$.

Any stratum will intersect a certain number of domains. Let us define the intersection among the d^{th} domain and the h^{th} sampling-stratum as $\mathcal{P}_h \cap \mathcal{U}_d = \{k : k \in \mathcal{P}_h \wedge k \in \mathcal{U}_d\}$ and let N_{hd} denote the size of $\mathcal{P}_h \cap \mathcal{U}_d$. We can now define the following proportions: $W_h = N_h/N$, which is the stratum weight, $W_{hd} = N_{hd}/N_d$, which is the intersection weight within the domain, and $P_{hd} = N_{hd}/N_h$, which is the relative size of the intersection within the stratum. The definitions of weights and proportion used in this paper are displayed in Table 1.

4.1 Bias of $\bar{y}_{s_d}$ under stratified designs

The arithmetic mean of Y for s_d (Eq. (4)) is certainly one of the simplest estimator of the domain mean, but it may be significantly biased under stratified random or stratified systematic designs (Pacificar Jr 1997). A notable exception is constituted by stratified designs with sample allocation proportional to the size of the strata (Holt and Smith 1979). In this case the estimator $\tilde{y}_{s_d}$ (Eq. (1)) corresponds to the arithmetic sample mean $\bar{y}_{s_d}$ (Eq. (4)), as long as $n \gg 0$, to avoid spurious rounding off effects due to limited allocated sample size. In general, under stratified designs, the magnitude of the bias of $\bar{y}_{s_d}$ will depend on the allocation of the sample units among the strata and on the homogeneity of the domains (Kish 1980). The development for the quantification of bias in domains under stratified random designs is provided in Appendix A).

4.2 Estimators under unknown domain size

Let denote s_{hd} the intersection of the domain $\mathcal{U}_d$ and the sample drawn in the stratum $\mathcal{P}_h$, and n_{hd} denote the size of this subsample. Under a stratified random sampling, with H strata intersecting D domains, Eq. (1) can be written as:

$$\tilde{y}_{s_d} = \hat{y}_{s_d} = \frac{\sum_{h=1}^H \frac{N_h}{n_h} \sum_{k \in s_{hd}} y_k}{\sum_{h=1}^H \frac{N_h}{n_h} n_{hd}}, \quad (8)$$

as shown in Särndal et al (1992, example 10.3.3).

Let us call $\tilde{y}_{sd}$ in Eq. (8) π -estimator. It might be informative to re-define the right-hand side of Eq. (8) as

$$\tilde{y}_{sd} = \frac{N \sum_{h=1}^H W_h p_{hd} \bar{y}_{hd}}{N \sum_{h=1}^H W_h p_{hd}}, \quad (9)$$

where $\bar{y}_{hd} = n_{hd}^{-1} \sum_{k \in s_{hd}} y_k$ is the arithmetic mean in s_{hd} . This reformulation makes more explicit that $\tilde{y}_{sd}$ is the ratio of an estimator of the population total of y in $\mathcal{U}_d$ to an estimator of N_d .

An estimator of the variance of $\tilde{y}_{sd}$ is

$$V(\tilde{y}_{sd}) = \frac{1}{\hat{N}_d^2} \sum_{h=1}^H N_h^2 \frac{1 - f_h}{n_h} \frac{\sum_{k \in s_{hd}} (y_k - \bar{y}_{s_{hd}})^2 + n_{hd}(1 - p_{hd})(\bar{y}_{s_{hd}} - \hat{y}_{sd})^2}{n_h - 1}, \quad (10)$$

where $\hat{N}_d = \sum_{h=1}^H \frac{n_{hd}}{n_h} N_h$, as in Särndal et al (1992, example 10.3.3).

4.3 Estimators under known domain size

Spatially explicit domains: a nested group estimator

In situations in which it is possible to classify each population unit into a domain, so that the size N_{hd} of each intersection is known, we propose an alternative estimator of domain means. In these cases, an unbiased estimator of the mean of the domain $\mathcal{U}_d$ can be obtained considering the domain $\mathcal{U}_d$ itself divided into further strata, given by its intersections with the sampling-strata, (which are $\mathcal{U}_d \cap \mathcal{P}_1, \dots, \mathcal{U}_d \cap \mathcal{P}_H$), so that $\mathcal{U}_d = \bigcup_{h=1}^H (\mathcal{P}_h \cap \mathcal{U}_d)$, and subsequently applying the usual stratified sampling estimator. The weight of each “nested stratum” is given by the ratio of the size of the intersection to the total size of the domain. This estimator for the mean of the domain $\mathcal{U}_d$ is $\bar{y}_d^{NG}$ (*NG* for *nested group*):

$$\bar{y}_d^{NG} = \sum_{h=1}^H W_{hd} \tilde{y}_{s_{hd}} = \frac{1}{N_d} \sum_{h=1}^H N_{hd} \tilde{y}_{s_{hd}} \quad (11)$$

where $W_{hd} = N_{hd}/N_d$ and

$$\tilde{y}_{s_{hd}} = \frac{\sum_{k \in s_{hd}} \frac{y_k}{\pi_k}}{\hat{N}_{hd}} \quad (12)$$

is the π -weighted intersection sample mean, with $\hat{N}_{hd} = \sum_{k \in s_{hd}} \pi_k^{-1}$. Eq. (11) is a special case of the post-stratified domain estimator (cf. Särndal et al 1992, Eq. 10.7.4 and Remark 10.7.3) for stratified designs, in which the strata are used as post-strata.

If a random or systematic sample has been selected in each stratum, the estimator $\tilde{y}_{s_{hd}}$ in Eq. (12) is identical to the arithmetic sample mean $\bar{y}_{s_{hd}} = (\sum_{k \in s_{hd}} y_k)/n_{hd}$, and Eq. (11) becomes

$$\bar{y}_d^{NG} = \frac{1}{N_d} \sum_{h=1}^H \frac{N_{hd} \sum_{k \in s_{hd}} y_k}{n_{hd}} \quad (13)$$

It is worthwhile to notice that $\bar{y}_d^{NG}$ requires $n_{hd} > 0$, while the π -estimator - Eq. (9) - requires only $n_h > 0$.

As in the previous development in §4.2, it is informative to re-define the right-hand side of Eq. (13), which simplifies further into:

$$\bar{y}_d^{NG} = \frac{N \sum_{h=1}^H W_h P_{hd} \bar{y}_{hd}}{N_d}, \quad (14)$$

because it makes more evident that, unlike Eq. (9), $\bar{y}_d^{NG}$ is not a ratio of two estimators, but rather a ratio of an estimator of the domain total to the actual size of the domain. Notice also that the sample estimator p_{hd} in the numerator of (9) is substituted here by the known value of the relative size P_{hd} .

The variance of $\bar{y}_d^{NG}$ is

$$V(\bar{y}_d^{NG}) = \sum_{h=1}^H W_{hd}^2 V(\tilde{y}_{s_{hd}}) = \frac{1}{N_d^2} \sum_{h=1}^H (N_{hd}^2 V(\tilde{y}_{s_{hd}})), \quad (15)$$

where $V(\tilde{y}_{s_{hd}})$ is the variance of the estimator $\tilde{y}_{s_{hd}}$.

If a random sample has been selected in each stratum, $V(\tilde{y}_{s_{hd}})$ can be re-expressed by analogy to Eq. (6) as

$$V_{RS}(\bar{y}_d^{NG}) = \frac{1}{N_d^2} \sum_{h=1}^H \left(N_{hd}^2 \left(\frac{1}{n_{hd}^0} - \frac{1}{N_{hd}} \right) \left(1 + \frac{Q_{hd}}{n_{hd}^0} \right) S_{hd}^2 \right) \quad (16)$$

where $n_{hd}^0 = n_h P_h$ is the expected domain intersection sample size, $Q_{hd} = 1 - P_h$ and $S_{hd}^2 = (N_{hd} - 1)^{-1} \sum_{k \in (\mathcal{U}_d \cap \mathcal{P}_h)} (y_k - \bar{y}_{hd})^2$ is the intersection variance.

By analogy to Eq. (7), an estimator of $V_{RS}(\bar{y}_d^{NG})$ is

$$\hat{V}_{RS}(\bar{y}_d^{NG}) = \frac{1}{N_d^2} \sum_{h=1}^H N_{hd}^2 \left(\frac{1}{n_{hd}} - \frac{1}{\hat{N}_{hd}} \right) S_{s_{hd}}^2 \quad (17)$$

where $S_{s_{hd}}^2 = (n_{hd} - 1)^{-1} \sum_{k \in s_{hd}} (y_k - \bar{y}_{s_{hd}})^2$ is the intersection sample variance and $\hat{N}_{hd} = N_h p_{hd}$. It is worthwhile to notice that (17) requires at least $n_{hd} \geq 2$ to allow $S_{s_{hd}}^2$ to be calculated.

The considerations regarding the sample size of the post-stratified estimator also apply to Eq. (11). That is, none of the intersection sample sizes n_{hd} should be too small. Särndal et al (1992, Remark 10.7.2) suggests a minimum sample size of at least 10 observations in each intersection.

Relative precision of the nested group and π -estimators

Under stratified random sampling the approximate variance of the π -estimator shown in Eq. (2) takes the form

$$AV^*(\tilde{y}_{s_d}) = \frac{1}{N_d^2} \sum_{h=1}^H \left(N_{hd}^2 \left(\frac{1}{n_{hd}^0} - \frac{1}{N_{hd}} \right) \left(1 + \frac{Q_{hd}}{n_{hd}^0} \right) \left(S_{hd}^2 + Q_{hd} (\bar{y}_{\mathcal{U}_d} - \bar{y}_{hd})^2 \right) \right) \quad (18)$$

A proof is provided in the Appendix B.

The variance of the nested group estimator is

$$AV^*(\tilde{y}_d^{NG}) = \frac{1}{N_d^2} \sum_{h=1}^H \left(N_{hd}^2 \left(\frac{1}{n_{hd}^0} - \frac{1}{N_{hd}} \right) \left(1 + \frac{Q_{hd}}{n_{hd}^0} \right) S_{hd}^2 \right) \quad (19)$$

which implies that $AV^*(\tilde{y}_{s_d}) \geq AV^*(\tilde{y}_d^{NG})$ always. The smaller the domain and the larger the differences among the strata means, the larger the gain in precision due to the use of the nested group estimator is. The drawback is that the nested group estimator is more *demanding* in terms of sample size, as it requires to have at least one sample in each intersection $\mathcal{P}_h \cap \mathcal{U}_d$.

The minimum of the $V(\tilde{y}_d^{NG})$ for a certain domain $\mathcal{U}_d$, given a fixed total sample size n , is obtained when:

$$n_h \approx \frac{W_{hd} S_{hd} / \sqrt{P_{hd}}}{\sum_{i=1}^H W_{id} S_{id} / \sqrt{P_{id}}} \quad (20)$$

Eq. (20) corresponds to the approximate optimum allocation for the nested estimator for the domain $\mathcal{U}_d$ (cf. Cochran 1977, Chap.5), and contrasts to the traditionally used Neyman optimum allocation for stratified random sampling (Neyman 1934):

$$n_h \approx \frac{W_{hd} S_{hd}}{\sum_{i=1}^H W_{id} S_{id}} \quad (21)$$

A proof on the development of Eq. (20) is provided in Appendix C.

5 Numerical tests of estimators

The properties of the above mentioned estimators were examined in a simulation study. We chose here a spatially explicit domain subject to stratified systematic sampling. Let us consider a population $\mathcal{P}$ consisting of 320 non-overlapping square units each with area 1 ha labeled $k = 1, \dots, 320$, so that $\mathcal{P} = \{u_1, \dots, u_k, \dots, u_{320}\}$. The population $\mathcal{P}$ is partitioned into 2 strata a and b , of size 150 and 170 ha, respectively. Let Y be the variable of interest. Values of Y have been randomly assigned, according to a normal distribution with mean and variance parameters as described in Table 2, to each population unit in the 2 strata. Further, let us assume that a random stratified sample s of size 35 has to be drawn without replacement from the population based on the two strata a and b . That is, a random sample s_a of size n_a has to be selected from the stratum a and a random sample s_b of size n_b from the stratum b , so that $n_a + n_b = 35$. The population has also been partitioned into 2 domains, A and B , of size 96 and 224 ha, respectively (Fig. 1). Population statistics are displayed in Table 2.

The domain averages $\bar{Y}_A$ and $\bar{Y}_B$ were estimated from the sample s . The number of plots selected in strata a and b had not been initially defined and 16 different plot allocation strategies has been tested, with $n_a \in (10, 25)$ and $n_b = n - n_a$. For each allocation 10^5 independent sample replicates of $n = 35$ were drawn and from each of those samples the domain means were estimated. Given the large number of samples and allocation regimes, we simulated parallel code with the package `doParallel` (Revolution

Table 2 Statistics of strata and domains used in the simulation study

Population total	
$N = 320$	
$s = 35$	
strata	domains
$N_a = 150$	$N_A = 96$
$N_b = 170$	$N_B = 224$
$\bar{Y}_a = 15.6$	$\bar{Y}_A = 19$
$\bar{Y}_b = 24$	$\bar{Y}_B = 20.5$
$S_a^2 = 26.6$	$S_A^2 = 36.1$
$S_b^2 = 13.9$	$S_B^2 = 36.9$

Analytics and Weston 2015) in R (R Core Team 2016), using a cluster of 16 CPU and 30 GB of RAM provided by the FAO-hosted SEPAL platform (SEPAL 2016). We contrasted the following estimators:

1. the domain sample arithmetic mean, Eq. (4)
2. the π -estimator, Eq. (9)
3. the nested group estimator, Eq. (14)

The means of the 10^5 sample replicates, estimates for the 2 domains for each plot allocation and for each estimator are presented in Fig. 2.

As expected, the arithmetic sample mean proves biased, whenever the sample allocation is far from being proportional to the strata size (which corresponds to the allocation “16-19”). $\tilde{y}_{sd}$ and $\tilde{y}_d^{NG}$ are approximately unbiased. The MSE is defined as the sum of the variance and the squared bias. In our example, the nested group estimate presents smaller MSE than the π -weighted estimate in all allocation scenarios (Fig. 3), and both always smaller than the MSE for the arithmetic mean. The numerically obtained optimum allocation strategy, would correspond to “22-13” (π -weighted) *vs.* “19-16” (nested group) when minimizing MSE for the “A” domain mean, and “21-14” for both estimators in the MSE minimization of the “B” domain.

Only by teasing apart the two components of the MSE, however, can one disentangle the role of bias and precision in each of the estimates. This becomes particularly relevant for REDD+ countries aiming to follow IPCC (2003) guidelines, recommending the minimization of uncertainty (i.e., precision) as much as possible. Precision (i.e., variance) estimates in the numerical tests show that $V(\tilde{y}_d^{NG})$ is always smaller than $V(\tilde{y}_{sd})$ (Fig. 4). However, the arithmetic mean presents smaller variance values in those allocation strategies far from the optimum. Minimum variances for both π -weighted and nested group estimators match the MSE values and indicate that for these two estimators the vast majority of the MSE is due to variance (and hence, reinforcing the unbiasedness of these two estimators).

6 Discussion

The amount of information which large-scale environmental surveys (such as national forest inventories) are expected to produce has considerably increased over time (McDonald 2003). In the case of GHG emissions reporting, this expectation might include

Fig. 1 The area of study consists of a rectangular region of 320 ha, subdivided into 320 non-overlapping square areas of 1 hectare. Sampling- strata *a* and *b* are divided by the solid line, while domains *A*, in red and *B*, in green are divided by the dotted line. For illustration purposes, a simple random sample is shown here independently drawn from each sampling-stratum, with allocation not proportional to the size of the strata (in this a particular allocation $n_a = 25$, red dots, and $n_b = 10$, blue dots).

the production of estimates for a certain number of domains of interest (such as land use categories) (Tubiello et al 2014), often identified after and independently of the forest inventory (IPCC 2003). But obtaining accurate and unbiased estimates for such domains is often a non trivial exercise, especially in the presence of complex survey designs (Lehtonen and Pahkinen 2004).

Thus, when the domains are spatially explicit (i.e. each population unit is classified into a domain) and all the forest inventory sample units geo-referenced, it is always possible to assign automatically each of n sample units into a domain $\mathcal{U}_d$, even when the information regarding the domains was not collected during the NFI. Often, however, the domains might not be spatially explicit and their sizes might have been estimated independently of the forest inventory, such as, for example, through an external, ancillary sample-based land use survey with a different sampling design. This can occur frequently during the preparation of a GHGI report, where activity data (areas of land use or land use changes) and emission factors (i.e., biomass, volume,...) are typically compiled from disparate sources. This method for the representation of land in tabular form falls within

Fig. 2 Means of the estimates for the domains *A* and *B*, by allocation and estimator. The grey dashed horizontal line is the real mean of the domains

Fig. 3 Mean squared errors of the estimates for the domains *A* and *B*, by allocation and estimator. Dotted green and orange vertical lines reflect the allocations at which the MSE of the domain mean is minimized in the π - vs. nested group estimators, respectively. Black solid and dashed vertical lines correspond to nested group (Eq. (20)) vs. Neyman (Eq. (21)) theoretical optimum allocations. The y-axis is log-transformed for better visualization.

the IPCC definitions of *approach 1* and *approach 2*, as described in IPCC (2003, Chap. 2) and IPCC (2006, Vol. 4, Chap. 3), and it is widely used for the estimation of land use and land use changes. An example of this is the case in which the absolute sizes of land use categories are independently estimated through visual (or augmented visual) interpretation of a sample of remote imagery (Bey et al 2016).

In this case, in order to estimate the domain averages it is first of all necessary to classify each of the n forest inventory sample units into one of the spatially-implicit

Fig. 4 Variance of the estimates for the domains A and B, by allocation and estimator. Dotted green and orange vertical lines reflect the allocations at which the variance of the domain mean is minimized in the π - vs. nested group estimators, respectively. Black solid and dashed vertical lines as in Fig. 3. The y-axis is log-transformed for better visualization.

domains $\mathcal{U}_d$. To prevent any possible bias, re-classification needs to be done using the same methodology adopted to estimate the domain sizes. If, for example, these have been estimated through sample-based visual interpretation, then the n sample units need to be interpreted using the same type of imagery and, possibly, the same interpreters of the land use survey. The domain mean estimator to be used is the estimator $\tilde{y}_{s_d}$ in Eq. (1), which under a simple random or systematic sampling corresponds to the domain sample mean Eq. (4) and under a stratified random or stratified systematic sampling takes the form of Eq. (9).

In an attempt to offer a set of rules for the selection of adequate domain estimators, we propose a decision tree (Fig. 5) that aims to guide forestry academics and NFI assessment teams through each step depending on:

1. the stratified nature of the NFI design
2. the ancillary nature of the domain sizes
3. whether the domains are spatially implicit or explicit
4. whether the sampling (per stratum) is SRS or systematic

Overall, π -weighted estimators should be considered whenever the sampling per stratum ($\forall H \geq 1$) does not follow SRS or systematic designs, or else when the domains are spatially implicit and independently estimated. Under a SRS or systematic design, when $H = 1$ or $H > 1$ the domain sample mean Eq. (4) or Eq. (9) are recommended, respectively. Finally, if $H > 1$, domain sizes are independent from the NFI and spatially explicit, nested group estimators outperform the others, using the π -weighted version (Eq. (11)) if the per stratum samples were not SRS or systematically taken.

The use of nested estimators, thus, should ideally be known in order to facilitate allocation strategies previous to the design of the forest inventory. Notice that Eq. (20) keeps a striking similarity to the optimal allocation equation of Cochran (1977, p. 98)

Fig. 5 Decision tree for the selection of the adequate domain mean estimator

(Schreuder et al 1993). But instead, variables per stratum h are accounted on a per stratum/domain intersection hd , and Cochran's costs of sampling a unit in stratum h are replaced by P_{hd} . Hence, when the stratum is filled by the domain, $P_{hd} = 1$ and optimum allocation corresponds to Neyman's (21). Otherwise, $P_{hd} < 1$ will effectively rescale the weight assigned to individual sampling units in the stratum, akin to a reduction in cost per sampling unit.

In the simulation exercise, Eq. (20) outperforms Neyman's Eq. (21) for both domains as references. However, it is still an approximation, as shown in Appendix C, largely driven by the limitations imposed in the exercise, when n_h is small. Although the situation under which the application of nested group estimators and the nested group optimal allocation strategy might seem rare, many countries find themselves in practice conducting international reporting where per ha. emission factors are calculated from stratified inventories, and the calculation of domain sizes comes from independent, spatially explicit sources. As shown above, this is where nested group estimators may provide opportunities to reduce both bias and sampling error, outperforming not only the often misused domain arithmetic means, but also the classical unbiased π -weighted estimators.

While the nested group approach might seem the ideal one given its performance in our example, it is subject to several assumptions that often may not be as realistic. First, $n_{hd} \geq 2$ is a necessary condition to obtain a measure of precision; second, and most important, domain sizes are assumed to be error-free. This assumption, although often taken, is far from realistic, since spatially explicit obtained information always contains errors, even if only sampling ones. Despite this last assumption, most international reporting so far from countries to the UNFCCC has been known to observe it, at least

336 for static pictures (i.e., area changes are calculated with their errors). In such a case, the
337 use of nested estimators might be the best option for REDD+ reporting.

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Appendices

A The bias of the domain sample mean under a random stratified sampling

Similarly to §4, let us consider the case in which a stratified random sampling is carried out on the population $\mathcal{P}$, based on the H sampling-strata. Let denote s_{hd} the intersection of the domain $\mathcal{U}_d$ and the sample drawn in the sampling-stratum $\mathcal{P}_h$, and n_{hd} the size of this sub-sample. The mean of Y for s_d can be written as:

$$\bar{y}_{s_d} = \frac{\sum_{h=1}^H \sum_{k \in s_{hd}} y_k}{n_d} = \frac{\sum_{h=1}^H n_{hd} \bar{y}_{s_{hd}}}{n_d} \quad (22)$$

where $\bar{y}_{s_{hd}}$ is the sample mean of the sample drawn in the in the stratum $\mathcal{P}_h$, and belonging to the domain $\mathcal{U}_d$. The number n_{hd} of sample units falling into $\mathcal{P}_h \cap \mathcal{U}_d$ varies depending on the sampling strategy and on the sample allocation adopted. If a simple random or systematic sample is taken in each sampling-stratum the expected value of the number of units n_{hd} that are in s_d is given by:

$$E(n_{hd}) = W_{hd} n_h = N_{hd} f_h \quad (23)$$

where $W_{hd} = N_{hd}/N_h$ is the relative size of the intersection $\mathcal{P}_h \cap \mathcal{U}_d$ within the stratum $\mathcal{P}_h$. The expected value of the number of sample units n_d that happen to fall into the domain $\mathcal{U}_d$ can be expressed as a linear function of the expected number of sample units in each intersection:

$$E(n_d) = \sum_{h=1}^H E(n_{hd}) = \sum_{h=1}^H W_{hd} n_h \quad (24)$$

Denote by A_d the event $E(n_d) \geq 1$. If n is large enough $Pr(A_d)$ is close to 1. Under the condition A_d , the expected value of $\bar{y}_{s_d}$ for the domain $\mathcal{U}_d$ is given by

$$E(\bar{y}_{s_d} | A_d) = \frac{\sum_{h=1}^H W_{hd} n_h \bar{Y}_{hd}}{\sum_{h=1}^H W_{hd} n_h} \quad (25)$$

We will now assume that A_d will certainly occur. Since the population mean of the domain $\mathcal{U}_d$ can be written as:

$$\bar{Y}_d = \frac{\sum_{h=1}^H N_{hd} \bar{Y}_{hd}}{N_d} \quad (26)$$

the bias of the arithmetic mean $\bar{y}_{s_d}$ for the domain $\mathcal{U}_d$ therefore amounts to:

$$BIAS(\bar{y}_{s_d}) = E(\bar{y}_{s_d}) - \bar{Y}_d = \frac{\sum_{h=1}^H W_{hd} n_h \bar{Y}_{hd}}{\sum_{h=1}^H W_{hd} n_h} - \frac{\sum_{h=1}^H N_{hd} \bar{Y}_{hd}}{N_d} \quad (27)$$

Under a stratified random sampling with a sample allocation proportional to the size of the strata, where $n_h = nN_h/N = N_h f$, the arithmetic mean proves unbiased since

$$E(\bar{y}_{s_d}) = \frac{\sum_{h=1}^H W_{hd} N_h f \bar{Y}_{hd}}{\sum_{h=1}^H W_{hd} N_h f} = \frac{\sum_{h=1}^H N_{hd} \bar{Y}_{hd}}{\sum_{h=1}^H N_{hd}} = \frac{\sum_{h=1}^H N_{hd} \bar{Y}_{hd}}{N_d} = \bar{Y}_d \quad (28)$$

B A better approximation of the variance of the π -estimator under a stratified random sampling

Under a random stratified sampling with H strata, indexed with the letter h , (where $h = 1, \dots, H$), (2) can be re-expressed as

$$AV(\tilde{y}_{s_d}) = \frac{1}{N_d^2} \sum_{h=1}^H \left(\frac{\Delta_{kl}}{\pi_k^2} \left[\sum_{k \in (\mathcal{P}_h \cap \mathcal{U}_d)} (y_k - \bar{y}_{\mathcal{U}_d}) \right]^2 - \frac{\Delta_{kl} - \Delta_{kk}}{\pi_k^2} \sum_{k \in (\mathcal{P}_h \cap \mathcal{U}_d)} (y_k - \bar{y}_{\mathcal{U}_d})^2 \right) \quad (29)$$

and

$$\Delta_{kl} = \begin{cases} \frac{n_h}{N_h} (1 - \frac{n_h}{N_h}), & \text{for } k = l, \text{ (we can call it } \Delta_{kk}) \\ \frac{n_h(N_h - n_h)}{N^2(N_h - 1)}, & \text{for } k \neq l \text{ and } k, l \text{ belonging to the same stratum} \\ 0, & \text{for } k \neq l \text{ and } k, l \text{ belonging to a different stratum} \end{cases} \quad (30)$$

therefore

$$AV(\tilde{y}_{s_d}) = \frac{1}{N_d^2} \sum_{h=1}^H \left(\frac{N_h - n_h}{n_h(N_h - 1)} \right) \left(N_h \sum_{k \in (\mathcal{P}_h \cap \mathcal{U}_d)} (y_k - \bar{y}_d)^2 - \left[\sum_{k \in (\mathcal{P}_h \cap \mathcal{U}_d)} (y_k - \bar{y}_d) \right]^2 \right) \quad (31)$$

decomposing the variance we obtain:

$$AV(\tilde{y}_{s_d}) = \frac{1}{N_d^2} \sum_{h=1}^H \left(\frac{N_h - n_h}{n_h(N_h - 1)} \right) \left(N_h \left[\sum_{k \in (\mathcal{P}_h \cap \mathcal{U}_d)} (y_k - \bar{y}_{hd})^2 + N_{hd}(\bar{y}_{\mathcal{U}_d} - \bar{y}_{hd})^2 \right] - \left[\sum_{k \in (\mathcal{P}_h \cap \mathcal{U}_d)} (y_k - \bar{y}_{hd}) + N_{hd}(\bar{y}_{\mathcal{U}_d} - \bar{y}_{hd}) \right]^2 \right) \quad (32)$$

hence

$$\begin{aligned}
 AV(\tilde{y}_{s_d}) &= \frac{1}{N_d^2} \sum_{h=1}^H \left(\frac{N_h - n_h}{n_h(N_h - 1)} \right) \\
 &\quad \left(N_h \left[\sum_{k \in (\mathcal{P}_h \cap \mathcal{U}_d)} (y_k - \bar{y}_{hd})^2 + N_{hd}(\bar{y}_{\mathcal{U}_d} - \bar{y}_{hd})^2 \right] - [N_{hd}(\bar{y}_{\mathcal{U}_d} - \bar{y}_{hd})]^2 \right) = \\
 &\quad \frac{1}{N_d^2} \sum_{h=1}^H \left(\frac{N_h - n_h}{n_h(N_h - 1)} \right) \\
 &\quad \left(N_h \sum_{k \in (\mathcal{P}_h \cap \mathcal{U}_d)} (y_k - \bar{y}_{hd})^2 \frac{N_{hd} - 1}{N_{hd} - 1} + N_{hd}(\bar{y}_{\mathcal{U}_d} - \bar{y}_{hd})^2 (N_h - N_{hd}) \right) = \\
 &\quad \frac{1}{N_d^2} \sum_{h=1}^H \left(\frac{N_h - n_h}{n_h(N_h - 1)} \right) \left(N_h(N_{hd} - 1)S_{hd}^2 + N_{hd}(\bar{y}_{\mathcal{U}_d} - \bar{y}_{hd})^2 (N_h - N_{hd}) \right) = \\
 &\quad \frac{1}{N_d^2} \sum_{h=1}^H \left(\frac{N_h - n_h}{n_h} \right) \left(N_h P_{hd} S_{hd}^2 + P_{hd}(\bar{y}_{\mathcal{U}_d} - \bar{y}_{hd})^2 (N_h - N_{hd}) \right) = \\
 &\quad \frac{1}{N_d^2} \sum_{h=1}^H \left(\frac{1 - f_h}{f_h} \right) \left(N_h P_{hd} S_{hd}^2 + P_{hd}(\bar{y}_{\mathcal{U}_d} - \bar{y}_{hd})^2 (N_h - N_{hd}) \right) = \\
 &\quad \frac{1}{N_d^2} \sum_{h=1}^H \left(\frac{1 - f_h}{n_h} \right) \left(N_h^2 P_{hd} S_{hd}^2 + P_{hd}(\bar{y}_{\mathcal{U}_d} - \bar{y}_{hd})^2 (N_h^2 - N_{hd} N_h \frac{N_h}{N_h}) \right) = \\
 &\quad \frac{1}{N_d^2} \sum_{h=1}^H \left(\frac{1 - f_h}{n_h} \right) \left(N_h^2 P_{hd} S_{hd}^2 + P_{hd}(\bar{y}_{\mathcal{U}_d} - \bar{y}_{hd})^2 N_h^2 Q_{hd} \right) = \\
 &\quad \frac{1}{N_d^2} \sum_{h=1}^H \left(N_h^2 \frac{1 - f_h}{n_h} P_{hd} (Q_{hd}(\bar{y}_{\mathcal{U}_d} - \bar{y}_{hd})^2 + S_{hd}^2) \right) \quad (33)
 \end{aligned}$$

where $P_{hd} = \frac{N_{hd}}{N_h}$, $Q_{hd} = 1 - P_{hd}$ and $f_h = n_h/N_h$.

By analogy with Särndal 10.3.15, (33) can also be expressed as:

$$AV(\tilde{y}_{s_d}) = \frac{1}{N_d^2} \sum_{h=1}^H \left(N_{hd}^2 \left(\frac{1}{n_{hd}^0} - \frac{1}{N_{hd}} \right) (Q_{hd}(\bar{y}_{\mathcal{U}_d} - \bar{y}_{hd})^2 + S_{hd}^2) \right) \quad (34)$$

where $n_{hd}^0 = n_h \frac{N_{hd}}{N_h}$.

By conditioning on the domain sample size, similarly to the development in §10.4, of Särndal et al (1992), we get a closer approximation to $V(\tilde{y}_{s_d})$

$$AV^*(\tilde{y}_{s_d}) = \frac{1}{N_d^2} \sum_{h=1}^H \left(N_{hd}^2 \left(\frac{1}{n_{hd}^0} - \frac{1}{N_{hd}} \right) \left(1 + \frac{Q_{hd}}{n_{hd}^0} \right) (Q_{hd}(\bar{y}_{\mathcal{U}_d} - \bar{y}_{hd})^2 + S_{hd}^2) \right) \quad (35)$$

C Optimum sample allocation for domain estimation under random stratified sampling

Theorem : The sample sizes $n_1, \dots, n_h, \dots, n_H$ that minimize the $V(\bar{y}_{ne_d})$ under a random stratified sampling, subject to the constraint $n_1 + \dots + n_h + \dots + n_H = n$ are approximated by

$$n_h \approx \frac{W_{hd}S_{hd}/\sqrt{P_{hd}}}{\sum_{i=1}^H W_{id}S_{id}/\sqrt{P_{id}}} \quad (36)$$

Proof Under a random stratified sampling, neglecting the finite population correction $1/N_{hd}$, (19) can be written as

$$AV^*(\tilde{y}_d^{NG}) = \sum_{h=1}^H \frac{W_{hd}^2 S_{hd}^2 (n_h P_{hd} + Q_{hd})}{(n_h P_{hd})^2} = \sum_{h=1}^H \frac{W_{hd}^2 S_{hd}^2 (P_{hd}(n_h - 1) + 1)}{(n_h P_{hd})^2} \quad (37)$$

Where $Q_{hd} = 1 - P_{hd}$ and $W_{hd} = N_{hd}/N_d$. Under the condition $n_h \gg 0$, $n_h - 1 \approx n_h$ and $(n_h P_{hd} + 1)/n_h P_{hd} \approx 1$. (37) therefore simplifies to

$$AV^*(\tilde{y}_d^{NG}) = \sum_{h=1}^H \frac{W_{hd}^2 S_{hd}^2}{n_h P_{hd}} \quad (38)$$

The minimum of this function can be found using the method of Lagrange multipliers. The Lagrange function is:

$$L(n_1, \dots, n_h, \dots, n_H, \lambda) = \sum_{h=1}^H \frac{W_{hd}^2 S_{hd}^2}{n_h P_{hd}} + \lambda \left(\sum_{h=1}^H n_h - n \right) \quad (39)$$

For $h = 1, \dots, h, \dots, H$, where λ is the Lagrange multiplier. The partial derivatives of this function are

$$\frac{\partial L}{\partial n_h} = -\frac{W_{hd}^2 S_{hd}^2}{n_h^2 P_{hd}} + \lambda \quad (40)$$

By setting the partial derivatives of this function equal to zero we obtain

$$n_h = \frac{1}{\sqrt[2]{\lambda}} \frac{W_{hd} S_{hd}}{\sqrt{P_{hd}}} \quad (41)$$

By summing these equations over h :

$$n \approx \frac{1}{\sqrt[2]{\lambda}} \sum_{h=1}^H \frac{W_{hd} S_{hd}}{\sqrt{P_{hd}}} \quad (42)$$

Thus,

$$\frac{1}{\sqrt[2]{\lambda}} \approx \frac{n}{\sum_{h=1}^H \frac{W_{hd} S_{hd}}{\sqrt{P_{hd}}}} \quad (43)$$

and

$$n_h \approx \frac{W_{hd} S_{hd}/\sqrt{P_{hd}}}{\sum_{i=1}^H W_{id} S_{id}/\sqrt{P_{id}}} \quad (44)$$

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