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Comparison of EEG source reconstructed functional networks in healthy subjects elicited during visual oddball task

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29 **Abstract**

30 In this paper we have reconstructed electroencephalography (EEG) sources using weighted
31 Minimum Norm Estimator (wMNE) for visual oddball experiment to estimate brain functional
32 networks. Secondly we have evaluated the impact of time-frequency decomposition algorithms
33 and scout functions on brain functional networks estimation using phase-locked value (PLV).
34 Lastly, we compared the difference between target stimuli with response (TR) and non-target
35 with no response (NTNR) cases in terms of brain functional connectivity (FC). We acquired
36 the EEG data from 20 healthy participants using 129 channels EEG sensor array for visual
37 oddball experiment. Three scout functions: i) MEAN, ii) MAX and iii) PCA were used to
38 extract the regional time series signals. We transformed the regional time series signals into
39 complex form using two methods: i) Wavelet Transform (WT) and ii) Hilbert Transform (HT).
40 The instantaneous phases were extracted from the complex form of the regional time series
41 signals. The FC was estimated using PLV. The joint capacity of the time-frequency
42 decomposition algorithms/scout functions applied to reconstructed EEG sources was evaluated
43 using two criteria: i) localization index (LI) and ii) R. The difference in FC between TR and
44 NTNR cases was evaluated using these two criteria. Our results show that the WT has higher
45 impact on LI values and it is better than HT in terms of consistency of the results as the standard
46 deviation (SD) of WT is lower. In addition, WT/PCA pair is better than other pairs in terms of
47 consistency as the SD of the pair is lower. This pair is able to estimate the connectivity within
48 parietal region which corresponds to P300 response; although WT/MEAN is also able to do
49 that, However, WT/PCA has lower SD than WT/MEAN. Lastly, the differences in connectivity
50 between TR and NTNR cases over parietal, central, right temporal and limbic regions which
51 correspond to target detection, P300 response and motor response were observed. Therefore,
52 we conclude that the output of the connectivity estimation might be affected by time-frequency
53 decomposition algorithms/scout functions pairs. Among the pairs, WT/PCA yields best results

54 for the visual oddball task. Moreover, TR and NTNR cases are different in terms of estimated
55 functional networks.

56

57 **Introduction**

58 Brain connectivity may be defined as the links between different units of the brain. These links
59 can be anatomical or structural referred to as structural connectivity (SC), statistical
60 dependencies known as functional connectivity (FC) and due to causal interaction known as
61 effective connectivity (EC).

62 Neuroimaging techniques are widely used to estimate the brain cortical networks
63 involved in the normal brain cognitive functions as well as in neurological diseases [1-6].
64 Diffusion Tensor Imaging (DTI) can be adapted to estimate SC with higher capability [7-9].
65 However, this technique is unable to estimate the dynamic connectivity among the cortical
66 regions. The functional Magnetic Resonance Imaging (fMRI) technique is widely utilized to
67 characterize the cortical FC [10-12] as it provides excellent spatial resolution. However fMRI
68 has relatively lower temporal resolution [13,14] (slow sampling rate; ~1s). Hence it cannot
69 capture the dynamic activity of the cognitive processes that have extremely short duration.
70 These processes require excellent temporal resolution to capture the dynamic changes. Thus,
71 Electroencephalography (EEG) can solve this problem. EEG is used to measure the scalp
72 electrical potentials using sensor-array. EEG provides excellent temporal resolution. Hence,
73 EEG data with suitable signal processing techniques can provide relative information regarding
74 brain FC elicited during cognitive activities [15-18]. However, EEG suffers from low spatial
75 resolution issue due to volume conduction [19,20]. Same underlying source may influence the
76 EEG signals acquired from two neighbourhood sensors [21]. Thus, estimation of connectivity
77 on EEG signals measured from scalp does not exactly convey the true neural linkages among

78 two brain areas [22]. Some approaches have been proposed to solve this issue. For example,
79 non-linear methods like phase-locked value (PLV) [23] and imaginary coherence (IC) [24]
80 have been proposed for FC estimation as these approaches are insensitive to volume conduction.
81 The application of these methods on reconstructed EEG source signals provides superior spatial
82 and temporal resolution [25-27].

83 Many algorithms have been proposed for EEG source reconstruction [28-31]. For FC
84 estimation, several linear and non-linear methods have been developed [27,32,33]. In [34-37],
85 some studies have discussed the application of the connectivity estimation methods on the
86 dynamics source signals reconstructed from scalp EEG. These methods provide high efficiency
87 for the FC estimation as the FC is directly estimated from the source space (cortex level). In
88 this context firstly the algorithms used to perform EEG source localization by solving the ill-
89 posed EEG inverse problem for source localization have to be implemented, followed by the
90 FC estimation in the source space.

91 Several approaches have been proposed in the past decades in order to solve the ill-
92 posed EEG inverse problem. For example, Minimum Norm Estimator (MNE) [38], Depth-
93 weighted Minimum L2 Norm Estimator (wMNE) [39], Low Resolution Brain Electromagnetic
94 Tomography (LORETA) [40], standardized Low Resolution Brain Electromagnetic
95 Tomography (sLORETA) [41] and others. These methods are widely used to solve the ill-posed
96 inverse problem for EEG source localization in recent researches [42-45]. As an outcome, the
97 spatial resolution of the EEG has been improved using EEG source localization.

98 Secondly the brain FC estimation methods are categorized into linear and non-linear
99 methods. The linear approaches include cross-correlation [46] and coherence [47], whereas
100 non-linear methods include mutual information [48], phase synchronization [49] etc. Linear

101 and non-linear methods are widely used for FC estimations in the sensor space [50-52] as well
102 as source space [53-56].

103 Based on the literature review it is observed that the estimated FC depends on the
104 algorithms to solve the EEG ill-posed inverse problem and the methods for connectivity
105 estimation. Hassan et al. reported that the use of wMNE in conjunction with the phase-locking
106 value (PLV) provides better results as compared to the other combinations in the sensor space
107 [26,57]. This combination has been adapted for FC analysis in the source space [25,58-60].

108 In this research, we planned to utilized wMNE to reconstruct the dipolar sources from
109 EEG by solving the ill-posed inverse problem. Then, we applied PLV to estimate the pairwise
110 connections between the regions-of-interest (ROIs). Time-frequency decomposition
111 algorithms like complex Morlet Wavelet Transform (WT) and Hilbert Transform (HT) [33,61]
112 can be adapted to transform the signals in time domain into complex time-frequency domain
113 for instantaneous phase extraction. These two different time-frequency decomposition
114 algorithms may have an effect on the extraction of instantaneous phases that may affect the FC
115 estimation using PLV. In our study, we applied PLV on 148 regional time series signals to
116 estimate the FC.

117 The estimated dipolar sources on the cortex were downsampled into 148 regions based
118 on Destrieux atlas [62] to form regional time series. The dipolar sources within a region were
119 grouped together into one unique source. This unique source is then used to express the cortical
120 activity of that particular region from Destrieux atlas. Brainstorm toolbox [63] provides few
121 options (scout functions) to perform the grouping. The scout functions are MEAN, PCA,
122 MAX and others. MEAN averages all dipolar sources within a cortical region to produce one
123 unique source for that particular cortical region. Using MAX, the unique source selected from
124 the maximum sources across all the dipolar sources within that particular cortical region. And,

125 PCA takes the first mode of the PCA decomposition of all the sources within a cortical region
126 to form a unique source of that particular region. Different regional time series can be generated
127 using different scout functions. Thus, the scout functions can affect the extraction of
128 instantaneous phases from regional time series signals which may affect the FC estimation
129 using PLV.

130 Hence we believe that the network differences between two oddball cases are
131 significant. In addition we also assume that different time-frequency decomposition algorithms
132 and scout functions may have slightly different impact on FC estimation.

133 Based on our hypotheses, we have two main objectives. 1) To evaluate the differences
134 in terms of functional connectivity among oddball cases in the source space. Previously the
135 evaluation was done in the sensor space [50,51,64], 2) To assess the joint capacity of the time-
136 frequency decomposition algorithms / scout functions applied to reconstructed EEG sources to
137 evaluate brain FC elicited by our oddball task; as the joint capacity has not been evaluated by
138 other studies. In this study, we also assess the impact of the scout functions and time-frequency
139 decomposition algorithms on FC estimation.

140

141 **Methodology**

142 The flow chart of the research is depicted in Fig 1. Dense EEG electrode arrays was used to
143 acquire the EEG data for visual oddball experiment. Secondly the dipolar sources were
144 reconstructed from clean scalp EEG data using wMNE. Regional time series was computed
145 based on Destrieux atlas using different down-sampling scout functions (PCA, MAX and
146 MEAN). In the third step, time-frequency decomposition was carried out using Morlet WT and
147 HT. After decomposition, regional time series in complex form in gamma band was used to

148 extract the instantaneous phases. The extracted instantaneous phases were used to estimate the
149 FC using PLV. Proportional thresholding was applied to retain only 10% of strongest
150 connectivity. Lastly, performance of each combination of the time-frequency decomposition
151 algorithms with scout functions was evaluated based on the Localization index (LI) and R
152 criterions. Statistical tests were performed to evaluate the level of significance.

153

154 **Experiment setup and data acquisition**

155 In an oddball paradigm, the researchers asked the participants to distinguish the novel stimuli
156 (target) within a series of randomly displayed frequent stimuli (non-target).

157 We randomly presented the target stimuli (circle) and non-target (square) stimuli on the
158 computer monitor for 500ms during our visual oddball paradigm [64]. The fixation time was
159 set as 1000ms. During the fixation, an empty dark screen was presented. We requested the
160 subjects to pay attention towards the monitor. They have to make motor response by pressing
161 the keyboard button when the target stimuli appears on the computer monitor. When the the
162 non-target stimuli appears; the motor response is not required. Total 135 visual stimuli were
163 presented on the monitor. 40 out of 135 stimuli were the target stimuli, whereas 95 stimuli were
164 the non-target stimuli. The stimuli were projected on the monitor randomly.

165 Our oddball paradigm is categorized into 4 different oddball cases. The ‘correct’ cases
166 are target stimuli with response (TR) and non-target stimuli with no response (NTNR). While,
167 the ‘incorrect’ cases are target stimuli with no response (TNR) and non-target stimuli with
168 response (NTR). In TR case, the participants correctly respond to the target stimuli, whereas in
169 TNR case the subjects fail to respond to the target stimuli. In NTR case, the subjects respond
170 incorrectly to the non-target stimuli. In NTNR case, the participants did not provide the motor
171 response when non-target stimuli appeared. In this study, we used TR case for the evaluation

172 of the scout functions and time-frequency decomposition algorithms. Moreover, we used TR
173 and NTNR to compare the differences between the two cases in term of connectivity as these
174 two cases are opposite to each other.

175 The 128-channel sensor array (HydroCel Geodesic Sensor Net) from EGI company
176 with a sampling frequency of 250 Hz was used to acquire EEG data. The EEG data was
177 acquired from 20 right-handed healthy participants with an age of around 19–23 years with
178 normal or corrected-to-normal vision. None of them had a history of substance abuse and a
179 personal or family history of psychiatric or neurological diseases.

180 The sampling frequency of the EEG acquisition system is 250 Hz. The maximum time
181 period of the epoch is about 500ms. The data acquisition for TR case will be stopped once the
182 subjects provided the motor response, hence the period of the epoch for this case could be less
183 than 500 ms. The raw data was converted into Matlab format by netstation. The high frequency
184 artifacts and DC components were removed using a finite impulse response (FIR) digital filter
185 with a band-pass frequency range from 0.5 Hz to 70 Hz. The EEGLAB function called eegplot()
186 was used to plot the filtered EEG data. The EEG samples that consist of artefacts induced by
187 muscles contraction and eye blinking were manually rejected. For TR case, the clean EEG
188 data were shifted to the right to align with the event when the button is pressed by the
189 participants. For NTNR case, shifting is not required. The data of 2 participants was rejected.
190 For TR and NTNR cases, three trials have been randomly selected from each subject ($3 \times 18 =$
191 54 trials) to perform the analysis. We performed the analysis 3 times by selecting different
192 trials from each subject for both cases.

193

194 **EEG source reconstruction**

195 The generative model of EEG data, $E(t)$ can be expressed as linear consolidation of time-
196 varying current dipole sources $S(t)$ with 3-dimensional (3D) orientation:

$$E(t) = L \cdot S(t) + n(t) \quad (1)$$

197 where $n(t)$ denotes the additive noise and L denotes the lead fields matrix of the dipolar sources
198 [26]. This process is essentially known as forward modelling. On the other hand, inverse
199 modelling is known as the process of solving the inverse problem by reversing the step of
200 estimating $S(t)$ given $E(t)$ and L .

201 **Forward modelling**

202 The physical process of the neuronal current propagation from brain cortical surfaces to the
203 EEG electrodes on the scalp is described by the lead field L . The electrical conductivities and
204 geometry of the tissues in the head are required to compute L .

205 Ideally, the geometrical model of an individual's head should be obtained from various
206 structural MRI and digitized sensor positions. Unfortunately, taking individual MRI is costly.
207 Thus, anatomical templates are commonly used in EEG source analysis. We utilized ICBM152
208 template (a non-linear average of the MRI images of 152 individual's heads) for our study
209 [65,66]. To obtain the electrical properties of the tissues in the head, we utilized boundary
210 element method (BEM) [67]. The realistically-shaped shells that represent the brain, scalp and
211 skull are included in BEM.

212 Based on Destrieux atlas, the cortical surface was partitioned into 148 ROIs. EEG
213 forward modelling was done using Brainstorm toolbox. The surface meshes of the scalp, skull
214 and brain which are realistically-shaped were extracted from the ICBM152 template. BEM was
215 used to calculate the forward head model (lead field) from these 148 ROIs to the 129 EEG

216 channels as implemented in Open MEEG software package [68] included in Brainstorm
217 toolbox. In this case, we set the number of vertices per layer as 1922 (default). The electrical
218 conductivity for brain, skull and skin were set to 1 S/m, 0.0125 S/m and 1 S/m respectively.

219 **Inverse modelling**

220 In inverse modelling, dipolar sources are estimated over the cortical regions given the EEG
221 signals and lead field matrices. MNE [38] imposes L2-norm constraints on the source
222 distribution are efficient as the method is linear in the sensor data. L2-norm is introduced to
223 regularize the problem. A weighted matrix is introduced to MNE algorithm to improve the
224 source estimation in terms of surface sources. This method is known as wMNE [39]. The
225 weighting matrix adjusts the properties of the solution by reducing the bias inherent to MNE
226 algorithm. The source estimated by wMNE is expressed as

$$S_{wMNE} = (L^T W_E L + \rho I)^{-1} L^T W_E E \quad (2)$$

227 where W_E is the diagonal weighting matrix which consists of weighted factor for depth
228 normalization, ρ denotes the regularization parameter and I is the identity matrix. The inverse
229 estimation of sources was performed by Brainstorm toolbox. The value of ρ was set between
230 0.1 and 0.3 [60]. After that, the dipolar sources were projected on the 3D cortical surface. The
231 regional time series was computed based on three different scout functions offered by the
232 Brainstorm toolbox.

233

234 **Time-frequency decomposition**

235 We used HT and WT to decompose the regional time series into time-frequency representation.

236 Hilbert Transform

237 The regional time series signals were decomposed into gamma band (30 – 60 Hz) using FIR
238 band pass filter. After filtering, HT was applied. HT of a function $f(t)$ can be defined as
239 convolution of $f(t)$ with $1/\pi t$. HT of a regional time series signal $x(t)$ can be mathematically
240 represented as:

$$y(t) = \frac{1}{\pi} (PV) \int_{-\infty}^{\infty} \frac{x(\tau)}{t - \tau} d\tau \quad (3)$$

241 where PV denotes the Cauchy principle value [69].

242 Wavelet Transform

243 WT outputs a time-frequency plane for regional time series signal $x(t)$. During spectral analysis,
244 complex Morlet Wavelet function provides magnitude and phase information of the time series
245 signals [70]. Mathematically, the Wavelet function is defined as follow:

$$y(t) = \pi^{-0.25} \times e^{j\omega t} \times e^{-t^2/2} \quad (4)$$

246 where $y(t)$ is a sinusoid in complex form of $e^{j\omega t}$ multiplied by a normalization factor ($\pi^{-0.25}$)
247 and Gaussian envelope ($e^{-t^2/2}$). This process is to ensure the Morlet Wavelet has unit energy.

248

249 Functional connectivity estimation

250 HT and WT convert the time series signal $x(t)$ into complex function of time $\delta(t)$ defined as:

$$\delta(t) = x(t) + jy(t) = B(t)e^{-j\phi(t)} \quad (5)$$

251 where $\phi(t)$ denotes the instantaneous phase with respect to time and $B(t)$ denotes the
252 instantaneous amplitude with respect to time [69]. A MATLAB function *angle()* is used to
253 extract the instantaneous phases of the regional time series signals in radian form.

254 The phase differences $\theta_{ab}(t,n)$ between two regional time series signals a and b at time
255 bins t and trial n were computed as follows:

$$\theta_{ab}(t,n) = \phi_a(t,n) - \phi_b(t,n) \quad (6)$$

256 where $\phi_a(t,n)$ and $\phi_b(t,n)$ are the instantaneous phase of regional time series signals a and b
257 [71].

258 An index known as PLV was used to define the degree of synchronization between the
259 two estimated instantaneous phases [23]. Mathematically, PLV is expressed as:

$$PLV_{ab}^S(t) = \frac{1}{N} \left| \sum_{n=1}^N e^{j\theta_{ab}(t,n)} \right| \quad (7)$$

260 where S denotes the subjects and N denotes the total number of trials. The grand average of
261 PLV over 18 subjects $PLV_{ab}^{GA}(t)$ is defined as

$$PLV_{ab}^{GA}(t) = \frac{1}{M} \left| \sum_{S=1}^M PLV_{ab}^S(t) \right| \quad (8)$$

262 where M denotes the total number of subjects. Adjacency matrix was formed to represent the
263 connectivity graph. The connectivity graph was normalized with the 200 ms pre-stimulus
264 baseline using Z-score normalization procedure. The normalized graph is then defined as

$$\text{normPLV}_{ab}^{GA}(t) = (\text{PLV}_{ab}^{GA}(t) - \mu_{ab}^{GA}) / \sigma_{ab}^{GA} \quad (9)$$

265 where μ_{ab}^{GA} and σ_{ab}^{GA} are the grand-averaged mean and standard deviation calculated from the
266 200 ms pre-stimulus baseline.

267 Next, the connectivity graph was thresholded using proportional thresholding approach
268 [6,72]. A small percentage (10%) of strongest estimated connections were retained.

269

270 **Performance analysis**

271 In Destrieux atlas [62], 148 cortical regions were group into 14 macro ROIs. We predefined
272 the 11 distinct ROIs reported to be implicated in the visual oddball paradigm based on the
273 previously published functional imaging studies of visual oddball task [3,73-89]. The 11
274 predefined ROIs are listed in bottom of Fig 1.

275 We performed the performance analysis using two criterions. These criterions quantify
276 the identified networks distributed within the predefined ROIs as ‘correct’ networks whereas
277 the identified networks distributed outside the predefined ROIs are identified as ‘incorrect’
278 networks.

279 The first criteria is Localization Index (LI) [26]. LI is a ‘global’ indicator to quantify
280 the performance of the scout functions/time-frequency decomposition algorithms pair. It was
281 computed over the 11 predefined ROIs. LI is defined as the ratio between the number of
282 identified edges within all predefined ROIs and the total number of estimated edges.
283 Mathematically, LI is defined as

$$LI = \frac{NET_{\varepsilon}}{NET_{\varepsilon} + NET'_{\varepsilon}} \quad (10)$$

284 where NET_{ε} denotes the number of estimated connections within the 11 predefined ROIs and
285 NET'_{ε} denotes the quantity of estimated edges outside the predefined ROIs. The LI ranges
286 between 0 (no connections are identified with the predefined ROIs) and 1 (all connections are
287 identified within the predefined ROIs).

288 Another criteria used for performance analysis is R [26], known as the ‘local’ indicator
289 to quantify the local distribution of identified networks within each ROI. Ratio between
290 quantity of estimated connections within each predefined ROI and total identified connections
291 within all predefined ROIs. Mathematically, the R can be expressed as:

$$R_i = \frac{NET_{ROI}^i}{NET_{\varepsilon}} \quad (11)$$

292 where i denotes the 11 predefined ROIs (see Fig 1) and NET_{ROI}^i denotes the number of
293 estimated connections within the ROI i . The R_i criteria ranges from 0 (no estimated edges are
294 found inside ROI i) to 1 (all estimated edges are found inside ROI i).

295

296 **Results and discussion**

297 In this study, we have performed source localization of EEG data acquired during visual
298 oddball task. We used wMNE algorithm to solve the EEG inverse problem. Fig 2A depicts the
299 estimated current density sources on 3-dimensional (3D) cortex between 240 – 500 ms of the
300 epoch. From the top view of the cortex, it is observed that the majority of current sources are
301 intensively distributed on the parietal and central regions. These activations are generally
302 elicited by P300 and motor response. The bottom, left and right views show stronger current
303 sources over the left temporal region. On the front view, peak current sources are mainly

304 distributed on the frontal region. On the back view, lower intensity of current sources are
305 observed over occipital region.

306 We partitioned the cortical surface of the brain into 148 regions based on Destrieux
307 cortical atlas. These regions are equally parcelled over right and left hemispheres of the brain
308 surface. These regions are also known as scouts in Brainstorm jargon. We applied several scout
309 functions, i.e. MEAN, MAX and PCA, as source down-sampling algorithm to create the scout
310 (regional) time series (148 regions from Destrieux atlas). Fig 2B - 2D depicts the regional time
311 series projected on 3D cortex between 240 – 500 ms. As we can see on the figure, the regional
312 times series generated by different scout functions are different in terms of current density
313 distribution and intensity. Therefore, scout functions could be a factor that affecting the
314 performance of FC estimation.

315 We applied WT and HT to decompose the regional time series signals into time-
316 frequency domain. Fig 3 depicts the time-frequency representations of a regional time series
317 (right central region). The peak magnitude in gamma band (30 – 60 Hz) was observed over
318 both spectrograms which is elicited by motor planning and integration. However, both
319 algorithms show different intensity in gamma band as well as in other bands. Therefore, time-
320 frequency decomposition algorithms could be another factor that affects the performance of
321 FC estimation.

322 We extracted the instantaneous phase of the regional time series in gamma band using
323 PLV to estimate the FC. The connectivity graphs obtained for the 6 different combinations of
324 the time-frequency decomposition algorithms and scout functions are presented in Fig 4. The
325 colour-coded circles are the nodes of the network while the lines linking the two nodes are
326 denoted as an edge. The colours of the nodes show the intensity level of the node degree. The
327 main purpose of the node degree here is to use as a comparative parameter to distinguish the

328 identified networks estimated by different combinations of methodologies. Indeed, the
329 differences can be observed based on the edges. For qualitative visual inspection of the
330 estimated networks, the node degree is compulsory for the comparisons between the estimated
331 networks. The qualitative visual inspection of the estimated edges indicate that the results are
332 highly dependent on the two factors, i.e. time-frequency decomposition algorithms and scout
333 functions.

334 The performance analysis was carried out on TR case using **criterion LI** to quantify
335 the results shown in Fig 4. In this performance analysis, mean values of LI and their
336 corresponding standard deviations were used to quantify the efficiency (depends on LI values)
337 and consistency (depends on standard deviation values), respectively, of the scout functions
338 and time-frequency decomposition algorithms. We conducted three analyses in TR case using
339 different trial selections to evaluate the consistency of the methods based on the obtained
340 results. Fig 5 depicts the mean values of the criterion LI on TR case for different scout functions
341 (MEAN, MAX and PCA) and time-frequency decomposition algorithms (WT and HT). We
342 performed the Pearson's correlation analysis to describe the interplays between the variability
343 of each factor and the different factors/combinations. We noted that the combinations with
344 same scout function have lower correlation values (0.194 for Wavelet/PCA vs. Hilbert/PCA
345 and Wavelet/MAX vs. Hilbert/MAX) than the combinations with same time-frequency
346 decomposition algorithms (0.979 for Hilbert/PCA vs. Hilbert/MAX and 0.986 for
347 Wavelet/PCA vs. Wavelet/MAX). The correlation values show that time-frequency
348 decomposition algorithms have higher variability and therefore, the time-frequency
349 decomposition algorithms strongly impact the LI values as compared to the scout functions.

350 As observed, regardless of scout functions, HT yields slightly higher mean LI values
351 than WT. Theoretically, HT yields slightly higher efficiency than WT based on the connectivity
352 estimation over expected ROIs (based on literatures) using PLV. However, as we can observe,

353 the difference between these two time-frequency decomposition algorithms in term of LI are
354 minor (0.01 in PCA; 0.007 in MAX; 0.003 in MEAN). We performed Student's t-test. The
355 results show no significant difference between WT and HT in scout functions of PCA, MAX
356 and MEAN. Application of both algorithms produces similar results with minor difference
357 [69,90,91]. Therefore, we can conclude that application of both algorithms on connectivity
358 estimation using PLV is efficient as the result shows that PLV is able to localize more than
359 80% of significant connections using both algorithms to extract the instantaneous phases of the
360 regional time series. However, in terms of consistency, WT is better. Based on the results, we
361 observe that WT is more consistent in extracting instantaneous phases for connectivity
362 estimation as the standard deviation values are lower. As mentioned earlier, we conducted the
363 analysis three times on same methodology by different trial selections in TR case. The standard
364 deviation represents the fluctuations or more precisely, variability of the factors across different
365 selected trials on the same case. In this situation, WT is more consistent than HT across the
366 different trials. Therefore, we conclude that WT performed better in instantaneous phase
367 extractions for connectivity estimation for visual oddball paradigm.

368 Hence time-frequency decomposition algorithms have stronger effect on mean LI
369 values, whereas scout functions have minor impact on the mean LI values. Combinations of
370 scout functions (PCA, MAX, and MEAN) with same time-frequency decomposition algorithm
371 (HT) provide the higher mean LI value. The result indicates that these combinations have
372 higher efficiency in connectivity estimation over expected ROIs using PLV. Among these
373 combinations, MAX with HT provides highest averaged LI value (LI=0.843). However, some
374 minor differences are observed among these combinations. According to the results of the
375 Student's t-test, these minor differences are insignificant. Hence, in term of efficiency, PCA,
376 MAX and MEAN with HT provides similar results with minor differences. Nevertheless, in
377 term of consistency, MAX/HT is better as the standard deviation is smaller among these three

378 combinations. Therefore, the application of HT in conjunction with scout function MAX yields
379 better outcome than the other two combinations.

380 On the other hand, combinations of WT with three scout functions produce lower mean
381 LI values than combinations of HT with the three scout functions. In these three combinations,
382 WT/MEAN gives higher mean LI value than others. However, the differences are still minor.
383 Thus, we performed Student's t-test. The results demonstrate that WT/PCA and WT/MEAN
384 pairs are significantly different ($p < 0.05$). WT/MEAN pair provides higher efficiency in
385 connectivity estimation. However, in terms of consistency, WT/PCA pair is better.

386 Hence we can conclude that WT is better than HT in terms of consistency of the results
387 [92]. WT with MEAN scout function gives higher efficiency in connectivity estimation.
388 However, WT with PCA pair has better consistency than other combinations.

389 Now we discuss the outcomes obtained from the quantitative comparison of the
390 performance of the time-frequency decomposition algorithms and scout functions on FC
391 estimation, based on the **R criterion**. The R criterion is known as a 'local' indicator. The R
392 values reflect the distribution of estimated links in each predefined ROI obtained from literature.
393 R is known to be important as the brain regions activated during the visual oddball paradigm
394 (consists of P300 and motor response) are supposed to be distinct. Moreover, the estimated
395 network is known to be dependent on the time-frequency decomposition algorithms and scout
396 functions.

397 In Fig 6, the straight line curves of the R values obtained for the two time-frequency
398 decomposition algorithms are superimposed and plotted for each scout function. Results
399 indicate that all signal processing algorithms identified a comparable percentage of significant
400 connections for all scout functions. As shown in Fig 6 the SD values of WT/Scout functions is
401 mostly lower than the HT/Scout functions. Only few SD values in WT/MAX and WT/MEAN

402 pairs are slightly higher. (For examples: LF, LT and RT in WT/MAX pair; LF, LC, LT, RT
403 and LP in WT/MEAN pair). However, the WT is still considered as a consistent algorithm to
404 extract instantaneous phases for. This result is correlated with the result in the preceding part
405 for LI calculation.

406 Student's t test was carried out to statistically compare the differences between different
407 factors (WT/PCA vs. HT/PCA; WT/MAX vs. HT/MAX; WT/MEAN vs. HT/MEAN) in 4
408 different ROIs (LC; RC; LP; RP) to identify the significant pairs of factors with higher
409 efficiency. These 4 ROIs are significant in oddball tasks [93-96]. Neural activity in LP and RP
410 corresponds to P300 (decision making) while neural activity in LC and RC corresponds to
411 motor planning and integration.

412 As shown in Fig 6, combinations of WT with 3 scout functions yield higher averaged
413 R values as compared to combinations of HT with 3 scout functions. WT/PCA pair yields
414 higher average R values on the 4 ROIs than HT/PCA pair. Results indicate no significant
415 differences between the combinations in LC, RC and LP. However, a significant difference is
416 observed in RP ($p=0.023$). On the other hand, as depicted in Fig 6, Wavelet/MAX gives higher
417 average R values than Hilbert/MAX as well over the ROIs of LC, RC, LP and RP. The
418 differences are still minor between these two combinations. Statistical outcomes demonstrate
419 that no significant differences are observed on these two pairs of factors. Lastly, we applied
420 Student's t test on the combinations of WT/ MEAN and HT/MEAN. Results reveal that the
421 differences are not between the combinations in LC, RC and RP. However, a significant
422 difference is observed in LP ($p=0.021$).

423 Based on the statistical results, we note that WT/PCA pair yields greater R value than
424 Hilbert/PCA over parietal region (RP) and the difference is significant. Moreover, WT/MEAN
425 pair yields greater R value than Hilbert/MEAN over parietal region (LP) as well and the

426 difference is significant. According to other researches, activity over parietal region is
427 essentially elicited by P300 response which is a significant oddball event [97,98]. Thus, we
428 believe that WT/PCA and WT/MEAN pairs provide good performance for PLV to localize the
429 connectivity triggered by P300 response.

430 By combining the analysis from LI and R, we can say that WT is more consistent than
431 HT. Moreover, we also realized that WT/PCA and WT/MEAN pairs have high performance.
432 Hence the results of Wavelet/PCA pair is more consistent. Besides that, PLV also was able to
433 localize more than 80% of networks (LI=0.831) using WT/PCA pair. The efficiency of this
434 pair is acceptable and the consistency of this pair is better. Therefore, we conclude that
435 WT/PCA is adequate and a good choice for visual Oddball task.

436 We performed the comparisons between TR and NTNR cases in order to validate the
437 performance of the WT/PCA pair based on LI and R criterions. Moreover, we would like to
438 analyse the differences of TR versus NTNR in terms of FC using R criterion.

439 Fig 7 shows the distribution of the estimated brain functional networks on cortical
440 surface for TR and NTNR cases. As illustrated, the difference in terms of estimated
441 connectivity among both cases is obvious. Consequently, target and non-target stimuli elicited
442 different brain networks during oddball task. As depicted in Fig 7, the difference in the
443 estimated networks is illustrated on the cortical surface. Furthermore, the quantitative analysis
444 is required to evaluate the difference is done using LI and R parameters.

445 Fig 8 shows the mean LI value of WT/PCA for TR and NTNR cases. It is observed that
446 the PLV is able to localize denser networks over the predefined ROIs in TR case which are
447 significant for visual oddball event including P300, motor response and others elicited by target
448 stimuli. In our case, we observe that TR case has greater LI than NTNR case. In other words,
449 target stimuli triggered higher brain connectivity. We performed statistical test (ANOVA) to

450 evaluate the difference between these two cases. The TR case is significantly different ($p=0.002$)
451 from NTNR case in terms of average LI values. Thus, we conclude that TR case triggered
452 denser networks as compared to NTNR case [50,99]. Moreover, WT/PCA is sufficient for PLV
453 to use as a connectivity estimation modality for visual oddball paradigm.

454 So far, we compared the difference between TR and NTNR case using ‘global’
455 indicator. Now, we will analyse the differences between TR and NTNR cases within ROIs
456 using ‘local’ indicator, criterion R. The comparisons of R values between two cases were
457 plotted on a line graph shown in Fig 9. As seen the major differences between TR and NTNR
458 cases are observed within majority of ROIs especially LL, RL, LC, RC, LP, RP and LT. TR
459 case has denser cortical connectivity within these ROIs than NTNR case. ANOVA tests were
460 carried out for each ROI to statistically compare the difference between both cases within each
461 ROI.

462 For ROIs in limbic (LL & RL) regions, target stimuli elicited greater cortical activity.
463 Based on ANOVA the TR case is significantly different than NTNR case for R values within
464 LL and RL ($p=0.028$ & $p=0.002$ respectively). According to Destrieux atlas, Cingulate cortices
465 (Cingulate gyrus and sulcus) are included in the limbic regions. Our result show that target
466 stimuli elicited denser networks over bilateral limbic regions than non-target stimuli which is
467 in line with other researches [86,100,101]. These cortical activities are mostly related to P300
468 response (decision making for the response to target stimuli) [102-105] as well as target stimuli
469 detection [106]. Therefore, TR case is different with NTNR case in terms of the estimated
470 network over limbic regions as the target detection process and P300 response are present in
471 TR case, but absent in NTNR and the difference is significant.

472 For ROIs in central (LC & RC) regions, the difference between TR and NTNR cases in
473 terms of R is obvious. Greater central cortical activity is observed in TR case than in NTNR.

474 Results of the statistical test shows that TR case is different from NTNR case in terms of the
475 corresponding R values within these two ROIs and the differences are significant (LC: $p=0.05$;
476 RC: $p=0.03$). According to our oddball paradigm, instead of non-target stimuli, the subjects
477 provided motor response to the target stimuli. Thus, higher cortical activity is found over
478 central regions in TR case than NTNR case. Our result is correlated with other studies
479 [76,100,105,107-110]. Therefore, TR case is significantly different from NTNR in terms of
480 cortical network over central regions.

481 For ROI in right temporal (RT) lobe, superior temporal activity is observed in TR case.
482 ANOVA test indicates that the difference between TR and NTNR cases in terms of R values
483 are significant ($p=0.036$) within this ROI. Some studies reported that cortical connectivity
484 distributed over temporal regions corresponds to visual target detection [111] and P300
485 response [102,112,113]. Moreover, in [103,114], the authors reported that right temporal region
486 is more dominant than left temporal during P300 response. Hence, TR case is different from
487 NTNR case in terms of the connectivity over right temporal region for P300 response.

488 Lastly, in parietal (LP & RP) regions, higher parietal activity is noticed in TR case. The
489 results of statistical tests denote that both cases are significantly distinct with each other in LP
490 ($p=0.049$) and RP ($p=0.007$) in terms of their designated R values. Denser bilateral cortical
491 activity is observed over parietal regions in TR case that corresponds to P300 response
492 [105,115-118] and motor coordination for button pressing [76,119,120]. Thus, NTNR case has
493 lower bilateral parietal activity as no P300 and motor responses are required for non-target
494 stimuli.

495

496 **Conclusion**

497 In this study our aim is to observe the FC for visual oddball task using the source space. We
498 used wMNE method to reconstruct the sources for data acquired by EEG for visual oddball
499 task. We applied three different scout functions (MEAN, MAX and PCA) to generate the
500 regional time series signals. We applied two time-frequency decomposition algorithms (HT
501 and WT) to represent the regional time series signals into complex functions. We extracted
502 instantaneous phases from the complex form of regional time series signals and estimated the
503 FC using PLV. The connectivity graphs were proportionally thresholded to retain 10% of
504 strongest networks. We evaluated the performance of the scout functions/time-frequency
505 decomposition algorithms pairs based on LI and R. Lastly, we compared the differences
506 between TR and NTNR cases based on the LI and R.

507 Our results demonstrate that time-frequency decomposition algorithms have higher
508 impact on the LI values than the scout functions. In addition, WT is better than HT in terms of
509 the consistency of LI. All pairs show good efficiency in connectivity estimation as all pairs
510 yield more than 80% of LI. However, WT/PCA pair is more consistent than others. Moreover,
511 WT/PCA is capable to estimate the connectivity within parietal region which corresponds to
512 P300 response. Lastly, we observe the differences in connectivity between TR and NTNR cases
513 over parietal, central, right temporal and limbic regions which correspond to target detection,
514 P300 response and motor response.

515 In conclusion, the outcome of the connectivity estimation might be affected by scout
516 functions/time-frequency algorithm pairs. Consequently, WT/PCA is the best choice for visual
517 oddball task as the scout function to generate regional time series signals and time-frequency
518 decomposition algorithms to transform the signals into gamma band for instantaneous phase

519 extraction. The TR and NTNR cases are different in terms of FC. Greater R values are observed
520 over the regions which correspond to P300 and motor response.

521 The performance of the combinations of scout functions/time-frequency decomposition
522 algorithms have not been evaluated so far in the literature. We found that the WT/PCA is best
523 for visual oddball task. We believe that PCA is superior for generation of regional time series
524 signals and WT is superior for time-frequency decomposition for extraction of instantaneous
525 phases. On the other hand, we found that higher connectivity over parietal, temporal, central
526 region and limbic regions are significant for P300 response. Thus, we believe that this
527 discovery of P300 response could be used as an electrophysiological marker to distinguish the
528 healthy individuals and the subjects with mild cognitive impairment diseases as well as the
529 marker for the diagnosis and prediction of mild cognitive impairment disorders [96,121-123].

530

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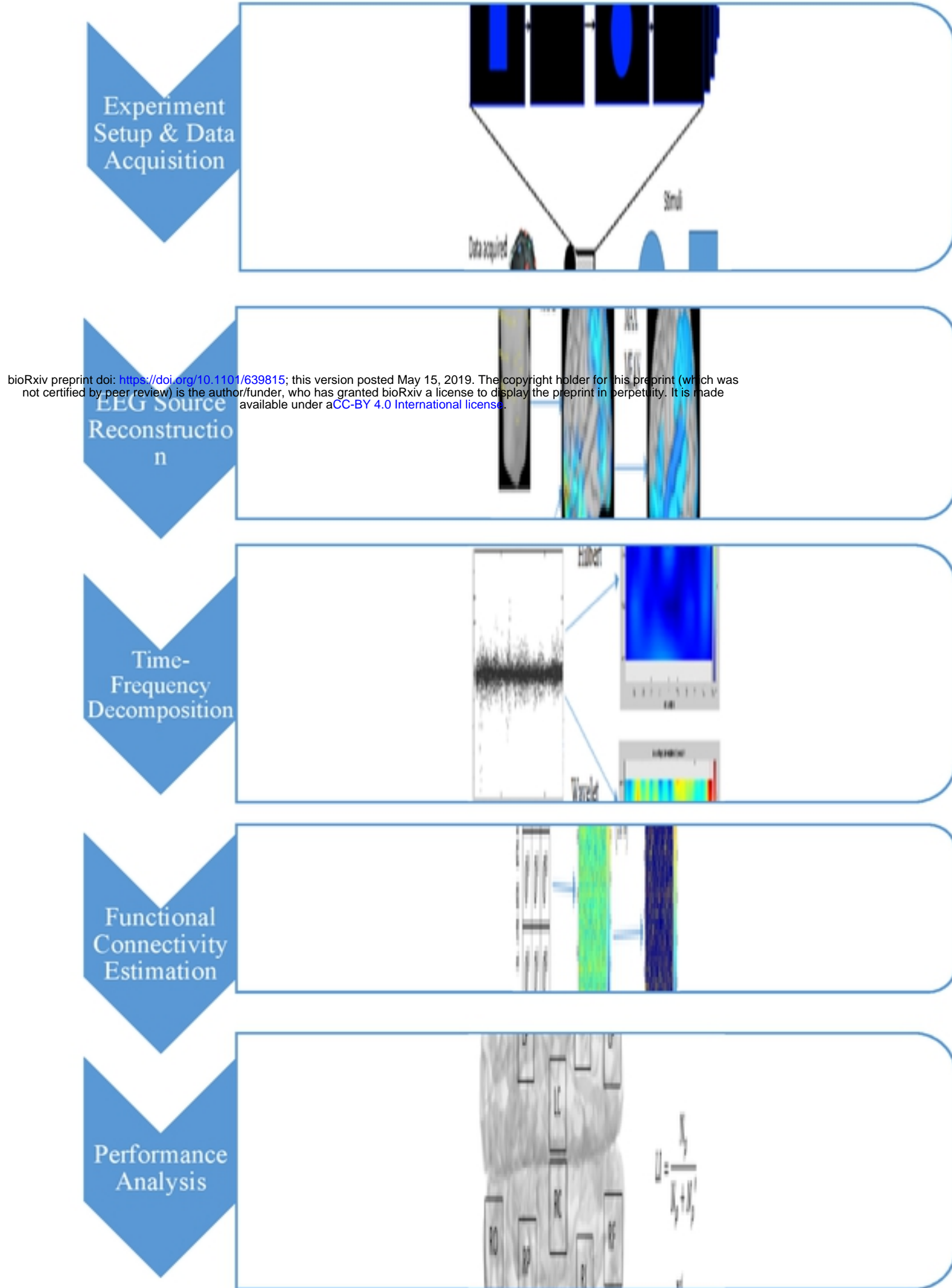
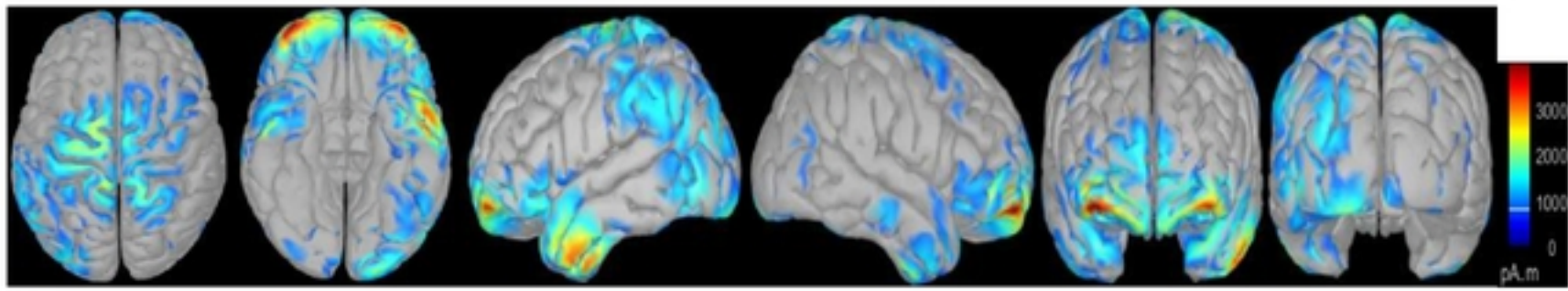


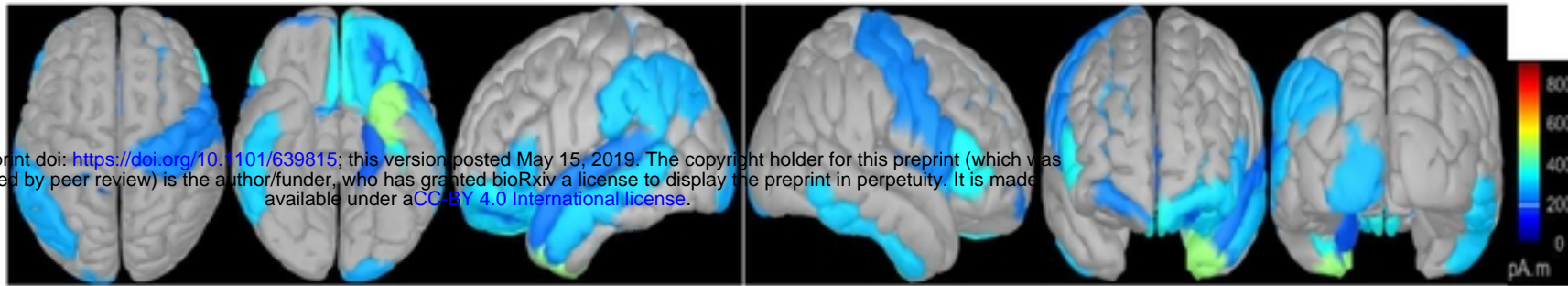
Fig 1. Flow chart of the study.

Top Bottom Left Right Front Back

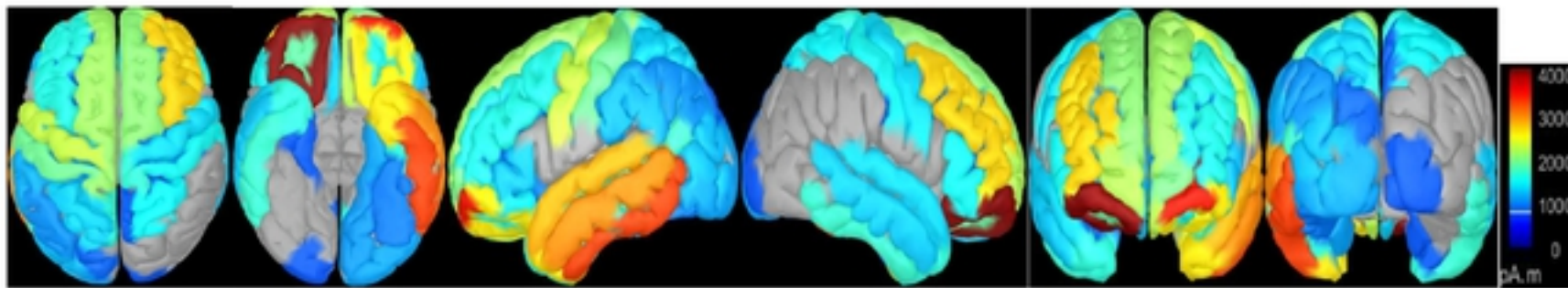


(A)

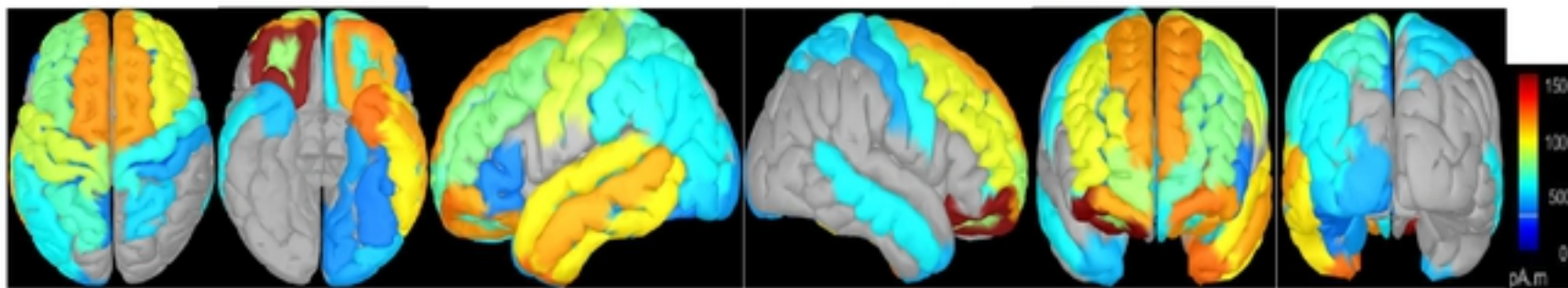
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(B)



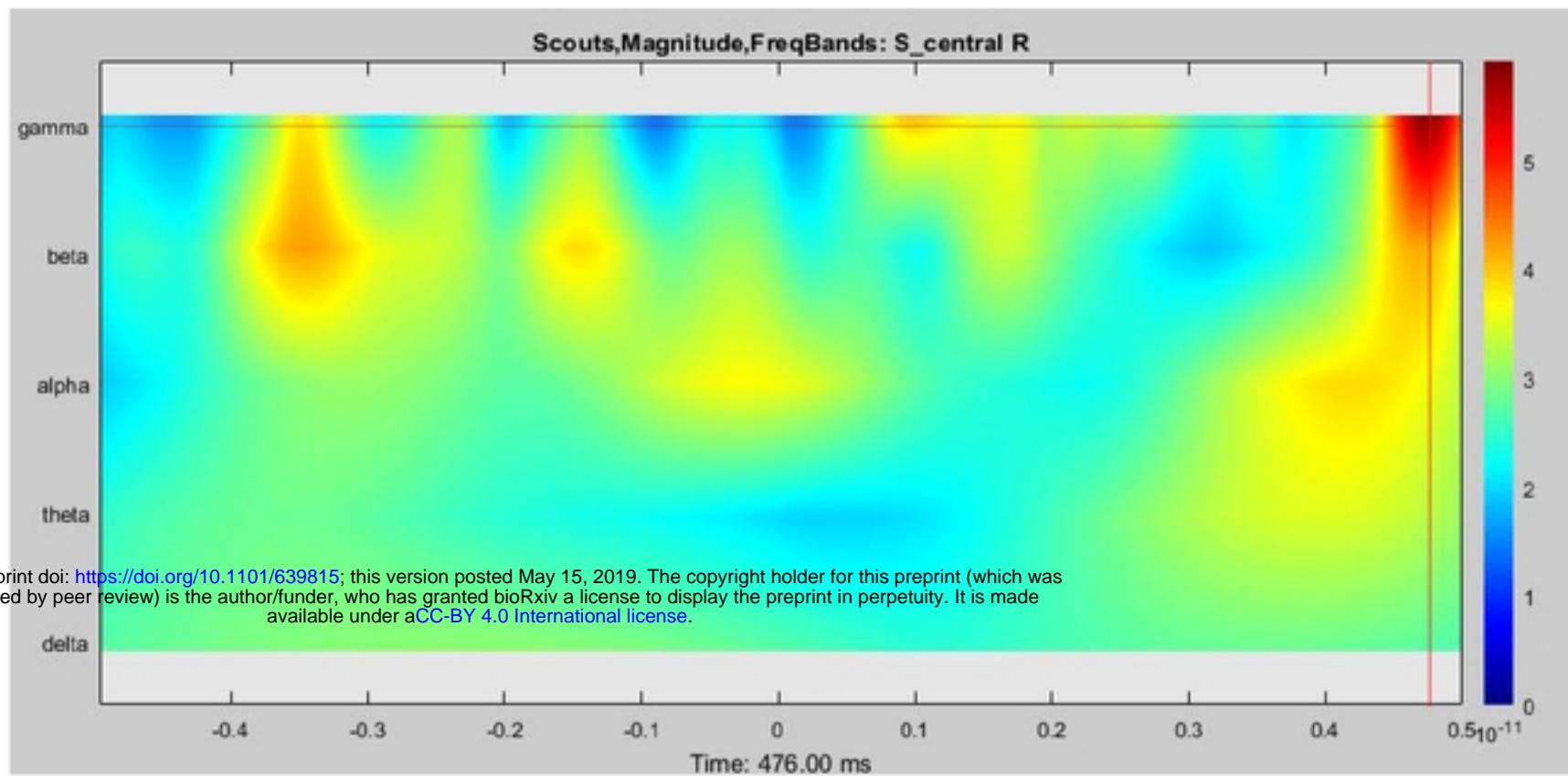
(C)



(D)

Fig 2. Different views of reconstructed sources on the cortical surface (A) and respective regional cortical sources using different downsampling scout functions: MEAN (B), MAX (C) and PCA (D).

Wavelet Transform



Hilbert Transform

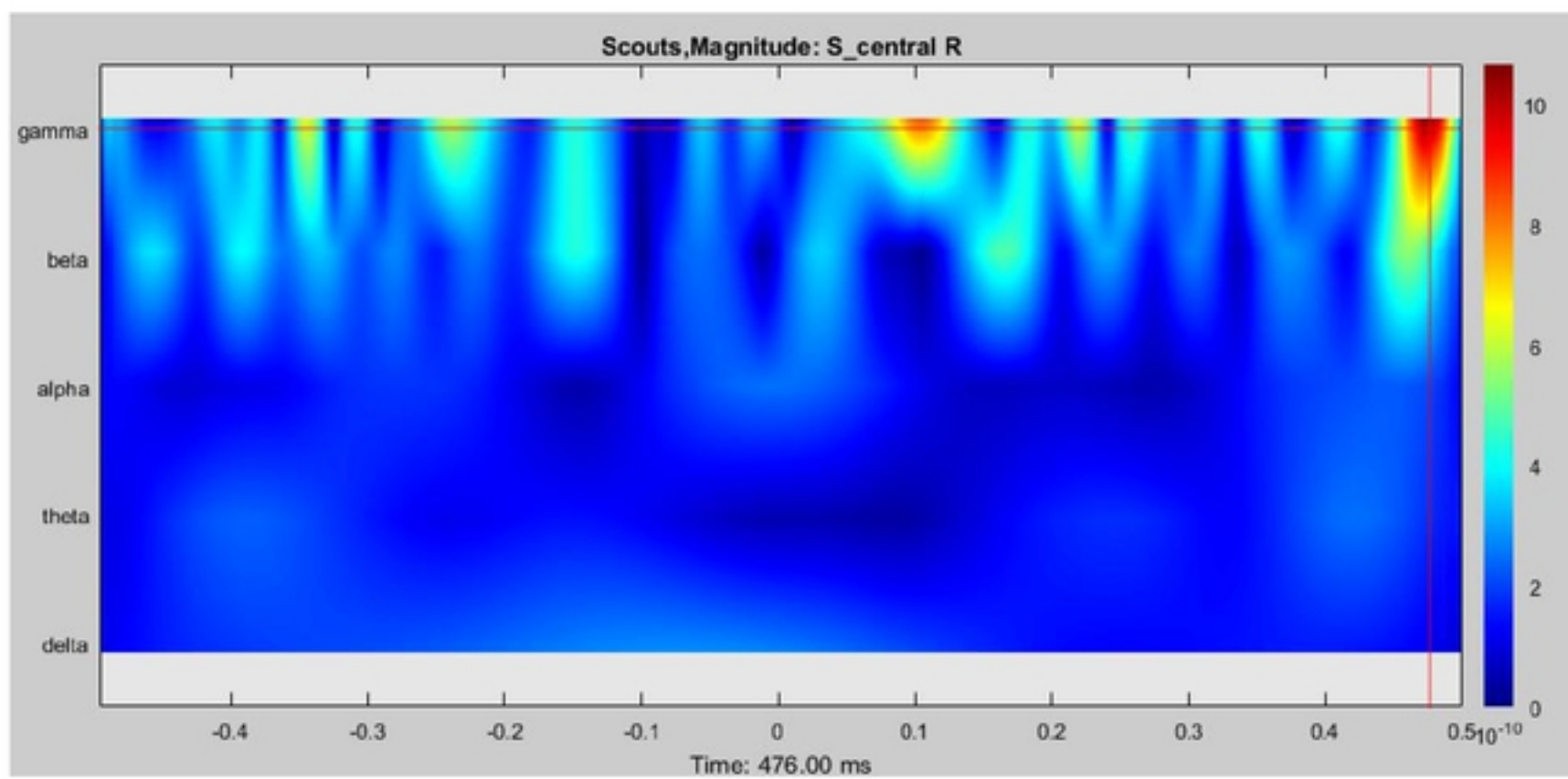
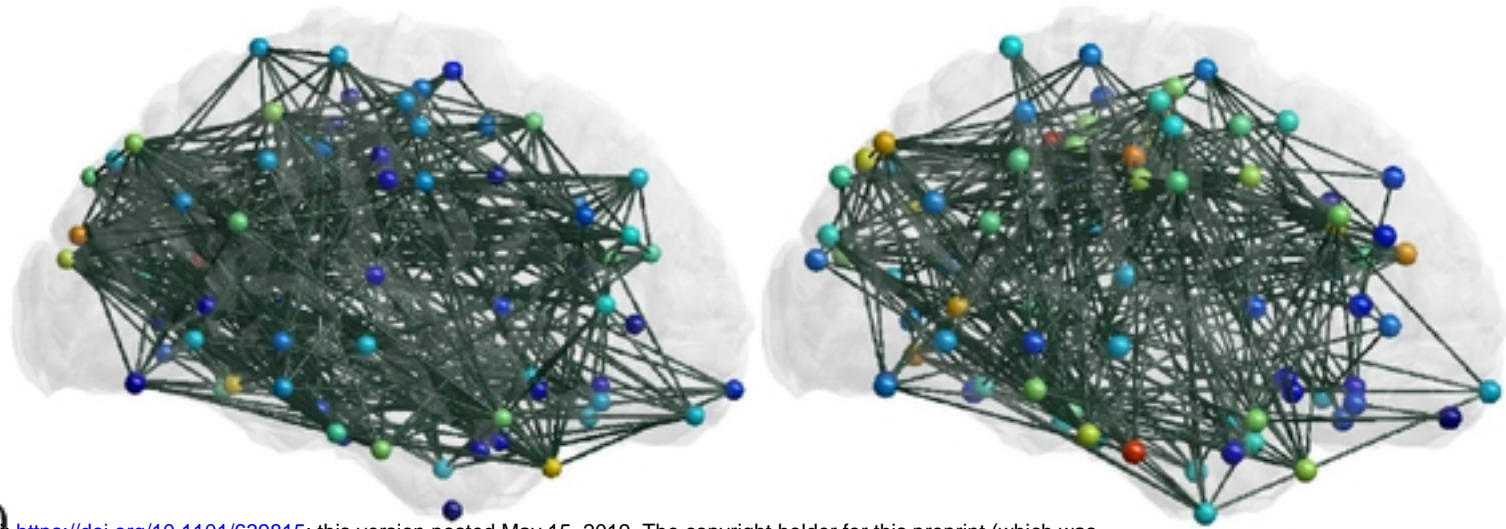


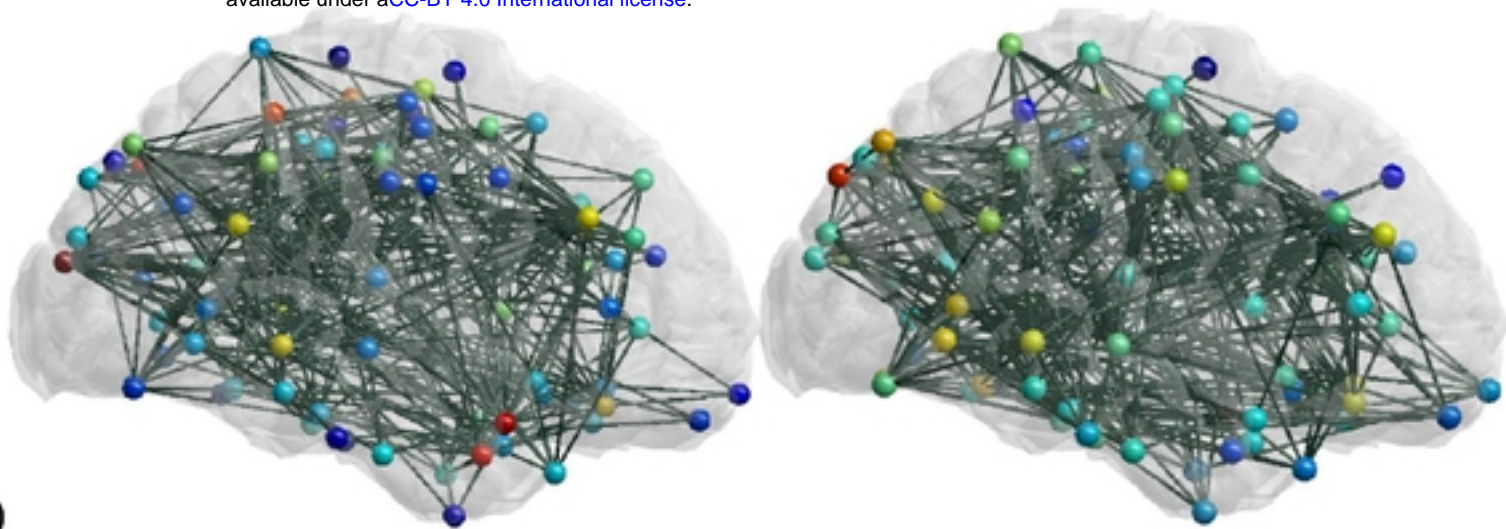
Fig 3. Magnitude of time-frequency decomposition for a central region from Destrieux atlas. Upper panel: Wavelet Transform; Lower panel: Hilbert Transform

Hilbert Transform

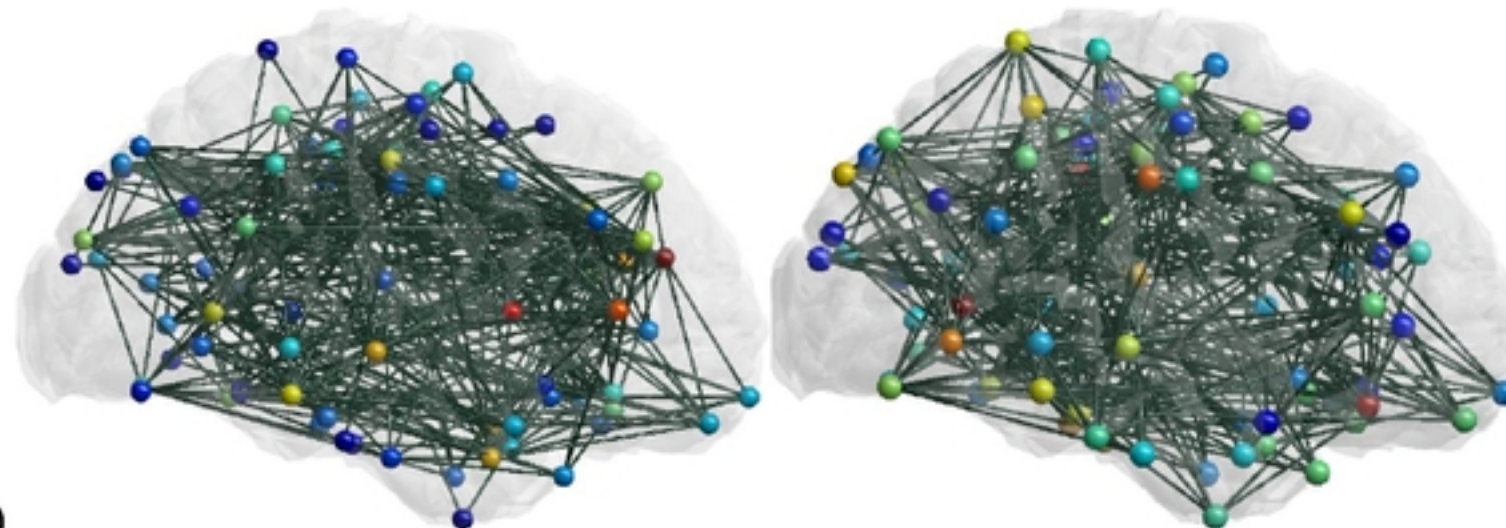
Wavelet Transform



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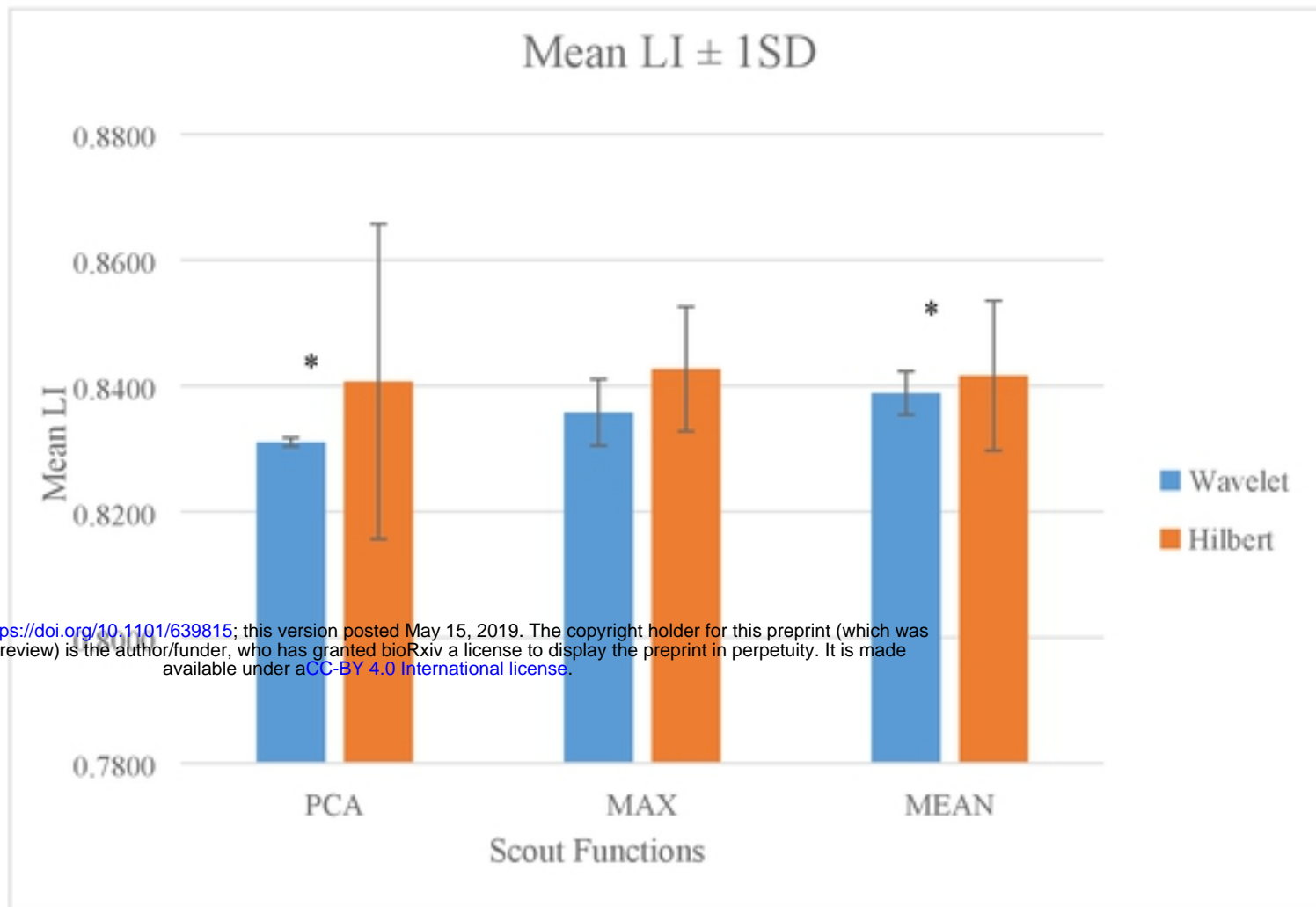


(B)



(C)

Fig 4. Connectivity estimated by PLV based on the instantaneous phases extracted using Hilbert Transform (left panel) and Wavelet Transform (right panel) from regional time series downsampled by different scout functions: (A). MEAN; (B). MAX; (C). PCA.



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Fig 5. Comparison of averaged LI values between different time-frequency decomposition algorithms for different scout functions. Asterisk above the bars indicates significant difference ($P \leq 0.05$). (LI: Localization Index; SD: Standard Deviation).

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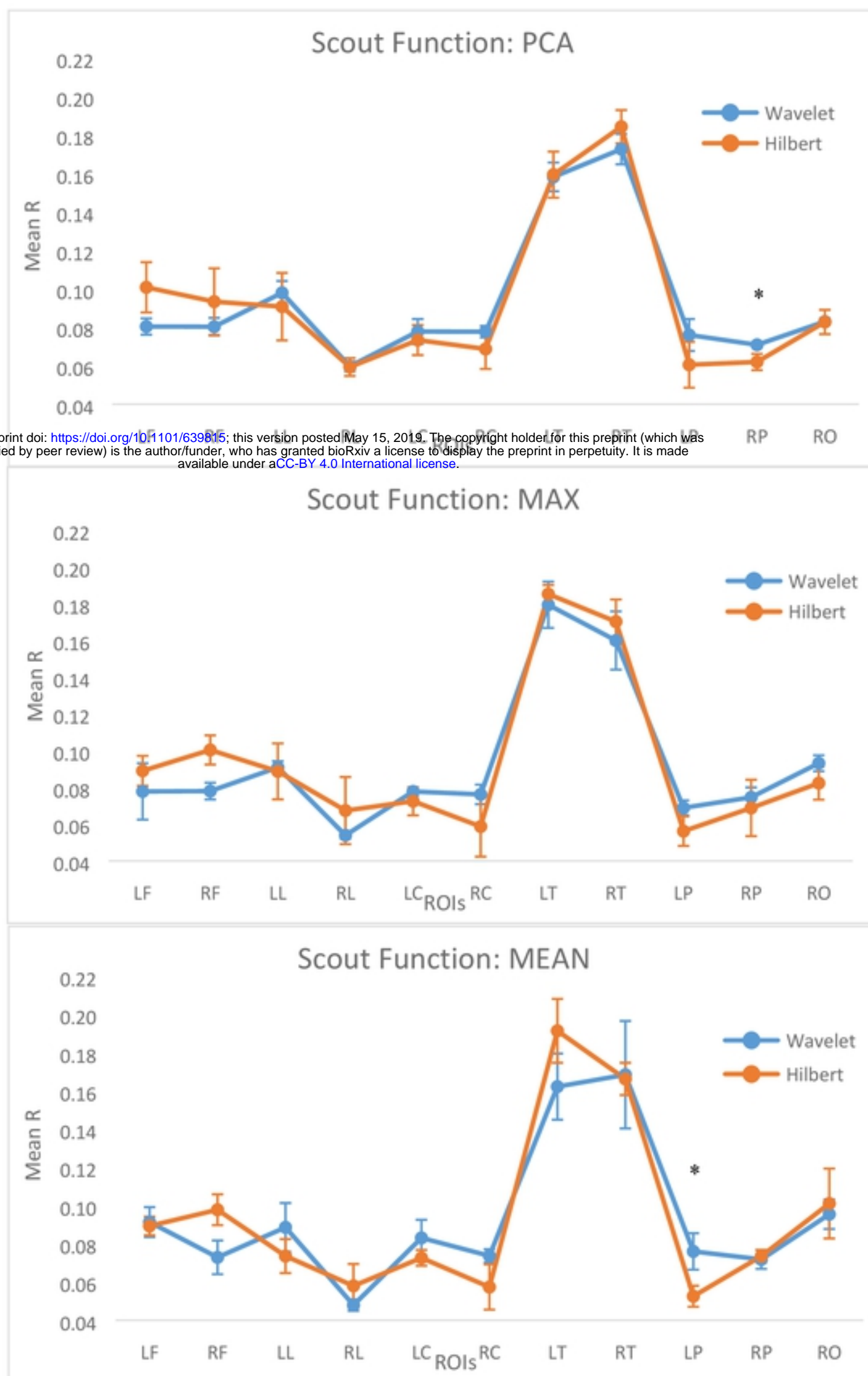
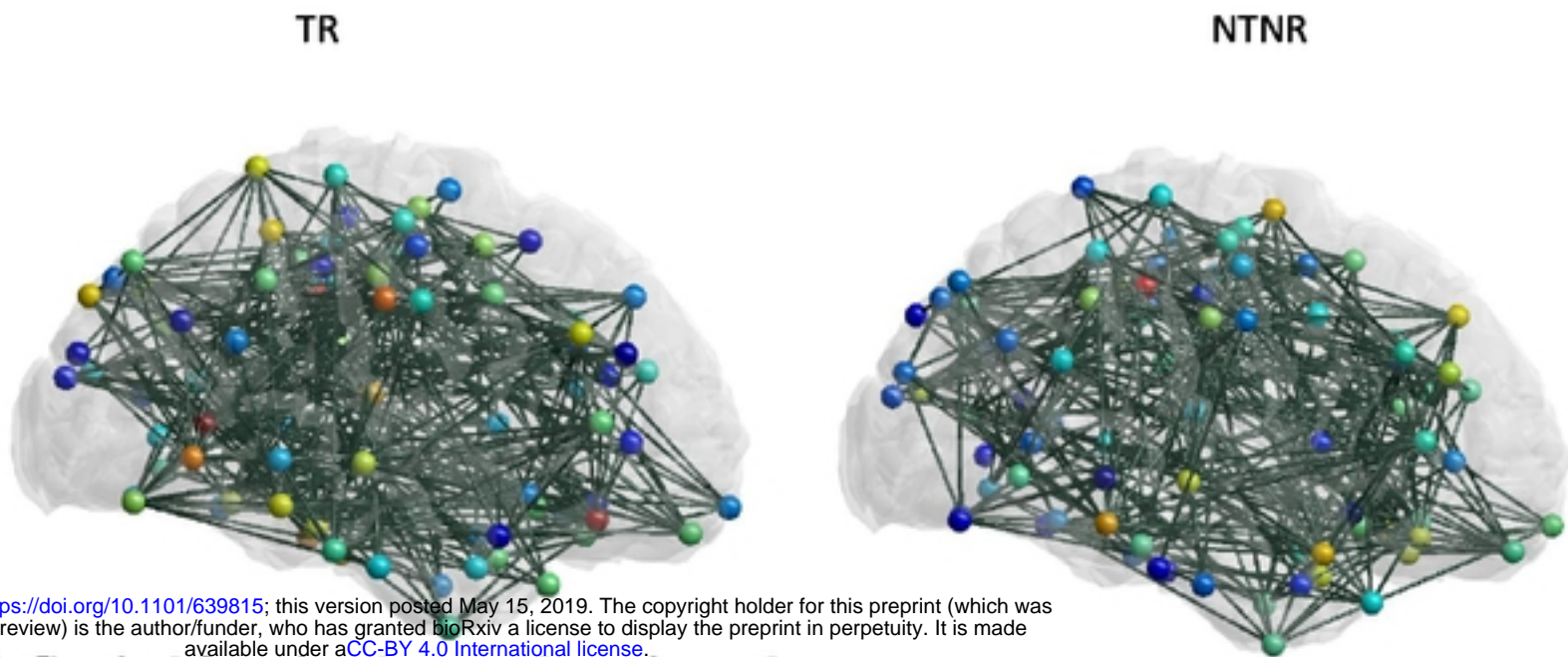


Fig 6. The mean and standard deviations of the R values (ratio of the identified connections within each ROI) obtained for the different scout functions.



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Fig 7. Cortical functional networks estimated using PLV based on the instantaneous phases extracted by Wavelet Transform/PCA pair for two oddball cases. Left panel: TR case; Right panel: NTNR case

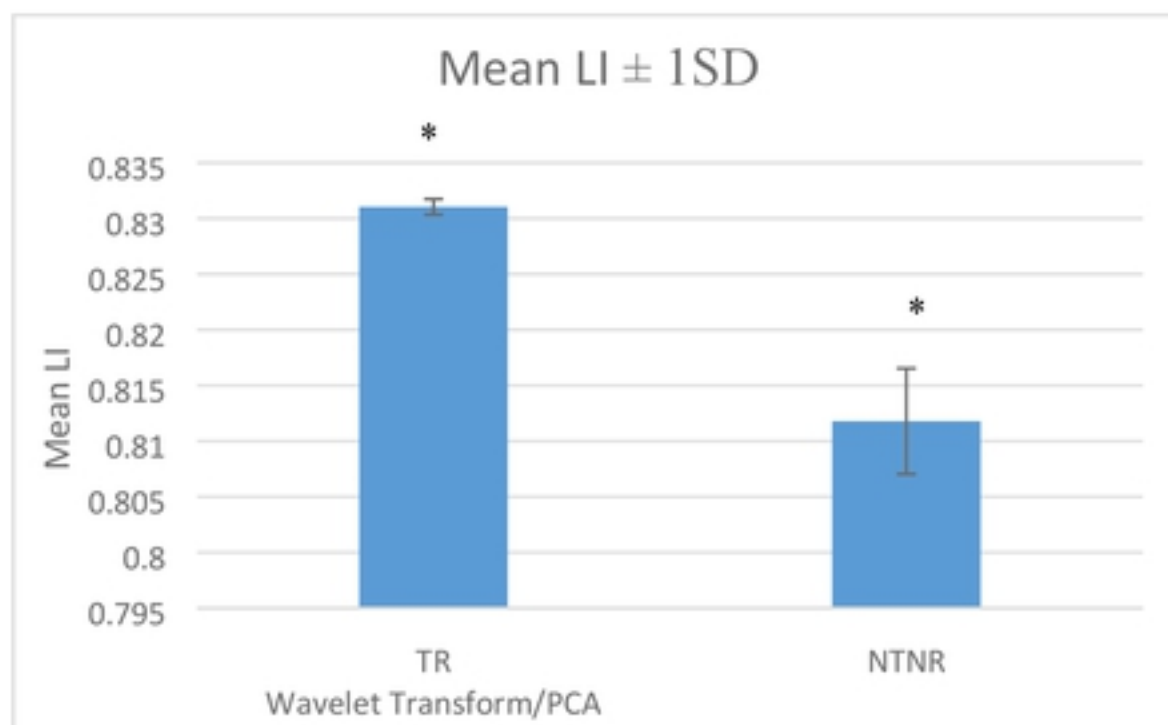


Fig 8. Comparison of mean LI between TR and NTNR cases. Asterisk above the bars indicates significant difference ($P \leq 0.05$). LI: Localization Index; SD: Standard Deviation.

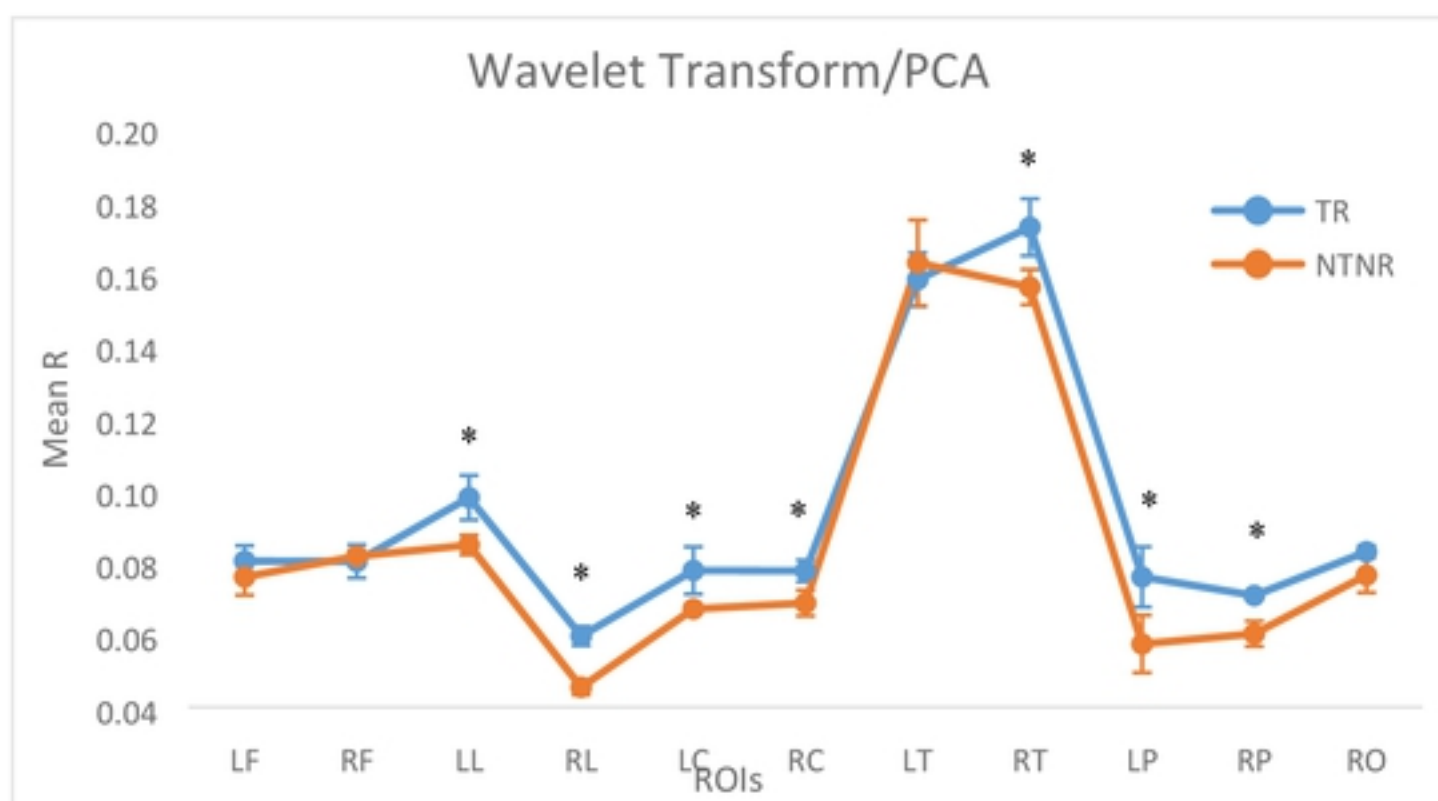


Fig 9. Comparison of mean R between TR and NTNR cases. Asterisk above the lines indicates significant difference ($P \leq 0.05$). R: ratio of the identified connections for within each ROI; SD: Standard Deviation.