# Non-Parametric Analysis of Inter-Individual Relations Using an Attention-Based Neural Network

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#### Abstract

In the past decade, social network analysis was widely adopted in animal studies, and it enabled the revelation of global characteristic patterns of animal social systems from pairwise inter-individual relations. Animal social networks are typically drawn based on geological proximity and/or frequency of social behaviors (e.g., grooming), but the appropriate choice of the distance/closeness metric is not clear especially when prior knowledge about the species/data is limited. In this study, the researchers explored a non-parametric analysis of inter-individual relations using a neural network with the attention mechanism, which plays a central role in natural language processing. The high interpretability of the attention mechanism and the flexibility of the entire neural network allow automatic detection of interindividual relations included in raw data. As case studies, three-dimensional location data collected from simulated agents and real Japanese macaques were analyzed.

**Keywords:** interaction, social network analysis, animal society, Japanese macaque, deep learning, attention mechanism

### Significance Statement

- Novel non-parametric analysis of inter-individual relations is proposed.
- The proposed method is based on an artificial neural network and automatically detects latent interindividual dependencies behind raw data, without prior assumptions about the possible types of relations or random distributions involved.
- The performance of the method was tested on simulated and real three-dimensional location data of Japanese macaques.
- The analysis will be effective especially when little is yet known about the species under study.

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# 1 Introduction

<sup>2</sup> Understanding the characteristics of animal social groups is a major objective of animal ecology. Complex
<sup>3</sup> social systems of eusocial insects and non-human primates are often viewed as biological models or precursors
<sup>4</sup> of human societies, and as such, have also attracted the interest of social scientists. In the past decade, social
<sup>5</sup> network analysis was widely adopted in animal studies, and it enabled us to reveal global characteristic
<sup>6</sup> patterns of animal social systems from pairwise inter-individual relations (Krause et al., 2015).

The application of social network analysis to animal studies requires an appropriate metric for the re-7 lational distance/closeness between individuals. Popular options of the metric include geological proximity 8 (often thresholded and converted to counts of co-appearance within the threshold; Silk et al., 2006b,a; Croft q et al., 2008; Clark, 2011; Boyland et al., 2013; Castles et al., 2014; Krause et al., 2015; Schofield et al., 2019) 10 and frequency of social behaviors (e.g., grooming of non-human primates; Chepko-Sade et al., 1989; Silk 11 et al., 2006b,a; Croft et al., 2008; Clark, 2011; King et al., 2011b,a; Castles et al., 2014; Krause et al., 2015). 12 However, the appropriate choice of the metric is not necessarily clear, especially when prior knowledge about 13 the species/data is limited (cf. Castles et al., 2014; Farine and Whitehead, 2015). For example, location in-14 formation for measuring the proximity is available from a wide variety of animals. This includes even those 15 species whose social activities are not yet well-known. Location information also became more reliable and 16 scalable thanks to the recent developments in bio-logging technology (Heupel et al., 2006; Rutz and Hays, 17 2009; Rutz et al., 2012; Fehlmann and King, 2016; King et al., 2018; Dore et al., 2020). However, naively 18 measuring the Euclidean distance between individuals is not necessarily reasonable because the vertical and 19 horizontal divergences would not have the same importance in social network analysis; Many terrestrial 20 animals do not fly or dive, and cannot control the vertical distance from other individuals. Even the hori-21 zontal distance among animal agents could have different social meanings if other factors, such as trees and 22 other objects, intervene. Hence, it is ideal to have a non-parametric, end-to-end analyzer of inter-individual 23 relations that runs on raw data. 24

The present study explores non-parametric analysis of inter-individual relations using a neural network. 25 Specifically, the researchers exploit an interpretable module called *attention mechanism*, as well as the 26 flexibility of the entire neural network that fits to different types of data. The attention mechanism was 27 originally invented for machine translation to represent relations between words in the source and target 28 languages (Figure 1a; Bahdanau et al., 2015). More recently, studies begin to use attention mechanism to 29 represent word relations within input sentences (self-attention, Figure 1b; Vaswani et al., 2017; Devlin et al., 30 2018). It is now considered central technology in today's natural language processing (NLP) in general. 31 The present study applies this technology to three-dimensional (3D) location data collected from Japanese 32 macaques (Macaca fuscata) to reveal their latent relations reflected in the data (Figure 1c), without prior 33 assumptions about the possible types of relation structures or noise distributions. The said approach was 34 validated by analyzing simulated data and recovering the latent relations among the virtual agents generating 35 the data. Even though only the location data are discussed in this study, the possible applications of our 36 relation analysis are not limited to the location data because of the flexibility of the neural network. 37

Our model organism, the Japanese macaque, exhibits rich affiliative and aggressive social behaviors and has been studied extensively for over more than 50 years for better understanding of the evolution of social systems in primate lineages, including humans (Nakagawa et al., 2010). This accumulated knowledge of the species is helpful to interpret/evaluate the results of our novel analysis even though the method is not limited to the species or other primates and could even be more valuable for further studies about animals that do not show intrepretable social activities.

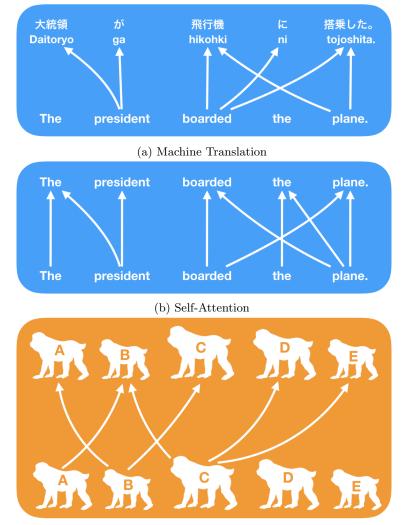
## 44 2 Materials & Methods

### 45 2.1 Overview of the Neural Network

The framework of the relation analysis in this study is to (i) train a neural network that predicts the 3D location of each individual macaque—simulated or real—from that of the other individuals, and then (ii)

check how much attention the network pays to each of the referent individuals when it makes the predictions.

<sup>49</sup> For simplicity, the network only receives the location data at a single timepoint and does not analyze temporal



(c) Inter-Individual Relations

Figure 1: History of the use of attention mechanism. (a) The original use of attention mechanism in machine translation, relating words in the source language (English) to ones in the target language (Japanese). (b) More recent application in NLP that represents relations between words within the input sentences. (c) Application to inter-individual relations explored in this study.

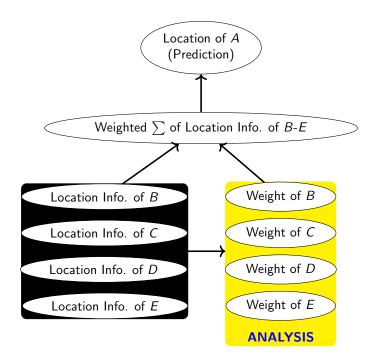


Figure 2: Schematic diagram of attention-based analysis.

changes in the location data, although the temporal information could include important traits of individuals
 and groups (cf. Morita et al., 2020) and thus should be discussed in future studies.

Figure 2 sketches the network structure, abstracting away from fine details (see the supporting information

S1 for the full structure of the network). The location of an individual named A is predicted from that of four other individuals, B, C, D, and E. The prediction is made from the weighted sum of the (transformed)

<sup>55</sup> location information of the four referents, where the weight of each referent—called *attention weight*—is also

 $_{56}$  derived from the location information. The attention weights govern the information flow from the referents;

57 they intuitively represent who is contributing how much to the prediction. Our analysis of the relations

<sup>58</sup> between the target and the referents is performed on these attention weights.

The attention weights were normalized and always have a sum of 1. However, this formalization has one disadvantage. The model never detects the independence of the target individual, as at least one referent always has a non-zero weight. Accordingly, the predictive performance of the attention model was compared with a baseline model that predicts the target without reference to the other individuals. If the attention weights are redundant, the attention model will have the same level of predictive performance as the noreferent baseline. The baseline model was trained to maximize the likelihood.<sup>1</sup>

### 65 2.2 Data

Attention-based relation analysis was performed on two simulated data ( $\S2.2.1$ ) and one real data ( $\S2.2.2$ ).

#### 67 2.2.1 Simulated Data

<sup>68</sup> The researchers tested the reliability of the attention-based relation analysis on two types of simulated data.

<sup>69</sup> Following the real data collected from Japanese macaques (see §2.2.2), both simulations had five individuals

<sup>70</sup> located in a bounded 3D space ( $[0.0, 5.0] \times [0.0, 4.0] \times [0.0, 2.5]$ ), resembling the group cage where the macaques <sup>71</sup> were kept.

The first simulation modeled the situation where the five agents moved in a sequence, each following the other (Figure 3a). This pattern was simulated by sampling the 3D location of each individual from

 $<sup>^{1}</sup>$ As reported in §2.2, the location of the target individual was discretized, which often improves the performance of neural networks (van den Oord et al., 2016a,b). Hence, the maximum likelihood training of the baseline model was simple. The occurrences of each discretized location value were counted and then the gathered data were normalized.

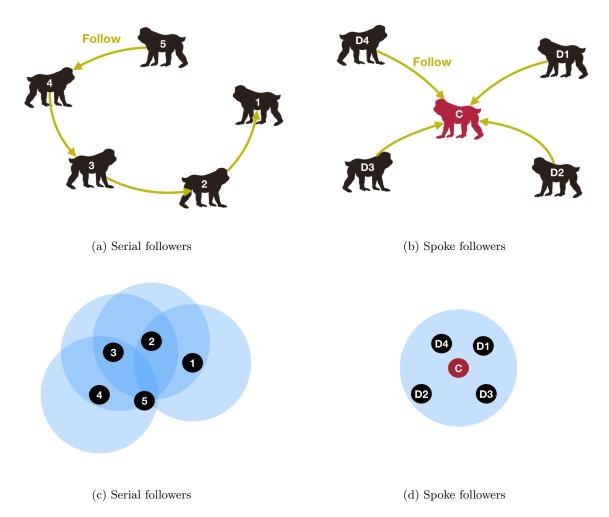


Figure 3: Two patterns of simulated data. (a) and (c) model animal agents that move in a sequence. (b) and (d) model the situation where there is a single hub individual (red) that is followed by the other four spoke dependents (black). (a) and (b) depict the relations among the animal agents modeled in the simulations. (c) and (d) describe the distributions from which the location data are sampled: The blue circles represent the support of the uniform distribution centered at each following individual.

the neighborhood of its predecessor: (i) the first individual was located uniformly randomly in the domain, and (ii) the (i + 1)-th individual was located uniformly randomly in the intersection of the domain and the sphere with 1.5 radius centered at the *i*-th individual's location, which was implemented by rejection sampling (Figure 3c).

The second simulation modeled the hub and spoke relation in which a single hub individual was followed by the other four spoke dependents (Figure 3b). The researchers simulated this situation by (i) first sampling the location of the hub individual uniformly from the domain, and (ii) sampling the location of the spoke individuals uniformly from the intersection of the domain and the sphere with 1.5 radius centered at the hub individual's location.

For each of the two simulations, 100,000 samples were generated—each containing 3D coordinates of the five individuals.<sup>2</sup> All the samples were used for the training and the attention analysis afterward. The researchers did not hold out a test portion of the data, as the study's purpose was not to test the general applicability of the model predictions, but rather to reveal the dependency relations in the data (just as in

<sup>&</sup>lt;sup>2</sup>The number of different target-referents pairs observed by the neural network was  $5 \times 100,000 = 500,000$ , since all the possible partitions of the five individuals were treated in the analysis as one target and four referents.

the linear regression tests).

<sup>88</sup> Note that in both cases, the location samples were the only information available to the neural network <sup>89</sup> analyzer. Furthermore, the settings of the simulations, including the type of the inter-individual relations and <sup>90</sup> the form of the conditional distributions, were not hard-coded in the analyzer, unlike other classical analyses <sup>91</sup> assuming a limited hypothesis space including the correct generative model (e.g., Bayesian inference). For <sup>92</sup> example, when analyzing the data from the second simulation, the network had to (i) discover the hub <sup>93</sup> structure among many other possible relation patterns behind the data, and (ii) identify the hub individual <sup>94</sup> while all the five agents were always close to one another.

Although the simulated data took on continuous values (residing in the bounded subspace of the 3D Euclidean), it has been reported that neural networks are often better at predictions of discrete categories (due to the flexibility of categorical distributions; van den Oord et al., 2016a,b, similar discrete predictions of location data were also adopted by Takeda and Komatani, 2016). Accordingly, the domain was split into 400 cubes  $(0.5 \times 0.5 \times 0.5)$ , and the network was trained to make a discrete prediction of the cube containing the target's location.

#### 101 **2.2.2 Real Data**

<sup>102</sup> In addition to the simulated data described in §2.2.1, the researchers analyzed real 3D location data of <sup>103</sup> five captive Japanese macaques in the Primate Research Institute, Kyoto University (KUPRI), Japan. The <sup>104</sup> subjects were two adult males and three adult females. The location recordings of the five macaques were <sup>105</sup> conducted for two weeks in an outdoor group cage  $(4 \times 5 \times 2.5 \text{ m})$ , where the subjects were allowed to freely <sup>106</sup> move and interact with one another. Each subject carried two Bluetooth<sup>®</sup> Low-Energy beacons, and their <sup>107</sup> 3D location was estimated based on the signals coming from these beacons (Quuppa Intelligent Locating <sup>108</sup> System<sup>TM</sup>). See Morita et al. (2020) for more details on the data collection procedure.

Although the system sampling frequency was set at 9 Hz, the actual rate was unstable because of 109 uncontrollable signal interference and reflection perturbation. The sampling from the  $2 \times 5 = 10$  beacons did 110 not also synchronize their timing. Accordingly, the researchers took the median value of the samples from 111 each individual (i.e., from the two beacons) for each dimension collected in every 3000 msec interval. The 112 medians over the same interval constituted the input-output pair for the neural network.<sup>3</sup> This sacrifices 113 time resolution of the collected data; however, this was not fatal to this study as the temporal information 114 was ignored in the analysis. The preprocessing above yielded a total of 327,592 sets of data.<sup>4</sup> Just as in the 115 simulations, all the data was used for both the model training and attention analysis without holding out a 116 test portion, and the target locations were discretized into 400 cubes  $(0.5 \times 0.5 \times 0.5 \text{ m})$ . 117

### **118 3 Results**

Figure 4 reports the average attention weights among five individuals in two representations. The heatmaps on the left-hand side represent the attention weight assigned to each referent individual (column) upon the prediction of the target individual (row) by the color density of the corresponding cell. Moreover, the directed graphs on the right-hand side represent the same information by the color density of the arrows coming from the referents to the targets.

The attention-based analysis correctly distinguished the two simulation patterns. Given the data from the serial follower simulation, the analyzer correctly assigned heavy weights (> 0.1) to the relations between the individuals with successive indices (e.g., "2" and "3"; Figure 4a,b). On another note, the hub-spoke simulation concentrated the attention weights to the hub individual when predicting the spoke dependents, and evenly distributed the weights to the spokes when predicting the hub (Figure 4c,d).

The analysis of the real data revealed that the female macaques were more informative referents than the males, especially when predicting the other females. The attention weight to Male 1 as a referent was smaller compared with all the females, except when Male 2 was predicted (where Female 1 collected zero

 $<sup>^{3}</sup>$ The network simultaneously analyzed all the possible choices of one individual as the prediction target and four as the referents.

<sup>&</sup>lt;sup>4</sup>Again, the researchers analyzed all the possible partitions of the five individuals into one target and four referents, and thus, the number of different target-referents pairs observed by the neural network was  $5 \times 327, 592 = 1,637,960$ .

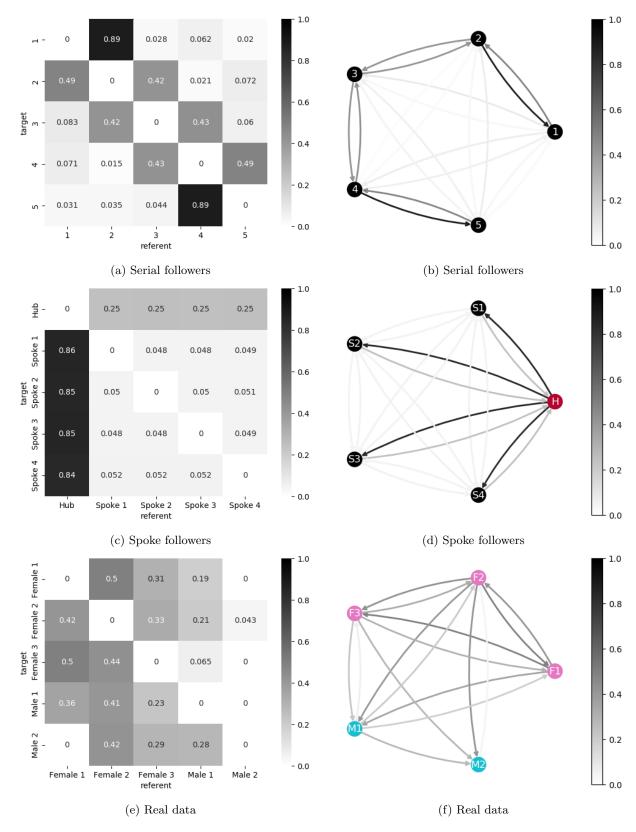


Figure 4: Attention weights. The same data are reported in heatmaps on the left-hand side and in directed graphs on the right-hand side. Top (a,b): results from the simulation with serial followers (Figure 3a,c). Middle (c,d): results from the simulation with a single hub individual and four spoke dependents (Figure 3b,d). Bottom (e,f): results from the real location data collected from two male and three female Japanese macaques (§2.2.2).

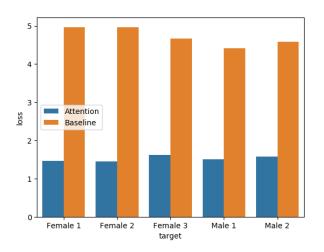


Figure 5: Average prediction loss (negative log probability) of the attention-based neural network and the no-referent baseline.

attention),<sup>5</sup> and Male 2 was almost never used as a referent (Figure 4e,f). It is of note, however, that the males did not move independently of the other individuals. The predictions of the males' location were based on three other individuals (Male 1 was dependent on the females, and Male 2 was dependent on Female 2, 3, and Male 1). While the neural network was unable to flag independence as the attention weights were never all zeros, these detected dependencies were not redundant because the network outperformed the no-referent baseline. As shown in Figure 5, the average prediction loss (i.e., negative log probability) of the attention model was smaller compared with the baseline across all the individuals.

### 139 4 Discussion

In the study, the attention analysis correctly identified the latent relations behind the two types of simulated data, one having serial followers and the other having the spoke followers. While these simulations were simple, it is of note that the analyses were performed without prior assumptions about the possible types of inter-individual relations or random distributions involved. Compared with the traditional distance/closeness-based analyses (Silk et al., 2006b,a; Croft et al., 2008; Clark, 2011; Boyland et al., 2013; Castles et al., 2014; Krause et al., 2015; Schofield et al., 2019), this method would be more effective in visualizing latent dependency patterns, especially when little is yet known about the properties of data.

The study also demonstrated that the attention analysis is applicable to raw real data, reporting a case 147 study of Japanese macaques. The researchers found that the location of females is more informative than 148 that of males in locating the other female individuals. This result is consistent with the female-oriented social 149 system of the macaques: Japanese macaques are a female-philopatrics species (represented by parturition in 150 the natal group and male emigration), and females usually build firmer and more stable social relationships 151 with one another than males (e.g., matrilineal social rank succession; Yamada, 1963; Furuichi, 1984; Mitani, 152 1986; Nakagawa et al., 2010). The females of the species are also reported to exhibit more tight and frequent 153 spatial cohesion (Otani et al., 2014). Therefore, knowing the location of some females is expected to increase 154 the chance of locating other females in the same group. In addition, the researchers' earlier study on the 155 same data showed that the males' movements (i.e. trajectories of the 3D location) reflect a greater degree 156 of individuality than that of the females (Morita et al., 2020). Because of such idiosyncratic movements, the 157 males' location may not be informative predictors of other individuals' location. The analysis of the real data 158 also revealed that one individual (Male 2) was almost never attended by the others. The discovery of such 159 distinguished individuals is useful to build new hypotheses about the animal society and plan behavioral 160

<sup>161</sup> experiments targeting them.

<sup>&</sup>lt;sup>5</sup>The average attention to Male 1, upon the predictions of Male 2, looked equal to the attention to Female 3, but it actually was statistically significantly smaller, considering the 10,000 samples of bootstrapping.

Attention analysis does not exploit any behavioral patterns that are particular to Japanese macaques, 162 and researchers can use it for location data of other animals, including ones that do not exhibit prototypical 163 social behaviors such as grooming. It can also be used if the conventional metric of distance/closeness is 164 unavailable. The researchers further emphasize that attention analysis is not limited to location data because 165 the flexibility of the neural network would allow its application to a wide variety of data with interacting 166 components. For example, vocal communication has been of major interest to behavioral biologists as well 167 as evolutionary linguists (Levinson, 2016). Attention analysis could potentially reveal latent communication 168 flow when applied to the vocalization recordings of multiple individuals. It is to be noted, however, that 169 the proposed method needs to be extended and refined for such broader applications and for more detailed 170 analyses of location/movement. For example, the current version does not process temporal changes in 171 location, whereas the implementation of temporal analysis is crucial in analyzing dynamic behaviors and 172 vocal communication. Since the attention mechanism was developed for NLP, however, processing time 173 series data should not be so hard (see Vaswani et al., 2017; Shaw et al., 2018; Dai et al., 2019, for popular 174 ways to encode time information). 175

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# 187 Ethical Statement

All the procedures were reviewed and approved by the Animal Welfare and Care Committee of KUPRI (Permission # 2018-203) and complied with the institutional guidelines (Primate Research Institute, 2010).

## <sup>190</sup> Author contributions

Project organization: IM HK; Animal arrangements: HK SA NSH; Apparatus building: AT IM HK; Data acquisition: AT IM HK; Animal cares: AK AT IM HK; Data management; HK AT TM; Computational modeling: TM; Manuscript writing: IM HK TM.

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