Residual errors in visuomotor adaptation persist despite extended motor preparation periods

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Abstract

A consistent finding in sensorimotor adaptation is a persistent undershoot of full compensation, such that performance asymptotes with residual errors greater than seen at baseline. This behaviour has been attributed to limiting factors within the implicit adaptation system, which reaches a sub-optimal equilibrium between trial-by-trial learning and forgetting. However, recent research has suggested that allowing longer motor planning periods prior to movement eliminates these residual errors. The additional planning time allows required cognitive processes to be completed before movement onset, thus increasing accuracy. Here we looked to extend these findings by investigating the relationship between increased motor preparation time and the size of imposed visuomotor rotation (30°, 45° or 60°), with regards to the final asymptotic level of adaptation. We found that restricting preparation time to 0.35 seconds impaired adaptation for moderate and larger rotations, resulting in larger residual errors compared to groups with additional preparation time. However, we found that even extended preparation time failed to eliminate persistent errors, regardless of magnitude of cursor rotation. Thus, the asymptote of adaptation was significantly less than the degree of imposed rotation, for all experimental groups. Additionally, there was a positive relationship between asymptotic error and implicit retention. These data suggest that a prolonged motor preparation period is insufficient to reliably achieve complete adaptation and therefore our results provide support for the proposal that the balance between error-based learning and forgetting (i.e., incomplete retention) contributes to asymptotic adaptation levels.

Key Words: Sensorimotor Adaptation; Motor Preparation; Mental Rotation; Learning Asymptote

69 Introduction

70 Sensorimotor adaptation has been extensively studied using visuomotor rotations
 71 (Cunningham, 1989; Krakauer, Ghilardi, & Ghez, 1999; Krakauer, Pine, Ghilardi, & Ghez,
 72 2000). In this task, individuals adapt reaching movements to counter visual feedback that is
 73 rotated, for example, 30° or 45° from the hand's position. However, adaptation is typically
 74 incomplete, and performance plateaus with errors a few degrees greater than at baseline,
 75 regardless of the rotation magnitude imposed (Fernandez-Ruiz, Wong, Armstrong, &
 76 Flanagan, 2011; Huberdeau, Haith, & Krakauer, 2015; van der Kooij, Brenner, van Beers, &
 77 Smeets, 2015; Vaswani et al., 2015; Weightman, Brittain, Punt, Miall, & Jenkinson, 2020;
 78 Langsdorf, Maresch, Hegele, McDougle, & Schween, 2021). State-space models of learning
 79 accurately capture this incomplete compensation (Smith, Ghazizadeh, & Shadmehr, 2006;
 80 Kording, Tenenbaum, & Shadmehr, 2007). In these models, error-driven learning and
 81 forgetting (or a reversion to baseline) work in opposition, and equilibrate below optimal
 82 performance, resulting in the commonly observed persistent error.

83 However, Vaswani and colleagues (2015) demonstrated that under certain conditions,
 84 individuals disengage from this limited error-dependent learning to attain greater task
 85 success. In one of their experimental conditions, Vaswani et al. (2015) 'clamped' visual
 86 feedback after an initial learning block, such that a small, fixed, visual error was presented,
 87 regardless of movement accuracy. They found that under these conditions, participants
 88 appeared to select an alternative, more exploratory learning policy, which enabled them to
 89 close the errors and even to overcompensate for the rotation (which was not predicted by
 90 the state-space model). The authors suggested that the altered feedback distribution
 91 triggered alternative learning processes (and enabled the elimination of residual errors),
 92 which are usually suppressed during naturalistic feedback conditions.

More recently, Langsdorf et al. (2021) presented an alternative theory to explain why under normal, non-clamped environments, the central nervous system fails to eliminate residual errors during motor adaptation. They suggested an intrinsic speed-accuracy trade-off: where time consuming planning processes are interrupted by the imperative onset of movement, resulting in fast, but inaccurate movements. In their study, they showed that when an obligatory 2.5 second wait period was introduced between target presentation and movement initiation, participants were able to fully adapt to a 45° rotation, leaving no persisting errors at the end of learning. However, if this wait period was not enforced or was introduced at the end of the movement, when no planning was assumed to be taking place, participants failed to fully counteract the rotation. The authors highlighted mental rotation as a time-consuming cognitive process potentially involved in the planning of visuomotor adaptation.

For some time now, visuomotor adaptation has been framed as a combination of distinct learning processes (Mazzoni & Krakauer, 2006; Taylor, Krakauer, & Ivry, 2014; Bond & Taylor, 2015; McDougle, Bond, & Taylor, 2015; Voets, Panouilleres, & Jenkinson, 2020). These processes are customarily described as implicit and explicit. The implicit component adapts slowly and is driven by sensory prediction errors (Smith et al., 2006; Tseng, Diedrichsen, Krakauer, Shadmehr, & Bastian, 2007). The explicit component is a fast adaptation process and involves, among other processes, strategic re-aiming to counter the detected perturbation (Taylor & Ivry, 2011; Heuer & Hegele, 2008; McDougle et al., 2015). Such strategies are thought to include a form of mental rotation (McDougle & Taylor, 2019). Langsdorf et al. (2021) suggest that under naturalistic feedback conditions, parametric mental rotations from the target to the intended movement goal are prematurely

terminated (despite no time constraints) and result in aimed movement trajectories falling short of the imposed rotation.

Behavioural and neurophysiological research suggests a role of mental rotation in the planning of movements aimed at angles away from visually defined targets (Georgopoulos & Massey, 1987; Bhat & Sanes, 1998; Georgopoulos, Lurito, Petrides, Schwartz, & Massey, 1989; Lurito, Georgakopoulos, & Georgopoulos, 1991; Pellizzer & Georgopoulos, 1993). Neuronal population vectors recorded in the monkey motor cortex gradually rotate from a stimulus direction to a cued movement direction during the planning of a reach (Georgopoulos et al., 1989; Lurito et al., 1991). Additionally, the completion of mental rotation tasks require long reaction times with larger magnitudes of rotation (Shepard & Metzler, 1971; Georgopoulos & Massey, 1987); a signature of cognitive strategies (Fernandez-Ruiz et al., 2011; Haith, Huberdeau, & Krakauer, 2015; McDougale & Taylor, 2019).

Given this knowledge, we aimed to replicate and extend the findings of Langsdorf et al. (2021), in order to further understand the roles of extended planning periods and mental rotation in attaining full adaptation. We designed an online visuomotor adaptation task, where participants had either long (2.5 seconds), medium (1 second) or short (0.35 seconds) enforced preparation periods between target presentation and movement onset, and were required to adapt to either a small (30°), moderate (45°) or large (60°) visuomotor rotation. Previous studies (Langsdorf et al., 2021) suggest that the 45° rotation would be fully corrected with the longest preparation period; errors for the middle interval would be greater; and a substantial residual error should be found for the shortest preparation interval. This negative relationship between preparation interval and residual error should be most obvious for the 60° rotation; the smallest rotation (30°) might allow full

compensation even at the shortest preparation interval. In other words, the response time could be considered the sum of a mental rotation period linearly related to the rotation magnitude, and a fixed movement initiation period; if the sum exceeds the prescribed preparation interval, then residual errors should be seen.

Materials and Methods

Participants

A total of 180 participants were recruited (aged 18-37 years, mean $\pm$ SD = 23 $\pm$ 4 years, 82 males); all gave informed consent before participating and received no remuneration for completing the study. The study was approved by the University of Birmingham ethics board (Science, Technology, Engineering and Mathematics Ethical Review Committee). Participants were self-reported as right-handed (161) or left-handed (19) and used their preferred hand to complete the task (all but 5 of the left-handed participants completed the task using their right hand). All participants had normal, or corrected to normal, vision and reported no history of neurological disease. Participants were pseudorandomised into one of nine experimental groups (each n = 20), which differed in the amount of preparation time provided (0.35, 1 or 2.5 seconds) and the magnitude of cursor rotation (30°, 45° or 60°).

Task

We developed a visuomotor adaptation task using the behavioural science experiment platform: PsychoPy (Peirce et al., 2019), which was implemented online via Pavlovia (<https://pavlovia.org>). Participants were required to have access to a desktop or laptop computer with internet connection and a mouse or trackpad to navigate through and complete the task (117 participants used a trackpad; 63 participants used a mouse).

Participants were sent a link to access the task and entered a unique code which determined which combination of preparation time and rotation angle they would encounter. Participants were asked to sit in a location of their choosing, so that they could easily see their computer screen and comfortably reach and manipulate the mouse or trackpad. They made centre-out movements with either their mouse or on their trackpad from an on-screen central starting position to targets which appeared on an invisible circular array surrounding it (Figure. 1a). They were told to make one fast and straight ‘shooting’ movement, aiming to get the on-screen cursor as close as possible to the target. Prior to starting the task, all participants completed a brief tutorial, which included the task instructions and aims. At this point, participants were asked to contact a researcher if they were unclear about any part of the task and/or had any questions relating to the instructions.

At the beginning of every trial the cursor (red filled circle) would be located in the centre of the screen (grey background). The cursor was surrounded by two larger red annuli, which formed a bullseye-like formation (Figure. 1b). At a set moment, the outer ring disappeared, followed by the inner ring 0.5 seconds later, and the cursor then changed colour from red to white after a further 0.5 seconds. Participants were told that this sequence of events should be treated as a countdown to movement and that they should aim to time their movement so that it was initiated in synchrony with the cursor changing colour from red to white (Figure. 1b). Depending on the experimental group, the target (green filled circle) would appear either 2.5 seconds, 1 second or 0.35 seconds before the movement cue - thus creating three distinct preparation periods. The target could appear at any one of eight possible locations, equally spaced (separated by 45°) around an invisible circular array centred on the start position, and pseudorandomised so that the target appeared at each

location once every cycle of eight trials. The position at which the cursor passed the invisible perimeter was displayed for 0.5 seconds as static open white circle, providing feedback of movement accuracy. After an inter-trial interval of 0.5 seconds the cursor would reset to the central position ready for the next trial. Participants were encouraged to move their hand back to a comfortable starting position after each trial. All elements of the visual display were scaled according to the size of the task window and thus were the same relative size for all participants. Consequently, the physical movement size required varied between participants depending on their set up and was not recorded beyond input device. If participants attempted to move 0.15 seconds before or after the go cue, or if movement time exceeded 0.25 seconds, the message "Response too fast/slow" appeared on the screen and the trial was aborted. These measures were to encourage fast movements, initiated correctly with the task instructions.

Figure 1: The experimental design. **a** Participants used either a mouse or trackpad to direct an on-screen cursor towards targets presented radially around a central starting position. **b** An example of the cursor countdown sequence and movement cue. At the beginning of each

trial the (red) cursor would appear in the centre of the screen, flanked by two larger (red) rings (shown here on the top row). During the trial the two rings would disappear in sequence and the cursor would change colour to white. Participants were required to initiate their movement in synchrony with the cursor colour change, using the disappearing rings as a countdown. The target (shown on the bottom row) would appear either 2.5, 1 or 0.35 seconds prior to the movement cue, depending on group assignment. c Time course of the study protocol. Participants completed 40 baseline trials, followed by 280 adaptation trials (where either a 30°, 45° or 60° cursor rotation was imposed), then 40 no-feedback trials and finally 40 de-adaptation trials.

Experimental Design

Participants first performed eight practice trials (one at each target location). These trials were performed with veridical cursor feedback and were used to familiarise the participants with the timing of their version of the task. The main task directly followed the practice trials and included four phases: baseline, adaptation, no-feedback and de-adaptation (Figure. 1c). During baseline trials (n = 40) participants received veridical cursor feedback, such that the on-screen cursor moved in accordance with participants' movements. Adaptation trials immediately followed, in which the cursor feedback was rotated 30°, 45° or 60° (depending on the experimental group, see below) relative to participants' movement. This block lasted 280 trials, selected to ensure learning approached its asymptotic limit, based on pilot data collected prior to the present study. While there is some indication that full asymptotic saturation of learning was not achieved in all conditions, regression analysis of the last 40 trials of adaptation indicated that there was no significant trend remaining (all p > 0.19) and thus we use the term 'asymptote' to refer to the final state reached at the end of the 280 adaptation trials. Following adaptation trials, participants performed no-feedback trials (n = 40). During these trials, participants were told to stop using any strategies they might have employed to achieve the task objectives and try to aim directly for the target. The cursor was hidden at all times during the trial,

apart from when located in the central position for the countdown cue. End-point error was not displayed during the no-feedback phase. Veridical cursor feedback and display of end-point error were then restored for the final de-adaptation trials (n = 40). There were nine participant groups (Table. 1), to cover all combinations of preparation time (long: 2.5 seconds, medium: 1 second, short: 0.35 seconds) and the magnitude of cursor rotation (large: 60°, moderate: 45°, small: 30°). The preparation time was held constant throughout the whole task; the rotation was applied only during the adaptation phase.

	0.35 seconds			1 second			2.5 seconds		
	30°	45°	60°	30°	45°	60°	30°	45°	60°
N (n male)	20 (9)	20 (6)	20 (8)	20 (11)	20 (12)	20 (4)	20 (10)	20 (13)	20 (9)
Age (years) ± SD	23.5 (± 2.0)	25.4 (± 3.4)	25.9 (± 3.4)	21.0 (± 1.1)	21.5 (± 3.7)	22.6 (± 5.0)	20.8 (± 1.3)	21.0 (± 1.6)	22.7 (± 3.7)

Table 1: Summary of experimental groups.

Data Analysis

There were three main outcome variables: reach angle, response time and movement duration. Our primary dependent variable - reach angle - was the angular difference between the target location and participants' movement at end-point (i.e., the difference in angle between the vector linking the starting position and the target marker, and the vector linking the starting position and the point at which participants' movement crossed the target circle perimeter). Trials were deemed outliers and removed if they fell 2.5 standard deviations outside the group average on each trial. A total of 1.06% of all trials were removed from further analysis. Data from each participant was then averaged into bins of 4 trials to be used for visual representation and statistical analysis. Response time was defined as the time period between target presentation and movement onset (i.e., cursor movement breaking an invisible line immediately surrounding the starting position) and

movement duration was defined as the time period between movement onset and when movement crossed the target circle. Reach angle data was not recorded for trials where the response or movement time limits were violated.

Statistical Analysis

Asymptotic levels of adaptation were defined as the mean error over the last 40 trials of the adaptation phase and compared between groups in a two-way ANOVA (Rotation Magnitude = 3 levels (30°/45°/60°) x Preparation Time = 3 levels (0.35 seconds/1 second/2.5 seconds)), with any significant main effects or interactions followed up with Bonferroni-corrected multiple comparisons. Asymptotic differences from the imposed rotation magnitude were compared using a Wilcoxon Signed Rank test, after data from some groups failed normality checks (Shapiro-Wilk test). All statistical analyses were carried out in MATLAB (R2018b) and SPSS (IBM, version 27). All ANOVAs were run as general linear models. The threshold for statistical significance was set at $p < 0.05$ and we report W , F and p -values, as well as effect sizes from ANOVAs (partial eta squared (η^2)).

Modelling

To model the adaptation data, we made two assumptions. First, the time required to plan a reach action was linearly proportional to the rotation magnitude M (i.e., mental rotation speed (rs) was constant). If preparation time (T) was insufficient, the planned reach angle was to the angle mentally reached. Second, the asymptotic level of adaptation (achieved reach angle, A) would be proportional to the planned reach angle scaled by the learning ratio (lr) of learning and forgetting rates (Smith et al., 2006). Thus,

$$A = lr * \min(M, rs * T), \quad (1)$$

with two free parameters, lr and rs . The mean asymptotic reach angles for the 9 groups were fitted with this equation using the MATLAB 'nlinfit' function, estimating lr and rs , and providing 95% confidence intervals for each. The learning ratio lr defines the proportion of the rotation magnitude reached at steady state i.e., an angle where learning driven by the remaining error and forgetting back to baseline are in equilibrium; the ratio of $lr/(1-lr)$.

Results

Baseline performance does not differ between groups

Differences in reach angle during the baseline phase were assessed in a two-way ANOVA (Rotation Magnitude x Preparation Time), which revealed no significant main effects for Rotation Magnitude ($F(2, 172) = 0.71, p = 0.93, \eta^2 = 0.001$), Preparation Time ($F(2, 172) = 0.29, p = 0.75, \eta^2 = 0.003$), and no significant Rotation Magnitude*Preparation Time interaction ($F(4, 172) = 0.45, p = 0.77, \eta^2 = 0.1$). This result suggests that all groups performed similarly during baseline trials (Figure. 2) and thus, group differences are unlikely to influence performance later in the task. We felt this analysis important, given the limited experimenter input associated with online research.

Figure 2: Mean reach angle and response time for each of the experimental groups. Top panel: Reach error ($\pm$ standard error, shaded region) is averaged every four trials into bins for (from left to right) the 30°, 45° and 60° groups, with zero degrees and the magnitude of imposed rotation shown as a dotted and dashed line respectively. Bottom panel: Mean response time (time between target presentation and movement initiation), $\pm$ standard error (shaded region) for each group. Note, preparation times were predetermined at 0.35, 1 or 2.5 seconds (dotted lines) and were tightly controlled.

The effect of differing preparation time on asymptotic levels of adaptation

A two-way ANOVA comparing asymptotic levels of adaptation revealed significant main effects for Rotation Magnitude ($F(2, 172) = 121.01, p < 0.001, \eta^2 = 0.59$), Preparation Time ($F(2, 172) = 15.17, p < 0.001, \eta^2 = 0.15$) and a significant Rotation Magnitude*Preparation Time interaction ($F(4, 172) = 5.24, p < 0.001, \eta^2 = 0.11$). Multiple comparisons revealed that in the 45° rotation group, there were some differences between learning asymptotes, with regards to preparation time provided. The 0.35 second preparation time group displayed impaired adaptation compared to the 1 and 2.5 second groups (both $p < 0.001$), with no further differences between the latter two conditions ($p > 0.99$). However, contrary to Langsdorf et al. (2021), all final levels of adaptation significantly differed from 45° (0.35 seconds: $W = -210.0, p < 0.001, 95\% \text{ CI} = [-16.72, -11.32]$; 1 second: $W = -200.0, p < 0.001, 95\% \text{ CI} = [-9.71, -2.50]$; 2.5 seconds: $W = -210.0, p < 0.001, 95\% \text{ CI} = [-9.33, 3.18]$). The 0.35 seconds preparation time group compensated 67.3% for the rotation, with the 1 and 2.5 second groups achieving 85.1% and 86.1% compensation respectively (Figures. 2 & 3), suggesting that additional preparation time allowed for greater compensation but not the elimination of residual errors.

Similarly, for the 60° rotation condition, shortening planning time to 0.35 seconds significantly reduced the final level of adaptation compared to both 1 and 2.5 second preparation periods (0.35 seconds vs 1 second: $p = 0.001$, 0.35 seconds vs 2.5 seconds: $p <$

0.001). However, there was no difference between the 1 and 2.5 second groups with respect to final adaptation levels ($p = 0.17$). Participants averaged 62.4% compensation with 0.35 seconds preparation time, 75.0% with 1 second preparation time and 81.7% with 2.5 seconds preparation time (Figures. 2 & 3). Additionally, all asymptotic levels of adaptation significantly differed from the imposed 60° rotation (0.35 seconds: $W = -210$, $p < 0.001$, 95% CI = [-31.14, -16.02]; 1 second: $W = -210.0$, $p < 0.001$ 95% CI = [-16.27, -10.27]; 2.5 seconds: $W = -206.0$, $p < 0.001$, 95% CI = [-16.76, -6.44]).

In the 30° rotation group, there were no differences in asymptotic error between any of the different preparation time groups (all $p > 0.99$, Figure. 2). Furthermore, all final levels of adaptation differed significantly from 30° (0.35 seconds: $W = -210.0$, $p < 0.001$, 95% CI = [-5.35, -2.39]; 1 second: $W = -204.0$, $p < 0.001$, 95% CI = [-6.87, -2.98]; 2.5 seconds: $W = -210.0$, $p < 0.001$, 95% CI = [-8.09, -3.25]), with adaptation reaching 84.7%, 82.8% and 82.0% of the optimum, respectively (Figure. 3).

In summary, our results support previous work suggesting that mental rotation contributes an interval to the planning process which is proportional to rotation magnitude, and that short periods of preparation interrupt planning, leading the greater residual errors. However, for the smallest rotation, we found no relationship between preparation time and error, suggesting that mental rotation was completed within the allowed time. But even in these circumstances, there were significant residual errors. In fact, in opposition to results reported by Langsdorf et al. (2021), all groups displayed incomplete adaptation regardless of the preparation time provided.

Figure 3: The asymptotic levels of adaptation for each participant in each of the rotation magnitude and preparation time groups. Filled circles represent the adaptation asymptote for each participant (defined as the average of the last 40 adaptation trials), with mean values and standard error depicted by horizontal and vertical lines respectively. Dashed horizontal lines depict the imposed cursor rotation for each group.

Modelling asymptotic performance

The nine group mean asymptotic reach angles were well fitted by the model (Figure. 4), with the confidence intervals of the fit overlapping with each group mean. The estimated values of the two free parameters were $lr = 0.814$ (95% CI: 0.761- 0.867) and $rs = 118.9$ degrees/sec, (95% CI 101.64 - 136.34). From the learning ratio, lr , the learning rate is estimated to be at least 4.4 times the forgetting rate. This is potentially an underestimate, however, as some of adaptation curves may not have fully saturated (Figure. 2), despite regression analysis indicating no significant trend (all $p > 0.19$).

Figure 4. The group mean asymptotic adaptation angles (coloured dots, ± 1 SEM) are well estimated by the model (see main text). The model (black dots, $\pm 95\%$ confidence intervals) assumes a fixed mental rotation speed and a fixed ratio between learning and forgetting rates.

Restricting motor preparation time resulted in a stronger implicit retention

Implicit retention was defined as the mean reach angle in the first 16 no-feedback trials (two cycles of reaches to each target location) and was compared between groups in a two-way ANOVA (Rotation Magnitude x Preparation Time). Results from the ANOVA revealed a significant main effect of Rotation Magnitude ($F(2, 172) = 6.71, p = 0.002, \eta^2 = 0.07$) and Preparation Time ($F(2, 172) = 18.33, p < 0.001, \eta^2 = 0.18$), but no significant interaction ($F(4, 172) = 1.08, p = 0.37, \eta^2 = 0.03$). Multiple comparisons showed that participants in the restricted 0.35 second motor preparation time groups displayed greater retention than both the 1 second ($p < 0.001$) and 2.5 second ($p < 0.001$) groups, with no differences between the latter two ($p > 0.99$).

Input device (trackpad vs mouse) had no effect on late adaptation levels

In order to determine whether the input device used to complete the task affected the extent of adaptation, we compared asymptotic learning levels in each rotation and preparation time group, dependent on whether a mouse or trackpad was used, in a 3x3x2 mixed-design ANOVA (Rotation Magnitude x Preparation Time x Input Device). The ANOVA revealed no significant main effect of Input Device ($F(1, 172) = 1.13, p = 0.29, \eta^2 = 0.007$) and no significant three-way interaction ($F(4, 172) = 0.38, p = 0.82, \eta^2 = 0.009$). In fact, no interaction that included the term Input Device revealed significance (Rotation Magnitude*Input Device: $F(2, 172) = 0.53, p = 0.59, \eta^2 = 0.006$, Preparation Time*Input Device: $F(2, 172) = 0.21, p = 0.81, \eta^2 = 0.003$), suggesting that the input device used had little effect on adaptive performance during the task (Supplementary Figure. 1, see <https://doi.org/10.6084/m9.figshare.14797926>).

Discussion

We aimed to test the assumption that increased motor preparation periods may allow for more complete adaptation during visuomotor rotation tasks. As such, we hypothesised that shorter preparation periods would be sufficient to fully counteract a 30° rotation, as a small rotation would require less (and therefore quicker) mental rotation before motor execution. We then predicted that this effect would scale with an increased cursor rotation, so that 45° and 60° would require greater mental rotation and thus more time to fully compensate. Indeed, we did find that restricting planning time for moderate and larger rotations resulted in impaired final adaptation levels and greater implicit retention compared to those groups with more preparation time. However, contrary to research from Langsdorf et al. (2021), we

found no evidence to suggest that extended motor preparation periods allow for the elimination of residual errors observed during late stages of adaptation, as all groups displayed final adaptation performance significantly lower than the imposed cursor rotation.

Hence, we failed to replicate the results from Langsdorf et al. (2021), who found that enforcing a 2.5 second planning period between target presentation and reach onset allowed individuals to fully counteract a 45° visuomotor rotation, leaving no residual mean error at asymptote. The authors suggested that the extended planning period allowed for time-consuming cognitive processes, such as mental rotation, to be completed prior to the go-signal and resulted in complete compensation. This theory, centred around a speed-accuracy trade-off, seems plausible given that reaction times increase in a linear fashion when subjects are asked to reach at increasing angles from a target - a relationship that mimics the behaviour seen in mental rotation tasks (Shepard & Metzler, 1971; Georgopoulos & Massey, 1987; McDougle & Taylor, 2019). Accordingly, brain regions activated in both visuomotor adaptation and mental rotation tasks have also been shown to overlap (Anguera, Reuter-Lorenz, Willingham, & Seidler, 2010), suggesting that mental rotation contributes to visuomotor adaptation. Recent evidence investigating preparatory activity in the motor cortex of non-human primates further suggests the necessity for motor planning time in visuomotor adaptation (Vyas, O'Shea, Ryu, & Shenoy, 2020). In addition, Langsdorf et al. (2021) found that delaying movement initiation resulted in an overcompensation of the imposed rotation, similar to the overshoot in reach estimation shown by Georgopoulos and Massey (1987), suggesting similar cognitive rotation strategies may have been in play.

Notwithstanding these studies, we found that on average participants' learning plateaued before eliminating error, with asymptotic learning levels statistically different from the degree of imposed rotation for all rotational groups (30°, 45°, 60°), regardless of the amount of preparation time enforced. These findings are consistent with previous reports which have suggested that sustained errors during visuomotor adaptation are a product of the implicit learning system; either suppressing alternative learning mechanisms which may be able to overcome persisting errors (Shmuelof et al., 2012; Vaswani et al., 2015) and/or modulating the system's sensitivity to errors dependent on their size, variability and history (Albert et al., 2021).

One factor that may explain the discrepancy between our results and those of Langsdorf et al. (2021), is the level of experimental control. Our study was conducted online, with participants completing the task unsupervised at home, whereas Langsdorf et al. (2021) conducted a laboratory-based study. The disparities associated with these environments may have contributed to small but significant differences in motivation, attention and behaviour. That said, our data are typical of many previous lab-based visuomotor adaptation studies, with comparable levels of final performance (Huberdeau et al., 2015; Morehead, Qasim, Crossley, & Ivry, 2015; Vaswani et al., 2015; Neville & Cressman, 2018; Weightman et al., 2020; Weightman, Brittain, Miall, & Jenkinson, 2021). Furthermore, initial evidence suggests that kinematic data and results from online motor learning studies are analogous with those collected in a controlled lab environment (Tsay, Lee, Ivry, & Avraham, 2021) and that online tasks perform well in terms of accuracy and precision with regards to timing of visual stimuli and response capture (Bridges, Pitiot, MacAskill, & Peirce, 2020).

An additional difference between the two studies, which may have had some bearing on the results, is the nature of response cueing used. We used a visual countdown sequence

which enabled participants to accurately synchronise their movements with the go-signal and ensured a tight coupling between response times and the preparation time groupings. In contrast, Langsdorf et al. (2021) displayed the target and instructed participants to wait until they heard a tone before responding. This difference in protocol resulted in response times closer to 3 seconds. One may argue that more than 2.5 seconds are required to fully prepare for a 45° rotated reach. This is unlikely however, as we show that even a 30° angle was not fully compensated, and there was no evidence for a relationship with the preparation interval for those groups. Previous research has also shown that mental rotation and aiming towards angles up to 90° can be achieved in ~1 second (McDougle & Taylor, 2019). The modelling data additionally supports this, as it assumes that mental rotation to the target angle is achieved within the allotted preparation time for most conditions (with the eventual reach angle reduced by the learning ratio). There is perhaps an argument to suggest that attending to the countdown sequence may have interfered with mental rotation and other cognitive planning processes, by, for instance vying for attentional resources and thus contributing to a consistent reach undershoot (Taylor & Thoroughman, 2007; Galea, Sami, Albert, & Miall, 2010). Nevertheless, prior studies using auditory response cueing have not cited attention to the timed-response sequence as a potential confound (Haith et al., 2015; Leow, Gunn, Marinovic, & Carroll, 2017; McDougle & Taylor, 2019).

Despite participants failing to eliminate residual errors during late adaptation, our data do include some hallmarks of a speed-accuracy trade-off. We found that motor adaptation was impaired in the 45° and 60° rotational groups, when planning time was restricted to 0.35 seconds. This result is in line with previous studies who report reduced error compensation when preparation times are limited (Fernandez-Ruiz et al., 2011; Leow, Gunn, et al., 2017;

Leow, Marinovic, Riek, & Carroll, 2017; Albert et al., 2021) and may reflect the suppression of explicit re-aiming/cognitive strategies. Additionally, impaired adaptation associated with restricted preparation times was coupled with an increased retention during no-feedback trials, which is consistent with the idea that learning involved more implicit, procedural processes (Fernandez-Ruiz et al., 2011; Haith et al., 2015). The greatest retention was seen in the 0.35 seconds / 60° group, which implies that the greater residual errors in this group led to stronger implicit learning. This suggestion is reinforced by the equal retention seen for the 2.5 second condition, across all three rotation magnitudes. In this case, the residual errors are approximately equal, because the preparation time exceeded that required for mental rotation. However, these assumptions should be treated with some caution after recent commentary on how the dichotomy of implicit and explicit components of motor adaptation are inferred (Hadjiosif & Krakauer, 2021).

Although not statistically evident, a speed-accuracy trade-off may also be apparent in the 60° rotational group (Figure. 3). On average, there was a linear increase in learning asymptote as preparation time increased, which may reflect how mental rotation of the intended movement angle increases the accuracy of reaches (McDougle & Taylor, 2019; Langsdorf et al., 2021). Addition of further adaptation trials might exaggerate these asymptotic differences, until statistically significant, yet data from our other rotational groups and previous literature would suggest that errors would still persist. To achieve full compensation, it is possible that explicit information about the nature of rotation ought to be provided (McDougle & Taylor, 2019) or strategies primed using methods such as verbal aiming reports (Bond & Taylor, 2015; Brudner, Kethidi, Graeupner, Ivry, & Taylor, 2016; Wilterson & Taylor, 2019; Albert et al., 2021; Langsdorf et al., 2021), which are inherently coupled with increased reaction/plan times.

In summary, our data suggests that extending motor preparation and planning periods alone is insufficient to eliminate residual errors during visuomotor adaptation, irrespective of the size of imposed cursor rotation. While increased preparation time may help to improve error reduction at larger rotation magnitudes, our results suggest there remains a limit at which learning saturates at asymptote, perhaps only overcome with priming of explicit strategies, further instruction or changes to experimental variables. Understanding why the central nervous system fails to fully adapt movements in response to environmental changes may be key when aiming to optimise rehabilitation protocols following brain injury or disease.

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635

636 **Author Contributions**

637 MW, JSB and NJ conceived and designed the study with input from RCM. MW collected the
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641 The authors declare no competing interests.